

Document Title	SWS_CANTransportLayer: Complete Change Documentation 4.3.0 - 4.3.1
Document Owner	AUTOSAR
Document Responsibility	AUTOSAR
Document Identification No	695

Document Status	Final
Part of AUTOSAR Standard	Classic Platform
Part of Standard Release	4.3.1

Table of Contents

1	SWS_CANTransportLayer	3
1.1	Specification Item ECUC_CanTp_00245	3
1.2	Specification Item ECUC_CanTp_00265	4
1.3	Specification Item ECUC_CanTp_00282	5
1.4	Specification Item SWS_CanTp_00031	7
1.5	Specification Item SWS_CanTp_00093	10
1.6	Specification Item SWS_CanTp_00160	14
1.7	Specification Item SWS_CanTp_00216	15
1.8	Specification Item SWS_CanTp_00229	18
1.9	Specification Item SWS_CanTp_00254	19
1.10	Specification Item SWS_CanTp_00260	24
1.11	Specification Item SWS_CanTp_00264	28
1.12	Specification Item SWS_CanTp_00269	31
1.13	Specification Item SWS_CanTp_00293	33
1.14	Specification Item SWS_CanTp_00294	34
1.15	Specification Item SWS_CanTp_00305	35
1.16	Specification Item SWS_CanTp_00324	40
1.17	Specification Item SWS_CanTp_00330	44
1.18	Specification Item SWS_CanTp_00332	45
1.19	Specification Item SWS_CanTp_00335	46
1.20	Specification Item SWS_CanTp_00345	47
1.21	Specification Item SWS_CanTp_00346	52
1.22	Specification Item SWS_CanTp_00348	56
1.23	Specification Item SWS_CanTp_00349	57

1 SWS_CANTransportLayer

1.1 Specification Item ECUC_CanTp_00245

Trace References:

none

Content:

Name	CanTpNbrCanTpRxNSdu.CanTpNbr		
Description	Value in seconds of the performance requirement for (N_Br + N_Ar). N_Br is the elapsed time between the receiving indication of a FF or CF or the transmit confirmation of a FC, until the transmit request of the next FC.		
Multiplicity	1 0..1		
Type	EcucFloatParamDef		
Range	[0 .. INF]		
Default value	-		
Post-Build Variant Value	true		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	-	
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #77438: Clarification about CanTpNbr

Problem description:

Could you make clarification about CanTpNbr[ECUC_CanTp_00245].

Current description @ R4.3.0: its multiplicity is 1.

But I think that its multiplicity is 0..1.

In some cases there is no need to set CanTpNbr.

If CanTpRxTaType is CANTP_FUNCTIONAL or CANTP_CANFD_FUNCTIONNAL, only SF is received.

If only SF is received, N_Br timeout is not measured. So it is no need to set CanTpNbr.

The multiplicity of the similar parameter CanTpNcr[ECUC_CanTp_00279] is 0..1.

Based on the above, I think that the multiplicity should be 0..1.

Agreed solution:

Change CanTpNbr(ECUC_CanTp_00245) multiplicity to optional (1 -> 0..1).
–Last change on issue 77438 comment 2–

BW-C-Level:

Application	Specification	Bus
1	1	1

1.2 Specification Item ECUC_CanTp_00265

Trace References:

none

Content:

Name	CanTpNcsCanTpTxNSdu.CanTpNcs		
Description	Value in seconds of the performance requirement of (N_Cs + N_As). N_Cs is the time which elapses between the transmit request of a CF N-PDU until the transmit request of the next CF N-PDU in which CanTp is allowed to request the Tx data of a Consecutive Frame N_PDU.		
Multiplicity	0..1		
Type	EcucFloatParamDef		
Range	[0 .. INF]		
Default value	–		
Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	–	
	Post-build time	X	VARIANT-POST-BUILD
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	–	
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #75560: Description of EcuC parameter CanTpNcs is wrong

Problem description:

The following description is wrong:

SWS Item ECUC_CanTp_00265 :

Name CanTpNcs

Description Value in seconds of the performance requirement of (N_Cs + N_As).
N_Cs

is the time which elapses between the transmit request of a CF N-PDU until the transmit request of the next CF N-PDU.

Adaption of the description to fit the correct functional requirements:

[SWS_CanTp_00167] After a transmission request from upper layer, the CanTp module shall start time-out N_Cs before the call of PduR_CanTpCopyTxData. If no data is available before the timer elapsed, the CanTp module shall abort the communication. ()

Note: If no data is available before the expiration of the N_Cs timer (ISO 15765-2

specification defines the following performance requirement: $(N_Cs + N_As) < 0.9 \cdot N_Cr$ timeout), the CanTp module shall abort this transmission session.

[SWS_CanTp_00280] If data is not available within N_Cs timeout the CanTp module shall notify the upper layer of this failure by calling the callback function PduR_CanTpTxConfirmation with the result E_NOT_OK. ()

–Last change on issue 75560 comment 8–

Agreed solution:

Update ECUC_CanTp_00265 to:

Name CanTpNcs

Description Value in seconds of the performance requirement of $(N_Cs + N_As)$. N_Cs is the time in which CanTp is allowed to request the Tx data of a Consecutive Frame N_PDU.

–Last change on issue 75560 comment 2–

BW-C-Level:

Application	Specification	Bus
1	1	1

1.3 Specification Item ECUC_CanTp_00282

Trace References:

none

Content:

Name	CanTpTc
Description	Switch for enabling Transmit Cancellation and Receive Cancellation.

Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	–		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	–	
	Post-build time	–	
Scope / Dependency	scope: local		

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #74682: [CanTp]: CanTpTc cannot handle Receive Cancellation

Problem description:

ECUC_CanTp_00282:

CanTpTc

Description:

Switch for enabling Transmit Cancellation and Receive Cancellation.

It is not sure how CanTpTc which is in container
CanTp\{}CanTpConfig\{}CanTpChannel\{}CanTpTxNSdu

can enable\{}disable the control for something inside
CanTp\{}CanTpConfig\{}CanTpChannel\{}CanTpRxNSdu
–Last change on issue 74682 comment 12–

Agreed solution:

SWS_CanTp:

Update description of ECUC_CanTp_00282 to:

"Switch for enabling Transmit Cancellation."

TPS_SystemTemplate:

Update description of CanTpConnection.cancellation to

"With this switch Tx Cancellation can be turned on or off. Please note that the Rx Cancellation is always enabled."

–Last change on issue 74682 comment 6–

BW-C-Level:

Application	Specification	Bus
1	1	1

1.4 Specification Item SWS_CanTp_00031

Trace References:

SRS_Can_01076

Content:

If **default development** error detection for the CanTp module is enabled the CanTp module shall raise an error (CANTP_E_UNINIT) when the PDU Router or CAN Interface tries to use any function (except CanTp_GetVersionInfo) before the function CanTp_Init has been called.

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #73570: No "default error" in AUTOSAR

Problem description:

The DET was renamed from development error tracer to default error tracer.

This change was most of the time done automatically and unfortunately renamed "developement error" to "default error".

"default error" should always be followed by "tracer", otherwise, "development error" is probably the right term.

This could increase the impact (compared to my selection of impacted document, but formally, the configuration parameters *DevErrorDetect are not using the correct description:

"Switches the Default Error Tracer (Det) detection and notification..."

The parameter switches on/off the developement error detection. The DET does not need to be detected and can be present even when the parameter is set to false.

Agreed solution:

Rename "default error" to "development error" in all impacted documents, but not in an automated way (Do not change "default error tracer" to "developement error tracer"!)

Blueprint/Example:

- sub chapter is now called "7.x Default errors"
- "[SWS_xxx_yyyyy]

In case default error detection is enabled for the xxxx module: The xxxx module

shall check API parameters for validity and report detected errors to the DET. ()"

- "[SWS_xxx_yyyyy]

If default error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the default error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"

- "In case default errors are enabled,..."

- "module raises the Default error XXX_E_TRANSITION"

- "The DET provides services to store default errors"

...

The correct text would be:

- sub chapter is called "7.x Development errors"

- "[SWS_xxx_yyyyy]

In case development error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected development errors to the DET. ()"

- "[SWS_xxx_yyyyy]

If development error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the development error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"

- "In case development errors are enabled,..."

- "module raises the development error XXX_E_TRANSITION"

- "The DET provides services to store development errors"

Solution for SWS_RTE:

— SWS_RTE —

- Change 4.8 Default errors to 4.8 Development errors

- Change "Errors which can occur at runtime in the RTE are classified as default errors" to "Errors which can occur at runtime in the RTE are classified as development errors"

- Remove [SWS_Rte_07676]

- Change [SWS_RTE_06611]"If a violation is detected the RTE shall report a default error to the DET." to "If a violation is detected the RTE shall report a development error to the DET."

- Change [SWS_Rte_06631]

[SWS_Rte_06631] d The RTE shall use the OS Application Identifier as the Instance Id to enable the developer to identify in which runtime section of the RTE the error occurs. This Instance ID is even unique across multi cores and so implicitly allows the development error to be traced to a specific core. c(SRS_BSW_00337)

SRS_Libraries:

- In chapter "3 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_SPALGeneral:

- In chapter "6.1.1.3.1 [SRS_SPAL_00157] ...": Rename "Development Error Tracer" to "Default Error Tracer"
- In chapter "6.1.1.4.2 [SRS_SPAL_12448] ...": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_FlashTest:

- In chapter "6.1 Functional Requirements": Rename "Development Error Tracer" to "Default Error Tracer"
- In chapter "7 References":
Rename "Development Error Tracer" to "Default Error Tracer"
Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_MFXLibrary:

- In chapter "2 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SWS_MemoryAbstractionInterface:

- In chapter "3.1 Input documents":
Rename "Development Error Tracer" to "Default Error Tracer"
Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_FlexRayNetworkManagement:

- In chapter "3.3 Related AUTOSAR documents":
Rename "Development Error Tracer" to "Default Error Tracer"
Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_CANStateManager:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_PDURouter:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_EEPROMDriver:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"
–Last change on issue 73570 comment 47–

BW-C-Level:

Application	Specification	Bus
1	1	1

1.5 Specification Item SWS_CanTp_00093

Trace References:

none

Content:

If a multiple segmented session occurs (on both receiver and sender side) with a handle whose communication type is functional, the CanTp module shall reject the request and generate, if the default error detection is enabled, a development error report the runtime error code CANTP_E_INVALID_TATYPE to the Default Error Tracer.

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #59085: Rollout of 'Runtime errors'

Problem description:

Inconsistencies in SWS with semantics of Default errors
–Last change on issue 59085 comment 26–

Agreed solution:

solution in Column "G" of the new attachment
<https://www.autosar.org/bugzilla/attachment.cgi?id=4604>

Notes:

- It is not enough just to migrate the error from one classification table to another.

Please also check the related requirements (and background information) which is referring to that error and adapt them if needed.

- The review task of the ITs shall be done by the WP to which the specification "belongs".

*** BSW UML Model ***

SWS_CanNm:

Chapter 8.6.1 Optional Interfaces:

Add within SWS_CanNm_00325 the API function Det_ReportRunTimeError

SWS_LinIf:

SWS_LinIf_00359: add Det_ReportRuntimeError

SWS_UdpNm:

Replace UDPNM_E_NO_INIT with UDPNM_E_UNINIT in description of API UdpNm_MainFunction_<Instance Id> (SWS_UdpNm_00234)

*** ECUC XML ***

Not affected. No configuration of runtime error reporting required (see SWS BSW General).

—Last change on issue 59085 comment 88—

BW-C-Level:

Application	Specification	Bus
1	4	1

- RfC #73570: No "default error" in AUTOSAR

Problem description:

The DET was renamed from development error tracer to default error tracer.

This change was most of the time done automatically and unfortunately re-named "developement error" to "default error".

"default error" should always be followed by "tracer", otherwise, "development error" is probably the right term.

This could increase the impact (compared to my selection of impacted docu-

ment, but formally, the configuration parameters *DevErrorDetect are not using the correct description:

"Switches the Default Error Tracer (Det) detection and notification..."

The parameter switches on/off the development error detection. The DET does not need to be detected and can be present even when the parameter is set to false.

Agreed solution:

Rename "default error" to "development error" in all impacted documents, but not in an automated way (Do not change "default error tracer" to "development error tracer"!)

Blueprint/Example:

- sub chapter is now called "7.x Default errors"

- "[SWS_xxx_yyyyy]

In case default error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected errors to the DET. ()"

- "[SWS_xxx_yyyyy]

If default error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the default error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"

- "In case default errors are enabled,..."

- "module raises the Default error XXX_E_TRANSITION"

- "The DET provides services to store default errors"

...

The correct text would be:

- sub chapter is called "7.x Development errors"

- "[SWS_xxx_yyyyy]

In case development error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected development errors to the DET. ()"

- "[SWS_xxx_yyyyy]

If development error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the development error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"

- "In case development errors are enabled,..."

- "module raises the development error XXX_E_TRANSITION"

- "The DET provides services to store development errors"

Solution for SWS_RTE:

- SWS_RTE —
- Change 4.8 Default errors to 4.8 Development errors
- Change "Errors which can occur at runtime in the RTE are classified as default errors" to "Errors which can occur at runtime in the RTE are classified as development errors"
- Remove [SWS_Rte_07676]
- Change [SWS_RTE_06611] "If a violation is detected the RTE shall report a default error to the DET." to "If a violation is detected the RTE shall report a development error to the DET."
- Change [SWS_Rte_06631]
[SWS_Rte_06631] d The RTE shall use the OS Application Identifier as the Instance Id to enable the developer to identify in which runtime section of the RTE the error occurs. This Instance ID is even unique across multi cores and so implicitly allows the development error to be traced to a specific core. c(SRS_BSW_00337)

SRS_Libraries:

- In chapter "3 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_SPALGeneral:

- In chapter "6.1.1.3.1 [SRS_SPAL_00157] ...": Rename "Development Error Tracer" to "Default Error Tracer"
- In chapter "6.1.1.4.2 [SRS_SPAL_12448] ...": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_FlashTest:

- In chapter "6.1 Functional Requirements": Rename "Development Error Tracer" to "Default Error Tracer"
- In chapter "7 References":
Rename "Development Error Tracer" to "Default Error Tracer"
Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_MFXLibrary:

- In chapter "2 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SWS_MemoryAbstractionInterface:

- In chapter "3.1 Input documents":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_FlexRayNetworkManagement:

- In chapter "3.3 Related AUTOSAR documents":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_CANStateManager:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_PDURouter:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_EEPROMDriver:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"
-Last change on issue 73570 comment 47-

BW-C-Level:

Application	Specification	Bus
1	1	1

1.6 Specification Item SWS_CanTp_00160

Trace References:

none

Content:

References to c-configuration parameters (link time and post-build time) will be placed in a separate h-file. The h-file should be the same as pre-compilation parameters.

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #74681: [CanTp]: [SWS_CanTp_00160] requirement not clear.

Problem description:

There is a requirement is CanTp SWS:

[SWS_CanTp_00160] References to c-configuration parameters (link time and post-build time) will be placed in a separate h-file. The h-file should be the same as pre-compilation parameters. ()

understanding:

Declaration of link time and post-build time relevant variables are to be kept in separate header file(not in CanTp_Cfg.h).

Second part of the requirement is not clear, which states
"The h-file should be the same as pre-compilation parameters".

It looks contradictory to me w.r.t. First part of the requirement.

Clarification needed.

–Last change on issue 74681 comment 19–

Agreed solution:

Remove SWS_CanTp_00160.

–Last change on issue 74681 comment 16–

BW-C-Level:

Application	Specification	Bus
1	1	1

1.7 Specification Item SWS_CanTp_00216**Trace References:**

none

Content:

API function	Description
CanIf_Transmit	Requests transmission of a PDU.

API function	Description
Det_ReportRuntimeError	Service to report runtime errors. If a callout has been configured then this callout shall be called.
PduR_CanTpCopyRxData	This function is called to provide the received data of an I-PDU segment (N-PDU) to the upper layer. Each call to this function provides the next part of the I-PDU data. The size of the remaining data buffer is written to the position indicated by bufferSizePtr.
PduR_CanTpCopyTxData	This function is called to acquire the transmit data of an I-PDU segment (N-PDU). Each call to this function provides the next part of the I-PDU data unless retry->TpDataState is TP_DATARETRY. In this case the function restarts to copy the data beginning at the offset from the current position indicated by retry->TxTpData Cnt. The size of the remaining data is written to the position indicated by availableDataPtr.
PduR_CanTpRxIndication	Called after an I-PDU has been received via the TP API, the result indicates whether the transmission was successful or not.
PduR_CanTpStartOfReception	This function is called at the start of receiving an N-SDU. The N-SDU might be fragmented into multiple N-PDUs (FF with one or more following CFs) or might consist of a single N-PDU (SF). The service shall provide the currently available maximum buffer size when invoked with TpSduLength equal to 0.
PduR_CanTpTxConfirmation	This function is called after the I-PDU has been transmitted on its network, the result indicates whether the transmission was successful or not.

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #59085: Rollout of 'Runtime errors'

Problem description:

Inconsistencies in SWS with semantics of Default errors
–Last change on issue 59085 comment 26–

Agreed solution:

solution in Column "G" of the new attachment
<https://www.autosar.org/bugzilla/attachment.cgi?id=4604>

Notes:

- It is not enough just to migrate the error from one classification table to another. Please also check the related requirements (and background information) which is referring to that error and adapt them if needed.
- The review task of the ITs shall be done by the WP to which the specification "belongs".

*** BSW UML Model ***

SWS_CanNm:

Chapter 8.6.1 Optional Interfaces:

Add within SWS_CanNm_00325 the API function Det_ReportRunTimeError

SWS_LinIf:

SWS_LinIf_00359: add Det_ReportRuntimeError

SWS_UdpNm:

Replace UDPNM_E_NO_INIT with UDPNM_E_UNINIT in description of API UdpNm_MainFunction_<Instance Id> (SWS_UdpNm_00234)

*** ECUC XML ***

Not affected. No configuration of runtime error reporting required (see SWS BSW General).

–Last change on issue 59085 comment 88–

BW-C-Level:

Application	Specification	Bus
1	4	1

- RfC #77935: [PduR] Misleading description of CopyRxData

Problem description:

Name: Martin Schlodder
Role: Member of WP-A2

Description/Motivation:

The description of the CopyRxData API says: "The size of the remaining data is written to the position indicated by bufferSizePtr."

This text seems to have been copied from the CopyTxData call, where it is correct. CopyRxData should talk about "remaining buffer", not "remaining data".

Agreed solution:

In the description of the API PduR_<User:LoTp>CopyRxData (SWS_PduR_00512), replace "remaining data" by "remaining buffer".

BW-C-Level:

Application	Specification	Bus
1	1	1

1.8 Specification Item SWS_CanTp_00229

Trace References:

none

Content:

If the task was aborted due to As, Bs, Cs, Ar, Br, Cr timeout, the CanTp module shall raise the DET error CANTP_E_RX_COM (in case of a reception operation) or CANTP_E_TX_COM (in case of a transmission operation). If the task was aborted due to any other protocol error, the CanTp module shall raise the **DET error runtime error code** CANTP_E_COM to the **Default Error Tracer**.

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #59085: Rollout of 'Runtime errors'

Problem description:

Inconsistencies in SWS with semantics of Default errors
–Last change on issue 59085 comment 26–

Agreed solution:

solution in Column "G" of the new attachment
<https://www.autosar.org/bugzilla/attachment.cgi?id=4604>

Notes:

- It is not enough just to migrate the error from one classification table to another. Please also check the related requirements (and background information) which is referring to that error and adapt them if needed.
- The review task of the ITs shall be done by the WP to which the specification "belongs".

*** BSW UML Model ***

SWS_CanNm:

Chapter 8.6.1 Optional Interfaces:

Add within SWS_CanNm_00325 the API function Det_ReportRunTimeError

SWS_LinIf:

SWS_LinIf_00359: add Det_ReportRuntimeError

SWS_UdpNm:

Replace UDPNM_E_NO_INIT with UDPNM_E_UNINIT in description of API UdpNm_MainFunction_<Instance Id> (SWS_UdpNm_00234)

*** ECUC XML ***

Not affected. No configuration of runtime error reporting required (see SWS BSW General).

–Last change on issue 59085 comment 88–

BW-C-Level:

Application	Specification	Bus
1	4	1

1.9 Specification Item SWS_CanTp_00254

Trace References:

none

Content:

If **default development** error detection is enabled the function CanTp_CancelTransmit shall check the validity of TxPduld parameter. If the parameter value is invalid, the CanTp_CancelTransmit function shall raise the development error CANTP_E_PARAM_ID and return E_NOT_OK (see SWS_CanTp_00294).

If the parameter value indicates a cancel transmission request for an N-SDU that it is not on transmission process the CanTp module shall **raise the DET error report a runtime error code CANTP_E_OPER_NOT_SUPPORTED to the Default Error Tracer** and the service shall return E_NOT_OK.

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #59085: Rollout of 'Runtime errors'

Problem description:

Inconsistencies in SWS with semantics of Default errors

–Last change on issue 59085 comment 26–

Agreed solution:

solution in Column "G" of the new attachment
<https://www.autosar.org/bugzilla/attachment.cgi?id=4604>

Notes:

- It is not enough just to migrate the error from one classification table to another. Please also check the related requirements (and background information) which is referring to that error and adapt them if needed.
- The review task of the ITs shall be done by the WP to which the specification "belongs".

*** BSW UML Model ***

SWS_CanNm:

Chapter 8.6.1 Optional Interfaces:

Add within SWS_CanNm_00325 the API function Det_ReportRunTimeError

SWS_LinIf:

SWS_LinIf_00359: add Det_ReportRuntimeError

SWS_UdpNm:

Replace UDPNM_E_NO_INIT with UDPNM_E_UNINIT in description of API
UdpNm_MainFunction_<Instance Id> (SWS_UdpNm_00234)

*** ECUC XML ***

Not affected. No configuration of runtime error reporting required (see SWS BSW General).

–Last change on issue 59085 comment 88–

BW-C-Level:

Application	Specification	Bus
1	4	1

- RfC #73570: No "default error" in AUTOSAR

Problem description:

The DET was renamed from development error tracer to default error tracer.

This change was most of the time done automatically and unfortunately re-named "development error" to "default error".

"default error" should always be followed by "tracer", otherwise, "development error" is probably the right term.

This could increase the impact (compared to my selection of impacted document, but formally, the configuration parameters *DevErrorDetect are not using the correct description:

"Switches the Default Error Tracer (Det) detection and notification..."

The parameter switches on/off the development error detection. The DET does not need to be detected and can be present even when the parameter is set to false.

Agreed solution:

Rename "default error" to "development error" in all impacted documents, but not in an automated way (Do not change "default error tracer" to "development error tracer"!)

Blueprint/Example:

- sub chapter is now called "7.x Default errors"

- "[SWS_xxx_yyyyy]

In case default error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected errors to the DET. ()"

- "[SWS_xxx_yyyyy]

If default error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the default error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"

- "In case default errors are enabled,..."

- "module raises the Default error XXX_E_TRANSITION"

- "The DET provides services to store default errors"

...

The correct text would be:

- sub chapter is called "7.x Development errors"

- "[SWS_xxx_yyyyy]

In case development error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected development errors to the DET. ()"

- "[SWS_xxx_yyyyy]

If development error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the development error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"

- "In case development errors are enabled,..."

- "module raises the development error XXX_E_TRANSITION"

- "The DET provides services to store development errors"

Solution for SWS_RTE:

– SWS_RTE –

- Change 4.8 Default errors to 4.8 Development errors

- Change "Errors which can occur at runtime in the RTE are classified as default errors" to "Errors which can occur at runtime in the RTE are classified as development errors"

- Remove [SWS_Rte_07676]

- Change [SWS_RTE_06611]"If a violation is detected the RTE shall report a default error to the DET." to "If a violation is detected the RTE shall report a development error to the DET."

- Change [SWS_Rte_06631]

[SWS_Rte_06631] d The RTE shall use the OS Application Identifier as the Instance Id to enable the developer to identify in which runtime section of the RTE the error occurs. This Instance ID is even unique across multi cores and so implicitly allows the development error to be traced to a specific core. c(SRS_BSW_00337)

SRS_Libraries:

- In chapter "3 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_SPALGeneral:

- In chapter "6.1.1.3.1 [SRS_SPAL_00157] ...": Rename "Development Error Tracer" to "Default Error Tracer"

- In chapter "6.1.1.4.2 [SRS_SPAL_12448] ...": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_FlashTest:

- In chapter "6.1 Functional Requirements": Rename "Development Error Tracer" to "Default Error Tracer"

- In chapter "7 References":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_MFXLibrary:

- In chapter "2 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SWS_MemoryAbstractionInterface:

- In chapter "3.1 Input documents":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_FlexRayNetworkManagement:

- In chapter "3.3 Related AUTOSAR documents":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_CANStateManager:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_PDURouter:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_EEPROMDriver:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

–Last change on issue 73570 comment 47–

BW-C-Level:

Application	Specification	Bus
1	1	1

1.10 Specification Item SWS_CanTp_00260

Trace References:

none

Content:

If **default development** error detection is enabled the function CanTp_CancelReceive shall check the validity of RxPduId parameter. If the parameter value is invalid, the CanTp_CancelReceive function shall raise the development error CANTP_E_PARAM_ID and return E_NOT_OK (see SWS_CanTp_00294).

If the parameter value indicates a cancel reception request for an N-SDU that it is not on reception process the CanTp module shall **raise the DET error report the runtime error code CANTP_E_OPER_NOT_SUPPORTED to the Default Error Tracer** and the service shall return E_NOT_OK.

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #59085: Rollout of 'Runtime errors'

Problem description:

Inconsistencies in SWS with semantics of Default errors
–Last change on issue 59085 comment 26–

Agreed solution:

solution in Column "G" of the new attachment
<https://www.autosar.org/bugzilla/attachment.cgi?id=4604>

Notes:

- It is not enough just to migrate the error from one classification table to another. Please also check the related requirements (and background information) which is referring to that error and adapt them if needed.
- The review task of the ITs shall be done by the WP to which the specification "belongs".

*** BSW UML Model ***

SWS_CanNm:

Chapter 8.6.1 Optional Interfaces:

Add within SWS_CanNm_00325 the API function Det_ReportRunTimeError

SWS_LinIf:

SWS_LinIf_00359: add Det_ReportRuntimeError

SWS_UdpNm:

Replace UDPNM_E_NO_INIT with UDPNM_E_UNINIT in description of API UdpNm_MainFunction_<Instance Id> (SWS_UdpNm_00234)

*** ECUC XML ***

Not affected. No configuration of runtime error reporting required (see SWS BSW General).

–Last change on issue 59085 comment 88–

BW-C-Level:

Application	Specification	Bus
1	4	1

- RfC #73570: No "default error" in AUTOSAR

Problem description:

The DET was renamed from development error tracer to default error tracer.

This change was most of the time done automatically and unfortunately renamed "developement error" to "default error".

"default error" should always be followed by "tracer", otherwise, "development error" is probably the right term.

This could increase the impact (compared to my selection of impacted document, but formally, the configuration parameters *DevErrorDetect are not using the correct description:

"Switches the Default Error Tracer (Det) detection and notification..."

The parameter switches on/off the developement error detection. The DET does not need to be detected and can be present even when the parameter is set to false.

Agreed solution:

Rename "default error" to "development error" in all impacted documents, but not in an automated way (Do not change "default error tracer" to "developement error tracer"!)

Blueprint/Example:

- sub chapter is now called "7.x Default errors"
- "[SWS_xxx_yyyyy]"
- In case default error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected errors to the DET. ()"
- "[SWS_xxx_yyyyy]"
- If default error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the default error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"
- "In case default errors are enabled,..."
- "module raises the Default error XXX_E_TRANSITION"
- "The DET provides services to store default errors"
- ...

The correct text would be:

- sub chapter is called "7.x Development errors"
- "[SWS_xxx_yyyyy]"
- In case development error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected development errors to the DET. ()"
- "[SWS_xxx_yyyyy]"
- If development error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the development error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"
- "In case development errors are enabled,..."
- "module raises the development error XXX_E_TRANSITION"
- "The DET provides services to store development errors"

Solution for SWS_RTE:

- SWS_RTE —
- Change 4.8 Default errors to 4.8 Development errors
- Change "Errors which can occur at runtime in the RTE are classified as default errors" to "Errors which can occur at runtime in the RTE are classified as development errors"
- Remove [SWS_Rte_07676]
- Change [SWS_RTE_06611]"If a violation is detected the RTE shall report a default error to the DET." to "If a violation is detected the RTE shall report a development error to the DET."
- Change [SWS_Rte_06631]
- [SWS_Rte_06631] d The RTE shall use the OS Application Identifier as the Instance Id to enable the developer to identify in which runtime section of the RTE the error

occurs. This Instance ID is even unique across multi cores and so implicitly allows the development error to be traced to a specific core. c(SRS_BSW_00337)

SRS_Libraries:

- In chapter "3 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_SPALGeneral:

- In chapter "6.1.1.3.1 [SRS_SPAL_00157] ...": Rename "Development Error Tracer" to "Default Error Tracer"
- In chapter "6.1.1.4.2 [SRS_SPAL_12448] ...": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_FlashTest:

- In chapter "6.1 Functional Requirements": Rename "Development Error Tracer" to "Default Error Tracer"
- In chapter "7 References":
Rename "Development Error Tracer" to "Default Error Tracer"
Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_MFXLibrary:

- In chapter "2 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SWS_MemoryAbstractionInterface:

- In chapter "3.1 Input documents":
Rename "Development Error Tracer" to "Default Error Tracer"
Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_FlexRayNetworkManagement:

- In chapter "3.3 Related AUTOSAR documents":
Rename "Development Error Tracer" to "Default Error Tracer"
Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_CANStateManager:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_PDURouter:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_EEPROMDriver:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"
–Last change on issue 73570 comment 47–

BW-C-Level:

Application	Specification	Bus
1	1	1

1.11 Specification Item SWS_CanTp_00264

Trace References:

none

Content:

The file structure of the CanTp module shall include ComStack_Types.h and Det.h(optional, if default error detection is configured as ON).

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #73570: No "default error" in AUTOSAR

Problem description:

The DET was renamed from development error tracer to default error tracer.

This change was most of the time done automatically and unfortunately renamed "developement error" to "default error".

"default error" should always be followed by "tracer", otherwise, "development error" is probably the right term.

This could increase the impact (compared to my selection of impacted document, but formally, the configuration parameters *DevErrorDetect are not using the correct description:

"Switches the Default Error Tracer (Det) detection and notification..."

The parameter switches on/off the development error detection. The DET does not need to be detected and can be present even when the parameter is set to false.

Agreed solution:

Rename "default error" to "development error" in all impacted documents, but not in an automated way (Do not change "default error tracer" to "development error tracer"!)

Blueprint/Example:

- sub chapter is now called "7.x Default errors"

- "[SWS_xxx_yyyyy]

In case default error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected errors to the DET. ()"

- "[SWS_xxx_yyyyy]

If default error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the default error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"

- "In case default errors are enabled,..."

- "module raises the Default error XXX_E_TRANSITION"

- "The DET provides services to store default errors"

...

The correct text would be:

- sub chapter is called "7.x Development errors"

- "[SWS_xxx_yyyyy]

In case development error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected development errors to the DET. ()"

- "[SWS_xxx_yyyyy]

If development error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the development error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"

- "In case development errors are enabled,..."

- "module raises the development error XXX_E_TRANSITION"

- "The DET provides services to store development errors"

Solution for SWS_RTE:

— SWS_RTE —

- Change 4.8 Default errors to 4.8 Development errors
- Change "Errors which can occur at runtime in the RTE are classified as default errors" to "Errors which can occur at runtime in the RTE are classified as development errors"
- Remove [SWS_Rte_07676]
- Change [SWS_RTE_06611] "If a violation is detected the RTE shall report a default error to the DET." to "If a violation is detected the RTE shall report a development error to the DET."
- Change [SWS_Rte_06631]
[SWS_Rte_06631] d The RTE shall use the OS Application Identifier as the Instance Id to enable the developer to identify in which runtime section of the RTE the error occurs. This Instance ID is even unique across multi cores and so implicitly allows the development error to be traced to a specific core. c(SRS_BSW_00337)

SRS_Libraries:

- In chapter "3 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_SPALGeneral:

- In chapter "6.1.1.3.1 [SRS_SPAL_00157] ...": Rename "Development Error Tracer" to "Default Error Tracer"
- In chapter "6.1.1.4.2 [SRS_SPAL_12448] ...": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_FlashTest:

- In chapter "6.1 Functional Requirements": Rename "Development Error Tracer" to "Default Error Tracer"
- In chapter "7 References":
Rename "Development Error Tracer" to "Default Error Tracer"
Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_MFXLibrary:

- In chapter "2 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SWS_MemoryAbstractionInterface:

- In chapter "3.1 Input documents":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_FlexRayNetworkManagement:

- In chapter "3.3 Related AUTOSAR documents":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_CANStateManager:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_PDURouter:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_EEPROMDriver:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

–Last change on issue 73570 comment 47–

BW-C-Level:

Application	Specification	Bus
1	1	1

1.12 Specification Item SWS_CanTp_00269

Trace References:

none

Content:

After reception of each Consecutive Frame the CanTp module shall call the PduR_CanTp CopyRxData() function with a PduInfo pointer containing data buffer and data length:

- 6 or 7 data length (bytes or less in case of the last CF). for CAN 2.0 frames
- DLC-1 or DLC-2 bytes for CAN FD frames (see Figure 5 and SWS_CanTp_00351).

The output pointer parameter provides CanTp with available Rx buffer size after data have been copied.

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #76256: [CanTp]: SWS_CanTp_00269 does not consider CANFD use case for data length

Problem description:

As per the following description:

[SWS_CanTp_00269] After reception of each Consecutive Frame the CanTp shall call the PduR_CanTpCopyRxData() function with a PduInfo pointer containing data buffer and 6 or 7 data length (or less in case of the last CF). The output pointer parameter provides CanTp with available Rx buffer size after data have been copied.
()

it is mentioned data length 6 or 7.

It does not consider the use case of CANFD where data length can possibly go near 64 bytes.

–Last change on issue 76256 comment 11–

Agreed solution:

- Change SWS_CanTp_00269 to:

After reception of each Consecutive Frame the CanTp module shall call the PduR_CanTpCopyRxData() function with a PduInfo pointer containing data buffer and data length:

- 6 or 7 bytes or less in case of the last CF for CAN 2.0 frames
- DLC-1 or DLC-2 bytes for CAN FD frames (see Figure 5 and SWS_CanTp_00351).

The output pointer parameter provides CanTp with available Rx buffer size after data have been copied.

–Last change on issue 76256 comment 2–

BW-C-Level:

Application	Specification	Bus
1	1	1

1.13 Specification Item SWS_CanTp_00293

Trace References:

none

Content:

The CanTp module shall be able to detect the following errors and exceptions depending on its configuration (development/production):

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #59085: Rollout of 'Runtime errors'

Problem description:

Inconsistencies in SWS with semantics of Default errors
–Last change on issue 59085 comment 26–

Agreed solution:

solution in Column "G" of the new attachment
<https://www.autosar.org/bugzilla/attachment.cgi?id=4604>

Notes:

- It is not enough just to migrate the error from one classification table to another. Please also check the related requirements (and background information) which is referring to that error and adapt them if needed.
- The review task of the ITs shall be done by the WP to which the specification "belongs".

*** BSW UML Model ***

SWS_CanNm:

Chapter 8.6.1 Optional Interfaces:

Add within SWS_CanNm_00325 the API function Det_ReportRunTimeError

SWS_LinIf:

SWS_LinIf_00359: add Det_ReportRuntimeError

SWS_UdpNm:

Replace UDPNM_E_NO_INIT with UDPNM_E_UNINIT in description of API

UdpNm_MainFunction_<Instance Id> (SWS_UdpNm_00234)

*** ECUC XML ***

Not affected. No configuration of runtime error reporting required (see SWS BSW General).

–Last change on issue 59085 comment 88–

BW-C-Level:

Application	Specification	Bus
1	4	1

1.14 Specification Item SWS_CanTp_00294

Trace References:

none

Content:

As shown in the above figure, when If a development error occurs, the CanTp returns module shall return the value E_NOT_OK . The error description is only reported via the API of the and report the error via the Default Error Tracer module (if development error detection is enabled).

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #59085: Rollout of 'Runtime errors'

Problem description:

Inconsistencies in SWS with semantics of Default errors

–Last change on issue 59085 comment 26–

Agreed solution:

solution in Column "G" of the new attachment
<https://www.autosar.org/bugzilla/attachment.cgi?id=4604>

Notes:

- It is not enough just to migrate the error from one classification table to another. Please also check the related requirements (and background information) which is referring to that error and adapt them if needed.
- The review task of the ITs shall be done by the WP to which the specification "belongs".

*** BSW UML Model ***

SWS_CanNm:

Chapter 8.6.1 Optional Interfaces:

Add within SWS_CanNm_00325 the API function Det_ReportRunTimeError

SWS_LinIf:

SWS_LinIf_00359: add Det_ReportRuntimeError

SWS_UdpNm:

Replace UDPNM_E_NO_INIT with UDPNM_E_UNINIT in description of API
UdpNm_MainFunction_<Instance Id> (SWS_UdpNm_00234)

*** ECUC XML ***

Not affected. No configuration of runtime error reporting required (see SWS BSW
General).

–Last change on issue 59085 comment 88–

BW-C-Level:

Application	Specification	Bus
1	4	1

1.15 Specification Item SWS_CanTp_00305

Trace References:

none

Content:

If **default development** error detection is enabled, the function CanTp_ChangeParameter shall check the validity of function parameters (Identifier, Parameter and requested value). If any of the parameter value is invalid, the CanTp_ChangeParameter function shall raise the development error CANTP_E_PARAM_ID and return E_NOT_OK (see [SWS_CanTp_00294](#)).

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #59085: Rollout of 'Runtime errors'

Problem description:

Inconsistencies in SWS with semantics of Default errors

–Last change on issue 59085 comment 26–

Agreed solution:

solution in Column "G" of the new attachment
<https://www.autosar.org/bugzilla/attachment.cgi?id=4604>

Notes:

- It is not enough just to migrate the error from one classification table to another. Please also check the related requirements (and background information) which is referring to that error and adapt them if needed.
- The review task of the ITs shall be done by the WP to which the specification "belongs".

***** BSW UML Model *****

SWS_CanNm:

Chapter 8.6.1 Optional Interfaces:

Add within SWS_CanNm_00325 the API function Det_ReportRunTimeError

SWS_LinIf:

SWS_LinIf_00359: add Det_ReportRuntimeError

SWS_UdpNm:

Replace UDPNM_E_NO_INIT with UDPNM_E_UNINIT in description of API
UdpNm_MainFunction_<Instance Id> (SWS_UdpNm_00234)

***** ECUC XML *****

Not affected. No configuration of runtime error reporting required (see SWS BSW General).

–Last change on issue 59085 comment 88–

BW-C-Level:

Application	Specification	Bus
1	4	1

- RfC #73570: No "default error" in AUTOSAR

Problem description:

The DET was renamed from development error tracer to default error tracer.

This change was most of the time done automatically and unfortunately re-named "developement error" to "default error".

"default error" should always be followed by "tracer", otherwise, "development error" is probably the right term.

This could increase the impact (compared to my selection of impacted document, but formally, the configuration parameters *DevErrorDetect are not using the correct description:

"Switches the Default Error Tracer (Det) detection and notification..."

The parameter switches on/off the developement error detection. The DET does not need to be detected and can be present even when the parameter is set to false.

Agreed solution:

Rename "default error" to "development error" in all impacted documents, but not in an automated way (Do not change "default error tracer" to "developement error tracer"!)

Blueprint/Example:

- sub chapter is now called "7.x Default errors"

- "[SWS_xxx_yyyyyy]

In case default error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected errors to the DET. ()"

- "[SWS_xxx_yyyyyy]

If default error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the default error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"

- "In case default errors are enabled,..."

- "module raises the Default error XXX_E_TRANSITION"

- "The DET provides services to store default errors"

...

The correct text would be:

- sub chapter is called "7.x Development errors"

- "[SWS_xxx_yyyyyy]

In case development error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected development errors to the DET. ()"

- "[SWS_xxx_yyyyy]

If development error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the development error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"

- "In case development errors are enabled,..."

- "module raises the development error XXX_E_TRANSITION"

- "The DET provides services to store development errors"

Solution for SWS_RTE:

— SWS_RTE —

- Change 4.8 Default errors to 4.8 Development errors

- Change "Errors which can occur at runtime in the RTE are classified as default errors" to "Errors which can occur at runtime in the RTE are classified as development errors"

- Remove [SWS_Rte_07676]

- Change [SWS_RTE_06611]"If a violation is detected the RTE shall report a default error to the DET." to "If a violation is detected the RTE shall report a development error to the DET."

- Change [SWS_Rte_06631]

[SWS_Rte_06631] d The RTE shall use the OS Application Identifier as the Instance Id to enable the developer to identify in which runtime section of the RTE the error occurs. This Instance ID is even unique across multi cores and so implicitly allows the development error to be traced to a specific core. c(SRS_BSW_00337)

SRS_Libraries:

- In chapter "3 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_SPALGeneral:

- In chapter "6.1.1.3.1 [SRS_SPAL_00157] ...": Rename "Development Error Tracer" to "Default Error Tracer"

- In chapter "6.1.1.4.2 [SRS_SPAL_12448] ...": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_FlashTest:

- In chapter "6.1 Functional Requirements": Rename "Development Error Tracer" to

"Default Error Tracer"

- In chapter "7 References":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_MFXLibrary:

- In chapter "2 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SWS_MemoryAbstractionInterface:

- In chapter "3.1 Input documents":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_FlexRayNetworkManagement:

- In chapter "3.3 Related AUTOSAR documents":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_CANStateManager:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_PDURouter:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_EEPROMDriver:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

–Last change on issue 73570 comment 47–

BW-C-Level:

Application	Specification	Bus
1	1	1

1.16 Specification Item SWS_CanTp_00324

Trace References:

none

Content:

If **default development** error detection is enabled the function CanTp_ReadParameter shall check the validity of function parameters (Id and Parameter). If any of the parameter value is invalid, the CanTp_ReadParameter function shall raise the development error CANTP_E_PARAM_ID and return E_NOT_OK (see SWS_CanTp_00294).

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #59085: Rollout of 'Runtime errors'

Problem description:

Inconsistencies in SWS with semantics of Default errors
–Last change on issue 59085 comment 26–

Agreed solution:

solution in Column "G" of the new attachment
<https://www.autosar.org/bugzilla/attachment.cgi?id=4604>

Notes:

- It is not enough just to migrate the error from one classification table to another. Please also check the related requirements (and background information) which is referring to that error and adapt them if needed.
- The review task of the ITs shall be done by the WP to which the specification "belongs".

*** BSW UML Model ***

SWS_CanNm:

Chapter 8.6.1 Optional Interfaces:

Add within SWS_CanNm_00325 the API function Det_ReportRunTimeError

SWS_LinIf:

SWS_LinIf_00359: add Det_ReportRuntimeError

SWS_UdpNm:

Replace UDPNM_E_NO_INIT with UDPNM_E_UNINIT in description of API UdpNm_MainFunction_<Instance Id> (SWS_UdpNm_00234)

*** ECUC XML ***

Not affected. No configuration of runtime error reporting required (see SWS BSW General).

–Last change on issue 59085 comment 88–

BW-C-Level:

Application	Specification	Bus
1	4	1

- RfC #73570: No "default error" in AUTOSAR

Problem description:

The DET was renamed from development error tracer to default error tracer.

This change was most of the time done automatically and unfortunately renamed "developement error" to "default error".

"default error" should always be followed by "tracer", otherwise, "development error" is probably the right term.

This could increase the impact (compared to my selection of impacted document, but formally, the configuration parameters *DevErrorDetect are not using the correct description:

"Switches the Default Error Tracer (Det) detection and notification..."

The parameter switches on/off the developement error detection. The DET does not need to be detected and can be present even when the parameter is set to false.

Agreed solution:

Rename "default error" to "development error" in all impacted documents, but not in an automated way (Do not change "default error tracer" to "developement error tracer"!)

Blueprint/Example:

- sub chapter is now called "7.x Default errors"
- "[SWS_xxx_yyyyy]
- In case default error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected errors to the DET. ()"
- "[SWS_xxx_yyyyy]
- If default error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the default error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"
- "In case default errors are enabled,..."
- "module raises the Default error XXX_E_TRANSITION"
- "The DET provides services to store default errors"
- ...

The correct text would be:

- sub chapter is called "7.x Development errors"
- "[SWS_xxx_yyyyy]
- In case development error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected development errors to the DET. ()"
- "[SWS_xxx_yyyyy]
- If development error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the development error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"
- "In case development errors are enabled,..."
- "module raises the development error XXX_E_TRANSITION"
- "The DET provides services to store development errors"

Solution for SWS_RTE:

- SWS_RTE —
- Change 4.8 Default errors to 4.8 Development errors
- Change "Errors which can occur at runtime in the RTE are classified as default errors" to "Errors which can occur at runtime in the RTE are classified as development errors"
- Remove [SWS_Rte_07676]
- Change [SWS_RTE_06611]"If a violation is detected the RTE shall report a default error to the DET." to "If a violation is detected the RTE shall report a development error to the DET."
- Change [SWS_Rte_06631]
- [SWS_Rte_06631] d The RTE shall use the OS Application Identifier as the Instance Id to enable the developer to identify in which runtime section of the RTE the error

occurs. This Instance ID is even unique across multi cores and so implicitly allows the development error to be traced to a specific core. c(SRS_BSW_00337)

SRS_Libraries:

- In chapter "3 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_SPALGeneral:

- In chapter "6.1.1.3.1 [SRS_SPAL_00157] ...": Rename "Development Error Tracer" to "Default Error Tracer"
- In chapter "6.1.1.4.2 [SRS_SPAL_12448] ...": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_FlashTest:

- In chapter "6.1 Functional Requirements": Rename "Development Error Tracer" to "Default Error Tracer"
- In chapter "7 References":
Rename "Development Error Tracer" to "Default Error Tracer"
Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_MFXLibrary:

- In chapter "2 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SWS_MemoryAbstractionInterface:

- In chapter "3.1 Input documents":
Rename "Development Error Tracer" to "Default Error Tracer"
Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_FlexRayNetworkManagement:

- In chapter "3.3 Related AUTOSAR documents":
Rename "Development Error Tracer" to "Default Error Tracer"
Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_CANStateManager:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_PDURouter:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_EEPROMDriver:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"
–Last change on issue 73570 comment 47–

BW-C-Level:

Application	Specification	Bus
1	1	1

1.17 Specification Item SWS_CanTp_00330

Trace References:

none

Content:

When CanTp_RxIndication is called for a SF or FF N-PDU with MetaData (indicating a generic connection), the CanTp module shall store the addressing information contained in the MetaData of the PDU and use this information for the initiation of the connection to the upper layer, for transmission of FC N-PDUs and for identification of CF N-PDUs. The addressing information in the MetaData depends on the addressing format:

- Normal, Extended, Mixed 11 bit: OEM dependent none
- Normal fixed, Mixed 29 bit: N_SA, N_TA

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #74706: [CanTp]: How to get OEM dependent metadata for CanIf_Transmit().

Problem description:

In requirement:

[SWS_CanTp_00335] When calling CanIf_Transmit() for an SF, FF, or CF of a generic connection (N-PDU with MetaData), the CanTp module shall provide the stored addressing information via MetaData of the N-PDU (at the end of the data referenced by PduInfoPtr). The addressing information in the MetaData depends on the addressing format:

Normal, Extended, Mixed 11 bit: OEM dependent

Normal fixed, Mixed 29 bit: N_SA, N_TA. ()

How CanTp will know what is the "OEM dependent" addressing MetaData information to be sent for Normal, Extended and Mixed 11 bit addressing format?

Agreed solution:

Replace "OEM dependent" with "none" in SWS_CanTp_00330, SWS_CanTp_00332 and SWS_CanTp_00335

–Last change on issue 74706 comment 13–

BW-C-Level:

Application	Specification	Bus
1	4	1

1.18 Specification Item SWS_CanTp_00332

Trace References:

none

Content:

When calling CanIf_Transmit() for an FC on a generic connection (N-PDU with MetaData), the CanTp module shall provide the stored addressing information via the MetaData of the N-PDU. The addressing information in the MetaData depends on the addressing format:

- Normal, Extended, Mixed 11 bit: OEM dependent none
- Normal fixed, Mixed 29 bit: N_SA (saved N_TA), N_TA (saved N_SA)

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #74706: [CanTp]: How to get OEM dependent metadata for CanIf_Transmit().

Problem description:

In requirement:

[SWS_CanTp_00335] When calling CanIf_Transmit() for an SF, FF, or CF of a generic connection (N-PDU with MetaData), the CanTp module shall provide the stored addressing information via MetaData of the N-PDU (at the end of the data referenced by PduInfoPtr). The addressing information in the MetaData depends on the addressing format:

Normal, Extended, Mixed 11 bit: OEM dependent

Normal fixed, Mixed 29 bit: N_SA, N_TA. ()

How CanTp will know what is the "OEM dependent" addressing MetaData information to be sent for Normal, Extended and Mixed 11 bit addressing format?

Agreed solution:

Replace "OEM dependent" with "none" in SWS_CanTp_00330, SWS_CanTp_00332 and SWS_CanTp_00335

–Last change on issue 74706 comment 13–

BW-C-Level:

Application	Specification	Bus
1	4	1

1.19 Specification Item SWS_CanTp_00335

Trace References:

none

Content:

When calling CanIf_Transmit() for an SF, FF, or CF of a generic connection (N-PDU with MetaData), the CanTp module shall provide the stored addressing information via MetaData of the N-PDU. The addressing information in the MetaData depends on the addressing format:

- Normal, Extended, Mixed 11 bit: OEM dependent none
- Normal fixed, Mixed 29 bit: N_SA, N_TA.

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #74706: [CanTp]: How to get OEM dependent metadata for CanIf_Transmit().

Problem description:

In requirement:

[SWS_CanTp_00335] When calling CanIf_Transmit() for an SF, FF, or CF of a generic connection (N-PDU with MetaData), the CanTp module shall provide the stored addressing information via MetaData of the N-PDU (at the end of the data referenced by PduInfoPtr). The addressing information in the MetaData depends on the addressing format:

Normal, Extended, Mixed 11 bit: OEM dependent

Normal fixed, Mixed 29 bit: N_SA, N_TA. ()

How CanTp will know what is the "OEM dependent" addressing MetaData information to be sent for Normal, Extended and Mixed 11 bit addressing format?

Agreed solution:

Replace "OEM dependent" with "none" in SWS_CanTp_00330, SWS_CanTp_00332 and SWS_CanTp_00335

–Last change on issue 74706 comment 13–

BW-C-Level:

Application	Specification	Bus
1	4	1

1.20 Specification Item SWS_CanTp_00345

Trace References:

SRS_Can_01073

Content:

If frames with a payload ≤ 8 (either CAN 2.0 frames or small CAN FD frames) are used for a Rx N-SDU and CanTpRxPaddingActivation is equal to CANTP_ON, then CanTp receives by means of CanTp_RxIndication() call an SF Rx N-PDU belonging to that N-SDU, with a length smaller than eight bytes (i.e. PduInfoPtr.SduLength < 8), CanTp shall reject the reception. If the default error detection is enabled, a development error The runtime error code CANTP_E_PADDING shall be triggered reported to the Default Error Tracer.

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #59085: Rollout of 'Runtime errors'

Problem description:

Inconsistencies in SWS with semantics of Default errors

–Last change on issue 59085 comment 26–

Agreed solution:

solution in Column "G" of the new attachment
<https://www.autosar.org/bugzilla/attachment.cgi?id=4604>

Notes:

- It is not enough just to migrate the error from one classification table to another. Please also check the related requirements (and background information) which is referring to that error and adapt them if needed.
- The review task of the ITs shall be done by the WP to which the specification "belongs".

*** BSW UML Model ***

SWS_CanNm:

Chapter 8.6.1 Optional Interfaces:

Add within SWS_CanNm_00325 the API function Det_ReportRunTimeError

SWS_LinIf:

SWS_LinIf_00359: add Det_ReportRuntimeError

SWS_UdpNm:

Replace UDPNM_E_NO_INIT with UDPNM_E_UNINIT in description of API
UdpNm_MainFunction_<Instance Id> (SWS_UdpNm_00234)

*** ECUC XML ***

Not affected. No configuration of runtime error reporting required (see SWS BSW General).

–Last change on issue 59085 comment 88–

BW-C-Level:

Application	Specification	Bus
1	4	1

- RfC #73570: No "default error" in AUTOSAR

Problem description:

The DET was renamed from development error tracer to default error tracer.

This change was most of the time done automatically and unfortunately re-named "development error" to "default error".

"default error" should always be followed by "tracer", otherwise, "development error" is probably the right term.

This could increase the impact (compared to my selection of impacted document, but formally, the configuration parameters *DevErrorDetect are not using the correct description:

"Switches the Default Error Tracer (Det) detection and notification..."

The parameter switches on/off the development error detection. The DET does not need to be detected and can be present even when the parameter is set to false.

Agreed solution:

Rename "default error" to "development error" in all impacted documents, but not in an automated way (Do not change "default error tracer" to "development error tracer"!)

Blueprint/Example:

- sub chapter is now called "7.x Default errors"

- "[SWS_xxx_yyyyy]

In case default error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected errors to the DET. ()"

- "[SWS_xxx_yyyyy]

If default error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the default error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"

- "In case default errors are enabled,..."

- "module raises the Default error XXX_E_TRANSITION"

- "The DET provides services to store default errors"

...

The correct text would be:

- sub chapter is called "7.x Development errors"

- "[SWS_xxx_yyyyy]

In case development error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected development errors to the DET. ()"

- "[SWS_xxx_yyyyy]

If development error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the development error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"

- "In case development errors are enabled,..."

- "module raises the development error XXX_E_TRANSITION"

- "The DET provides services to store development errors"

Solution for SWS_RTE:

– SWS_RTE —

- Change 4.8 Default errors to 4.8 Development errors

- Change "Errors which can occur at runtime in the RTE are classified as default errors" to "Errors which can occur at runtime in the RTE are classified as development errors"

- Remove [SWS_Rte_07676]

- Change [SWS_RTE_06611]"If a violation is detected the RTE shall report a default error to the DET." to "If a violation is detected the RTE shall report a development error to the DET."

- Change [SWS_Rte_06631]

[SWS_Rte_06631] d The RTE shall use the OS Application Identifier as the Instance Id to enable the developer to identify in which runtime section of the RTE the error occurs. This Instance ID is even unique across multi cores and so implicitly allows the development error to be traced to a specific core. c(SRS_BSW_00337)

SRS_Libraries:

- In chapter "3 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_SPALGeneral:

- In chapter "6.1.1.3.1 [SRS_SPAL_00157] ...": Rename "Development Error Tracer" to "Default Error Tracer"

- In chapter "6.1.1.4.2 [SRS_SPAL_12448] ...": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_FlashTest:

- In chapter "6.1 Functional Requirements": Rename "Development Error Tracer" to "Default Error Tracer"

- In chapter "7 References":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_MFXLibrary:

- In chapter "2 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SWS_MemoryAbstractionInterface:

- In chapter "3.1 Input documents":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_FlexRayNetworkManagement:

- In chapter "3.3 Related AUTOSAR documents":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_CANStateManager:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_PDURouter:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_EEPROMDriver:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

–Last change on issue 73570 comment 47–

BW-C-Level:

Application	Specification	Bus
1	1	1

1.21 Specification Item SWS_CanTp_00346

Trace References:

SRS_Can_01073

Content:

If frames with a payload ≤ 8 (either CAN 2.0 frames or small CAN FD frames) are used for a Rx N-SDU and CanTpRxPaddingActivation is equal to CANTP_ON, and CanTp receives by means of CanTp_RxIndication() call a last CF Rx N-PDU belonging to that N-SDU, with a length smaller than eight bytes (i.e. PduInfoPtr. SduLength $\neq 8$), CanTp shall abort the ongoing reception by calling PduR_CanTpRxIndication() with the result E_NOT_OK. **If the default error detection is enabled, a development error** The runtime error code CANTP_E_PADDING shall be **triggered** reported to the Default Error Tracer.

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #59085: Rollout of 'Runtime errors'

Problem description:

Inconsistencies in SWS with semantics of Default errors
–Last change on issue 59085 comment 26–

Agreed solution:

solution in Column "G" of the new attachment
<https://www.autosar.org/bugzilla/attachment.cgi?id=4604>

Notes:

- It is not enough just to migrate the error from one classification table to another. Please also check the related requirements (and background information) which is referring to that error and adapt them if needed.
- The review task of the ITs shall be done by the WP to which the specification "belongs".

*** BSW UML Model ***

SWS_CanNm:

Chapter 8.6.1 Optional Interfaces:

Add within SWS_CanNm_00325 the API function Det_ReportRunTimeError

SWS_LinIf:

SWS_LinIf_00359: add Det_ReportRuntimeError

SWS_UdpNm:

Replace UDPNM_E_NO_INIT with UDPNM_E_UNINIT in description of API
UdpNm_MainFunction_<Instance Id> (SWS_UdpNm_00234)

*** ECUC XML ***

Not affected. No configuration of runtime error reporting required (see SWS BSW
General).

–Last change on issue 59085 comment 88–

BW-C-Level:

Application	Specification	Bus
1	4	1

- RfC #73570: No "default error" in AUTOSAR

Problem description:

The DET was renamed from development error tracer to default error tracer.

This change was most of the time done automatically and unfortunately re-named "developement error" to "default error".

"default error" should always be followed by "tracer", otherwise, "development error" is probably the right term.

This could increase the impact (compared to my selection of impacted document, but formally, the configuration parameters *DevErrorDetect are not using the correct description:

"Switches the Default Error Tracer (Det) detection and notification..."

The parameter switches on/off the developement error detection. The DET does not need to be detected and can be present even when the parameter is set to false.

Agreed solution:

Rename "default error" to "development error" in all impacted documents, but not in an automated way (Do not change "default error tracer" to "developement error tracer"!)

Blueprint/Example:

- sub chapter is now called "7.x Default errors"
- "[SWS_xxx_yyyyyy]
In case default error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected errors to the DET. ()"
- "[SWS_xxx_yyyyyy]
If default error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the default error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"
- "In case default errors are enabled,..."
- "module raises the Default error XXX_E_TRANSITION"
- "The DET provides services to store default errors"
- ...

The correct text would be:

- sub chapter is called "7.x Development errors"
- "[SWS_xxx_yyyyyy]
In case development error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected development errors to the DET. ()"
- "[SWS_xxx_yyyyyy]
If development error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the development error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"
- "In case development errors are enabled,..."
- "module raises the development error XXX_E_TRANSITION"
- "The DET provides services to store development errors"

Solution for SWS_RTE:

- SWS_RTE —
- Change 4.8 Default errors to 4.8 Development errors
- Change "Errors which can occur at runtime in the RTE are classified as default errors" to "Errors which can occur at runtime in the RTE are classified as development errors"
- Remove [SWS_Rte_07676]
- Change [SWS_RTE_06611]"If a violation is detected the RTE shall report a default error to the DET." to "If a violation is detected the RTE shall report a development error to the DET."
- Change [SWS_Rte_06631]
[SWS_Rte_06631] d The RTE shall use the OS Application Identifier as the Instance Id to enable the developer to identify in which runtime section of the RTE the error occurs. This Instance ID is even unique across multi cores and so implicitly allows

the development error to be traced to a specific core. c(SRS_BSW_00337)

SRS_Libraries:

- In chapter "3 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_SPALGeneral:

- In chapter "6.1.1.3.1 [SRS_SPAL_00157] ...": Rename "Development Error Tracer" to "Default Error Tracer"
- In chapter "6.1.1.4.2 [SRS_SPAL_12448] ...": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_FlashTest:

- In chapter "6.1 Functional Requirements": Rename "Development Error Tracer" to "Default Error Tracer"
- In chapter "7 References":
Rename "Development Error Tracer" to "Default Error Tracer"
Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_MFXLibrary:

- In chapter "2 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SWS_MemoryAbstractionInterface:

- In chapter "3.1 Input documents":
Rename "Development Error Tracer" to "Default Error Tracer"
Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_FlexRayNetworkManagement:

- In chapter "3.3 Related AUTOSAR documents":
Rename "Development Error Tracer" to "Default Error Tracer"
Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_CANStateManager:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_PDURouter:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_EEPROMDriver:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"
–Last change on issue 73570 comment 47–

BW-C-Level:

Application	Specification	Bus
1	1	1

1.22 Specification Item SWS_CanTp_00348

Trace References:

SRS_Can_01073

Content:

If frames with a payload ≤ 8 (either CAN 2.0 frames or small CAN FD frames) are used for a Tx N-SDU and if CanTpTxPaddingActivation is equal to CANTP_ON, CanTp shall transmit by means of CanIf_Transmit() call, SF Rx Tx N-PDU or last CF Rx Tx N-PDU that belongs to that Tx N-SDU with the length of eight bytes(i.e. PduInfoPtr.SduLength = 8). Unused bytes in N-PDU shall be updated with CANTP_PADDING_BYTE (see ECUC_CanTp_00298).

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #77573: [CanTp] Padding during transmission does not apply to Rx N-PDUs

Problem description:

SWS_CanTp_00348 describes how to apply padding to an SF Rx N-PDU or the last CF Rx N-PDU belonging to a Tx N-SDU. These N-PDUs are not available, and could not be used for transmission of an N-SDU.

Agreed solution:

In SWS_CanTp_00348, replace Rx N-PDU by Tx N-PDU in both places.

BW-C-Level:

Application	Specification	Bus
1	1	1

1.23 Specification Item SWS_CanTp_00349

Trace References:

none

Content:

If CanTpTxPaddingActivation is equal to CANTP_ON for a Tx N-SDU, and if a FC N-PDU is received for that Tx N-SDU on a ongoing transmission, by means of CanTp_RxIndication() call, and the length of this FC is smaller than eight bytes (i.e. PduInfoPtr.SduLength <8) the CanTp module shall abort the transmission session by calling PduR_CanTpTxConfirmation() with the result E_NOT_OK. **If the default error detection is enabled, a development error** The runtime error code CANTP_E_PADDING shall be **triggered** **reported to the Default Error Tracer.**

RfCs affecting this spec item between releases 4.3.0 and 4.3.1:

- RfC #59085: Rollout of 'Runtime errors'

Problem description:

Inconsistencies in SWS with semantics of Default errors
–Last change on issue 59085 comment 26–

Agreed solution:

solution in Column "G" of the new attachment
<https://www.autosar.org/bugzilla/attachment.cgi?id=4604>

Notes:

- It is not enough just to migrate the error from one classification table to another. Please also check the related requirements (and background information) which is referring to that error and adapt them if needed.
- The review task of the ITs shall be done by the WP to which the specification "belongs".

*** BSW UML Model ***

SWS_CanNm:

Chapter 8.6.1 Optional Interfaces:

Add within SWS_CanNm_00325 the API function Det_ReportRunTimeError

SWS_LinIf:

SWS_LinIf_00359: add Det_ReportRuntimeError

SWS_UdpNm:

Replace UDPNM_E_NO_INIT with UDPNM_E_UNINIT in description of API
UdpNm_MainFunction_<Instance Id> (SWS_UdpNm_00234)

*** ECUC XML ***

Not affected. No configuration of runtime error reporting required (see SWS BSW
General).

–Last change on issue 59085 comment 88–

BW-C-Level:

Application	Specification	Bus
1	4	1

- RfC #73570: No "default error" in AUTOSAR

Problem description:

The DET was renamed from development error tracer to default error tracer.

This change was most of the time done automatically and unfortunately re-named "developement error" to "default error".

"default error" should always be followed by "tracer", otherwise, "development error" is probably the right term.

This could increase the impact (compared to my selection of impacted document, but formally, the configuration parameters *DevErrorDetect are not using the correct description:

"Switches the Default Error Tracer (Det) detection and notification..."

The parameter switches on/off the developement error detection. The DET

does not need to be detected and can be present even when the parameter is set to false.

Agreed solution:

Rename "default error" to "development error" in all impacted documents, but not in an automated way (Do not change "default error tracer" to "developement error tracer"!)

Blueprint/Example:

- sub chapter is now called "7.x Default errors"

- "[SWS_xxx_yyyyy]

In case default error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected errors to the DET. ()"

- "[SWS_xxx_yyyyy]

If default error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the default error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"

- "In case default errors are enabled,..."

- "module raises the Default error XXX_E_TRANSITION"

- "The DET provides services to store default errors"

...

The correct text would be:

- sub chapter is called "7.x Development errors"

- "[SWS_xxx_yyyyy]

In case development error detection is enabled for the xxxx module: The xxxx module shall check API parameters for validity and report detected development errors to the DET. ()"

- "[SWS_xxx_yyyyy]

If development error detection is enabled: the function shall check that the service xxx_Init was previously called. If the check fails, the function shall raise the development error XXX_E_NOT_INITIALIZED otherwise (if DET is disabled) return E_NOT_OK. ()"

- "In case development errors are enabled,..."

- "module raises the development error XXX_E_TRANSITION"

- "The DET provides services to store development errors"

Solution for SWS_RTE:

- SWS_RTE —

- Change 4.8 Default errors to 4.8 Development errors

- Change "Errors which can occur at runtime in the RTE are classified as default errors" to "Errors which can occur at runtime in the RTE are classified as development errors"

errors"

- Remove [SWS_Rte_07676]

- Change [SWS_RTE_06611]"If a violation is detected the RTE shall report a default error to the DET." to "If a violation is detected the RTE shall report a development error to the DET."

- Change [SWS_Rte_06631]

[SWS_Rte_06631] d The RTE shall use the OS Application Identifier as the Instance Id to enable the developer to identify in which runtime section of the RTE the error occurs. This Instance ID is even unique across multi cores and so implicitly allows the development error to be traced to a specific core. c(SRS_BSW_00337)

SRS_Libraries:

- In chapter "3 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_SPALGeneral:

- In chapter "6.1.1.3.1 [SRS_SPAL_00157] ...": Rename "Development Error Tracer" to "Default Error Tracer"

- In chapter "6.1.1.4.2 [SRS_SPAL_12448] ...": Rename "Development Error Tracer" to "Default Error Tracer"

SRS_FlashTest:

- In chapter "6.1 Functional Requirements": Rename "Development Error Tracer" to "Default Error Tracer"

- In chapter "7 References":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename	"AUTOSAR_SWS_DevelopmentErrorTracer"	to	"AU-
	TOSAR_SWS_DefaultErrorTracer"		

SWS_MFXLibrary:

- In chapter "2 Acronyms and abbreviations": Rename "Development Error Tracer" to "Default Error Tracer"

SWS_MemoryAbstractionInterface:

- In chapter "3.1 Input documents":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename	"AUTOSAR_SWS_DevelopmentErrorTracer"	to	"AU-
	TOSAR_SWS_DefaultErrorTracer"		

SWS_FlexRayNetworkManagement:

- In chapter "3.3 Related AUTOSAR documents":

Rename "Development Error Tracer" to "Default Error Tracer"

Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_CANStateManager:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_PDURouter:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"

SWS_EEPROMDriver:

- In chapter "3.1 Input documents": Rename "AUTOSAR_SWS_DevelopmentErrorTracer" to "AUTOSAR_SWS_DefaultErrorTracer"
–Last change on issue 73570 comment 47–

BW-C-Level:

Application	Specification	Bus
1	1	1