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4.2.1	AUTOSAR Release Management	 Removed obsolete configuration elements Harmonized with SWS BSW General
4.1.3	AUTOSAR Release Management	 Allow for parallel reception via TP (BAM/CMDT) and directly Clarified ambiguities regarding CTS parameters
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4.0.3	AUTOSAR Administration	API changes: CancelTransmit, CancelReceive, and ChangeParameter were changed to synchronous behavior
4.0.2	AUTOSAR Administration	 Fixed service API IDs Removed duplicate requirement J1939TP0099 Clarified requirements SWS_J1939Tp_00125 and SWS_J1939Tp_00189
4.0.1	AUTOSAR Administration	Initial release



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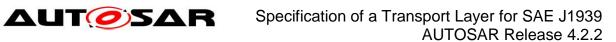


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1 Introduction and Functional Overview

This specification describes the functionality, the API, and the configuration of the AUTOSAR Basic Software module J1939Tp, which implements an SAE J1939 compatible transport layer for AUTOSAR. The terms J1939Tp and J1939 Transport Layer module are used synonymously in this document.

SAE J1939 has a broad acceptance in the truck domain, and consists of several documents describing the layers of the communication protocol from the physical layer to diagnostics and the application layer. SAE J1939-21 describes the data link and transport layer, which includes two transport protocol variants:

BAM (Broadcast Announce Message) for broadcast messages, and CMDT (Connection Mode Data Transfer) for point-to-point connections.

This specification defines how the transport protocol of SAE J1939-21 can be implemented in the AUTOSAR architecture. It only describes those parts of the implementation that are relevant to the AUTOSAR architecture. Protocol specific details like exact timings are not part of this specification. Therefore, to be able to implement the J1939 Transport Layer module, the reader of this specification must have access to the original SAE J1939-21specification document.

The module J1939Tp interfaces to the PDU Router and the CAN Interface, as shown in the following figure:

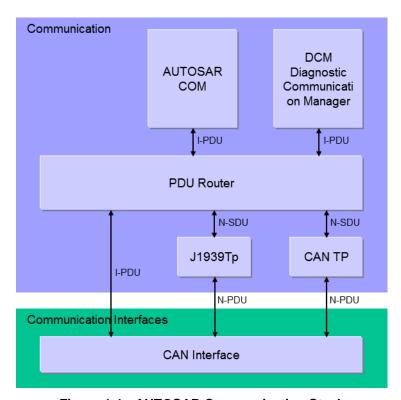


Figure 1-1: AUTOSAR Communication Stack

The purpose of J1939Tp is to segment and reassemble J1939 PGNs (N-SDUs) that are longer than 8 bytes. The segmented messages are sent and received via the CAN Interface.



The PDU-Router (PduR) deploys AUTOSAR COM and DCM I-PDUs onto different communication protocols (e.g. CAN or J1939, segmented via transport layer or directly). At runtime, the PduR decides where to route I-PDUs based on the I-PDU (L-SDU or N-SDU) identifier. In the same way, the CanIf uses the L-SDU (I-PDU or N-PDU) identifier to decide whether a received message must be processed by one of the available transport layer modules or may be forwarded directly to the PduR.

J1939Tp supports fixed and variable size N-SDUs (I-PDUs) with more than 8 bytes. I-PDUs that do not exceed 8 bytes are exchanged directly between PduR and Canlf.

Fixed size N-SDUs are always segmented by the J1939Tp, while variable size N-SDUs are only segmented when they exceed 8 bytes. J1939Tp forwards variable size N-SDUs with an actual size of 8bytes or less and a configured maximum size of more than 8 bytes directly to the Canlf. The transport protocol variant (BAM or CMDT) is chosen based on received N-PDUs when a large N-SDU is received, and on the configuration and the actual DA when a large N-SDU is transmitted.

J1939Tp supports handling of N-PDUs and N-SDUs with variable SA, DA, and Priority. In this case, the N-PDUs and N-SDUs will contain parts of the CAN ID in the MetaData (attached to the payload).

In summary, J1939Tp provides the following functionality:

- Segmentation and direct transmission of data in transmit direction
- Reassembling and direct reception of data in receive direction
- Control of data flow
- Timeout supervision
- Detection of errors during segmentation or reassembly



2 Glossary, Acronyms, and Abbreviations

The following table presents a glossary of J1939 specific terms. For all other terms, please check the AUTOSAR Glossary.

Glossary Term	Explanation
Address Claiming	Address Claiming forms the network management of SAE J1939 defined in the standard document SAE J1939/81. Address claiming assigns a temporary 8-bit identifier to each ECU connected to one J1939 network. Within this network, the 8-bit identifier is unique. The 8-bit identifier is used as source and target address of parameter groups (messages) transferred via the J1939 network. The address claiming procedure is based on the exchange of AddressClaimed messages (PGN 00EE00).
J1939 Diagnostics	The SAE J1939 diagnostic layer is defined in the standard document SAE J1939/73. The J1939 diagnostics is functionally similar to the UDS diagnostics, and has recently been extended to support OBD for emission relevant values.
Parameter	A parameter is a signal of the SAE J1939 application layer. Parameters are uniquely identified by the SPN.
Parameter Group	A parameter group is a message of the SAE J1939 application layer. Each parameter group contains several parameters (signals), and is uniquely identified by the PGN.
Transport Protocol	The SAE J1939 transport protocol is used for the segmented transmission of messages with more than 8 bytes of data. The transport protocol is defined in the network layer standard document (SAE J1939/21).



The following table lists acronyms and abbreviations that are specific to the J1939 transport layer. For all other abbreviations, please check the AUTOSAR Glossary and the AUTOSAR BSW Module List.

Acronym / Abbreviation	Description
BAM	Broadcast Announce Message, broadcast variant of SAE J1939
	transport protocol
CMDT	Connection Mode Data Transfer, peer-to-peer variant of SAE J1939 transport protocol
DA	Destination Address, part of the 29 bit identifier of SAE J1939 messages
DET	Default Error Tracer, supports development and runtime error reporting
DMx	Diagnostic messages of the SAE J1939 diagnostics layer
NAME	Unique 64 bit identifier of each ECU connected to an SAE J1939 network
PDUF	PDU Format, part of the 29 bit identifier of SAE J1939 messages which identifies the message and determines the layout of the 29 bit identifier
PDUS	PDU Specific, part of the 29 bit identifier of SAE J1939 messages which identifies broadcast messages which do not have a destination address
PG	Parameter Group, SAE J1939 term for a specific message layout, corresponds to an N-SDU of J1939Tp
PGN	Parameter Group Number, unique identifier of an SAE J1939 parameter group
SA	Source Address, part of the 29 bit identifier of SAE J1939 messages
SPN	Suspect Parameter Number, unique identifier of an SAE J1939 parameter
TP.CM	Connection Management message (PGN 00EC00) used by SAE J1939 transport protocol, corresponds to an N-PDU of J1939Tp
TP.CM_BAM	Broadcast Announce Message, variant of TP.CM that initiates a BAM transmission
TP.CM_CTS	Connection Mode Clear To Send, variant of TP.CM that is used for handshake during CMDT transmission
TP.CM_EndOfMsg Ack	End Of Message Acknowledge, variant of TP.CM that acknowledges correct reception of a CMDT transmission
TP.CM_RTS	Connection Mode Request To Send, variant of TP.CM that initiates a CMDT transmission
TP.Conn_Abort	Connection Abort, variant of TP.CM that terminates a CMDT transmission
TP.DT	Data Transfer message (PGN 00EB00) used by SAE J1939 transport protocol, corresponds to an N-PDU of J1939Tp



3 Related Documentation

3.1 Input Documents

- [1] List of Basic Software Modules AUTOSAR_TR_BSWModuleList.pdf
- [2] Layered Software Architecture AUTOSAR_EXP_LayeredSoftwareArchitecture.pdf
- [3] General Requirements on Basic Software Modules AUTOSAR_SRS_BSWGeneral.pdf
- [4] Specification of COM AUTOSAR_SWS_COM.pdf
- [5] Requirements on CAN AUTOSAR_SRS_CAN.pdf
- [6] Specification of CAN Interface AUTOSAR_SWS_CANInterface.pdf
- [7] Requirements on a Transport Layer for SAE J1939 AUTOSAR_SRS_SAEJ1939TransportLayer.pdf
- [8] Specification of PDU Router AUTOSAR_SWS_PDURouter.pdf
- [9] Specification of BSW Scheduler AUTOSAR_SWS_Scheduler.pdf
- [10] Specification of Default Error Tracer AUTOSAR_SWS_ DefaultErrorTracer.pdf
- [11] Basic Software Module Description Template AUTOSAR_SRS_BSWGeneral.pdf
- [12] Specification of ECU Configuration AUTOSAR_TPS_ECUConfiguration.pdf
- [13] Specification of System Template AUTOSAR_TPS_SystemTemplate.pdf
- [14] Specification of Memory Mapping AUTOSAR_SWS_MemoryMapping.pdf
- [15] General Specification of Basic Software Modules AUTOSAR_SWS_BSWGeneral.pdf



3.2 Related Standard Documents

- [16] SAE J1939-21(2006-12), Data Link Layer
- [17] SAE J1939-7x(2006-xx), Application Layer

3.3 Related specification

AUTOSAR provides a General Specification of Basic Software modules [15] (SWS BSW General), which is also valid for SAE J1939 Transport Layer.

Thus, the specification SWS BSW General shall be considered as additional and required specification for SAE J1939 Transport Layer.



4 Constraints and Assumptions

4.1 Limitations

The AUTOSAR architecture contains several communication system specific transport layers (J1939Tp, CanTp, FrTp, etc.). All of these modules need to have identical APIs, with the exception of API functions for which the PduR has separate configuration abilities.

The J1939Tp module does not implement the TriggerTransmit API, because it is only needed for time triggered bus architectures.

4.2 Applicability to Automotive Domains

The J1939 transport layer supports the implementation of ECUs that are designed to operate in a J1939 network.



5 Module Architecture

5.1 Dependencies on Other Modules

This section describes the relations between the J1939Tp and other AUTOSAR basic software modules. Besides the standard modules DET, EcuM, and SchM, which have interfaces to all BSW modules, J1939Tp only interacts with the PduR and the CanIf. The interfaces of J1939Tp are similar to the interfaces of CanTp.

The figure below shows the interactions between J1939Tp, PduR, and Canlf.

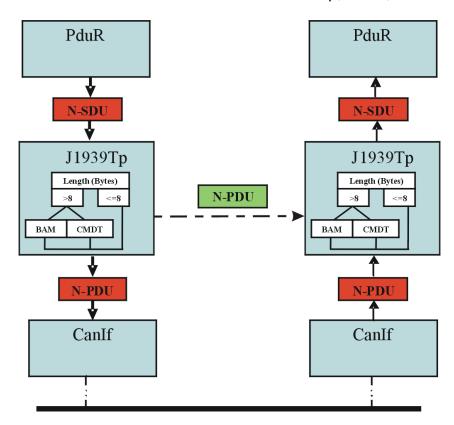


Figure 5-1: J1939 Transport Layer interactions

The J1939Tp's upper interface offers the PduR module access to transmitted and received N-SDUs corresponding to J1939 PGs with a maximum length of more than 8 bytes of data.

J1939 PGs with a maximum length of 8 bytes or less are exchanged directly between PduR and Canlf.

5.2 File Structure

AUTOSAR specifies that an ECU can be created from modules provided as object code, source code (generated or static), or both.



The decision to provide a module as object code or source code is based on a compromise between IP protection, test coverage, code efficiency and configurability at system generation time. Depending on the configurability requirements of the OEM, suppliers may deliver the J1939Tp module as object code or source code.

The file hierarchy defined in this section allows the separation of platform, compiler, and implementation specific definitions and declarations from general definitions, as well as the separation of source code and configuration.

5.2.1 Code File Structure

For details, refer to the chapter 5.1.6 "Code file structure" in SWS BSW General [15].

[SWS_J1939Tp_00007] [

Internally used data types and functions shall be defined locally in the implementation source files.] ()

This prevents visibility of these symbols outside of the J1939Tp module.

5.2.2 Header File Structure

The following picture shows the include file hierarchy used by the J1939 Transport Layer module.

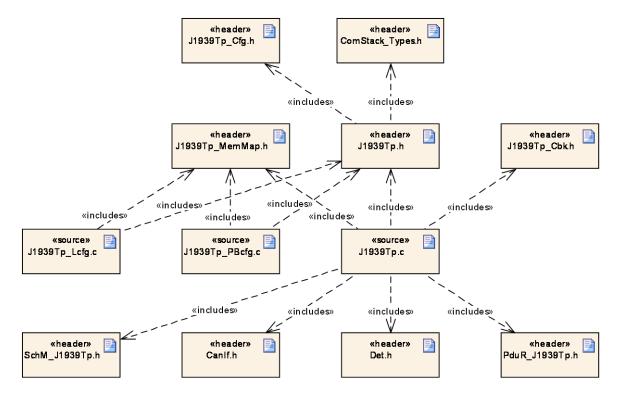


Figure 5-2: File Structure

[SWS_J1939Tp_00016] [



The implementation header files shall include ComStack Types.h.] ()

[SWS_J1939Tp_00193] [

The implementation source files shall include <code>Det.h</code> to import the default error notification API. This API is optional; the header is included depending on <code>ECUC_J1939Tp_00042:.</code> See also section 8.6.2. | ()

[SWS_J1939Tp_00015] [

The implementation source files shall include $PduR_J1939Tp.h$, which contains the callbacks functions of the PduR module that are used by the J1939Tp module. See also section 8.6.1. | ()

[SWS_J1939Tp_00172] [

The implementation source files shall include CanIf.h, which contains the service functions of the CanIf module that are used by the J1939Tp module. See also section 8.6.1.] ()



Requirements Traceability 6

Requirement	Description	Satisfied by
-	-	SWS_J1939Tp_00007
-	-	SWS_J1939Tp_00015
-	-	SWS_J1939Tp_00016
-	-	SWS_J1939Tp_00020
-	-	SWS_J1939Tp_00022
-	-	SWS_J1939Tp_00026
-	-	SWS_J1939Tp_00030
-	-	SWS_J1939Tp_00031
-	-	SWS_J1939Tp_00032
-	-	SWS_J1939Tp_00035
-	-	SWS_J1939Tp_00038
-	-	SWS_J1939Tp_00039
-	-	SWS_J1939Tp_00040
-	-	SWS_J1939Tp_00041
-	-	SWS_J1939Tp_00043
-	-	SWS_J1939Tp_00045
-	-	SWS_J1939Tp_00046
-	-	SWS_J1939Tp_00047
-	-	SWS_J1939Tp_00048
-	-	SWS_J1939Tp_00057
-	-	SWS_J1939Tp_00060
-	-	SWS_J1939Tp_00071
-	-	SWS_J1939Tp_00076
-	-	SWS_J1939Tp_00094
-	-	SWS_J1939Tp_00095
-	-	SWS_J1939Tp_00097
-	-	SWS_J1939Tp_00098
-	-	SWS_J1939Tp_00100
-	-	SWS_J1939Tp_00101
-	-	SWS_J1939Tp_00106
-	-	SWS_J1939Tp_00116
-	-	SWS_J1939Tp_00118
-	-	SWS_J1939Tp_00119
-	-	SWS_J1939Tp_00120
-	-	SWS_J1939Tp_00159
-	-	SWS_J1939Tp_00160



-	-	SWS_J1939Tp_00162
-	-	SWS_J1939Tp_00163
-	-	SWS_J1939Tp_00165
-	-	SWS_J1939Tp_00172
-	-	SWS_J1939Tp_00173
-	-	SWS_J1939Tp_00175
-	-	SWS_J1939Tp_00176
-	-	SWS_J1939Tp_00177
-	-	SWS_J1939Tp_00180
-	-	SWS_J1939Tp_00192
-	-	SWS_J1939Tp_00193
-	-	SWS_J1939Tp_00194
-	-	SWS_J1939Tp_00195
-	-	SWS_J1939Tp_00198
-	-	SWS_J1939Tp_00199
-	-	SWS_J1939Tp_00200
-	-	SWS_J1939Tp_00203
-	-	SWS_J1939Tp_00204
-	-	SWS_J1939Tp_00206
-	-	SWS_J1939Tp_00207
-	-	SWS_J1939Tp_00208
-	-	SWS_J1939Tp_00209
-	-	SWS_J1939Tp_00210
-	-	SWS_J1939Tp_00211
-	-	SWS_J1939Tp_00212
-	-	SWS_J1939Tp_00213
-	-	SWS_J1939Tp_00214
-	-	SWS_J1939Tp_00215
-	-	SWS_J1939Tp_00216
-	-	SWS_J1939Tp_00217
-	-	SWS_J1939Tp_00218
-	-	SWS_J1939Tp_00219
-	-	SWS_J1939Tp_00220
-	-	SWS_J1939Tp_00221
-	-	SWS_J1939Tp_00222
-	-	SWS_J1939Tp_00223
-	-	SWS_J1939Tp_00224
-	-	SWS_J1939Tp_00225
-	-	SWS_J1939Tp_00226
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	T	1
-	-	SWS_J1939Tp_00227
-	-	SWS_J1939Tp_00228
-	-	SWS_J1939Tp_00229
-	-	SWS_J1939Tp_00230
-	-	SWS_J1939Tp_00231
-	-	SWS_J1939Tp_00232
SRS_BSW_00005	Modules of the µC Abstraction Layer (MCAL) may not have hard coded horizontal interfaces	SWS_J1939Tp_99999
SRS_BSW_00101	The Basic Software Module shall be able to initialize variables and hardware in a separate initialization function	SWS_J1939Tp_00087
SRS_BSW_00161	The AUTOSAR Basic Software shall provide a microcontroller abstraction layer which provides a standardized interface to higher software layers	SWS_J1939Tp_99999
SRS_BSW_00162	The AUTOSAR Basic Software shall provide a hardware abstraction layer	SWS_J1939Tp_99999
SRS_BSW_00164	The Implementation of interrupt service routines shall be done by the Operating System, complex drivers or modules	SWS_J1939Tp_99999
SRS_BSW_00167	All AUTOSAR Basic Software Modules shall provide configuration rules and constraints to enable plausibility checks	SWS_J1939Tp_00084
SRS_BSW_00168	SW components shall be tested by a function defined in a common API in the Basis-SW	SWS_J1939Tp_99999
SRS_BSW_00170	The AUTOSAR SW Components shall provide information about their dependency from faults, signal qualities, driver demands	SWS_J1939Tp_99999
SRS_BSW_00171	Optional functionality of a Basic-SW component that is not required in the ECU shall be configurable at pre-compile-time	SWS_J1939Tp_00125
SRS_BSW_00314	All internal driver modules shall separate the interrupt frame definition from the service routine	SWS_J1939Tp_99999
SRS_BSW_00323	All AUTOSAR Basic Software Modules shall check passed API parameters for validity	SWS_J1939Tp_00188
SRS_BSW_00325	The runtime of interrupt service routines and functions that are running in interrupt context shall be kept short	SWS_J1939Tp_99999
SRS_BSW_00327	Error values naming convention	SWS_J1939Tp_00115
SRS_BSW_00333	For each callback function it shall be specified if it is called from interrupt context or not	SWS_J1939Tp_00110, SWS_J1939Tp_00114
SRS_BSW_00335	Status values naming convention	SWS_J1939Tp_00019
SRS_BSW_00336	Basic SW module shall be able to shutdown	SWS_J1939Tp_00093
SRS_BSW_00337	Classification of development errors	SWS_J1939Tp_00115
SRS_BSW_00341	Module documentation shall contains all	SWS_J1939Tp_99999



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report error events only after the DEM is fully operational. SRS_BSW_00419 If a pre-compile time configuration parameter is implemented as "const" it should be placed into a separate c-file	SRS_BSW_00416		SWS_J1939Tp_99999
is implemented as "const" it should be placed into a separate c-file	SRS_BSW_00417	report error events only after the DEM is fully	SWS_J1939Tp_99999
SRS_BSW_00423 BSW modules with AUTOSAR interfaces SWS_J1939Tp_99999	SRS_BSW_00419	is implemented as "const" it should be placed	SWS_J1939Tp_99999
	SRS_BSW_00423	BSW modules with AUTOSAR interfaces	SWS_J1939Tp_99999



	shall be describable with the means of the	
	SW-C Template	
SRS_BSW_00427	ISR functions shall be defined and documented in the BSW module description template	SWS_J1939Tp_99999
SRS_BSW_00433	Main processing functions are only allowed to be called from task bodies provided by the BSW Scheduler	SWS_J1939Tp_99999
SRS_BSW_00437	Memory mapping shall provide the possibility to define RAM segments which are not to be initialized during startup	SWS_J1939Tp_99999
SRS_BSW_00438	Configuration data shall be defined in a structure	SWS_J1939Tp_00187
SRS_BSW_00439	Enable BSW modules to handle interrupts	SWS_J1939Tp_99999
SRS_BSW_00440	The callback function invocation by the BSW module shall follow the signature provided by RTE to invoke servers via Rte_Call API	SWS_J1939Tp_99999
SRS_BSW_00441	Naming convention for type, macro and function	SWS_J1939Tp_00019, SWS_J1939Tp_00115
SRS_BSW_00447	Standardizing Include file structure of BSW Modules Implementing Autosar Service	SWS_J1939Tp_99999
SRS_BSW_00449	BSW Service APIs used by Autosar Application Software shall return a Std_ReturnType	SWS_J1939Tp_99999
SRS_BSW_00450	A Main function of a un-initialized module shall return immediately	SWS_J1939Tp_00023
SRS_BSW_00453	BSW Modules shall be harmonized	SWS_J1939Tp_99999
SRS_J1939_00001	The J1939 Transport Layer module shall be configurable to support only transport protocol variant BAM	SWS_J1939Tp_00125
SRS_J1939_00010	The J1939 Transport Layer module shall implement an interface for initialization	SWS_J1939Tp_00024
SRS_J1939_00011	The J1939 Transport Layer services shall not be operational before initializing the module	SWS_J1939Tp_00023, SWS_J1939Tp_00025
SRS_J1939_00019	The J1939 Transport Layer module shall support the transport protocol variant BAM	SWS_J1939Tp_00155
SRS_J1939_00020	The AUTOSAR J1939 Transport Layer module shall support the transport protocol variant CMDT	SWS_J1939Tp_00155
SRS_J1939_00022	The timeout values of the J1939 transport protocol variants shall be supervised	SWS_J1939Tp_00018, SWS_J1939Tp_00121, SWS_J1939Tp_00123
SRS_J1939_00023	The J1939 Transport Layer module shall handle unexpected PDUs according to the SAE J1939 specification	SWS_J1939Tp_00018, SWS_J1939Tp_00064
SRS_J1939_00024	Unused Bytes in N-PDUs shall be padded	SWS_J1939Tp_00068
SRS_J1939_00025	The J1939 Transport Layer module shall be able to manage connections via BAM and CMDT in parallel	SWS_J1939Tp_00062



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The AUTOSAR J1939 Transport Layer module shall be based on SAE J1939 specifications	SWS_J1939Tp_00018
The J1939 Transport Layer interface shall be independent of its internal configuration	SWS_J1939Tp_00157



7 Functional Specification

This chapter describes the functionality of the AUTOSAR J1939 Transport Layer. It explains the services provided to the upper and lower layers and the internal behavior of J1939Tp.

7.1 Basic Principles of SAE J1939

The SAE J1939 standard defines a set of Parameter Groups (PGs), each containing signals with defined content and semantics. The following information is provided for each PG:

- Payload length type: maximal number of bytes, fixed or variable size.
- Parameter Group Number (PGN): 18 bit value containing the following fields:
 - 2 bit data page information (DP and EDP)
 - 8 bit PDU-Format (PF)
 - o 8 bit PDU-Specific (PS)

PGNs with PDU-Format < 240 (format 1) identify point-to-point messages, while PGNs with PDU-Format >= 240 (format 2) identify broadcast messages. The PDU-Specific field is only relevant for broadcast messages (format 2); it is always zero for point-to-point messages (format 1).

J1939 uses 29-bit CAN identifiers to identify each message. The CAN identifier contains a 3-bit-priority, the PGN, the Source Address (SA), and the Destination Address (DA, only for point-to-point messages).

Usually, an ECU has just one node address, which is used as DA in received messages and as SA in transmitted messages. However, a single ECU can also implement several different J1939 nodes at once, each with its own node address. In this case, the ECU accepts any of these node addresses as DA and sends with any of the defined node addresses as SA.

The SAE J1939 transport layer uses two special point-to-point messages identified by PGNs of format 1 to transport segmented messages, both with a fixed length of 8 bytes. These messages are called transport frames in the context of this document.

TP.CM is used for connection management. The first byte of the payload identifies its role, which may be one of the following:

TP.CM_BAM is used to initiate a BAM transfer.

TP.CM RTS is transmitted to initiate a CMDT transfer.

TP.CM_CTS is used for flow control during a CMDT transfer.

TP.CM EndOfMsgAck indicates the end of a CMDT transfer.

TP.Conn_Abort indicates an error and terminates the CMDT transfer.

TP.DT contains a sequence number in the first byte and 7 bytes of data.

A single TP.CM or TP.DT frame, identified by a certain CAN Identifier, is used for different PGs. The PGN of the transported PG is contained in the payload of the TP.CM frames as specified in [16].



The destination address (DA) of CMDT related transport frames contains a legal node address and thus allows a point-to-point connection, while the DA of BAM related transport frames is always set to FF₁₆ to create a broadcast connection.

[SWS_J1939Tp_00018] [

The J1939Tp module shall follow the recommendations of SAE J1939-21 [16] if they are not explicitly excluded in this document.] (SRS_J1939_00022, SRS_J1939_00023, SRS_J1939_00040)

7.2 Basic Functionality of J1939Tp

This section describes aspects of the functionality of J1939Tp that are not related to neighboring modules.

[SWS_J1939Tp_00071] [

On errors and exceptions, the J1939Tp module shall not modify its current module state (see Figure 7-1: J1939 Transport Layer life cycle) but shall simply report the error event. | ()

To assure a unique PDU router handling of all J1939 PGs which is independent of the Payload Length type (variable or fixed), the J1939Tp is used for the transmission of all Parameter Groups that are longer than 8 Bytes, independent of their length being fixed or variable.

This means that PGs with variable length that have a configured maximum size of more than 8 bytes but do not exceed 8 bytes at runtime shall be transported using J1939Tp even though no segmentation is necessary and a direct transmission from PDU router to CAN Interface would be possible.

[SWS_J1939Tp_00155] [

The J1939 transport layer shall implement the following two J1939 transport protocol variants defined in [16]:

- BAM for broadcast transmission
- CMDT for point-to-point transmission (SRS_J1939_00019, SRS_J1939_00020)

[SWS J1939Tp 00125] [

The J1939 Transport Layer shall be configurable to either use both BAM and CMDT transport protocol variants, or only BAM, or only CMDT. J (SRS_BSW_00171, SRS_J1939_00001)

[SWS J1939Tp 00198] [

The layout and content of MetaData of N-SDUs and N-PDUs used by the J1939Tp is determined by MetaDataLength:

MetaDataLength Content of MetaData

0 [no meta data]

1 SA



- 2 SA, DA
- 4 SA, DA, [don't care], Priority << 2 [lower 2 bits ignored] Direct N-PDUs will contain the PGN in the ignored parts and instead of the DA in case of format 2 PGNs.] ()

[SWS_J1939Tp_00231] [

The J1939 Transport Layer module shall support several connections for the same PGN in parallel as long as they can be received or transmitted independently. | ()

For the definition of connections see section 7.5.7.

7.3 Initialization and Shutdown

The following figure summarizes all the requirements concerning initialization and shut down:

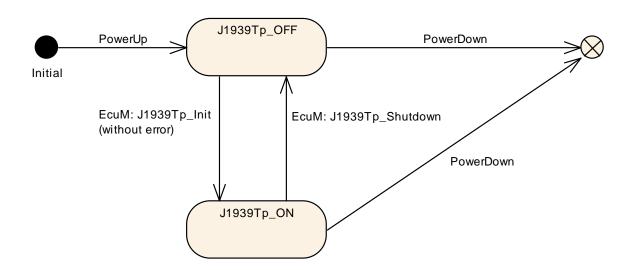


Figure 7-1: J1939 Transport Layer life cycle

[SWS_J1939Tp_00019] [

The J1939Tp module shall have two global states, J1939TP_ON and J1939TP OFF. J (SRS_BSW_00335, SRS_BSW_00441)

[SWS J1939Tp 00020] [

The J1939Tp module shall be in the J1939TP OFF state after power up.] ()

In the state $\tt J1939TP_OFF$, the J1939Tp allows for an update of the post build configuration.

[SWS_J1939Tp_00023] [



The J1939Tp module shall perform segmentation and reassembly tasks only when the J1939Tp is in the $\tt J1939TP_ON$ state. $\tt J$ (SRS_BSW_00406, SRS_BSW_00450, SRS_J1939_00011)

[SWS_J1939Tp_00076] [

The global state (see **SWS_J1939Tp_00019**) shall be used to check if the module has been initialized before calling an API.] ()

[SWS_J1939Tp_00025] [

If default error detection (DET) for the J1939Tp module is enabled, the J1939Tp module shall raise an error (J1939TP_E_UNINIT) when any function excepting J1939Tp_GetVersionInfo is called before the function J1939Tp_Init() has been called.] (SRS_BSW_00407, SRS_J1939_00011)

7.4 Communication with the Lower Layer

[SWS_J1939Tp_00157] [

All service interfaces provided to the lower layer shall be independent of the internal communication configuration and implementation of the J1939Tp.] (SRS_J1939_00042)

[SWS_J1939Tp_00041] [

J1939Tp shall send the transport frames TP.CM and TP.DT and direct frames using the service function <code>CanIf Transmit().]()</code>

7.4.1 Transmission Confirmation

The transmission confirmation $\tt J1939Tp_TxConfirmation()$ is called by Canlf to notify J1939 TP of successful transmission of an N-PDU.

[SWS_J1939Tp_00035] [

When no $\tt J1939Tp_TxConfirmation()$ is received within $\tt J1939TpTxConfTimeout$ (see <code>ECUC_J1939Tp_00006:</code>) seconds after a call to <code>CanIf_Transmit()</code>, the J1939Tp module shall abort the corresponding session, and any late confirmation shall be ignored. $\tt J()$

For transmitting sessions, the session abort is defined in SWS_J1939Tp_00032, while SWS_J1939Tp_00031 defines the behavior in case of a receiving session. The J1939Tp shall not try to send an abort frame (as defined by SWS_J1939Tp_00097) in this case.



7.4.2 Reception Indication

The J1939Tp module shall provide a J1939Tp_RxIndication() API to allow the CanIf to notify that a new N-PDU has been received (see **SWS_J1939Tp_00108**). CanIf shall perform the Reception Indication according to its configuration (i.e. in ISR context if configured so).

7.5 Internal Behavior

7.5.1 Session Handling

7.5.1.1 Close Transmission

[SWS_J1939Tp_00119] [

When the transport transmission session is successfully completed, the J1939Tp module shall call a notification service of the upper layer, $PduR_J1939TpTxConfirmation$, with the result E_OK, to notify that the N-SDU transfer is successfully processed. | ()

7.5.1.2 Abort Transmission

[SWS_J1939Tp_00032] [

An Abort Transmission feature shall indicate the upper layer that the transmission of a given N-SDU has been aborted. It uses the callback function PduR J1939TpTxConfirmation with E_NOT_OK.]()

7.5.1.3 Close Reception

[SWS_J1939Tp_00118] [

A close connection feature shall indicate the upper layer that the transport reception session is completed. It uses the $PduR_J1939TpRxIndication()$ with E_OK to indicate that the N-SDU reception is successfully processed. | ()

7.5.1.4 Abort Reception

[SWS_J1939Tp_00031] [

An Abort Reception feature shall indicate the upper layer that the reception of a given N-SDU has been aborted. It uses the $PduR_J1939TpRxIndication()$ with state $E_NOT_OK.$ ()

7.5.1.5 Abort CMDT Connection

[SWS_J1939Tp_00097] [



An Abort CMDT Connection feature shall indicate to the other ECU participating in the concerned connection that the current CMDT session (transmission or reception) cannot be completed successfully. A TP.Conn_Abort abort message shall be transmitted to the other ECU via CAN as specified by [16].] ()

Sending a TP.Conn_Abort is necessary every time an error happens after TP.CM_CTS has been successfully sent or received, and is advisable already after transmission or reception of TP.CM_RTS. The connection abort reason of the TP.Conn_Abort shall be set according to [16].

7.5.2 N-SDU Reception

Reception of an N-SDU is always initiated by the reception of a TP.CM message. In case of CMDT, this is a TP.CM RTS, in case of BAM a TP.CM BAM.

[SWS J1939Tp 00043] [

Depending on the control byte of the initializing TP.CM frame (BAM or RTS), the J1939Tp module shall use the variant BAM or CMDT of the J1939 transport protocol to handle the data reception. | ()

[SWS_J1939Tp_00038] [

When receiving an N-PDU containing a TP.CM_BAM or a TP.CM_RTS the J1939Tp module shall first notify the upper layer (PDU Router) before processing the frame reassembly. It uses the PduR_J1939TpStartOfReception function with the following parameters:

- the Identifier of the corresponding N-SDU,
- depending on MetaDataLength: the SA, DA and Priority,
- the total Data Length (after reassembly) and
- a pointer to a location where the upper layer stores its currently available buffer size.] ()

[SWS_J1939Tp_00162] [

After the reception of an N-PDU containing a TP.DT frame, the function PduR J1939TpCopyRxData shall be called with the following parameters:

- the Identifier of the corresponding N-SDU,
- PduInfoPtr with max. 7 bytes of data,
- a pointer to a location where the upper layer stores its currently available buffer size. | ()

[SWS J1939Tp 00173] [

The J1939Tp module shall abort the reception silently if any of the following conditions occurs:

- The PduR_J1939TpStartOfReception function returns BUFREQ_E_NOT_OK or BUFREQ_E_OVFL or
- the protocol chosen in SWS_J1939Tp_00043 does not match the transport protocol configured for the transported PGN (see ECUC_J1939Tp_00029 :) or



- the SA/DA of N-PDUs with MetaData do not match the configured SA/DA (see ECUC_J1939Tp_00179 : /ECUC_J1939Tp_00178 :).

In case of a BAM connection, no further activity is required.

In case of a CMDT connection, a CMDT Connection Abort shall be performed as described in **SWS_J1939Tp_00097**, and the connection abort reason shall be set to 1 (Already in one or more connection managed sessions and cannot support another). | ()

[SWS J1939Tp 00040] [

The J1939Tp module shall abort the reception like indicated in **SWS_J1939Tp_00031** if any of the following conditions occurs:

- The value returned by PduR_J1939TpStartOfReception via bufferSizePtr is smaller than the total data length of the N-SDU when received via the direct N-PDU.
- the Pdur J1939TpCopyRxData function returns BUFREQ E NOT OK, or
- the J1939Tp CancelReceive function is called.

In case of a BAM connection, no further activity is required.

In case of a CMDT connection, a CMDT Connection Abort shall be performed as described in SWS_J1939Tp_00097, and the connection abort reason shall be set to 1 (Already in one or more connection managed sessions and cannot support another) after the call to PduR_J1939TpStartOfReception, and to 2 (System resources were needed for another task so this connection managed session was terminated) in the other two cases.] ()

7.5.3 N-SDU Transmission

As described in section 7.3.2, the upper layer (PDU Router) asks for the transmission of an N-SDU by calling J1939Tp_Transmit(). The parameters of J1939Tp_Transmit() describe the Identifier of the N-SDU (NSduld) and a reference to a PduInfoType that indicates the full length of the N-SDU to transmit (full Tx N-SDU data length) and a pointer to the payload N-SDU, which may contain MetaData with SA, DA and Priority depending on the MetaDataLength of the N-SDU.

[SWS J1939Tp 00039] [

When configured, the transport protocol variant (BAM/CMDT, see ECUC_J1939Tp_00137:) and the SA/DA (see ECUC_J1939Tp_00181:/ECUC_J1939Tp_00180:) shall be used for transmission. For N-SDUs with MetaInfo, these parameters are optional. If SA or DA is not configured, the value provided via the MetaData shall be used. If the transport protocol is not configured, it shall be chosen based on the actual DA: BAM when DA is 0xFF, CMDT otherwise.]

[SWS J1939Tp 00045] [

The function J1939Tp_Transmit shall use the NSduld and the SduLength provided in the PduInfoType structure. It shall not use the payload of N-SDUs, only the contained MetaData. | ()



[SWS_J1939Tp_00047] [

After a transmission request from the upper layer, the J1939Tp module shall initiate the transmission by sending:

- For CMDT: a TP.CM RTS frame

- For BAM: a TP.CM_BAM frame] ()

[SWS_J1939Tp_00046] [

For each TP.DT frame to be sent, the J1939Tp module shall previously call PduR J1939TpCopyTxData with the following parameters:

- the Identifier of the corresponding N-SDU,
- PduInfoType structure with up to 7 bytes as SduLength,
- the retry parameter, and
- a pointer to a location where the upper layer stores its currently available data.

[SWS_J1939Tp_00228] [

When $PduR_J1939TpCopyTxData$ returns $BUFREQ_E_BUSY$, the J1939Tp shall retry the call to $PduR_J1939TpCopyTxData$ until the data is available or a timeout occurs.] ()

[SWS_J1939Tp_00218] [

If J1939TpTxRetrySupport is disabled, the parameter retry of PduR_J1939TpCopyTxData shall allways be set to the NULL_PTR.] ()

[SWS J1939Tp 00219] [

For BAM transmissions, the parameter retry of PduR_J1939TpCopyTxData shall allways be set to the NULL_PTR.] ()

[SWS J1939Tp 00220] [

If J1939TpTxRetrySupport is enabled, a valid RetryInfoType stuct shall be provided via the parameter retry of PduR_J1939TpCopyTxData during CMDT transmissions.] ()

See section 7.5.4.2 for a description how the J1939 Transport Layer module uses the RetryInfoType during CMDT transmission.

[SWS J1939Tp 00048] [

The J1939Tp module shall abort the transmission session like specified in **SWS_J1939Tp_00032** if any of the following conditions occur:

- The upper Layer returns the PduR_J1939TpCopyTxData function call with BUFREQ E NOT OK or
- the J1939Tp CancelTransmit function is called.

In case of a CMDT connection, a CMDT Connection Abort shall be performed as described in **SWS_J1939Tp_00097**, and the connection abort reason shall be set to



2 (System resources were needed for another task so this connection managed session was terminated).] ()

7.5.4 Data Flow on the CAN Bus

7.5.4.1 Data Flow using Direct Transmission

The following figure shows an example of direct message transmission between two ECUs using J1939Tp. This is the only case of transmission of a J1939Tp N-SDU using no TP.CM or TP.DT frame. The SA is always included in the CAN identifier. Depending on the PDU-Format of the concerned PG, the CAN Identifier might contain the DA.

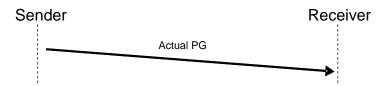


Figure 7-2: Example of direct data flow for PGs of variable length <= 8 Bytes

7.5.4.2 Data Flow using CMDT

The following figure shows an example of segmented message transmission between two ECUs using CMDT as transport protocol variant. The CMDT transport protocol variant is used for peer-to-peer communication (i.e. 1 to 1 communication, like physical addressing in diagnostics). In the example, the transmitted PG has a total length of 16 bytes, which corresponds to 3 blocks of 7 bytes.

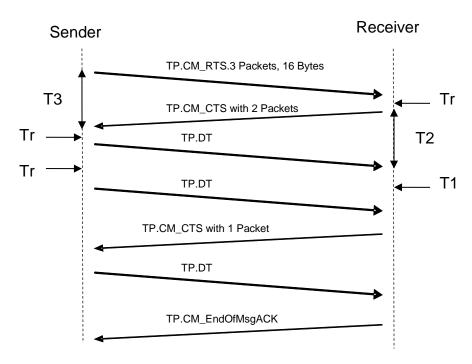


Figure 7-3: Example of data flow without error using CMDT as transport protocol variant



The J1939 transport protocol uses the initial sequence of RTS and CTS to determine the number of packets per block.

[SWS J1939Tp 00165] [

If J1939TpTxDynamicBlockCalculation is enabled, after J1939Tp_Transmit has been called, the J1939Tp shall call $PduR_J1939TpCopyTxData$ once with info-SduLength set to 0 and retry set to NULL_PTR to obtain the available amount of data via availableDataPtr. | ()

[SWS_J1939Tp_00207] [

If J1939TpTxDynamicBlockCalculation and J1939TpTxMaxPacketsPerBlock are enabled, the J1939Tp shall compare the available amount of data returned by $PduR_J1939TpCopyTxData$ to J1939TpTxMaxPacketsPerBlock and use use the smaller of these two values to calculate the maximum number of packets field of the TP.CM_RTS message.] ()

[SWS_J1939Tp_00208] [

If J1939TpTxDynamicBlockCalculation is enabled but J1939TpTxMaxPacketsPerBlock is disabled, the J1939Tp shall use the available amount of data returned by PduR_J1939TpCopyTxData to calculate the maximum number of packets field of the TP.CM RTS message. | ()

[SWS J1939Tp 00209] [

If J1939TpTxDynamicBlockCalculation is disabled, the J1939Tp shall use J1939TpTxMaxPacketsPerBlock for the maximum number of packets field of the TP.CM_RTS message. | ()

[SWS_J1939Tp_00210] [

J1939TpRxDynamicBlockCalculation J1939TpRxPacketsPerBlock and are enabled. the J1939Tp shall compare the value returned by PduR J1939TpStartOfReception for the available buffer size to J1939TpRxPacketsPerBlock and use the lower value to calculate the number of packets field of the TP.CM_CTS message. | ()

[SWS J1939Tp 00211] [

If J1939TpRxDynamicBlockCalculation is enabled but J1939TpRxPacketsPerBlock is disabled, the J1939Tp shall use the value returned by PduR_J1939TpStartOfReception for the available buffer size to calculate the number of packets field of the TP.CM_CTS message. | ()

[SWS J1939Tp 00226] [

After reception of the TP.CM_RTS and after reception of the last N-PDU of a block, if the reported buffer size is large enough for the next block, the J1939Tp shall transmit a TP.CM_CTS message requesting the next block. The number of packets requested



by TP.CM_CTS shall be constant during the complete reception of one N-SDU, only in the last TP.CM_CTS this number shall be reduced to the number of remaining packets.] ()

[SWS_J1939Tp_00227] [

When there is not enough buffer reported by PduR_J1939TpStartOfReception or PduR_J1939TpCopyRxData for the reception of a complete block, the J1939Tp shall call PduR_J1939TpCopyRxData with info->SduLength set to 0 until the buffer is large enough for one block, or a timeout occurs. | ()

[SWS_J1939Tp_00229] [

While monitoring the buffer state as defined by **SWS_J1939Tp_00227**, the J1939Tp shall send TP.CM_CTS wait frames (number of packets set to 0, see also [16]) according to the timing requirements defined in [16]. | ()

[SWS J1939Tp 00212] [

If J1939TpRxRetrySupport is enabled, the J1939Tp shall adapt the value returned by PduR_J1939TpStartOfReception for the available buffer size according to J1939TpRxDynamicBufferRatio before using it to calculate the number of packets field of the TP.CM_CTS message as specified in SWS_J1939Tp_00210 and SWS_J1939Tp_00211. | ()

[SWS_J1939Tp_00213] [

If J1939TpRxDynamicBlockCalculation is disabled, the J1939Tp shall use J1939TpRxPacketsPerBlock to calculate the number of packets field of the TP.CM_CTS message.] ()

[SWS_J1939Tp_00217] [

If J1939TpTxRetrySupport is enabled, the J1939Tp shall call PduR J1939TpCopyTxData with

- TpDataState set to TP_DATACONF for the first call after reception of a TP.CM_CTS, and
- TpDataState set to TP_CONFPENDING for the following calls. | ()

[SWS J1939Tp 00195] [

If a TP.CM_CTS wait frame (number of packets set to 0, see also [16]) is received, the J1939Tp shall wait for another TP.CM_CTS frame.] ()

[SWS J1939Tp 00223] [

When the J1939Tp receives a TP.CM_CTS frame that requests data beyond the current position or preceding the position where the last TP.CM_CTS was received, it shall abort the transmission using the mechanisms described by SWS_J1939Tp_00032 and SWS_J1939Tp_00097 with reason FF₁₆ (SNA). | ()



[SWS_J1939Tp_00221] [

If J1939TpTxRetrySupport is enabled, when the J1939Tp receives a TP.CM_CTS frame requesting already sent data, it shall call $PduR_J1939TpCopyTxData$ with TpDataState set to TP_DATARETRY and TxTpDataCnt set to the number of bytes to be retransmitted. | ()

The number of bytes that need to be retransmitted is calculated from the position of the requested package relative to the current package.

[SWS J1939Tp 00194] [

If J1939TpTxRetrySupport is disabled, when the J1939Tp receives a TP.CM_CTS frame requesting already sent data, it shall abort the transmission using the mechanisms described by **SWS_J1939Tp_00032** and **SWS_J1939Tp_00097** with reason 255 (unassigned).] ()

[SWS J1939Tp 00222] [

If J1939TpRxRetrySupport is enabled, when a sequence error occurs during reception, the J1939Tp module shall, after the last TP.DT message of the block was received, send a TP.CM_CTS frame requesting the packages that follow the last correctly received package of the current block. \rfloor ()

[SWS_J1939Tp_00232] [

The content of a TP.DT message with a sequence error and of the TP.DT messages following a sequence error in the same block shall be discarded. | ()

Note: This means that for such messages PduR_J1939TpCopyRxData shall not be called.

[SWS_J1939Tp_00216] [

If J1939TpRxRetrySupport is disabled, when a sequence error occurs during reception, the J1939Tp module shall abort the reception session

- as specified in SWS_J1939Tp_00031 and
- as specified in SWS_J1939Tp_00097 with connection abort reason FF₁₆ (SNA).] ()

[SWS_J1939Tp_00123] [

J1939Tp shall implement all CMDT related timing constraints (Tr, Th, T1, T2, T3, T4) as described in [16]. They supervise the CMDT data flow. | (SRS_J1939_00022)

[SWS J1939Tp 00100] [

If a timeout occurs during CMDT transmission (see [16] for details) then the J1939Tp module shall abort the transmission session

- as specified in SWS J1939Tp 00032 and
- as specified in **SWS_J1939Tp_00097** with connection abort reason 3 (A timeout occurred and this is the connection abort to close the session) when



the timeout occurred after successful transmission of the TP.CM_RTS frame.
] ()

[SWS_J1939Tp_00159] [

If a timeout occurs during reception (see [16] for details) then the J1939Tp module shall abort the reception session

- as specified in SWS_J1939Tp_00031 and
- as specified in **SWS_J1939Tp_00097** with connection abort reason 3 (A timeout occurred and this is the connection abort to close the session). | ()

[SWS_J1939Tp_00098] [

If a TP.Conn_Abort frame is received after a TP.CM_RTS frame has been successfully sent by the ECU, the transmission shall be aborted like indicated in **SWS J1939Tp 00032**. No transmission of TP.Conn Abort is necessary. | ()

[SWS J1939Tp 00163] [

If a TP.Conn_Abort frame is received after a TP.CM_RTS frame has been received, the reception shall be aborted like indicated in **SWS_J1939Tp_00031**. No transmission of TP.Conn_Abort is necessary.] ()

7.5.4.3 Data Flow using BAM

[SWS J1939Tp 00121] [

J1939Tp shall implement the BAM related timing constraints (50ms, Tr, T1) as described in [16]. They supervise the BAM data flow. | (SRS_J1939_00022)

[SWS_J1939Tp_00160] [

If a timeout occurs during the BAM reception, the J1939Tp module shall abort the reception session as specified in **SWS_J1939Tp_00031**.] ()

[SWS J1939Tp 00192] [

After a sequence error, J1939Tp shall abort BAM connections as specified in SWS J1939Tp 00031. | ()

The following figure shows an example of segmented message transmission between two ECUs using BAM as transport protocol variant according to [16]. The BAM transport protocol variant is used for a broadcast communication (i.e. 1 to n communication, like functional addressing in diagnostics). In the example, the transmitted PG has a total length of 3 blocks of 7 bytes that have to be successively transmitted.



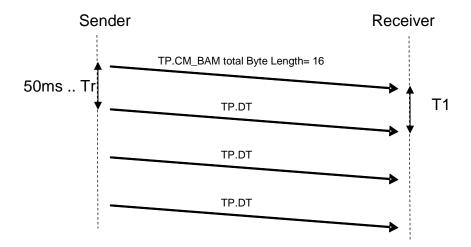


Figure 7-4: Example of data flow using BAM as transport protocol variant

7.5.5 N-SDU Buffer Management

J1939Tp shall have no internal PDU buffers. It requests data for sending directly from the upper layers via PduR_J1939TpCopyTxData() and provides received data directly to the upper layers via PduR_J1939TpCopyRxData().

To guarantee data consistency, the complete buffer of the upper layers must be locked during the whole data transmission or reception.

Data transmission is initialized when the PduR calls J1939Tp_Transmit() and is active after J1939Tp executed this call successfully until J1939Tp calls PduR J1939TpTxConfirmation():

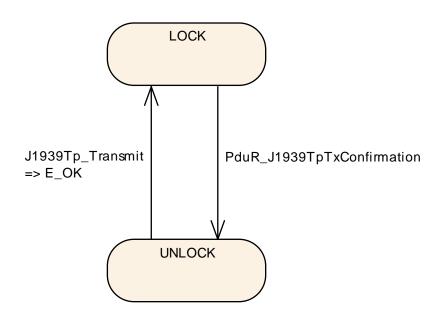


Figure 7-5: Tx Buffer locking



Data reception is initialized when J1939Tp calls PduR_J1939TpStartOfReception() and is active after the PduR executed this call successfully until J1939Tp calls PduR J1939TpRxIndication():

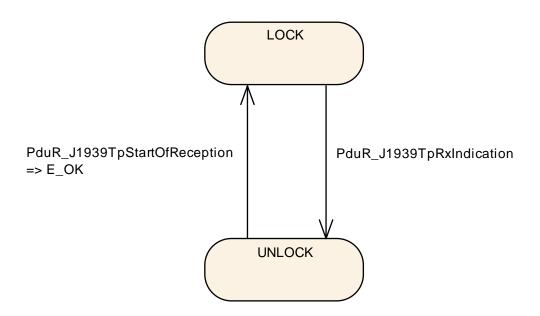


Figure 7-6: Rx Buffer locking

7.5.6 Relationship between N-SDU and N-PDU in J1939Tp

This section describes the relation that exists between an N-SDU and the set of N-PDUs that is required to transport the N-SDU data, as shown in the following figure.

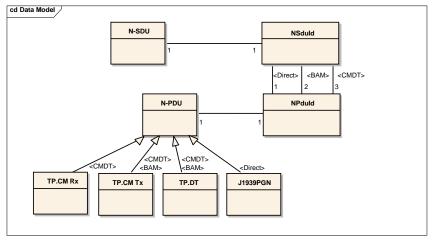


Figure 7-7: Relation between N-SDU and N-PDU

The N-PDUs as well as the N-SDU may use MetaData. In that case, the N-SDU stands for a certain PGN, and the N-PDUs stand for TP.CM, TP.DT, and direct PG, regardless of source and/or destination addresses.



[SWS_J1939Tp_00057] [

During reception, the N-SDU is identified by a combination of the PGN included in the payload of TP.CM and, when the N-SDU has no MetaData, from the addressing information implicitly encoded in the NPdulds or explicitly provided via the MetaData of the N-PDUs.] ()

[SWS_J1939Tp_00199] [

During transmission, the relevant set of N-PDUs is identified by the configured SA/DA of N-SDUs without MetaData, or by the SA/DA explicitly provided in the MetaData by the upper layer. | ()

7.5.7 Concurrent Connections

Connections only concern internal J1939Tp purposes. They are transparent for the upper and lower layers of J1939Tp but influence the handling of J1939Tp.

A J1939Tp connection is characterized by its direction (Receiving /Sending) and its type (BAM / CMDT / Direct). A J1939Tp connection of type BAM or CMDT uses the following transport related frames:

- control (TP.CM)
- data (TP.DT)

The CAN-Identifier corresponding to those transport specific frames is the same for all J1939 PGs longer than 8 bytes:

- sent from a given SA in the BAM case
- sent from a given SA to a given DA in the CMDT case

This reduces the possibility for J1939Tp to process concurrent connections.

[SWS J1939Tp 00120] [

The J1939Tp shall be able to handle connections in parallel for all N-SDUs that do not interfere in the usage of TP.DT frames with the same SA and DA. For channels with defined SA/DA and protocol type, only one TP connection and one direct connection can be open at any time. For channels with variable SA/DA, the maximum number of parallel connections is limited by the number of N-SDUs assigned to this channel.] ()

J1939Tp shall only support concurrent connections as described in section 5.10.5 of [16]. Note that one AUTOSAR ECU can represent several J1939 nodes and thus may have more than one address (used as SA or DA) assigned to it.

[SWS J1939Tp 00062] [

Each connection shall be independent of the other connections. | (SRS J1939 00025)

This means that a connection shall use its own resources, such as timer or state machine.



7.5.8 N-PDU Padding

[SWS_J1939Tp_00200] [

The J1939 Transport Layer module shall send TP.DT frames always with 8 bytes according to [16].] ()

[SWS_J1939Tp_00068] [

According to [16], all unused data bytes within the last TP.DT frame or the direct frame shall be set to 0xFF. | (SRS J1939 00024)

7.5.9 Handling of Unexpected N-PDU Arrivals

[SWS_J1939Tp_00064] [

The J1939Tp shall ignore unexpected N-PDUs that do not correspond to a currently active connection. J (SRS_J1939_00023)

[SWS_J1939Tp_00224] [

If J1939TpTxRetrySupport is disabled, when a TP.CM_CTS is received while TP.DT messages are being transmitted, J1939Tp shall abort the connection as specified in **SWS_J1939Tp_00032** and in **SWS_J1939Tp_00097** with connection abort reason 4 (CTS messages received when data transfer is in progress). | ()

[SWS J1939Tp 00225] [

When a TP.CM_RTS is received for a currently active connection, the J1939Tp shall stop this connection as specified in **SWS_J1939Tp_00031** and start a new connection as described in **SWS_J1939Tp_00038**.] ()

7.6 Error Classification

The J1939 Transport Layer module supports reporting of development and runtime errors.

7.6.1 Development Errors

[SWS_J1939Tp_00115] [

J1939Tp shall use the following development errors:

Type or error	Relevance	Related error code	Value [hex]
API service used in state J1939TP_OFF.	Development	J1939TP_E_UNINIT	0x01
J1939Tp_Init() called in state J1939TP_ON.	Development	J1939TP_E_REINIT	0x02
J1939Nm_Init was called with an invalid configuration pointer	Development	J1939NM_E_INIT_FAILED	0x03
API service called with null pointer.	Development	J1939TP_E_PARAM_POINTER	0x10



API service called with wrong ID.	Development	J1939TP_E_INVALID_PDU_SDU_ID	0x11
Timeout occurred on receiver side after reception of an intermediate TP.DT frame of a block.	Development	J1939TP_E_TIMEOUT_T1	0x30
Timeout occurred on receiver side after transmission of a TP.CM/CTS frame.	Development	J1939TP_E_TIMEOUT_T2	0x31
Timeout occurred on transmitter side after transmission of the last TP.DT frame of a block.	Development	J1939TP_E_TIMEOUT_T3	0x32
Timeout occurred on transmitter side after reception of a TP.CM/CTS(0) frame.	Development	J1939TP_E_TIMEOUT_T4	0x33
Timeout occurred on transmitter or receiver side while trying to send the next TP.DT or TP.CM frame.	Development	J1939TP_E_TIMEOUT_TR	0x34
Timeout occurred on receiver side while trying to send the next TP.CM/CTS frame after a TP.CM/CTS(0) frame.	Development	J1939TP_E_TIMEOUT_TH	0x35
Invalid value for "total message size" in received TP.CM/RTS frame.	Development	J1939TP_E_INVALID_TMS	0x40
Value for "total number of packets" in received TP.CM/RTS frame does not match the "total message size".	Development	J1939TP_E_INVALID_TNOP	0x41
Invalid value for "maximum number of packets" in received TP.CM/RTS frame.	Development	J1939TP_E_INVALID_MNOP	0x42
Unexpected PGN in received TP.CM frame.	Development	J1939TP_E_INVALID_PGN	0x43
Invalid value for "number of packets" in received TP.CM/CTS frame.	Development	J1939TP_E_INVALID_NOP	0x44
Invalid value for "next packet number" in received TP.CM/CTS frame.	Development	J1939TP_E_INVALID_NPN	0x45
Invalid value for "connection abort reason" in received TP.Conn_Abort frame.	Development	J1939TP_E_INVALID_CAR	0x46
Unexpected serial number in received TP.DT frame.	Development	J1939TP_E_INVALID_SN	0x47

] (SRS_BSW_00327, SRS_BSW_00337, SRS_BSW_00385, SRS_BSW_00441)

7.6.2 Runtime Errors

Runtime errors have not yet been classified.

7.6.3 Transient Faults

There are no transient faults.

7.6.4 Production Errors

There are no production errors.



7.6.5 Extended Production Errors

There are no extended production errors.

7.7 API Parameter Checking

J1939TP_E_PARAM_POINTER shall be reported as specified in [15] by SWS_BSW_00212.

[SWS_J1939Tp_00188] [

If default error detection for the J1939Tp is enabled, all APIs using a SDU- or PDU-Identifier shall check the input Identifier and raise the development error: J1939TP_E_INVALID_PDU_SDU_ID in case the API has been called for a not configured PDU or SDU. J (SRS_BSW_00323)



8 API Specification

8.1 Imported Types

This section lists all externally defined types that are used by J1939Tp. These types are included from the headers corresponding to the module names listed in the table below.

[SWS_J1939Tp_00230] [

<u>[0440_013331P</u>	ννο_υ 1959 1 β_00250]		
Module	Imported Type		
ComStack_Types	BufReq_ReturnType		
	PduldType		
	PduInfoType		
	PduLengthType		
	RetryInfoType		
	TPParameterType		
Std_Types	Std_ReturnType		
	Std_VersionInfoType		

]()

8.2 Type Definitions

This section lists the types defined by J1939Tp.

[SWS_J1939Tp_00175] [

Name:	J1939Tp_ConfigType		
Туре:	Structure		
Range:	implementation specific The content of the initialization data structure is implementation specific.		
Description:	Data structure containing post-build configuration data of J1939-TP.		

]()

The J1939Tp_ConfigType defines a structure that contains configuration parameters J1939Tp uses at run time. It is provided as an argument to J1939Tp_Init().

8.3 Function Definitions

This section defines a list of functions provided for upper layer modules. All these APIs shall provide the following development errors:

8.3.1 J1939Tp_Init

[SWS_J1939Tp_00087] [

5116_613631P_66661]		
Service name:	J1939Tp_Init	



Syntax:	<pre>void J1939Tp_Init(const J1939Tp_ConfigType* ConfigPtr)</pre>		
Service ID[hex]:	0x01		
Sync/Async:	Synchronous		
Reentrancy:	Non Reentrant		
Parameters (in):	ConfigPtr F	Pointer to configuration data structure.	
Parameters (inout):	None		
Parameters (out):	None		
Return value:	None		
Description:	This function initia	alizes the J1939Tp module.	

(SRS_BSW_00101, SRS_BSW_00358)

After power up, J1939Tp is in a state called J1939TP_OFF. In this state, J1939Tp is not yet configured, and therefore cannot perform any communication task. The J1939Tp module's environment (usually the ECU Manager) will call J1939Tp Init() before using the J1939Tp module for further processing.

[SWS_J1939Tp_00024] [

The function J1939Tp_Init() shall initialize all global variables of the module and reset all transport protocol connections. | (SRS_J1939_00010)

[SWS_J1939Tp_00022] [

J1939Tp_Init() shall change to the internal state J1939TP_ON after successful initialization.] ()

[SWS_J1939Tp_00026] [

If called when the J1939Tp module is in the global state $\tt J1939TP_ON$, the function $\tt J1939Tp_Init()$ shall raise the development error J1939TP_E_REINIT and do nothing.] ()

[SWS_J1939Tp_00187] [

The provided ConfigPtr shall only be used, when post-build configuration is enabled, or when different configuration variants must be supported. Otherwise, the parameters should be accessed directly to avoid indirection via the ConfigPtr. J (SRS BSW 00400, SRS BSW 00405, SRS BSW 00414, SRS BSW 00438)

The structure of type J1939Tp_ConfigType pointed to by the ConfigPtr contains post-build parameters of the J1939Tp module. In link time or pre-compile configured environments, the structure may contain a set of post-build parameters that differ between several configuration variants. It is expected that link time and pre-compile parameters may not change for different configuration variants.

J1939Tp_Init() has no return value because configuration data errors should be detected during configuration time (e.g. by the configuration tools). Furthermore, if a hardware error occurs, it will be reported via the error manager modules.



J1939TP_E_INIT_FAILED shall be reported as specified in [15] by SWS_BSW_00050.

8.3.2 J1939Tp_Shutdown

[SWS_J1939Tp_00093] [

Service name:	J1939Tp_Shutdown		
Syntax:	void J1939Tp_Shutdown(
	void		
)		
Service ID[hex]:	0x02		
Sync/Async:	Synchronous		
Reentrancy:	Non Reentrant		
Parameters (in):	None		
Parameters	None		
(inout):			
Parameters (out):	None		
Return value:	None		
Description:	This function is used to shutdown the J1939Tp module.		

(SRS_BSW_00336)

To close down communication, the state handling (usually the ECU Manager) calls $\tt J1939Tp_Shutdown()$.

[SWS_J1939Tp_00094] [

<code>J1939Tp_Shutdown()</code> shall close all pending transport protocol connections, free all resources and set the <code>J1939Tp</code> module into the global state <code>J1939TP_OFF</code> state. <code>J()</code>

[SWS_J1939Tp_00095] [

J1939Tp_Shutdown() shall not raise a notification about the pending frame transmission or reception. | ()

8.3.3 J1939Tp_GetVersionInfo

[SWS_J1939Tp_00089] [

Service name:	J1939Tp_GetVersionInfo	
Syntax:	void J1939Tp_GetVersionInfo(Std VersionInfoType* VersionInfo	
) — — — — — — — — — — — — — — — — — — —	
Service ID[hex]:	0x03	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant	
Parameters (in):	None	
Parameters	None	



(inout):		
Parameters (out):		Pointer to the location where the version information of J1939Tp shall be stored.
Return value:	None	
Description:	Returns the version information of J1939Tp.	

] (SRS_BSW_00407)

Note that the function J1939Tp_GetVersionInfo may be called in global state $\tt J1939TP$ OFF, i.e. before initialization of the J1939Tp module.

8.3.4 J1939Tp_Transmit

[SWS_J1939Tp_00096] [

<u>[0440_019391P_</u>			
Service name:	J1939Tp_Transmit		
Syntax:	<pre>Std_ReturnType J1939Tp_Transmit(PduIdType TxSduId, const PduInfoType* TxInfoPtr</pre>		
)		
Service ID[hex]:	0x05		
Sync/Async:	Synchronous		
Reentrancy:	Reentrant		
	TxSduld	ID of the J1939Tp N-SDU to be transmitted. The available IDs are configured via J1939TpTxNSduld.	
Parameters (in):	TxInfoPtr Pointer to structure with length and content of the J1939Tp N-SDU that shall be transmitted. The content of this structure is cused to transfer addressing information and priority of N-SDUs with MetaData, and shall be NULL otherwise.		
Parameters (inout):	None		
Parameters (out):	None		
Return value:	Std_ReturnType E_OK: The request has been accepted. E_NOT_OK: The request failed. This happens when a resource could not be allocated, e. g. when the requested transmission would use a channel that is currently active.		
Description:	This service fund	ction is used to request the transfer of a J1939Tp N-SDU.	

(SRS_BSW_00357)

As described in SWS_J1939Tp_00119 and SWS_J1939Tp_00032, the J1939Tp module will notify the upper layer by calling the PduR_J1939TpTxConfirmation callback when the transmit request has been completed.

[SWS_J1939Tp_00101] [

The function J1939Tp_Transmit shall reject a request, if the J1939Tp_Transmit service is called for an N-SDU identifier that is being used in a currently running J1939 Transport Layer session.] ()

[SWS J1939Tp 00030] [

The function $J1939Tp_Transmit()$ shall reject the transmit request and return the status value E_NOT_OK if the transmission needs a transport protocol and the channel is occupied (see also 7.5.7). \int ()



The term channel refers to a communication relation with identical SA and DA.

8.3.5 J1939Tp_CancelTransmit

[SWS_J1939Tp_00177] [

<u>[0110_013331P_</u>	.00111]		
Service name:	J1939Tp_CancelTransmit		
Syntax:	Std_ReturnType J1939Tp_CancelTransmit(PduIdType TxSduId)		
Service ID[hex]:	0x09		
Sync/Async:	Synchronous		
Reentrancy:	Non Reentrant		
Parameters (in):	TxSduld ID of the J1939Tp N-SDU to be canceled. The available IDs are configured via J1939TpTxNSduld.		
Parameters (inout):	None		
Parameters (out):	None		
Return value:	Std_ReturnType E_OK: The request has been accepted. E_NOT_OK: The request failed. This happens when the provided N-SDU is currently not transmitted.		
Description:	This service function is used to cancel the ongoing transmission of a J1939Tp N-SDU.		

]()

[SWS_J1939Tp_00203] [

J1939Tp_CancelTransmit shall return E_NOT_OK if the TxSduld is invalid, if TxSduld is currently not active, if currently a direct frame is transmitted, if the last TP.DT frame has already been transmitted during BAM transmission, or if the TP.CM_EOMAck frame has already been received during CMDT transmission.] ()

[SWS_J1939Tp_00214] [

The J1939Tp_CancelTransmit API shall only be available when J1939TpCancellationSupport is enabled.] ()

8.3.6 J1939Tp_CancelReceive

[SWS J1939Tp 00176] [

Service name:	J1939Tp_CancelReceive		
Syntax:	Std_ReturnType J1939Tp_CancelReceive(PduIdType RxSduId		
Service ID[hex]:	0x0a		
•	Synchronous		
Reentrancy:	Non Reentrant		
Parameters (in):	RxSduld ID of the J1939Tp N-SDU to be canceled. The available IDs are configured via J1939TpRxNSduld.		
Parameters (inout):	None		



Parameters (out):	None	
Return value:	Std_ReturnType E_OK: The request has been accepted. E_NOT_OK: The request failed. This happens when the provided I-PDU does not refer to an N-SDU that is currently received.	
Description:	This service function is used to cancel the ongoing reception of a J1939Tp N-SDU.	

]()

[SWS_J1939Tp_00204] [

J1939Tp_CancelReceive shall return E_NOT_OK if the RxSduld is invalid, if RxSduld is currently not active, if currently a direct frame is received, if the last TP.DT frame has already been received during BAM reception, or if the TP.CM_EOMAck frame has already been sent during CMDT reception.] ()

[SWS_J1939Tp_00215] [

The J1939Tp_CancelReceive API shall only be available when J1939TpCancellationSupport is enabled.] ()

8.3.7 J1939Tp_ChangeParameter

[SWS_J1939Tp_00180] [

Service name:	J1939Tp_ChangeParameter				
Syntax:	<pre>Std_ReturnType J1939Tp_ChangeParameter(PduIdType RxSduId, TPParameterType Parameter, uint16 Value)</pre>				
Service ID[hex]:	0x08				
Sync/Async:	Synchronous				
Reentrancy:	Non Reentrant				
Parameters (in):		ID of the N-SDU for which parameters should be changed. The available IDs are configured via J1939TpRxNSduld.			
		ID of parameter that should be changed. New value for changed parameter.			
Parameters (inout):	None				
Parameters (out):	None				
Return value:		urnType E_OK: The request has been accepted. E_NOT_OK: The request failed. This happens when the provided parameter does not exist.			
Description:	This service function is used to change reception parameters of J1939Tp for a specific N-SDU.				

]()

[SWS_J1939Tp_00206] [

J1939Tp_ChangeParameter shall return E_NOT_OK if the Sduld is invalid, if the Parameter is not TP_BS, or if the Value is larger than 255.] ()



8.4 Callback Notifications

This is a list of functions provided for other modules. The function prototypes of the callback functions shall be provided in the file J1939Tp_Cbk.h.

8.4.1 J1939Tp_RxIndication

[SWS J1939Tp 00108] [

<u>[0110_013331P_</u>	<u></u>					
Service name:	J1939Tp_RxIndication					
Syntax:	<pre>void J1939Tp_RxIndication(PduIdType RxPduId, const PduInfoType* PduInfoPtr)</pre>					
Service ID[hex]:	0x42					
Sync/Async:	Synchronous					
Reentrancy:	Reentrant	Reentrant for different Pdulds. Non reentrant for the same Pduld.				
	RxPduld	RxPduId ID of the received I-PDU.				
Parameters (in):		Contains the length (SduLength) of the received I-PDU and a pointer to a buffer (SduDataPtr) containing the I-PDU.				
Parameters (inout):	None					
Parameters (out):	None					
Return value:	None					
Description:	Indication of a received I-PDU from a lower layer communication interface module.					

(SRS_BSW_00359, SRS_BSW_00360)

The J1939Tp module provides the J1939Tp_RxIndication() API to allow the Canlf to notify that a new N-PDU has been received.

[SWS_J1939Tp_00110] [

The function J1939Tp_RxIndication shall be callable in interrupt context (it could be called from the CAN receive interrupt). \(\) (SRS_BSW_00333)

8.4.2 J1939Tp TxConfirmation

[SWS_J1939Tp_00112] [

<u> </u>	4 '		
Service name:	J1939Tp_TxConfirmation		
Syntax:	void J1939Tp TxConfirmation(
	PduIdType TxPduId		
)		
Service ID[hex]:	0x40		
Sync/Async:	Synchronous		
Reentrancy:	Reentrant for different Pdulds. Non reentrant for the same Pduld.		
Parameters (in):	TxPduld ID of the I-PDU that has been transmitted.		
Parameters	None		
(inout):			
Parameters (out):	None		
Return value:	None		
Description:	The lower layer communication interface module confirms the transmission of an I-PDU.		



(SRS_BSW_00359, SRS_BSW_00360)

The J1939Tp module implements the J1939Tp_TxConfirmation API to allow the Canlf module to confirm that a TP related frame (TP.CM, TP.DT) or direct frame has been successfully transmitted to the J1939 network.

[SWS_J1939Tp_00114] [

The function J1939Tp_TxConfirmation shall be callable in interrupt context (it could be called from the CAN transmit interrupt).] (SRS_BSW_00333)

8.5 Scheduled Functions

The Basic Software Scheduler directly calls the functions listed in this section. Scheduled functions shall have no return value and no parameter, and need not be reentrant.

8.5.1 J1939Tp MainFunction

[SWS J1939Tp 00104] [

<u> </u>	4 '		
Service name:	J1939Tp_MainFunction		
Syntax:	void J1939Tp MainFunction(
	void		
)		
Service ID[hex]:	0x04		
Description:	Main function of the J1939Tp. Used for scheduling purposes and timeout		
	supervision.		

[SWS_J1939Tp_00106] [

The calling frequency of the function J1939Tp_MainFunction is determined by the parameter J1939TpMainFunctionPeriod (see **ECUC_J1939Tp_00044**:).] ()

8.6 Expected Interfaces

In this section, all interfaces required from other modules are listed.

8.6.1 Mandatory Interfaces

This section defines all interfaces, which are required to fulfill the core functionality of the module.

[SWS J1939Tp 00116] [

API function	Description
CanIf_Transmit	This service initiates a request for transmission of the CAN L-PDU
	specified by the CanTxSduld and CAN related data in the L-SDU



	structure.
PduR_J1939TpCopyRxData	This function is called to provide the received data of an I-PDU segment (N-PDU) to the upper layer. Each call to this function provides the next part of the I-PDU data. The size of the remaining data is written to the position indicated by bufferSizePtr.
PduR_J1939TpCopyTxData	This function is called to acquire the transmit data of an I-PDU segment (N-PDU). Each call to this function provides the next part of the I-PDU data unless retry->TpDataState is TP_DATARETRY. In this case the function restarts to copy the data beginning at the offset from the current position indicated by retry->TxTpDataCnt. The size of the remaining data is written to the position indicated by availableDataPtr.
PduR_J1939TpRxIndication	Called after an I-PDU has been received via the TP API, the result indicates whether the transmission was successful or not.
	This function is called at the start of receiving an N-SDU. The N-SDU might be fragmented into multiple N-PDUs (FF with one or more following CFs) or might consist of a single N-PDU (SF).
PduR_J1939TpTxConfirmation	This function is called after the I-PDU has been transmitted on its network, the result indicates whether the transmission was successful or not.

]()

8.6.2 Optional Interfaces

This section defines all interfaces that are required to fulfill an optional functionality of the module.

[SWS_J1939Tp_00060] [

API function	Description
Det_ReportError	Service to report development errors.

]()



9 Sequence Diagrams

The following sequence diagrams shall give an impression of the way the J1939 Transport Layer module shall behave and interoperate with other BSW modules. They are not complete and not binding for the implementation.

9.1 Reception of Direct PG

The following diagram shows the interaction of the J1939 Transport Layer module with the CAN Interface and the PDU Router during reception of a direct PG, i.e. an N-SDU with dynamic length that is not larger than 8 bytes.

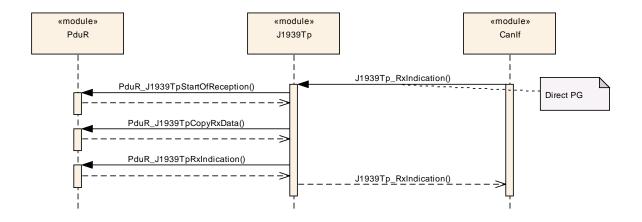


Figure 9-1: Reception of Direct PG

9.2 Reception via BAM

The following diagram shows the interaction of the J1939 Transport Layer module with the CAN Interface and the PDU Router during reception of a PG via BAM, i.e. an N-SDU that is larger than 8 bytes and is sent to the whole network.



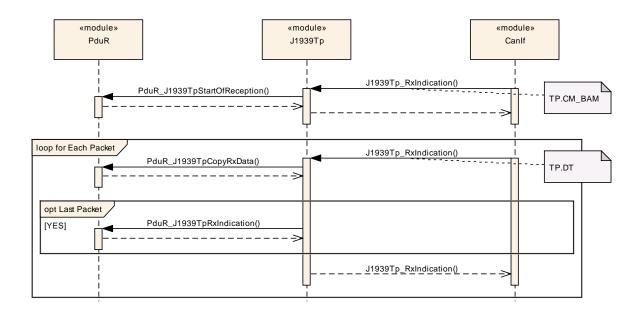


Figure 9-2: Reception via BAM

9.3 Reception via CMDT

The following diagram shows the interaction of the J1939 Transport Layer module with the CAN Interface and the PDU Router during reception of a PG via CMDT, i.e. an N-SDU that is larger than 8 bytes and is sent directly to the receiving node.



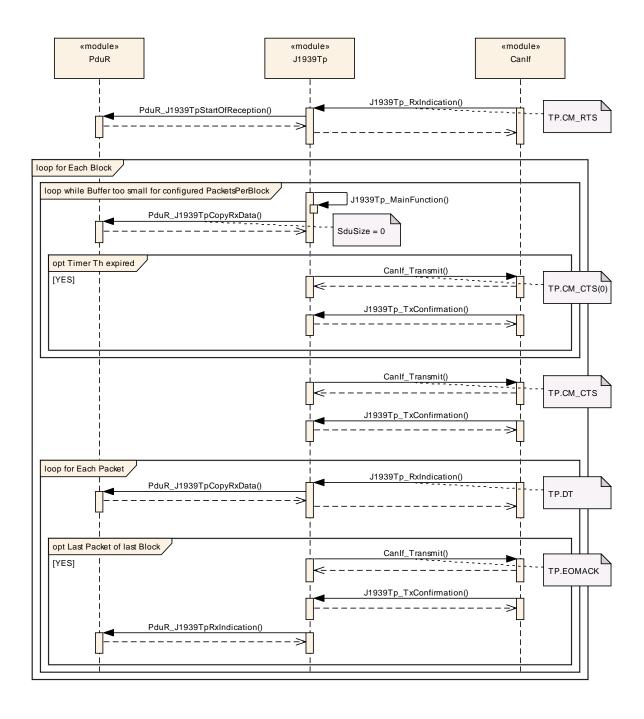


Figure 9-3: Reception via CMDT

9.4 Transmission of Direct PG

The following diagram shows the interaction of the J1939 Transport Layer module with the PDU Router and the CAN Interface during transmission of a direct PG, i.e. an N-SDU with dynamic length that is not larger than 8 bytes.



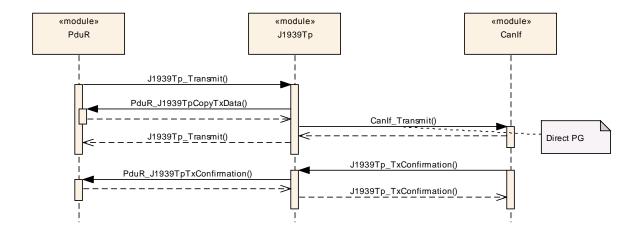


Figure 9-4: Transmission of Direct PG

9.5 Transmission via BAM

The following diagram shows the interaction of the J1939 Transport Layer module with the PDU Router and the CAN Interface during transmission of a PG via BAM, i.e. an N-SDU that is larger than 8 bytes and is sent to the whole network.

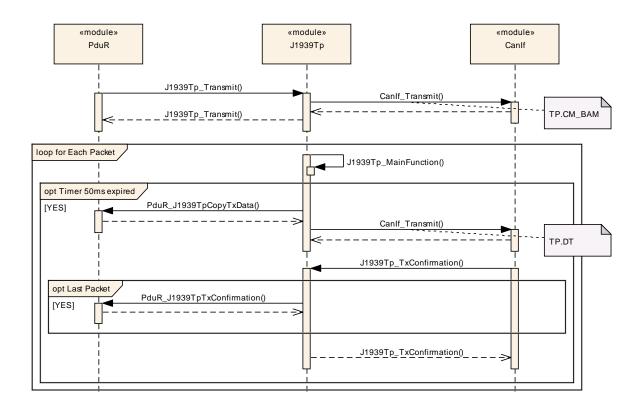


Figure 9-5: Transmission via BAM

9.6 Transmission via CMDT

The following diagram shows the interaction of the J1939 Transport Layer module with the PDU Router and the CAN Interface during transmission of a PG via CMDT, i.e. an N-SDU that is larger than 8 bytes and is sent directly to the receiving node.



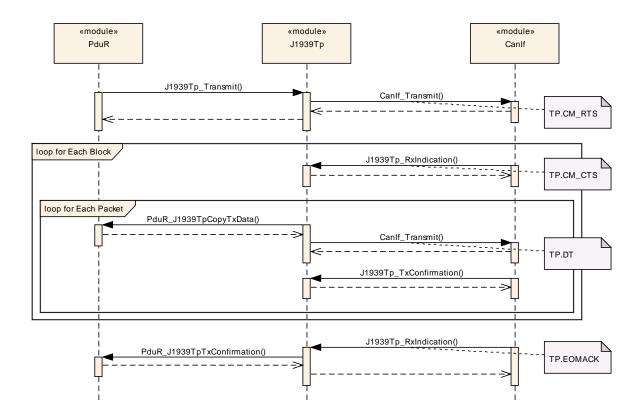


Figure 9-6: Transmission via CMDT

9.7 Handling of Retry during CMDT Transmission

The following diagram shows the interaction of the J1939 Transport Layer module with the PDU Router in the sender and the receiver node during transmission of a PG via CMDT when a retry is performed because some data is lost.



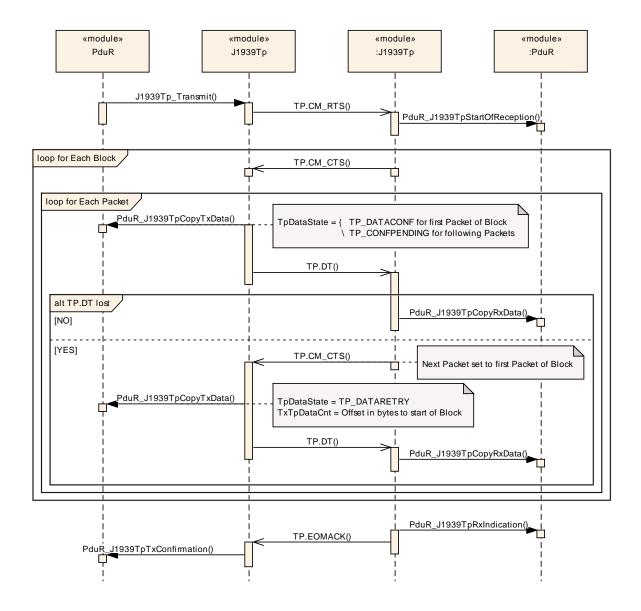


Figure 9-7: Retry Handling



10 Configuration Specification

In general, this chapter defines configuration parameters and their clustering into containers. Section 10.1 describes fundamentals and the template used for the tables in section 10.2. Section 10.2 specifies the configuration structure (containers) and the configuration parameters of J1939Tp. Section 10.3 specifies published information of J1939Tp.

The configuration parameters are derived from a network description database, which is based on the System Template. The configuration tool will extract all relevant information to configure the J1939 Transport Protocol.

[SWS_J1939Tp_00084] [

The consistency of the configuration must be checked by the configuration tool at configuration time. Configuration rules and constraints for plausibility checks will be performed where possible, during configuration time. | (SRS_BSW_00167)

10.1 How to Read this Chapter

For details, refer to the chapter 10.1 "Introduction to configuration specification" in the SWS BSW General [15].

10.2 Containers and Configuration Parameters

The following sections summarize all configuration parameters. Additional information on the usage of these parameters can be found in chapter 7 and 8.

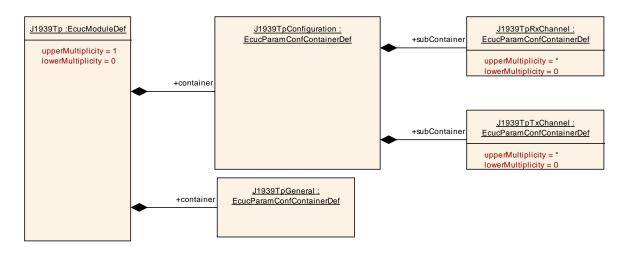


Figure 10-1: Module Configuration



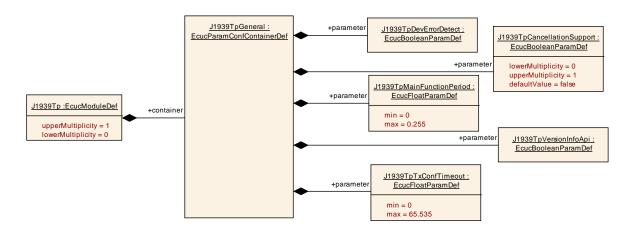


Figure 10-2: General Parameters



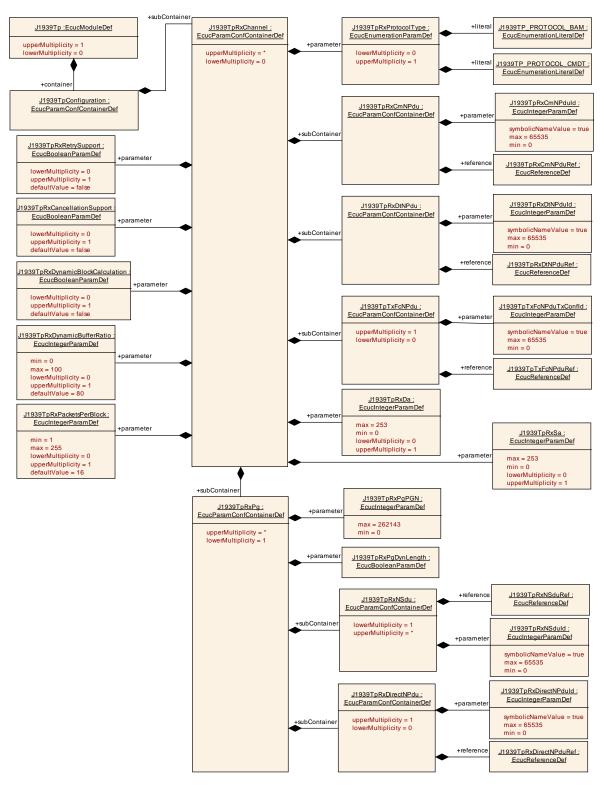


Figure 10-3: Configuration of Rx Channel



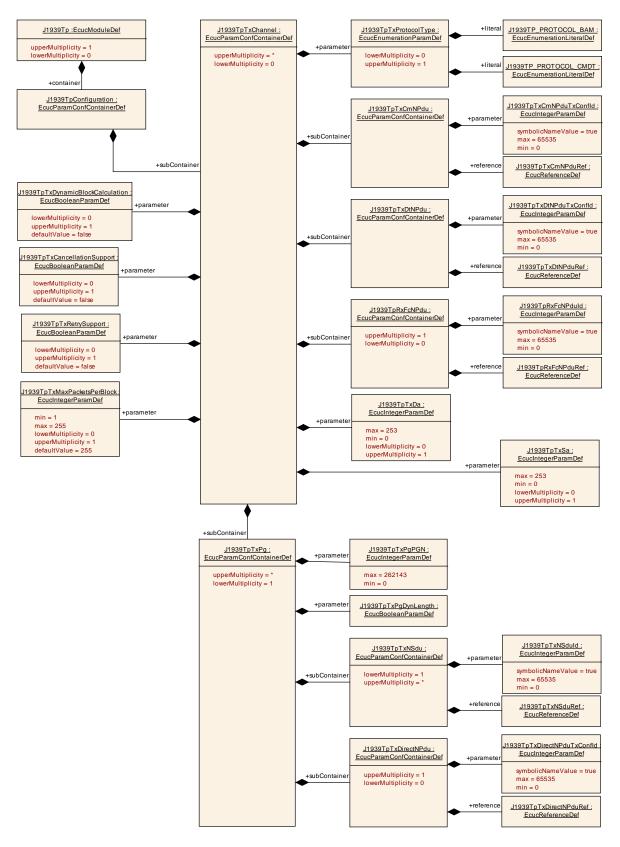


Figure 10-4: Configuration of Tx Channel



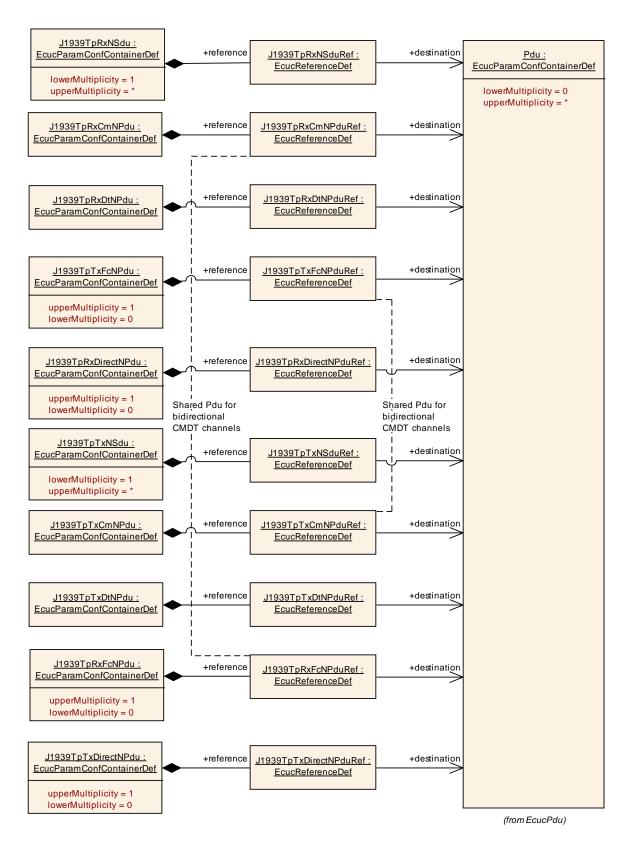


Figure 10-5: References to PDUs



10.2.1 J1939Tp

SWS Item	ECUC_J1939Tp_00127:
Module Name	J1939Tp
Module Description	Configuration of the J1939Tp (J1939 Transport Protocol) module.
Post-Build Variant Support	true

Included Containers			
Container Name	Multiplicity	Scope / Dependency	
J1939TpConfiguration	1	This container contains the configuration parameters and sub containers of the J1939Tp module that define the communication paths.	
J1939TpGeneral		This container describes the general configuration parameters of the J1939Tp module.	

10.2.2 J1939TpGeneral

SWS Item	ECUC_J1939Tp_00033:
Container Name	J1939TpGeneral
Description	This container describes the general configuration parameters of the J1939Tp module.
Configuration Parameters	

SWS Item	ECUC_J1939Tp_00174:			
Name	J1939TpCancellationSupport			
Description	Enable transmit and receive cancellation.			
	The APIs J1939Tp_CancelTransmit() and J1939Tp_CancelReceive() will only be available when this parameter is enabled.			
Multiplicity	01			
Туре	EcucBooleanParamDef			
Default value	false			
Post-Build Variant Multiplicity	false			
Post-Build Variant Value	false			
Multiplicity Configuration	Pre-compile time X All Variants			
Class	Link time			
	Post-build time			
Value Configuration Class	Pre-compile time	Χ	All Variants	
	Link time			
	Post-build time			
Scope / Dependency	scope: local			

SWS Item	ECUC_J1939Tp_00042:			
Name	J1939TpDevErrorDetect			
•	Switches the Default Error Tracer (Det) detection and notification ON or OFF. true: enabled (ON). false: disabled (OFF).			
Multiplicity	1			
Туре	EcucBooleanParamDef			
Default value				



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Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time X All Variants		
	Link time		
	Post-build time		
Scope / Dependency	scope: local		

SWS Item	ECUC_J1939Tp_00044:				
Name	J1939TpMainFunctionPeriod	t			
Description	Allow to configure the time for the MainFunction (in seconds). Please note: This configuration value shall be equal to the value in the ScheduleManager module.				
Multiplicity	1	1			
Туре	EcucFloatParamDef				
Range	0 0.255	0 0.255			
Default value					
Post-Build Variant Value	false	false			
Value Configuration Class	Pre-compile time X All Variants				
	Link time				
	Post-build time				
Scope / Dependency	scope: ECU				

SWS Item	ECUC_J1939Tp_00006:				
Name	J1939TpTxConfTimeout	J1939TpTxConfTimeout			
Description	Timeout in seconds for the Canlf Tx confirmation. After this time the J1939Tp assumes that an N-PDU could not be transmitted. Please note: The Tx confirmation timeout should be set to a value that enabled detection of a lost Tx confirmation in time, and that ensures that normal transmission delay caused by lower message priority does not lead to an error.				
Multiplicity	1				
Туре	EcucFloatParamDef				
Range	0 65.535				
Default value					
Post-Build Variant Value	false				
Value Configuration Class	Pre-compile time X All Variants				
	Link time				
	Post-build time				
Scope / Dependency	scope: local	•			

SWS Item	ECUC_J1939Tp_00051:				
Name	J1939TpVersionInfoApi				
Description	The function J1939Tp_GetVersionInfo is configurable (On/Off) by this configuration parameter.				
Multiplicity	1	1			
Туре	EcucBooleanParamDef	EcucBooleanParamDef			
Default value					
Post-Build Variant Value	false	false			
Value Configuration Class	Pre-compile time X All Variants				
	Link time				
	Post-build time	ŀ			
Scope / Dependency	scope: local				

No Included Containers



10.2.3 J1939TpConfiguration

SWS Item	ECUC_J1939Tp_00052:
Container Name	J1939TpConfiguration
	This container contains the configuration parameters and sub containers of the J1939Tp module that define the communication paths.
Configuration Parameters	

Included Containers		
Container Name	Multiplicity	Scope / Dependency
J1939TpRxChannel	0*	This container describes a reception channel of the J1939Tp module. A channel referencing N-PDUs without MetaData is used for all N-SDUs that share the same source address (SA) and the same destination address (BAM: DA = 0xFF, CMDT: DA!= 0xFF). A channel with N-PDUs with MetaData is used for all possible source and destination addresses.
J1939TpTxChannel	0*	This container describes a transmission channel of the J1939Tp module. A channel referencing N-PDUs without MetaData is used for all N-SDUs that share the same source address (SA) and the same destination address (BAM: DA = 0xFF, CMDT: DA != 0xFF). A channel with N-PDUs with MetaData is used for all possible source and destination addresses.

10.2.4 J1939TpRxChannel

SWS Item	ECUC_J1939Tp_00053:
Container Name	J1939TpRxChannel
Description	This container describes a reception channel of the J1939Tp module. A channel referencing N-PDUs without MetaData is used for all N-SDUs that share the same source address (SA) and the same destination address (BAM: DA = 0xFF, CMDT: DA != 0xFF). A channel with N-PDUs with MetaData is used for all possible source and destination addresses.
Configuration Paramet	ers

SWS Item	ECUC_J1939Tp_00186:			
Name	J1939TpRxCancellationSupport			
Description	Enable receive cancellation using the API J1939Tp_CancelReceive() for this channel.			
Multiplicity	01			
Туре	EcucBooleanParamDef			
Default value	false			
Post-Build Variant Multiplicity	false			
Post-Build Variant Value	false			
Multiplicity Configuration	Pre-compile time	Χ	All Variants	
Class	Link time			
	Post-build time			
Value Configuration Class	Pre-compile time X All Variants			
	Link time			
	Post-build time			
Scope / Dependency	scope: local			

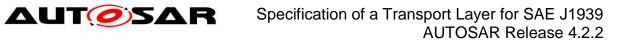
SWS Item	ECUC_J1939Tp_00178:



Name	J1939TpRxDa				
Description	Destination address (DA) of this channel. This parameter is only required for channels with fixed DA which use N-PDUs with MetaData containing the DA.				
Multiplicity	01				
Туре	EcucIntegerParamDef				
Range	0 253				
Default value					
Post-Build Variant Multiplicity	true				
Post-Build Variant Value	true				
Multiplicity Configuration	Pre-compile time X VARIANT-PRE-COMPILE				
Class	Link time				
	Post-build time	Х	VARIANT-LINK-TIME, VARIANT-POST- BUILD		
Value Configuration Class	Pre-compile time	Χ	VARIANT-PRE-COMPILE		
	Link time				
	Post-build time	Х	VARIANT-LINK-TIME, VARIANT-POST- BUILD		
Scope / Dependency	scope: local		-		

SWS Item	ECUC_J1939Tp_00187:			
Name	J1939TpRxDynamicBlockCalculation			
Description			mber of packets that can be sent" value	
	in TP.CM_CTS, based on the size of buffers in upper layers reported via			
	StartOfReception and PduR	_J193	9TpCopyRxData.	
Multiplicity	01			
Туре	EcucBooleanParamDef			
Default value	false			
Post-Build Variant Multiplicity	false			
Post-Build Variant Value	false			
Multiplicity Configuration	Pre-compile time	Х	All Variants	
Class	Link time			
	Post-build time			
Value Configuration Class	SS Pre-compile time X All Variants Link time			
	Post-build time			
Scope / Dependency	scope: local			

SWS Item	ECUC_J1939Tp_00188:			
Name	J1939TpRxDynamicBufferRatio			
Description	Percentage of available buff	er that	shall be used for retry.	
-	This parameter is only applic	cable v	when "J1939TpRxRetrySupport" and	
	"J1939TpRxDynamicBlockC	alcula	tion" are enabled.	
Multiplicity	01			
Туре	EcucIntegerParamDef	EcucIntegerParamDef		
Range	0 100			
Default value	80			
Post-Build Variant Multiplicity	false			
	false			
Multiplicity Configuration	Pre-compile time	Χ	All Variants	
Class	Link time			
	Post-build time			
Value Configuration Class	Pre-compile time	Χ	All Variants	





	ink time		
	Post-build time	I	
Scope / Dependency	scope: local		
	dependency: Only applicable when "J1939TpRxRetrySupport" and		
	"J1939TpRxDynamicBlockCalculation" are enabled		

SWS Item	ECUC_J1939Tp_00189:			
Name	J1939TpRxPacketsPerBlock			
Description	Number of TP.DT frames the receiving J1939Tp module allows the sender to send before waiting for another TP.CM_CTS. This parameter is transmitted in the TP.CM_CTS frame, and is thus only relevant for reception of messages via CMDT. When J1939TpRxDynamicBlockCalculation is enabled, this parameter specifies a maximum for the calculated value. For further details on this parameter value see SAE J1939/21.			
Multiplicity	01			
Туре	EcucIntegerParamDef			
Range	1 255			
Default value	16			
Post-Build Variant Multiplicity	false			
Post-Build Variant Value	false			
Multiplicity Configuration	Pre-compile time	Χ	All Variants	
Class	Link time	1		
	Post-build time	ŀ		
Value Configuration Class	Pre-compile time	Χ	All Variants	
	Link time			
	Post-build time			
Scope / Dependency	scope: local			

SWS Item	ECUC_J1939Tp_00029:			
Name	J1939TpRxProtocolType			
Description	Protocol type used by this channel. This parameter is only required for channels with fixed destination address.			
Multiplicity	01			
Туре	EcucEnumerationParamDef			
Range	J1939TP_PROTOCOL_BAM	(Br Thi	939 transport protocol type BAM oadcast Announce Message). Is protocol uses two N-PDUs: e CmNPdu and the DtNPdu.	
	J1939TP_PROTOCOL_CMDT	CM Tra N-F	P39 transport protocol type IDT (Connection Mode Data ansfer). This protocol uses three PDUs: The CmNPdu, the NPdu, and the FcNPdu.	
Post-Build Variant Multiplicity	false	•		
Post-Build Variant Value	false			
Multiplicity	Pre-compile time	X	All Variants	
Configuration	Link time			
Class	Post-build time			
Value	Pre-compile time	X	All Variants	
Configuration	Link time			
Class	Post-build time			
Scope / Dependency	scope: local			



SWS Item	ECUC_J1939Tp_00185:			
Name	J1939TpRxRetrySupport			
Description	Enable support for triggering repetition of failed transmission using TP.CM_CTS with a packet number that has already been sent. Retransmission is triggered when a sequence number is missing or a timeout occurs during reception.			
Multiplicity	01			
Туре	EcucBooleanParamDef	EcucBooleanParamDef		
Default value	false			
Post-Build Variant Multiplicity	false			
Post-Build Variant Value	false			
Multiplicity Configuration	Pre-compile time	Χ	All Variants	
Class	Link time			
	Post-build time	-		
Value Configuration Class	Pre-compile time	Χ	All Variants	
	Link time			
	Post-build time			
Scope / Dependency	scope: local	•		

SWS Item	ECUC_J1939Tp_00179:			
Name	J1939TpRxSa			
Description	Source address (SA) of this channel. This parameter is only required for channels with fixed SA which use N-PDUs with MetaData.			
Multiplicity	01			
Туре	EcucIntegerParamDef			
Range	0 253			
Default value				
Post-Build Variant Multiplicity	true			
Post-Build Variant Value	true			
Multiplicity Configuration	Pre-compile time	Χ	VARIANT-PRE-COMPILE	
Class	Link time	-		
	Post-build time	X	VARIANT-LINK-TIME, VARIANT-POST- BUILD	
Value Configuration Class	Pre-compile time	Χ	VARIANT-PRE-COMPILE	
	Link time			
	Post-build time	Х	VARIANT-LINK-TIME, VARIANT-POST- BUILD	
Scope / Dependency	scope: local			

Included Containers		
Container Name	Multiplicity	Scope / Dependency
J1939TpRxCmNPdu	1	This N-PDU represents the TP.CM frame of a J1939 transport protocol session. TP.CM is used both by BAM and CMDT to initialize the connection. For CMDT, it is also used to abort the connection.
J1939TpRxDtNPdu	1	This N-PDU represents the TP.DT frame of a J1939 transport protocol session. TP.DT is used both by BAM and CMDT to transfer the contents of an N-SDU.
J1939TpRxPg	1*	Parameter group received by the J1939 transport layer.
J1939TpTxFcNPdu	01	This N-PDU represents the TP.CM frame that is used in reverse direction for a J1939 transport protocol session using the CMDT protocol type. TP.CM in reverse direction is used for intermediate and final acknowledgement of received data and to abort the connection.



Please note: This sub container is only required when
J1939TpRxProtocolType is J1939TP_PROTOCOL_CMDT or
when it is not configured at all.

10.2.5 J1939TpRxCmNPdu

SWS Item	ECUC_J1939Tp_00128:
Container Name	J1939TpRxCmNPdu
Description	This N-PDU represents the TP.CM frame of a J1939 transport protocol session. TP.CM is used both by BAM and CMDT to initialize the connection. For CMDT, it is also used to abort the connection.
Configuration Parameters	

SWS Item	ECUC_J1939Tp_00129:			
Name	J1939TpRxCmNPduld			
Description	The N-PDU identifier used for	or com	munication with Canlf.	
Multiplicity	1			
Type	EcucIntegerParamDef (Sym	EcucIntegerParamDef (Symbolic Name generated for this parameter)		
Range	0 65535			
Default value				
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Χ	All Variants	
	Link time			
	Post-build time			
Scope / Dependency	scope: ECU	•		

SWS Item	ECUC_J1939Tp_00158:				
Name	J1939TpRxCmNPduRef	J1939TpRxCmNPduRef			
Description	Reference to the Pdu object	repre	senting the N-PDU.		
Multiplicity	1				
Туре	Reference to [Pdu]	Reference to [Pdu]			
Post-Build Variant Value	true				
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE				
	Link time				
	Post-build time	Χ	VARIANT-LINK-TIME, VARIANT-POST-		
			BUILD		
Scope / Dependency	scope: local				

No Included Containers

10.2.6 J1939TpRxDtNPdu

SWS Item	ECUC_J1939Tp_00117:
Container Name	J1939TpRxDtNPdu
Description	This N-PDU represents the TP.DT frame of a J1939 transport protocol session. TP.DT is used both by BAM and CMDT to transfer the contents of an N-SDU.
Configuration Parameters	

SWS Item	ECUC_J1939Tp_00133:



Name	J1939TpRxDtNPduld			
Description	The N-PDU identifier used for communication with Canlf.			
Multiplicity	1			
Туре	EcucIntegerParamDef (Sym	bolic N	Name generated for this parameter)	
Range	0 65535	0 65535		
Default value				
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Χ	All Variants	
	Link time			
	Post-build time			
Scope / Dependency	scope: ECU			

SWS Item	ECUC_J1939Tp_00134:			
Name	J1939TpRxDtNPduRef	J1939TpRxDtNPduRef		
Description	Reference to the Pdu object	repre	senting the N-PDU.	
Multiplicity	1			
Туре	Reference to [Pdu]	Reference to [Pdu]		
Post-Build Variant Value	true	true		
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time			
	Post-build time	Χ	VARIANT-LINK-TIME, VARIANT-POST-	
			BUILD	
Scope / Dependency	scope: local			

No Included Containers

10.2.7 J1939TpRxPg

SWS Item	ECUC_J1939Tp_00050:
Container Name	J1939TpRxPg
Description	Parameter group received by the J1939 transport layer.
Configuration Parameters	

SWS Item	ECUC_J1939Tp_00066:			
Name	J1939TpRxPgDynLength			
Description	This flag is set to TRUE when the N-SDU refers to a PGN with variable length. Please note: When this attribute is TRUE, the sub container J1939TpRxDirectNPdu is required.			
Multiplicity	1	1		
Туре	EcucBooleanParamDef			
Default value				
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Χ	All Variants	
	Link time			
	Post-build time	-		
Scope / Dependency				

SWS Item	ECUC_J1939Tp_00065:
Name	J1939TpRxPgPGN
Description	PGN of the referenced N-SDUs.
Multiplicity	1
Туре	EcucIntegerParamDef



Range	0 262143		
Default value			
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	Χ	All Variants
	Link time		
	Post-build time		
Scope / Dependency	scope: local		

Included Containers		
Container Name	Multiplicity	Scope / Dependency
J1939TpRxDirectNPdu	01	This N-PDU represents the short frame that is used for a dynamic length PGN when it has a length of less that 8 bytes. Please note: This sub container is only necessary when J1939TpRxPgDynLength is TRUE.
J1939TpRxNSdu		This container describes the parameters that are relevant for the reception of a specific N-SDU.

10.2.8 J1939TpRxDirectNPdu

SWS Item	ECUC_J1939Tp_00130:
Container Name	J1939TpRxDirectNPdu
Description	This N-PDU represents the short frame that is used for a dynamic length PGN when it has a length of less that 8 bytes. Please note: This sub container is only necessary when J1939TpRxPgDynLength is TRUE.
Configuration Parameters	

SWS Item	ECUC_J1939Tp_00131:			
Name	J1939TpRxDirectNPduId	J1939TpRxDirectNPduId		
Description	The N-PDU identifier used for	or com	munication with Canlf.	
Multiplicity	1			
Type	EcucIntegerParamDef (Sym	bolic N	Name generated for this parameter)	
Range	0 65535			
Default value				
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Χ	All Variants	
	Link time	ŀ		
	Post-build time			
Scope / Dependency	scope: ECU			

SWS Item	ECUC_J1939Tp_00132:			
Name	J1939TpRxDirectNPduRef	J1939TpRxDirectNPduRef		
Description	Reference to the Pdu object	repre	senting the N-PDU.	
Multiplicity	1			
Туре	Reference to [Pdu]	Reference to [Pdu]		
Post-Build Variant Value	true	true		
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time			
	Post-build time	Χ	VARIANT-LINK-TIME, VARIANT-POST-	
			BUILD	
Scope / Dependency	scope: local			

No Included Containers



10.2.9 J1939TpRxNSdu

SWS Item	ECUC_J1939Tp_00063:
Container Name	J1939TpRxNSdu
II IASCRINTIAN	This container describes the parameters that are relevant for the reception of a specific N-SDU.
Configuration Parameters	

SWS Item	ECUC_J1939Tp_00184:			
Name	J1939TpRxNSduld			
Description	This is a unique identifier for a received N-SDU. This Id is used in the CancelReceive and ChangeParameter API call.			
Multiplicity	1			
Туре	EcucIntegerParamDef (Symbolic Name generated for this parameter)			
Range	0 65535			
Default value				
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Χ	All Variants	
	Link time			
	Post-build time			
Scope / Dependency	scope: ECU			

SWS Item	ECUC_J1939Tp_00069:			
Name	J1939TpRxNSduRef			
Description	Reference to the Pdu object	repre	senting the N-SDU.	
Multiplicity	1			
Туре	Reference to [Pdu]			
Post-Build Variant Value	true			
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time			
	Post-build time X VARIANT-LINK-TIME, VARIANT-POST-			
	BUILD			
Scope / Dependency	scope: local			

No Included Containers

J1939TpTxFcNPdu 10.2.10

SWS Item	ECUC_J1939Tp_00135:
Container Name	J1939TpTxFcNPdu
Description	This N-PDU represents the TP.CM frame that is used in reverse direction for a J1939 transport protocol session using the CMDT protocol type. TP.CM in reverse direction is used for intermediate and final acknowledgement of received data and to abort the connection. Please note: This sub container is only required when J1939TpRxProtocolType is J1939TP_PROTOCOL_CMDT or when it is not configured at all.
Configuration Parameters	



SWS Item	ECUC_J1939Tp_00168:				
Name	J1939TpTxFcNPduTxConfld				
Description	The N-PDU identifier used for	The N-PDU identifier used for Tx confirmation from CanIf.			
Multiplicity	1				
Туре	EcucIntegerParamDef (Symbolic Name generated for this parameter)				
Range	0 65535				
Default value					
Post-Build Variant Value	false				
Value Configuration Class	Pre-compile time X All Variants				
	Link time				
	Post-build time				
Scope / Dependency	scope: ECU				

SWS Item	ECUC_J1939Tp_00136:			
Name	J1939TpTxFcNPduRef			
Description	Reference to the Pdu object representing the N-PDU. Please note: When two channels have identical but exchanged source and destination addresses, the Pdu referenced by this parameter is shared with J1939TpTxCmNPduRef of the corresponding J1939TpTxChannel.			
Multiplicity	1			
Туре	Reference to [Pdu]			
Post-Build Variant Value	true			
Value Configuration Class	Pre-compile time	Χ	VARIANT-PRE-COMPILE	
	Link time			
	Post-build time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
Scope / Dependency	scope: local	•		

No Included Containers

10.2.11 J1939TpTxChannel

SWS Item	ECUC_J1939Tp_00059:
Container Name	J1939TpTxChannel
Description	This container describes a transmission channel of the J1939Tp module. A channel referencing N-PDUs without MetaData is used for all N-SDUs that share the same source address (SA) and the same destination address (BAM: DA = 0xFF, CMDT: DA != 0xFF). A channel with N-PDUs with MetaData is used for all possible source and destination addresses.
Configuration Parame	eters

SWS Item	ECUC_J1939Tp_00192:		
Name	J1939TpTxCancellationSupport		
Description	Enable transmit cancellation using the API J1939Tp_CancelTransmit() for this channel.		
Multiplicity	01		
Туре	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Multiplicity	false		
Post-Build Variant Value	false		
Multiplicity Configuration	Pre-compile time X All Variants		
Class	Link time		



	Post-build time	-	
Value Configuration Class	Pre-compile time	Χ	All Variants
	Link time		
	Post-build time	1	
Scope / Dependency	scope: local		

SWS Item	ECUC_J1939Tp_00180:			
Name	J1939TpTxDa			
Description	Destination address (DA) of this channel. This parameter is only required for channels with fixed DA which use N-PDUs with MetaData containing the DA.			
Multiplicity	01			
Туре	EcucIntegerParamDef			
Range	0 253			
Default value				
Post-Build Variant Multiplicity	true			
Post-Build Variant Value	true			
Multiplicity Configuration	Pre-compile time	Х	VARIANT-PRE-COMPILE	
Class	Link time			
	Post-build time	Х	VARIANT-LINK-TIME, VARIANT-POST- BUILD	
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE	
	Link time			
	Post-build time	Х	VARIANT-LINK-TIME, VARIANT-POST- BUILD	
Scope / Dependency	scope: local			

SWS Item	ECUC_J1939Tp_00191:			
Name	J1939TpTxDynamicBlockCalculation			
Description	Enable dynamic calculation of "maximum number of packets that can be sent" value in TP.CM_RTS, based on the available amount of data in upper layers reported via PduR_J1939TpCopyTxData.			
Multiplicity	01			
Туре	EcucBooleanParamDef			
Default value	false			
Post-Build Variant Multiplicity	false			
Post-Build Variant Value	false			
Multiplicity Configuration	Pre-compile time	X	All Variants	
Class	Link time			
	Post-build time			
Value Configuration Class	Pre-compile time X All Variants			
	Link time			
	Post-build time			
Scope / Dependency	scope: local			

SWS Item	ECUC_J1939Tp_00190:
Name	J1939TpTxMaxPacketsPerBlock
Description	Maximum number of TP.DT frames the transmitting J1939Tp module is ready to send before waiting for another TP.CM_CTS. This parameter is transmitted in the TP.CM_RTS frame, and is thus only relevant for transmission of messages via CMDT. When J1939TpTxDynamicBlockCalculation is enabled, this parameter specifies a maximum for the calculated value. For further details on this parameter value see SAE J1939/21.



Multiplicity	01		
Туре	EcucIntegerParamDef		
Range	1 255		
Default value	255		
Post-Build Variant Multiplicity	false		
Post-Build Variant Value	false		
Multiplicity Configuration	Pre-compile time	Χ	All Variants
Class	Link time		
	Post-build time		
Value Configuration Class	Pre-compile time	Χ	All Variants
	Link time		
	Post-build time		
Scope / Dependency	scope: local		

SWS Item	ECUC_J1939Tp_00137:				
Name	J1939TpTxProtocolType				
Description	Protocol type used by this channel. This parameter is only required for channels with fixed destination address.				
Multiplicity	01				
Туре	EcucEnumerationParamDef				
Range	J1939TP_PROTOCOL_BAM	(Bro Thi	039 transport protocol type BAM oadcast Announce Message). s protocol uses two N-PDUs: e CmNPdu and the DtNPdu.		
	J1939TP_PROTOCOL_CMDT	CM Tra N-F	D39 transport protocol type IDT (Connection Mode Data Insfer). This protocol uses three PDUs: The CmNPdu, the IPdu, and the FcNPdu.		
Post-Build Variant Multiplicity	false				
Post-Build Variant Value	false				
Multiplicity	Pre-compile time	Χ	All Variants		
Configuration	Link time				
Class	Post-build time				
Value	Pre-compile time	Х	All Variants		
Configuration	Link time				
Class	Post-build time				
Scope / Dependency	scope: local				

SWS Item	ECUC_J1939Tp_00193:			
Name	J1939TpTxRetrySupport			
Description	Enable support for repetition of failed transmission using TP.CM_CTS with a packet number that has already been sent. Retransmission is handled via the retry feature of PduR_J1939TpCopyTxData.			
Multiplicity	01			
Туре	EcucBooleanParamDef			
Default value	false			
Post-Build Variant Multiplicity	false			
Post-Build Variant Value	false			
Multiplicity Configuration	Pre-compile time X All Variants			
Class	Link time			
	Post-build time			



Value Configuration Class	Pre-compile time	Χ	All Variants
	Link time	I	
	Post-build time		
Scope / Dependency	scope: local		

SWS Item	ECUC_J1939Tp_00181:			
Name	J1939TpTxSa			
Description	Source address (SA) of this channel. This parameter is only required for channels with fixed SA which use N-PDUs with MetaData.			
Multiplicity	01			
Туре	EcucIntegerParamDef			
Range	0 253			
Default value				
Post-Build Variant Multiplicity	true			
Post-Build Variant Value	true			
Multiplicity Configuration	Pre-compile time X VARIANT-PRE-COMPILE			
Class	Link time			
	Post-build time	Х	VARIANT-LINK-TIME, VARIANT-POST- BUILD	
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE	
	Link time			
	Post-build time	Х	VARIANT-LINK-TIME, VARIANT-POST- BUILD	
Scope / Dependency	scope: local	•		

Included Containers					
Container Name	Multiplicity	Scope / Dependency			
J1939TpRxFcNPdu	01	This N-PDU represents the TP.CM frame that is used in reverse direction for a J1939 transport protocol session using the CMDT protocol type. TP.CM in reverse direction is used for intermediate and final acknowledgement of received data and to abort the connection. Please note: This sub container is only required when J1939TpRxProtocolType is J1939TP_PROTOCOL_CMDT or when it is not configured at all.			
J1939TpTxCmNPdu	1	This N-PDU represents the TP.CM frame of a J1939 transport protocol session. TP.CM is used both by BAM and CMDT to initialize the connection. For CMDT, it is also used to abort the connection.			
J1939TpTxDtNPdu		This N-PDU represents the TP.DT frame of a J1939 transport protocol session. TP.DT is used both by BAM and CMDT to transfer the contents of an N-SDU.			
J1939TpTxPg	1*	Parameter group transmitted by the J1939 transport layer.			

10.2.12 J1939TpRxFcNPdu

SWS Item	ECUC_J1939Tp_00144:
Container Name	J1939TpRxFcNPdu
Description	This N-PDU represents the TP.CM frame that is used in reverse direction for a J1939 transport protocol session using the CMDT protocol type. TP.CM in reverse direction is used for intermediate and final acknowledgement of received data and to abort the connection. Please note: This sub container is only required when J1939TpRxProtocolType is



	J1939TP_PROTOCOL_CMDT or when it is not configured at all.
Configuration Parameters	

SWS Item	ECUC_J1939Tp_00145:			
Name	J1939TpRxFcNPduld			
Description	The N-PDU identifier used for	or com	munication with CanIf.	
Multiplicity	1			
Type	EcucIntegerParamDef (Symbolic Name generated for this parameter)			
Range	0 65535			
Default value				
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Χ	All Variants	
	Link time			
	Post-build time			
Scope / Dependency	scope: ECU			

SWS Item	ECUC_J1939Tp_00146:			
Name	J1939TpRxFcNPduRef			
Description	Reference to the Pdu object representing the N-PDU. Please note: When two channels have identical but exchanged source and destination addresses, the Pdu referenced by this parameter is shared with J1939TpRxCmNPduRef of the corresponding J1939TpRxChannel.			
Multiplicity	1			
Туре	Reference to [Pdu]			
Post-Build Variant Value	true			
Value Configuration Class	Pre-compile time	Χ	VARIANT-PRE-COMPILE	
	Link time			
	Post-build timeXVARIANT-LINK-TIME, VARIANT-POST-BUILD			
Scope / Dependency	scope: local			

No Included Containers

J1939TpTxCmNPdu 10.2.13

SWS Item	ECUC_J1939Tp_00138:
Container Name	J1939TpTxCmNPdu
Description	This N-PDU represents the TP.CM frame of a J1939 transport protocol session. TP.CM is used both by BAM and CMDT to initialize the connection. For CMDT, it is also used to abort the connection.
Configuration Parameter	s

SWS Item	ECUC_J1939Tp_00170:			
Name	J1939TpTxCmNPduTxConfld			
Description	The N-PDU identifier used for Tx confirmation from CanIf.			
Multiplicity	1			
Туре	EcucIntegerParamDef (Symbolic Name generated for this parameter)			
Range	0 65535			
Default value				
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Χ	All Variants	
	Link time			
	Post-build time			



Scope / Dependency	scope: ECU			
SWS Item	ECUC_J1939Tp_00139:			
Name	J1939TpTxCmNPduRef			
Description	Reference to the Pdu object	ct repre	esenting the N-PDU.	
Multiplicity	1			
Type	Reference to [Pdu]	Reference to [Pdu]		
Post-Build Variant Value	true			
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time			
	Post-build time	X	VARIANT-LINK-TIME, VARIANT-POST- BUILD	
Scope / Dependency	scope: local			

No Included Containers

10.2.14 J1939TpTxDtNPdu

SWS Item	ECUC_J1939Tp_00142:
Container Name	J1939TpTxDtNPdu
Description	This N-PDU represents the TP.DT frame of a J1939 transport protocol session. TP.DT is used both by BAM and CMDT to transfer the contents of an N-SDU.
Configuration Parameters	

SWS Item	ECUC_J1939Tp_00171:			
Name	J1939TpTxDtNPduTxConfld			
Description	The N-PDU identifier used for	r Tx c	confirmation from Canlf.	
Multiplicity	1			
Туре	EcucIntegerParamDef (Symbolic Name generated for this parameter)			
Range	0 65535			
Default value				
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X All Variants			
	Link time			
	Post-build time			
Scope / Dependency	scope: ECU			

SWS Item	ECUC_J1939Tp_00143:			
Name	J1939TpTxDtNPduRef			
Description	Reference to the Pdu object	repre	senting the N-PDU.	
Multiplicity	1			
Туре	Reference to [Pdu]	Reference to [Pdu]		
Post-Build Variant Value	true	true		
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time			
	Post-build time X VARIANT-LINK-TIME, VARIANT-POST-			
	BUILD			
Scope / Dependency	scope: local			

No Included Containers



10.2.15 J1939TpTxPg

SWS Item	ECUC_J1939Tp_00070:
Container Name	J1939TpTxPg
Description	Parameter group transmitted by the J1939 transport layer.
Configuration Parameters	

SWS Item	ECUC_J1939Tp_00148:			
Name	J1939TpTxPgDynLength			
Description	This flag is set to TRUE when the N-SDU refers to a PGN with variable length. Please note: When this attribute is TRUE, the sub container J1939TpTxDirectNPdu is required.			
Multiplicity	1	1		
Туре	EcucBooleanParamDef			
Default value				
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X All Variants			
	Link time			
	Post-build time			
Scope / Dependency	scope: local			

SWS Item	ECUC_J1939Tp_00150:			
Name	J1939TpTxPgPGN			
Description	PGN of the referenced N-SD	Us.		
Multiplicity	1			
Туре	EcucIntegerParamDef			
Range	0 262143	0 262143		
Default value				
Post-Build Variant Value	false	false		
Value Configuration Class	Pre-compile time	Pre-compile time X All Variants		
	Link time			
	Post-build time			
Scope / Dependency	scope: local		•	

Included Containers		
Container Name	Multiplicity	Scope / Dependency
J1939TpTxDirectNPdu	01	This N-PDU represents the short frame that is used for a dynamic length PGN when it has a length of less that 8 bytes. Please note: This sub container is only necessary when J1939TpTxPgDynLength is TRUE.
J1939TpTxNSdu		This container describes the parameters that are relevant for the transmission of a specific N-SDU.

10.2.16 J1939TpTxDirectNPdu

SWS Item	ECUC_J1939Tp_00140:
Container Name	J1939TpTxDirectNPdu
Description	This N-PDU represents the short frame that is used for a dynamic length PGN when it has a length of less that 8 bytes. Please note: This sub container is only necessary when J1939TpTxPgDynLength is TRUE.
Configuration Parameters	



SWS Item	ECUC_J1939Tp_00169:				
Name	J1939TpTxDirectNPduTxCo	nfld			
Description	The N-PDU identifier used for	or Tx c	confirmation from CanIf.		
Multiplicity	1				
Туре	EcucIntegerParamDef (Sym	EcucIntegerParamDef (Symbolic Name generated for this parameter)			
Range	0 65535	0 65535			
Default value					
Post-Build Variant Value	false				
Value Configuration Class	Pre-compile time X All Variants				
	Link time	ł			
	Post-build time				
Scope / Dependency	scope: ECU				

SWS Item	ECUC_J1939Tp_00141:			
Name	J1939TpTxDirectNPduRef			
Description	Reference to the Pdu object	repre	senting the N-PDU.	
Multiplicity	1			
Туре	Reference to [Pdu]	Reference to [Pdu]		
Post-Build Variant Value	true	true		
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time			
	Post-build time X VARIANT-LINK-TIME, VARIANT-POST-			
			BUILD	
Scope / Dependency	scope: local			

No Included Containers

10.2.17 J1939TpTxNSdu

SWS Item	ECUC_J1939Tp_00147:
Container Name	J1939TpTxNSdu
II JOSEFINTIAN	This container describes the parameters that are relevant for the transmission of a specific N-SDU.
Configuration Parameters	

SWS Item	ECUC_J1939Tp_00149:				
Name	J1939TpTxNSduld				
Description	The N-SDU identifier used for	r com	munication with PduR.		
Multiplicity	1				
Туре	EcucIntegerParamDef (Symbolic Name generated for this parameter)				
Range	0 65535	0 65535			
Default value					
Post-Build Variant Value	false				
Value Configuration Class	Pre-compile time X All Variants				
	Link time				
	Post-build time				
Scope / Dependency	scope: ECU				

SWS Item	ECUC_J1939Tp_00151:
Name	J1939TpTxNSduRef
Description	Reference to the Pdu object representing the N-SDU.
Multiplicity	1



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Туре	Reference to [Pdu]				
Post-Build Variant Value	true				
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE		
	Link time				
	Post-build time		VARIANT-LINK-TIME, VARIANT-POST- BUILD		
Scope / Dependency	scope: local				

No Includ	ded Containers		

10.3 Published Information

For details, refer to the chapter 10.3 "Published Information" in the SWS BSW General [15].



11 Not applicable requirements

[SWS_J1939Tp_99999] [These requirements are not applicable to this specification.] (SRS_BSW_00005, SRS_BSW_00161, SRS_BSW_00162, SRS_BSW_00164, SRS_BSW_00168, SRS_BSW_00170, SRS_BSW_00314, SRS_BSW_00325, SRS_BSW_00341, SRS_BSW_00347, SRS_BSW_00375, SRS_BSW_00377, SRS_BSW_00413, SRS_BSW_00415, SRS_BSW_00416, SRS_BSW_00417, SRS_BSW_00419, SRS_BSW_00423, SRS_BSW_00427, SRS_BSW_00433, SRS_BSW_00437, SRS_BSW_00439, SRS_BSW_00440, SRS_BSW_00447, SRS_BSW_00449, SRS_BSW_00453)