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	Document Change History			
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24.01.2007	1.1.0	AUTOSAR Administration	 Integrated into BSW Scheduler header file structure Sequence diagrams clarified Superfluous text removed Maximum IPDU size clarified Signature for IpduM_Transmit made consistent with rest of stack. "Advice for users" revised Revision Information" added Legal disclaimer revised 	



Document Change History			
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		Administration	



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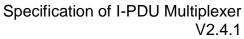
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	10.2.		IpduMRxDynamicPart	
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	10.2.		IpduMRxStaticSegment	
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1 Introduction and functional overview

This specification describes the functionality, APIs and the configuration of the AUTOSAR Basic Software module I-PDU Multiplexer IpduM.

PDU multiplexing means using the same PCI (Protocol Control Information) of a PDU (Protocol Data Unit) with more than one unique layout of its SDU (Service Data Unit). A selector field is a piece of the SDU of the multiplexed PDU. It is used to distinguish the contents of the multiplexed PDUs from each other.

Multiplexing of PDUs is currently known from CAN, but is not restricted to this communication system.

On sender-side, the I-PDU Multiplexer module is responsible to combine appropriate I-PDUs from COM to new, multiplexed I-PDUs and send them back to the PDU-Router. On receiver-side, it is responsible to interpret the content of multiplexed I-PDUs and provide COM with its appropriate separated I-PDUs taking into account the value of the selector field.



2 Acronyms and abbreviations

Abbreviation / Acronym:	Description:	
IpduM	I-PDU Multiplexer	
dynamic part	see [4]	
static part	see [4]	
selector field	see [4]	
signal	see [5]	
signal group	see [5]	
segment	The static or dynamic part may consist of more than one piece. These pieces are called segments. See also SWS_lpduM_00006 and Figure 3 .	
COM I-PDU	I-PDU assembled in the COM module out of COM Signals	
IpduM I-PDU	I-PDU assembled in the IpduM module out of two COM I-PDUs	
multiplexed I-PDU	see IpduM I-PDU	
instance of an I-PDU	IpduM I-PDU with one specific layout and content	



3 Related documentation



3.1 Input documents

- [1] Layered Software Architecture AUTOSAR_EXP_LayeredSoftwareArchitecture.pdf
- [2] General Requirements on Basic Software Modules AUTOSAR_SRS_BSWGeneral.pdf
- [3] Specification of RTE AUTOSAR_SWS_RTE.pdf
- [4] Requirements on I-PDU Multiplexer AUTOSAR_SRS_IPDUMultiplexer.pdf
- [5] Specification of Communication AUTOSAR_SWS_COM.pdf
- [6] General Specification of Basic Software Modules AUTOSAR_SWS_BSWGeneral.pdf



3.2 Related standards and norms

None



3.3 Related specification

AUTOSAR provides a General Specification on Basic Software modules [6], which is also valid for IPDU Multiplexer.

Thus, the specification SWS BSW General shall be considered as additional and required specification for IPDU Multiplexer.



4 Constraints and assumptions



4.1 Limitations

For transmission of multiplexed I-PDUs, minimum delay time observation cannot be taken into account. For more details, see [5] and 7.4.1.



4.2 Applicability to car domains

No restrictions.



4.3 Applicability to safety related environments

This document has been created in absence of a safety case and a safety plan. Thus, the direct results of this document can only be used within safety relevant systems after repeating certain process steps as required in the IEC 61508.



5 Dependencies to other modules

This chapter lists all the features from other modules that are used by the AUTOSAR IpduM and functionalities that are provided by AUTOSAR IpduM to other modules. Because the IpduM module deals with PDUs that are either sourced or sunk by other modules, care must be taken that shared configuration items are consistent between the modules.

The IpduM is arranged next to the PDU-Router in the layered architecture of AUTOSAR; see [1] and Figure 1.

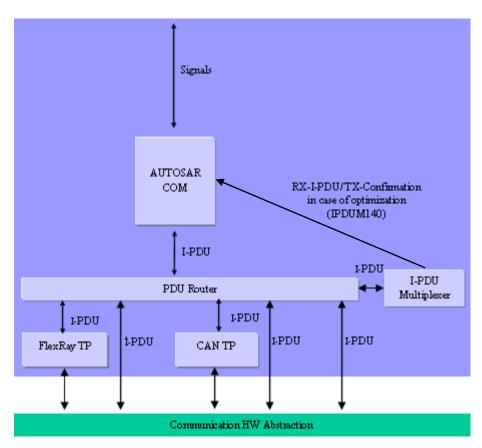


Figure 1 I-PDU Multiplexer in the AUTOSAR Architecture



5.1 AUTOSAR OS

[SWS_lpduM_00107] [The lpduM shall not directly access the AUTOSAR OS.] (SRS_BSW_00429)



5.2 RTE (BSW Scheduler)

The RTE includes the BSW-Scheduler (see [3]).

The IpduM module relies on the BSW-scheduler calling the IpduM_MainFunction function at a period as configured in IpduMConfigurationTimeBase.



5.3 PDU-Router

The following summarizes the functionality IpduM needs from the PDU-Router (for more details see Chapter 8.6):

- indication of incoming multiplexed I-PDUs
- sending interface for outgoing I-PDUs
- confirmation of I-PDUs which went out

The following list summarizes the functionality provided by the IpduM module for the PDU-Router module:

- indication interface for incoming I-PDUs, which are de-multiplexed
- sending interface for to be multiplexed I-PDUs
- confirmation interface for transmitted I-PDUs

The configuration of the PDU-Router module (e.g. look-up tables) must be such that the I-PDUs, which belong to multiplexed I-PDUs and represent a static or a dynamic part of a multiplexed I-PDU, are routed to the IpduM module.



5.4 COM

The configuration of the IpduM module relies on a corresponding configuration of the AUTOSAR COM module. For each multiplexed I-PDU, there need to be different I-PDUs for the static part and each layout of the dynamic part. For further information configured in the COM module, see Chapter 7.1 and especially Figure 3.

The IpduM further assumes that the correct selector field values are already contained in the COM's modules I-PDU representing the dynamic parts. See also SWS IpduM 00098.



5.5 File structure

5.5.1 Code file structure

This IpduM SWS does not define the code file structure completely.

5.5.2 Header file structure

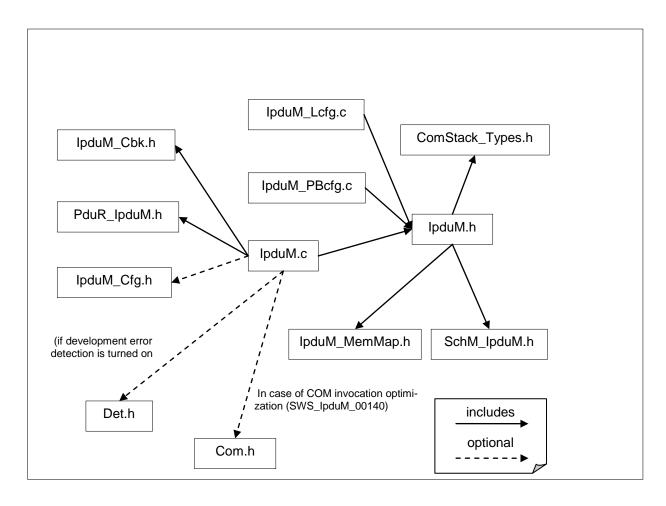
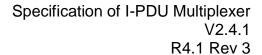


Figure 2 Header File Structure

[SWS_lpduM_00148]
The file lpduM.c shall include lpduM.h, lpduM_Cbk.h, PduR_lpduM.h, and optionally lpduM_Cfg.h, Det.h and Com.h. (SRS_BSW_00415)

[SWS_lpduM_00149] \(\text{The file lpduM_Lcfg.c shall include lpduM.h. } \) (SRS_BSW_00415)





[SWS_lpduM_00151] File lpduM.h shall include MemMap.h, SchM_lpduM.h and ComStack_Types.h. (SRS_BSW_00415)



6 Requirements traceability

Document: AUTOSAR requirements on Basic Software [2]

Requirement	Description	Satisfied by
-	-	SWS_lpduM_00104
-	-	SWS_lpduM_00105
-	-	SWS_lpduM_00166
-	-	SWS_lpduM_00168
-	-	SWS_lpduM_00169
-	-	SWS_lpduM_00171
-	-	SWS_lpduM_00172
BSW00431	-	SWS_lpduM_00999
BSW00434	-	SWS_lpduM_00999
SRS_BSW_00003	All software modules shall provide version and identification information	SWS_lpduM_00037
SRS_BSW_00005	Modules of the æC Abstraction Layer (MCAL) may not have hard coded horizontal interfaces	SWS_lpduM_00999
SRS_BSW_00101	The Basic Software Module shall be able to initialize variables and hardware in a separate initialization function	SWS_lpduM_00032, SWS_lpduM_00033
SRS_BSW_00162	The AUTOSAR Basic Software shall provide a hardware abstraction layer	SWS_lpduM_00999
SRS_BSW_00164	The Implementation of interrupt service routines shall be done by the Operating System, complex drivers or modules	SWS_lpduM_00999
SRS_BSW_00168	SW components shall be tested by a function defined in a common API in the Basis-SW	SWS_lpduM_00999
SRS_BSW_00171	Optional functionality of a Basic-SW component that is not required in the ECU shall be configurable at precompile-time	SWS_lpduM_00999
SRS_BSW_00314	All internal driver modules shall separate the interrupt frame definition from the service routine	SWS_lpduM_00999
SRS_BSW_00323	All AUTOSAR Basic Software Modules shall check passed API parameters for validity	SWS_lpduM_00028
SRS_BSW_00325	The runtime of interrupt service routines and functions that are running in interrupt context shall be kept short	SWS_IpduM_00999



CDC DCW 0000C		CMC In July 00000
SRS_BSW_00326	-	SWS_lpduM_00999
SRS_BSW_00336	Basic SW module shall be able to shutdown	SWS_lpduM_00999
SRS_BSW_00338	-	SWS_lpduM_00028
SRS_BSW_00339	Reporting of production relevant error status	SWS_lpduM_00999
SRS_BSW_00344	BSW Modules shall support link- time configuration	SWS_lpduM_00032
SRS_BSW_00357	For success/failure of an API call a standard return type shall be defined	SWS_lpduM_00102
SRS_BSW_00369	All AUTOSAR Basic Software Modules shall not return specific development error codes via the API	SWS_lpduM_00032, SWS_lpduM_00037, SWS_lpduM_00040, SWS_lpduM_00043, SWS_lpduM_00044, SWS_lpduM_00060
SRS_BSW_00375	Basic Software Modules shall report wake-up reasons	SWS_lpduM_00999
SRS_BSW_00377	A Basic Software Module can return a module specific types	SWS_lpduM_00999
SRS_BSW_00386	The BSW shall specify the configuration for detecting an error	SWS_lpduM_00999
SRS_BSW_00405	BSW Modules shall support multiple configuration sets	SWS_lpduM_00032
SRS_BSW_00406	A static status variable denoting if a BSW module is initialized shall be initialized with value 0 before any APIs of the BSW module is called	SWS_lpduM_00083, SWS_lpduM_00084
SRS_BSW_00407	Each BSW module shall provide a function to read out the version information of a dedicated module implementation	SWS_lpduM_00037
SRS_BSW_00415	Interfaces which are provided exclusively for one module shall be separated into a dedicated header file	SWS_lpduM_00148, SWS_lpduM_00149, SWS_lpduM_00150, SWS_lpduM_00151
SRS_BSW_00417	Software which is not part of the SW-C shall report error events only after the DEM is fully operational.	SWS_lpduM_00999
SRS_BSW_00422	Pre-de-bouncing of error status information is done within the DEM	SWS_lpduM_00999
SRS_BSW_00423	BSW modules with AUTOSAR interfaces shall be describable with the means of the SW-C Template	SWS_lpduM_00999
SRS_BSW_00425	The BSW module description temp- late shall provide means to model the defined trigger conditions of schedulable objects	SWS_lpduM_00103
SRS_BSW_00427	ISR functions shall be defined and documented in the BSW module description template	SWS_lpduM_00999
SRS_BSW_00429	BSW modules shall be only allowed to use OS objects and/or related OS services	SWS_lpduM_00107



0D0 B0W == :==		0000 1 1 1 1 00000
SRS_BSW_00432	Modules should have separate main processing functions for read/receive and write/transmit data path	SWS_lpduM_00999
SRS_BSW_00433	Main processing functions are only allowed to be called from task bodies provided by the BSW Scheduler	SWS_lpduM_00999
SRS_BSW_00437	Memory mapping shall provide the possibility to define RAM segments which are not to be initialized during startup	SWS_lpduM_00999
SRS_BSW_00438	Configuration data shall be defined in a structure	SWS_lpduM_00159
SRS_lpduM_02800	For a multiplexed IPDU there shall be exactly one selector field	SWS_lpduM_00004, SWS_lpduM_00007
SRS_lpduM_02801	The size in bits of the selector field shall be configurable	SWS_lpduM_00009
SRS_lpduM_02802	The position of the selector field within the PDU shall be configurable	SWS_lpduM_00005, SWS_lpduM_00155
SRS_lpduM_02803	It shall be possible not to assign a SDU layout to the unused selector field values	SWS_lpduM_00011
SRS_lpduM_02804	For each used selector field value a dynamic and static layout shall be configurable	SWS_lpduM_00006
SRS_lpduM_02806	The three parts of each multiplexed I-PDU must not necessarily be contiguous	SWS_lpduM_00010
SRS_lpduM_02807	The IPDU Multiplexer module shall be designed in a way that it does not produce any additional runtime	SWS_lpduM_00097
SRS_lpduM_02808	It shall be possible that the static part of a IPDU is zero bits long	SWS_lpduM_00004
SRS_lpduM_02809	-	SWS_lpduM_00067, SWS_lpduM_00068, SWS_lpduM_00098, SWS_lpduM_00143
SRS_lpduM_02810	The PduR shall be configured to send parts of multiplexed IPDUs to the IPduM on sender side	SWS_lpduM_00089, SWS_lpduM_00090, SWS_lpduM_00091
SRS_lpduM_02811	-	SWS_lpduM_00021
SRS_lpduM_02812	The PduR shall be configured to send multiplexed IPDUs for demultiplexing to the IPduM after they were received from the lower layer	SWS_lpduM_00041, SWS_lpduM_00042, SWS_lpduM_00086, SWS_lpduM_00140
SRS_lpduM_02813	The PduR shall be configured to send confirmations related to multiplexed IPDUs to IPduM after receiving them from the lower layer	SWS_lpduM_00022, SWS_lpduM_00101
SRS_lpduM_02814	The confirmation shall depend upon selector field	SWS_lpduM_00019, SWS_lpduM_00020, SWS_lpduM_00023, SWS_lpduM_00024, SWS_lpduM_00087, SWS_lpduM_00088,



		SWS_lpduM_00152
SRS_lpduM_02816	On sender side the IPduM shall combine the static and the appropriate dynamic part within IPduM	SWS_lpduM_00015, SWS_lpduM_00017
SRS_lpduM_02817	On receiver side the IPduM extracts the static and dynamic parts of the multiplexed IPDU	SWS_lpduM_00040
SRS_lpduM_02818	The IPduM confirms to COM the static part of the multiplexed IPDU and the dynamic part	SWS_lpduM_00022
SRS_lpduM_02819	There shall be no queuing of transmission requests on sender side	SWS_lpduM_00020, SWS_lpduM_00023

Requirement	Satisfied by
[SRS_BSW_00344]	Chapter 10.2.2, SWS_lpduM_00032
Reference to link-time	
configuration	
[SRS_BSW_00404]	Chapter 10.2
Reference to post build	
time configuration	
[SRS_BSW_00405]	SWS IpduM 00032
Reference to multiple	
configuration sets	
[SRS BSW 00345]	Chapter 10.2.2, ECUC_lpduM_00059, ECUC_lpduM_00047,
Pre-compile-time	ECUC_lpduM_00048, ECUC_lpduM_00049, ECUC_lpduM_00052,
configuration	ECUC_lpduM_00053, ECUC_lpduM_00056
[SRS_BSW_00159]	not scope of this specification
Tool-based configuration	Refers to Configuration WP.
[SRS BSW 00167]	not scope of this specification
Static configuration check-	Refers to Configuration WP.
ing	Trofold to Gottingulation VVI .
[SRS_BSW_00171]	not applicable
Configurability of optional	(there is no optional functionality)
functionality	(more to the optional furnationality)
[SRS_BSW_00170]	not scope of this specification
Data for reconfiguration of	Refers to Configuration WP.
AUTOSAR SW-	Troisis to comingulation vivi
Components	
[SRS_BSW_00380]	SWS_lpduM_00095, SWS_lpduM_00096
Separate C-Files for	implementation specific
configuration parameters	implementation operation
[SRS_BSW_00419]	Chapter 5.5
Separate C-Files for pre-	implementation specific
compile time configuration	implomentation opening
parameters	
[SRS_BSW_00381]	Chapter 5.5
Separate configuration	implementation specific
header file for pre-compile	Important opositio
time parameters	
[SRS_BSW_00412]	Chapter 5.5
Separate H-File for	implementation specific
configuration parameters	Implementation opposite
[SRS_BSW_00383]	not scope of this specification
List dependencies of	The coope of the openiodion
configuration files	
[SRS_BSW_00384]	Chapter 5, SWS_lpduM_00104, SWS_lpduM_00105
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List dependencies to other	
modules	
[SRS_BSW_00387]	Chapter 8.5
Specify the configuration	
class of callback function	
[SRS_BSW_00388]	Chapter 10.2,ECUC_lpduM_00070, ECUC_lpduM_00071,
Introduce containers	ECUC_lpduM_00082, ECUC_lpduM_00130
[SRS_BSW_00389]	Chapter 10.2
Containers shall have	
names	
[SRS_BSW_00390]	Chapter 10.2
Parameter content shall be	Onapior 1012
unique within the module	
[SRS_BSW_00391]	Chapter 10.2
Parameter shall have	Onaptor 10.2
unique names	
[SRS_BSW_00392]	Chapter 10.2
Parameters shall have a	Onaptor 10.2
i didiniotoro oriani maro di	
type	Chapter 10.2
[SRS_BSW_00393]	Onapier 10.2
Parameters shall have a	
range	Chapter 10.2
[SRS_BSW_00394]	Chapter 10.2
Specify the scope of the	
parameters	
[SRS_BSW_00395]	All parameter in Chapter 10.2 are required.
List the required	
parameters (per parameter)	
[SRS_BSW_00396]	Chapter 10.2
Configuration classes	
[SRS_BSW_00397]	Chapter 10.2
Pre-compile-time	
parameters	
[SRS_BSW_00398]	Chapter 10.2
Link-time parameters	
[SRS_BSW_00399]	Chapter 10.2
Loadable Post-build time	
parameters	
[SRS_BSW_00400]	Chapter 10.2
Selectable Post-build time	'
parameters	
[SRS_BSW_00438] Post	Chapter 10.2.1, SWS_lpduM_00159
Build Configuration Data	
Structure	
[SRS_BSW_00402]	ECUC_lpduM_00141, ECUC_lpduM_00142, SWS_lpduM_00160
Published information	
[SRS_BSW_00375]	not applicable
Notification of wake-up	(this layer cannot perform a wake-up)
reason	(tills layer carmot perform a wake-up)
[SRS_BSW_00101]	SWS_lpduM_00032, SWS_lpduM_00033, SWS_lpduM_00034,
Initialization interface	SWS_lpduM_00064, SWS_lpduM_00065
[SRS_BSW_00416]	not scope of this specification
Sequence of Initialization	refere to Mode Management Specification.
[SRS_BSW_00406]	SWS_lpduM_00083, SWS_lpduM_00084
Check module initialization	not applicable (not peeded)
[SRS_BSW_00437]	not applicable (not needed)
NoInit—Area in RAM	
[SRS_BSW_00168]	not applicable
Diagnostic interface	(not diagnostic interface included)



[SRS_BSW_00407]	SWS_lpduM_00037
Function to read out	
published parameters	
[SRS_BSW_00423]	not applicable
Usage of SW-C template to	(this module has no connection to the RTE)
describe BSW modules	
with AUTOSAR Interfaces	
[SRS_BSW_00424]	not scope of this specification
BSW main processing	Implementation specific
function task allocation	
[SRS_BSW_00425]	SWS_lpduM_00103, ECUC_lpduM_00131
Trigger conditions for	3443_ipadivi_00103, ECOC_ipadivi_00131
schedulable objects	and annual this annuitiestics
[SRS_BSW_00426]	not scope of this specification
Exclusive areas in BSW	Implementation specific
modules	
[SRS_BSW_00427]	not applicable
ISR description for BSW	(module does not provide ISRs)
modules	
[SRS_BSW_00428]	Chapter 8.6
Execution order	
dependencies of main	
processing functions	
[SRS_BSW_00429]	SWS_lpduM_00107
Restricted BSW OS	
functionality access	
[BSW00431]	not applicable
The BSW Scheduler	requirement for the scheduler)
	(requirement for the scheduler)
module implements task	
bodies	not onvice his
[SRS_BSW_00432]	not applicable
Modules should have	(transmit and receive functions are called synchronous by the adjacent
separate main processing	layers)
functions for read/receive	
and write/transmit data path	
[SRS_BSW_00433]	not applicable
Calling of main processing	(requirement for the scheduler)
functions	
[BSW00434]	not applicable
The Schedule Module shall	(requirement for the scheduler)
provide an API for exclusive	·
areas	
[SRS_BSW_00336]	not applicable
Shutdown interface	(not needed)
[SRS_BSW_00337]	SWS lpduM 00026, SWS lpduM 00106, SWS lpduM00153
Classification of errors	
[SRS_BSW_00338]	SWS_lpduM_00027, SWS_lpduM_00028, ECUC_lpduM_00059,
Detection and Reporting of	ECUC IpduM 00132, SWS IpudM 00154
development errors	E000_ipuulvi_00 102, 0vv0_ipuulvi_00 104
-	CMC InduM 00022 CMC InduM 00027 CMC InduM 00040
[SRS_BSW_00369]	SWS_lpduM_00032, SWS_lpduM_00037, SWS_lpduM_00040,
Do not return development	SWS_lpduM_00043, SWS_lpduM_00044, SWS_lpduM_00060
error codes via API	not applicable
[SRS_BSW_00339]	not applicable
Reporting of production	(module does not define any production relevant errors)
relevant errors and excep-	
tions	
[SRS_BSW_00422] Pre—	not applicable
de—bouncing of production	(not scope of this specification)
relevant error status	
[SRS_BSW_00417]	not applicable
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23 01 00	



Reporting of Error Events	(this module is part of the basic software)
by Non-Basic Software	
[SRS_BSW_00323]	SWS_lpduM_00028
API parameter checking	
[SRS_BSW_00004]	SWS_lpduM_00038, SWS_lpduM_00039, ECUC_lpduM_00059,
Version check	ECUC_lpduM_00134, SWS_lpduM_00165
[SRS_BSW_00409]	Figure 2
Header files for production	Ŭ
code error IDs	
[SRS_BSW_00385]	SWS_lpduM_00026
List possible error	
notifications	
[SRS_BSW_00386]	not applicable
Configuration for detecting	(implementation specific)
an error	
[SRS_BSW_00161]	SWS_lpduM_00074, SWS_lpduM_00078
Microcontroller abstraction	
[SRS_BSW_00162]	not applicable
ECU layout abstraction	(not scope of this specification)
[SRS_BSW_00005]	not applicable
No hard coded horizontal	
	(not scope of this specification)
interfaces within MCAL	CMC InduM 00140 CMC InduM 00440 CMC InduM 00450
[SRS_BSW_00415]	SWS_lpduM_00148, SWS_lpduM_00149, SWS_lpduM_00150,
User dependent include	SWS_lpduM_00151
files	
[SRS_BSW_00164]	not applicable
Implementation of interrupt	(module does not provide ISRs)
service routines	
[SRS_BSW_00325]	not applicable
Runtime of interrupt service	(module does not provide ISRs)
routines	
[SRS_BSW_00326]	not applicable
Transition from ISRs to OS	(module does not provide ISRs)
tasks	
[SRS_BSW_00342]	Chapter 10.2
Usage of source code and	
object code	
[SRS_BSW_00343]	Chapter 10.2
Specification and	
configuration of time	
[SRS_BSW_00160]	Chapter 10.2
Human-readable	
configuration data	
[SRS_BSW_00007]	SWS_lpduM_00073
HIS MISRA C	_, _
[SRS_BSW_00300]	Figure 2
Module naming convention	1 19410 2
[SRS_BSW_00413]	not scope of this specification
Accessing instances of	implementation specific
BSW modules	
[SRS_BSW_00347]	not scope of this specification
Naming separation of	implementation specific
different instances of BSW	
drivers	
	Chapter 9 2 1
[SRS_BSW_00305]	Chapter 8.3.1
Self-defined data types	
naming convention	not occup of this appoilingtion
[SRS_BSW_00307]	not scope of this specification
Global variables naming	implementation specific



convention	
[SRS_BSW_00310]	Chapter 8.4 and 8.5
API naming convention	
[SRS_BSW_00373]	Chapter 8.6
Main processing function	Chapter 6.0
naming convention	01410 1-1-14 00000
[SRS_BSW_00327]	SWS_lpduM_00026
Error values naming	
convention	
[SRS_BSW_00335]	not scope of this specification
Status values naming	implementation specific
convention	
[SRS_BSW_00350]	SWS_lpduM_00027
Development error	
detection keyword	
[SRS_BSW_00408]	Chapter 10.2
Configuration parameter	Onapici 10.2
naming convention	
[SRS_BSW_00410]	not scope of this specification
Compiler switches shall	implementation specific
have defined values	
[SRS_BSW_00411]	SWS_lpduM_00039
Get version info keyword	
[SRS_BSW_00346]	Figure 2
Basic set of module files	· · · · · · · ·
[SRS_BSW_00158]	Figure 2
Separation of configuration	I Iguic 2
from implementation	
[SRS_BSW_00314]	not applicable
Separation of interrupt	(module does not provide ISRs)
frames and service routines	
[SRS_BSW_00370]	Chapter 8.5
Separation of callback	
interface from API	
[SRS_BSW_00435] Module	Figure 2
Header File Structure for	
the Basic Software	
Scheduler	
[SRS_BSW_00436] Module	Figure 2
Header File Structure for	1 19410 2
the Basic Software Memory	
Mapping	
[SRS_BSW_00348]	Figure 2
	Figure 2
Standard type header	not come of this appoilings:
[SRS_BSW_00353]	not scope of this specification
Platform specific type	implementation specific
header	
[SRS_BSW_00361]	not scope of this specification
Compiler specific language	implementation specific
extension header	
[SRS_BSW_00301]	not scope of this specification
Limit imported information	implementation specific
[SRS_BSW_00302]	not scope of this specification
Limit exported information	implementation specific
[SRS_BSW_00328]	not scope of this specification
Avoid duplication of code	implementation specific
[SRS_BSW_00312]	not scope of this specification
Shared code shall be	implementation specific
reentrant	



1000 0000	
[SRS_BSW_00006]	not scope of this specification
Platform independency	implementation specific
[SRS_BSW_00357]	Chapter 8, SWS_lpduM_00102
Standard API return type	
[SRS_BSW_00377]	not applicable
Module specific API return	(no specific return types)
types	
[SRS_BSW_00304]	Figure 2
AUTOSAR integer data	
types	
[SRS_BSW_00355]	Chapter 8.3
Do not redefine AUTOSAR	implementation specific
integer data types	
[SRS_BSW_00378]	not scope of this specification
AUTOSAR boolean type	implementation specific
[SRS_BSW_00306]	not scope of this specification
Avoid direct use of compiler	implementation specific
and platform specific	
keywords	and a second of the second of
[SRS_BSW_00308]	not scope of this specification
Definition of global data	implementation specific
[SRS_BSW_00309]	SWS_lpduM_00075, SWS_lpduM_00077
Global data with read-only	
constraint	
[SRS_BSW_00371]	Chapter 8.4 and 8.5
Do not pass function	
pointers via API	
[SRS_BSW_00358]	Chapter 8.4.1
Return type of init functions	01
[SRS_BSW_00414]	Chapter 8.4.1
Parameter of init function	01
[SRS_BSW_00376]	Chapter 8.6
Return type and	
parameters of main	
processing functions [SRS BSW 00359]	Chapter 8.5
Return type of callback	Chapter 6.5
functions [SRS_BSW_00360]	Chapter 8.5
Parameters of callback	Οπαρισι σ.σ
functions	
[SRS_BSW_00329]	Chapter 8
Avoidance of generic	Onapioi o
interfaces	
[SRS_BSW_00330]	SWS IpduM 00076, SWS IpduM 00085
Usage of macros / inline	
functions instead of	
functions	
[SRS_BSW_00331]	Chapter 8
Separation of error and	I · · ·
status values	
[SRS_BSW_00009]	not scope of this specification
Module User	implementation specific
Documentation	'
[SRS_BSW_00401]	Chapter 10.2
Documentation of multiple	'
instances of configuration	
parameters	
[SRS_BSW_00172]	not scope of this specification
<u> </u>	



Compatibility and	implementation specific
documentation of	
scheduling strategy	
[SRS_BSW_00010]	not scope of this specification
Memory resource	implementation specific
documentation	
[SRS_BSW_00333]	not scope of this specification
Documentation of callback	implementation specific
function context	
[SRS_BSW_00374]	Chapter 10.3
Module vendor	
identification	
[SRS_BSW_00379]	Chapter 10.3
Module identification	
[SRS_BSW_00003]	SWS_lpduM_00037, ECUC_lpduM_00059
Version identification	
[SRS_BSW_00318]	Chapter 10.3
Format of module version	
numbers	
[SRS_BSW_00321]	not scope of this specification
Enumeration of module	implementation specific
version numbers	
[SRS_BSW_00341]	not scope of this specification
Microcontroller compatibility	implementation specific
documentation	
[SRS_BSW_00334]	not scope of this specification
Provision of XML file	Refers to Configuration WP

Document: AUTOSAR requirements on Basic Software cluster IpduM [4]

Requirement	Satisfied by
[SRS_lpduM_02800]	SWS_lpduM_00004, SWS_lpduM_00007
Exactly one selector field per PDU	
[SRS_lpduM_02801]	SWS_lpduM_00009, ECUC_lpduM_00052
Size of the selector field	
[SRS_lpduM_02802]	SWS_lpduM_00005, SWS_lpduM_00155
Position of the selector field	
[SRS_lpduM_02815]	ECUC_lpduM_00052
Compile Time configuration of the selector field	
[SRS_lpduM_02803]	SWS_lpduM_00011
Unused values of the selector field	
[SRS_lpduM_02804]	SWS_lpduM_00006
Support for static and dynamic parts of the PDU	
[SRS_lpduM_02808]	SWS_lpduM_00004, ECUC_lpduM_00133
Support of multiplexed PDUs with a static part of	
length "zero"	
[SRS_lpduM_02809]	SWS_lpduM_00068, SWS_lpduM_00067,
Initialization of multiplexed PDUs	SWS_lpduM_00098, SWS_lpduM_00143
[SRS_lpduM_02806]	SWS_lpduM_00010
Semantic of the multiplexer	
[SRS_lpduM_02810]	SWS_lpduM_00089, SWS_lpduM_00090,
Routing of multiplexed PDUs on sender side	SWS_lpduM_00091, ECUC_lpduM_00112
[SRS_lpduM_02816]	SWS_lpduM_00015, SWS_lpduM_00017,
Combining of multiplexed PDUs on sender side	ECUC_lpduM_00114, ECUC_lpduM_00120,
	ECUC_lpduM_00121, ECUC_lpduM_00125,
	ECUC_lpduM_00126, ECUC_lpduM_00127,
	ECUC_lpduM_00128, ECUC_lpduM_00129,
	ECUC_lpduM_00157
[SRS_lpduM_02811]	SWS_lpduM_00021, ECUC_lpduM_00052



Requirement	Satisfied by
Triggering condition on sender side	
[SRS_lpduM_02812]	SWS_lpduM_00041, SWS_lpduM_00042,
Routing of multiplexed PDUs on receiver side	SWS_lpduM_00086, ECUC_lpduM_00108,
	ECUC_lpduM_00109, SWS_lpduM_00140
[SRS_lpduM_02817]	SWS_lpduM_00040, ECUC_lpduM_00113,
De-multiplexing PDUs on receiver side	ECUC_lpduM_00114, ECUC_lpduM_00115
[SRS_lpduM_02813]	SWS_lpduM_00022, SWS_lpduM_00101
Routing of Send Confirmations	
[SRS_lpduM_02818]	SWS_lpduM_00022, ECUC_lpduM_00124,
Confirmation replication of multiplexed PDUs	ECUC_lpduM_00163, ECUC_lpduM_00164,
	ECUC_lpduM_00158
[SRS_lpduM_02814]	SWS_lpduM_00023, SWS_lpduM_00024,
Correct confirmation handling of multiplexed	SWS_lpduM_00019, SWS_lpduM_00020,
PDUs	SWS_lpduM_00087,SWS_lpduM_00088,
1000 1 111 00000	SWS_lpduM_00152
[SRS_lpduM_02807]	SWS_lpduM_00097
No Runtime Overhead for systems without PDU	
multiplexing	0000 1 1 1 1 00000 0000 1 1 1 1 00000
[SRS_lpduM_02819]	SWS_lpduM_00020, SWS_lpduM_00023
No queuing of transmission requests on sender	
side	

AUTOSAR Release 4.0 Concept Incorporation

Concept	Satisfied by
Debugging concept	SWS_lpduM_00144, SWS_lpduM_00145,
	SWS_lpduM_00146, SWS_lpduM_00147



7 Functional specification



7.1 Introduction and definitions

I-PDU multiplexing means using the same I-PDU ID transferred from the PDU-Router to the Communication Hardware Abstraction Layer with more than one unique layout of this I-PDU; see also [1].

[SWS_lpduM_00004] [A multiplexed I-PDU consists of a static part and a dynamic part, where the static part consists of zero or more signals or signal groups. The dynamic part consists of the selector field and one or more signals or signal groups; see Figure 3.] (SRS_lpduM_02800, SRS_lpduM_02808)

The dynamic part of an I-PDU is comparable with a union in "C". With help of the selector field inside the I-PDU, the actual layout of the I-PDU is selected.

[SWS_lpduM_00005] [The position of the static and the dynamic part of the multiplexer shall be arbitrary and has to be configurable per I-PDU; see Figure 3, for configuration see Chapter 10.2.2. | (SRS_lpduM_02802)

[SWS_lpduM_00006] [It shall be possible that the static and the dynamic part consist of more than one element. These elements of the static or dynamic parts are called segments. | (SRS_lpduM_02804)

[SWS_lpduM_00007] [There shall be only one selector field within one multiplexed I-PDU.] (SRS_lpduM_02800)

The value of the selector field defines how the content of the dynamic part of the I-PDU will be interpreted.

[SWS_lpduM_00009] [The selector field of one I-PDU shall have a configurable size between one and eight contiguous bits. | (SRS_lpduM_02801)

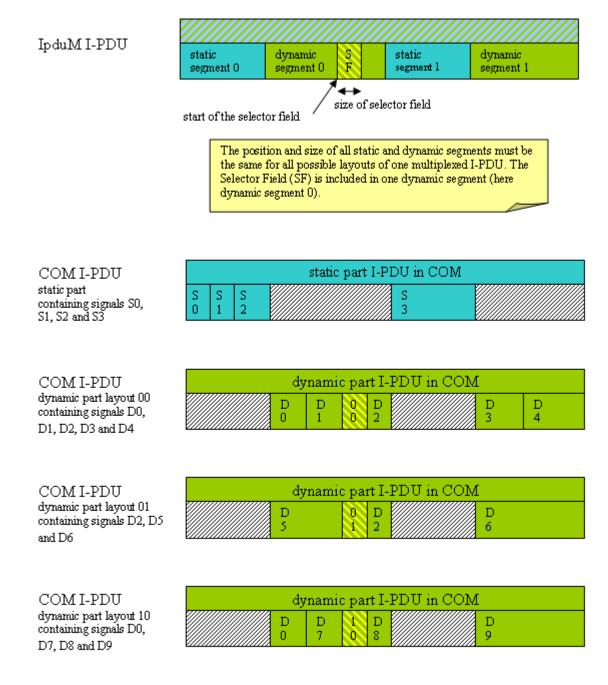
[SWS_lpduM_00010] [The position of the selector field within the I-PDU shall be defined by configuration. | (SRS_lpduM_02806)

The configuration rules for the selector field are defined in Chapter 10.4.1.

Multiplexing of PDUs is currently only known from CAN, but it is not restricted to this communication system.

However, because the module is layered next to the PDU-Router above the interface layer (Communication Hardware Abstraction) in the AUTOSAR layer architecture this feature also could be used with LIN or FlexRay.





A segment of the dynamic or static part contains either a single signal or signal group or a collection of signals and signal groups.

Figure 3 Possible layout of a multiplexed I-PDU



7.2 General

[SWS_lpduM_00097] [The lpduM shall be implemented so that no other modules depend on it and that it is be possible to build a system without the lpduM module if it is not needed.] (SRS_lpduM_02807)

There is one COM I-PDU for the static part and one COM I-PDU for each layout of the dynamic part of one multiplexed IpduM I-PDU, so the IpduM combines at most two I-PDUs of COM.

[SWS_lpduM_00098] [The lpduM module shall not set the selector field.] (SRS_lpduM_02809)

The IpduM module relies on the configuration of the COM module. For each dynamic layout, an I-PDU needs to be configured in COM. Such I-PDUs already have to contain the correct selector field value. The selector field values in COM can be initialized by configuring them as signals that are initialized with an init value but are never written after initialization.

For a detailed description of the transmission and reception of a multiplexed I-PDU see Chapter 7.4 and 7.5.

[SWS_lpduM_00140] [It shall be allowed to optimize the Rx- and Tx-Confirmation path from the lpduM module via the PDU-Router module to the COM layer to call the COM API directly from the lpduM module without including the PDU-Router. This shall be indicated by setting the published parameter lpduMRxDirectComInvocation to TRUE, see ECUC_lpduM_00142.] (SRS_lpduM_02812)

In case of the COM invocation, optimization as defined above lpduM.c needs to include Com.h, see Figure 2 Header File Structure.



7.3 Initialization

The IpduM module provides an initialization function IpduM_Init defined in SWS_IpduM_00032. This function initializes all internal global variables and the buffers of the IpduM I-PDUs. For more details, see Chapter 8.3.1.

The environment of the IpduM shall call IpduM_Init before calling any other function of the IpduM module.

The implementer has to ensure that IPDUM_E_UNINIT is returned in development mode in case an API function is called before the module is initialized.

For the I-PDU data transmission pathway through the IpduM module, a buffer is allocated inside the IpduM module. This buffer needs to be initialized because it might be transmitted before it has been fully populated with data by the COM module. The initialization data of this buffer is derived from the initial values of the COM module's configuration as follows:

- [SWS_lpduM_00067] [The lpduM shall initialize its internal transmit buffers with the configured pattern lpduMIPduUnusedAreasDefault.] (SRS_lpduM_02809)
- 2) **[SWS_lpduM_00068]** [The initial signal values of the initial dynamic part shall be set according to initial values of the referenced COM I-PDU (IpduMInitialDynamicPart -> IpduMTxDynamicPart -> IpduMTxDynamicPduRef).] (SRS IpduM 02809)
- 3) [SWS_lpduM_00143] [The initial signal values of the static part shall be set according to the intial values of the referenced COM I-PDU (lpduMTxStaticPart -> lpduMTxStaticPduRef)] (SRS_lpduM_02809)

The selector field is contained within one segment of the intial dynamic part and therefore is initialized implicitly.

For optimization, the initial bit pattern for the buffer can be worked out at configuration-time and then copied at run-time.



7.4 Transmission

Inside COM, there are separated I-PDUs for the static part and one for each dynamic part of a multiplexed I-PDU.

The static part and the dynamic parts are treated in COM as separate I-PDUs with their own I-PDU IDs.

[SWS_lpduM_00015] [For a multiplexed I-PDU lpduM shall merge the corresponding two COM I-PDUs representing the associated static part and the last received dynamic part into one single lpduM I-PDU with a new unique I-PDU ID. lpduM shall send out this new lpduM I-PDU to the PDU-Router module, see also Figure 1.] (SRS_lpduM_02816)

For details about the trigger of the transmission, see Chapter 7.4.2.

All control functionalities like deadline monitoring of the COM I-PDUs and update-bit evaluation are out of the scope of the IpduM and have to be done by the COM layer. For details about the timing-behavior of the new combined I-PDU see Chapter 7.4.2.

7.4.1 Transmission request

The IpduM module provides an IpduM_Transmit function so that the PDU-R is able to initiate the transmission of an I-PDU; see SWS IpduM 00043.

[SWS_lpduM_00017] [The function lpduM_Transmit shall assemble the multiplexed I-PDU, using the related static and dynamic part, and transmit it according to the trigger conditions/ modes as defined in SWS_lpduM_00021 and ECUC_lpduM_00125.] (SRS_lpduM_02816)

As defined in Chapter 7.3, each outgoing I-PDU has an initial value so that, should an I-PDU be transmitted by the IpduM module before both static and dynamic parts have been sent from COM to the IpduM, a value defined by the configuration is transmitted.

[SWS_lpduM_00019] [The configuration of the lpduM shall contain a dedicated timeout for each lpduM I-PDU within the lpduM module in the configuration parameter lpduMTxConfirmationTimeout. | (SRS_lpduM_02814)

This timeout defines until when the transmission confirmation for this I-PDU has to be received after the transmission. For transmission confirmation, see Chapter 7.4.3.

The timeout period shall take into account the delays in the lower layers.

[SWS_IpduM_00020] [In case the IpduMTxConfirmationTimeout was configured to a value greater than 0, as long as the corresponding timeout timer has not elapsed, and no transmission confirmation for that multiplexed I-PDU was received, the function IpduM Transmit shall not allow a new transmission request from the upper layer



with a COM I-PDU that belongs to the same IpduM I-PDUs.] (SRS_IpduM_02814, SRS_IpduM_02819)

In case IpduMTxConfirmationTimeout was omitted or configured to 0, the IpduM module does not block any new transmission requests.

[SWS_lpduM_00152] [As long as the timeout (defined in the configuration parameter lpduMTxConfirmationTimeout) has not elapsed and as long as no transmission confirmation for the lpduM I-PDU is received, the function lpduM_Transmit shall return with E_NOT_OK for a new transmission request from the upper layer with a COM I-PDU that belongs to the same lpduM I-PDUs. | (SRS_lpduM_02814)

If the IpduMTxConfirmationTimeout is omitted or configured to 0, the parts of the multiplexed I-PDU may be overwritten even in case they were not already sent or confirmed.

In case a multiplexed I-PDU is only triggered for sending by either updating the dynamic or static part, the non-triggering part might be overwritten if updated multiple times between two transmissions even with a configured IpduMTxConfirmation-Timeout. This happens, since the confirmation timeout timer is only started, if the triggering part is updated.

It may be useful to configure the IpduM transmission confirmation timeout depended of the transmission deadline monitoring timeouts for the single COM I-PDUs of the COM layer configuration; see also [5].

7.4.2 Transmission trigger

The IpduM module receives the static and the dynamic part of a multiplexed I-PDU by separated two transmission requests as two single COM I-PDUs from the PDU-Router module.

[SWS_IpduM_00021] [The IpduM module shall be configurable to send a transmission request for the new multiplexed I-PDU to the PDU-Router because of the following trigger conditions/ modes:

- receiving a static part
- receiving a dynamic part
- receiving a static or a dynamic part
- does not trigger transmission because of receiving anything of this I-PDU (IpduMTxTriggerMode None) in case of TriggerTransmit

For configuration, see ECUC IpduM 00052. I (SRS IpduM 02811)

The four trigger conditions/ modes defined by SWS_lpduM_00021 allow controlling the transmission mode of the new assembled I-PDU by the transmission modes of the single I-PDUs sent by COM, see also [5].



Not all of four trigger conditions/ modes defined by SWS_lpduM_00021 guarantee the minimum delay time between consecutive transmissions of different instances of multiplexed I-PDUs, because if the transmission is triggered by static and dynamic part or only by the dynamic part, COM does not take care for the minimum delay time. COM treats the static part and the different dynamic parts as unrelated standalone I-PDUs.

The configuration "does not trigger transmission because of receiving anything" is needed if an I-PDU is only sent out because of a TriggerTransmit of a lower layer. With the API IpduM_TriggerTransmit it is possible for lower layers to trigger a send out of an I-PDU.

In case the IpduMTxTriggerMode is None and the lower layer triggers the transmission via IpduM_TriggerTransmit, the IpduMTxConfirmationPduId needs to be configured since this ID is also used for resolving the I-PDU in case of IpduM_TriggerTransmit, see also ECUC_IpduM_00158.

7.4.3 Just-In-Time update of parts

Sometimes it may be unwanted that the IpduM module not just sends out the locally stored parts, since these parts may contain outdated information e.g. update-bits. Therefore, the IpduM supports a per part configurable just-in-time update mechanism.

[SWS_lpduM_00168] [In case the transmission of a multiplexed I-PDU is triggered by the update of one part and lpduMJitUpdate is configured to true for the second part, the lpduM module shall update the second part via PduR_lpduMTriggerTransmit before the multiplexed I-PDU is sent out via PduR_lpduMTransmit.] ()

[SWS_lpduM_00171] [In case the transmission of a multiplexed I-PDU is triggered by the update of one part and lpduMJitUpdate is configured to true for the second part, the multiplexed I-PDU shall not be send if the JIT-update request via PduR_lpduMTriggerTransmit returns E_NOT_OK.| ()

[SWS_lpduM_00169] [In case the contents of a multiplexed I-PDU is requested via lpduM_TriggerTransmit, the lpduM module shall update all parts which have lpduMJitUpdate configured to true before returning the contents of the multiplexed I-PDU. | ()

[SWS_lpduM_00172] [In case the contents of a multiplexed I-PDU is requested via lpduM_TriggerTransmit and lpduMJitUpdate is configured to true for any multiplexed part, lpduM_TriggerTransmit shall return E_NOT_OK if any of the JIT-update requests via PduR_lpduMTriggerTransmit return E_NOT_OK.] ()



7.4.4 Transmission confirmation

Transmission confirmations are given to the IpduM module by the PDU-Router according to the configuration of the I-PDUs in the PDU-Router.

[SWS_lpduM_00022] [If the IpduM receives a TxConfirmation for a specific IpduM I-PDU, it shall translate this confirmation into the corresponding confirmations for the COM I-PDUs, which were contained in the last sent out multiplexed IpduM I-PDU.] (SRS_lpduM_02813, SRS_lpduM_02818)

Depending on the configuration of IpduMTxDynamicConfirmation (ECUC_IpduM_00163) and IpduMTxStaticConfirmation (ECUC_IpduM_00164), the IpduM will pass zero, one or two confirmations towards COM for one send request. The number of confirmations given to the upper layer does not depend on the IpduMTxTriggerMode.

Examples:

- a) If neither IpduMTxDynamicConfirmation nor IpduMTxStaticConfirmation for the corresponding IpduMTxRequest is configured to true, no COM confirmation is generated.
- b) If IpduMTxStaticConfirmation is configured to true but and IpduMTxDynamic-Confirmation is configured to false (or vice versa), then only one COM confirmation is generated.
- c) If both IpduMTxStaticConfirmation and IpduMTxDynamicConfirmation is configured to true, then two COM confirmations are generated; to the I-PDU representing the static part and the I-PDU representing the dynamic part.

[SWS_lpduM_00023] [If the Tx-Confirmation is not received within the configured timeout lpduMTxConfirmationTimeout the lpduM shall allow new transmission requests for this specific I-PDU after timeout is elapsed. J (SRS_lpduM_02814, SRS_lpduM_02819)

[SWS_lpduM_00024] [The lpduM shall discard unexpected Tx-Confirmations silently. This may happen if a previously requested transmit request has been timed out, but is confirmed now. I (SRS_lpduM_02814)

There is no need for an error entry in the case of timeout violation because this is already done in COM, if needed. In the case of a proper configuration of the communication stack, the timeout violation in the lpduM modules occurs at the same time than the Deadline Monitoring violation in the COM module.



7.5 Reception

Every I-PDU which is received by the Communication Hardware Abstraction (CAN Interface, Lin Interface, FlexRay Interface) is given to the PDU-Router. The PDU-Router routes multiplexed I-PDUs to the IpduM module. The IpduM module separately routes the static and dynamic parts of the multiplexed I-PDU to their destinations.

It is known at configuration-time which incoming I-PDU IDs correspond to multiplexed I-PDUs with a static part configured. The I-PDU ID is all that is necessary to work out if there is a static part present.

As all multiplexed I-PDUs contain a dynamic part this part always has to be routed.

There are no requirements to handle or notify wrongly configured parts. Hence, if the received I-PDU contains segments not configured for reception on this ECU, they will be ignored silently. Furthermore, if an I-PDU is configured with a PduLength of 0, it will also be ignored silently, since no meaningful processing can be configured.

This situation might occur in a gateway setting, if a multiplexed I-PDU is always routed onto another bus by the PDU Router, but contains a signal in one dynamic part that must be passed to the application. In this case, the multiplexed PDU would have to be routed to the IpduM as well.



7.6 Error classification

The following errors and exceptions shall be detectable by the IpduM module depending on its build version (development/production mode):

	Type or error	Relevance	Related error code	Value [hex]
SWS_lpduM_00026	API service called with	Development	IPDUM_E_PARAM	10
	wrong parameter			
SWS_lpduM_00162	API service called with	Development	IPDUM_E_PARAM_POINTER	11
	a NULL pointer. In case			
	of this error, the API			
	service shall return			
	immediately without any			
	further action, except			
	for reporting this devel-			
	opment error.			
SWS_lpduM_00153	API service used with-	Development	IPDUM_E_UNINIT	20
	out module initialization			



7.7 Error detection and notification

[SWS_IpduM_00028] [If IpduMDevErrorDetect is configured to TRUE, all IpduM APIs shall check their input parameters and report detected errors to DET by IPDUM_E_PARAM for normal parameter and IPDUM_E_PARAM_POINTER for pointer parameters.] (SRS_BSW_00338, SRS_BSW_00323)



8 API specification



8.1 Imported types

This chapter lists all imported types and the corresponding header files.

[SWS_lpduM_00102] [

Module	Imported Type
ComStack_Types	PduldType
	PduInfoType
Std_Types	Std_ReturnType
	Std_VersionInfoType

J (SRS_BSW_00357)



8.2 Type definitions

8.2.1 IpduM_ConfigType

[SWS_lpduM_00159] [

<u> </u>	4
Name:	IpduM_ConfigType
Туре:	Structure
Range:	Implementation specific.
•	This is the type of the data structure containing the initialization data for the I-PDU multiplexer.

J (SRS_BSW_00438)



8.3 Function definitions

This is a list of functions provided for upper layer modules.

8.3.1 IpduM Init

[SWS_lpduM_00032] [

<u>[0110_ipaaiii_00</u>			
Service name:	lpduM_Init		
Syntax:	void IpduM_Init(
	<pre>const IpduM_ConfigType* config</pre>		
Service ID[hex]:	0x00		
Sync/Async:	Synchronous		
Reentrancy:	Non Reentrant		
Parameters (in):	config Implementation specific structure with configuration parameters.		
Parameters (inout):	None		
Parameters (out):	None		
Return value:	None		
Description:	Initializes the I-PDU Multiplexer.		

(SRS BSW 00344, SRS BSW 00405, SRS BSW 00101, SRS BSW 00369)

[SWS_lpduM_00033] [The function lpduM_Init shall initialize all module-related global variables. | (SRS_BSW_00101)

[SWS_IpduM_00083] [In case, the configuration parameter IpduMDevErrorDetect equals TRUE: if the parameter config does not reference a valid configuration, the function IpduM_Init shall raise the development error IPDUM_E_PARAM_POINTER. | (SRS_BSW_00406)

[SWS_lpduM_00084] [The behavior of the lpduM is unspecified until a correct call to lpduM_Init is made. | (SRS_BSW_00406)

8.3.2 IpduM_GetVersionInfo

[SWS_lpduM_00037] [

Service name:	lpduM_GetVersionInfo
Syntax:	void IpduM_GetVersionInfo(
	Std_VersionInfoType* versioninfo
)
Service ID[hex]:	0x01
Sync/Async:	Synchronous
Reentrancy:	Reentrant
Parameters (in):	None
Parameters (inout):	None
Parameters (out):	versioninfo Pointer to where to store the version information of this module.
Return value:	None
Description:	Service returns the version information of this module.



| (SRS_BSW_00407, SRS_BSW_00369, SRS_BSW_00003)

8.3.3 IpduM_Transmit

[SWS_lpduM_00043] [

<u>[3443_ipaaivi_00</u>	0-10]		
Service name:	IpduM_Transmit		
Syntax:	Std_ReturnType IpduM_Transmit(
	PduIdType PdumTxPduId,		
	const Pd	uInfoType* PduInfoPtr	
)		
Service ID[hex]:	0x03		
Sync/Async:	Synchronous		
Reentrancy:	Non Reentrant for	or the same PDU-ID. Reentrant for different PDU-ID.	
	PdumTxPduId	ID of I-PDU to be transmitted.	
		Range: 0(maximum number of I-PDU IDs which are multiplexed)	
Parameters (in):		- 1	
	PduInfoPtr	A pointer to a structure with I-PDU related data that shall be	
		transmitted: data length and pointer to I-SDU buffer	
Parameters (inout):	None		
Parameters (out):	None		
Return value:	Std_ReturnType	E_OK: Transmit request is accepted	
		E_NOT_OK: Transmit request is not accepted	
Description:	Service is called	by the PDU-Router to request a transmission.	

[(SRS_BSW_00369)

For a detailed description read Chapter 7.4.1.



8.4 Call-back notifications

8.4.1 **IpduM_RxIndication**

[SWS_lpduM_00040] [

<u>[3443_ipuulvi_00</u>	0+0]		
Service name:	lpduM_RxIndication		
Syntax:	void IpduM_RxIndication(
	PduIdType RxPduId,		
	const PduInfoType* PduInfoPtr		
)		
Service ID[hex]:	0x42		
Sync/Async:	Synchronous		
Reentrancy:	Reentrant for different Pdulds. Non reentrant for the same Pduld.		
	RxPduld ID of the received I-PDU.		
Parameters (in):	PduInfoPtr Contains the length (SduLength) of the received I-PDU and a pointer to a buffer (SduDataPtr) containing the I-PDU.		
Parameters (inout):	None		
Parameters (out):	None		
Return value:	None		
Description:	Indication of a received I-PDU from a lower layer communication interface module.		

| (SRS_BSW_00369; SRS_lpduM_02817)

[SWS_lpduM_00041] [If there is a static part configured in a multiplexed SDU received from the PDU-R, the function lpduM_RxIndication transforms the incoming I-PDU ID into the correct I-PDU ID for the static part's destination and then forwards the SDU via the PDU-R, see PduR_lpduMRxIndication in the PDU-R SWS.] (SRS_lpduM_02812)

[SWS_lpduM_00042] [When a multiplexed I-PDU is received from the PDU-R the function lpduM_RxIndication uses the incoming I-PDU ID and the selector field to find out the correct I-PDU ID for the dynamic part's destination and then forwards the I-PDU via the PDU-R, see PduR_IpduMRxIndication in the PDU-R SWS.] (SRS_IpduM_02812)

[SWS_lpduM_00086] [The function lpduM_RxIndication shall be callable in interrupt context, e.g. from receive interrupt.] (SRS_lpduM_02812)

8.4.2 IpduM_TxConfirmation

[SWS_lpduM_00044] [

<u>[0110paa.n_cc</u>	•]		
Service name:	IpduM_TxConf	firmation	
Syntax:	void IpduM TxConfirmation(
	PduIdTy	pe TxPduId	
)		
Service ID[hex]:	0x40		
Sync/Async:	Synchronous		
Reentrancy:	Reentrant for different Pdulds. Non reentrant for the same Pduld.		
Parameters (in):	TxPduld	ID of the I-PDU that has been transmitted.	
Parameters (inout):	None		



Parameters (out):	None
Return value:	None
	The lower layer communication interface module confirms the transmission of an I-PDU.

(SRS_BSW_00369)

[SWS_lpduM_00088] [The function lpduM_TxConfirmation shall translate the confirmation received from the PDU-Router into confirmations for the I-PDUs which where contained in the sent multiplexed I-PDU.] (SRS_lpduM_02814)

These confirmations are given again to the PDU-Router that has to route them to COM.

[SWS_lpduM_00087] [The function lpduM_TxConfirmation shall be callable in interrupt context, e.g. from a transmit interrupt. | (SRS_lpduM_02814)

8.4.3 IpduM_TriggerTransmit

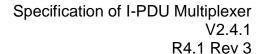
[SWS_lpduM_00060] [

Service name:	lpduM_TriggerTr	ansmit
Syntax:	PduIdType	pe IpduM_TriggerTransmit(e TxPduId, ype* PduInfoPtr
Service ID[hex]:	0x41	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant for diff	erent Pdulds. Non reentrant for the same Pduld.
	TxPduld	ID of the SDU that is requested to be transmitted.
Parameters (in):	PduInfoPtr	Contains a pointer to a buffer (SduDataPtr) to where the SDU data shall be copied. On return, the service will indicate the length of the copied SDU data in SduLength.
Parameters (inout):	None	
Parameters (out):	None	
Return value:	Std_ReturnType	E_OK: SDU has been copied and SduLength indicates the number of copied bytes. E_NOT_OK: No SDU data has been copied. PduInfoPtr must not be used since it may contain a NULL pointer or point to invalid data.
	buffer provided b copied data in Po	ne upper layer module (called module) shall copy its data into the y PduInfoPtr->SduDataPtr and update the length of the actual duInfoPtr->SduLength.

I (SRS BSW 00369)

[SWS_lpduM_00090] [The function lpduM_TriggerTransmit shall copy the contents of its I-PDU transmit buffer to the I-PDU buffer given by PduInfoPtr.] (SRS_lpduM_02810)

[SWS_lpduM_00091] [The lpduM shall take care about the data consistency during providing the data.] (SRS_lpduM_02810)





Use case: This function is used e.g. by the LIN Master for sending out a LIN frame. In this case, the trigger transmit can be initiated by the Master schedule table itself or a received LIN header.

This function is also used by the FlexRay Interface for requesting PDUs to be sent in static part (synchronous to the FlexRay global time).

[SWS_lpduM_00089] [The function lpduM_TriggerTransmit shall be callable in interrupt context. | (SRS_lpduM_02810)



8.5 Scheduled functions

Most of the functions of the IpduM module are called synchronous in the context of the upper layer (for transmission) and in the context of the lower layer (for reception). However, for the TxConfirmation timeout timer a scheduled function is needed.

[SWS_lpduM_00103] [

<u> </u>	
Service name:	IpduM_MainFunction
Syntax:	void IpduM_MainFunction(
	void
)
Service ID[hex]:	0x10
Description:	Performs the processes of the activities that are not directly initiated by the calls
	from PDU-R.

(SRS_BSW_00425)

[SWS_lpduM_00101] [The function lpduM_MainFunction shall perform the processing of the lpduM activities that are not directly initiated by the calls from PDU-R. This includes at least the TxConfirmation time observation.] (SRS_lpduM_02813)



8.6 Expected Interfaces

In this chapter, all interfaces required from other modules are listed.

8.6.1 Mandatory Interfaces

This chapter defines all interfaces that are required to fulfill the core functionality of the module.

[SWS_I	pduM 0	01	041	ſ

API function	Descr	iption

Actually, the IpduM module needs no APIs of other modules compulsorily, since the IpduM module could be used only for reception or transmission of multiplexed I-PDUs. In such a case the not used reception or transmission APIs of the PduR are optional. Hence, depending on the use-case all used APIs are optional. ()

8.6.2 Optional Interfaces

This chapter defines all interfaces that are required to fulfill an optional functionality of the module.

[SWS_lpduM_00105] [

API function	Description
Det_ReportError	Service to report development errors.
PduR_lpduMTransmit	Requests transmission of an I-PDU.
PduR_lpduMRxIndication	Indication of a received I-PDU from a lower layer communication interface module.
PduR_lpduMTriggerTransmit	Within this API, the upper layer module (called module) shall copy its data into the buffer provided by PduInfoPtr->SduDataPtr and update the length of the actual copied data in PduInfoPtr->SduLength.
PduR_lpduMTxConfirmation	The lower layer communication interface module confirms the transmission of an I-PDU.

] ()

8.6.3 Configurable interfaces

Not applicable



9 Sequence diagrams



9.1 Transmission of a multiplexed I-PDU and Transmit confirmation

The following sequence chart shows a transmit request initiated by the COM layer. The transmit request is for an I-PDU which has to be transmitted within a multiplexed I-PDU. In the IpduM module is configured that this transmitted I-PDU triggers the sending of the multiplexed I-PDU.



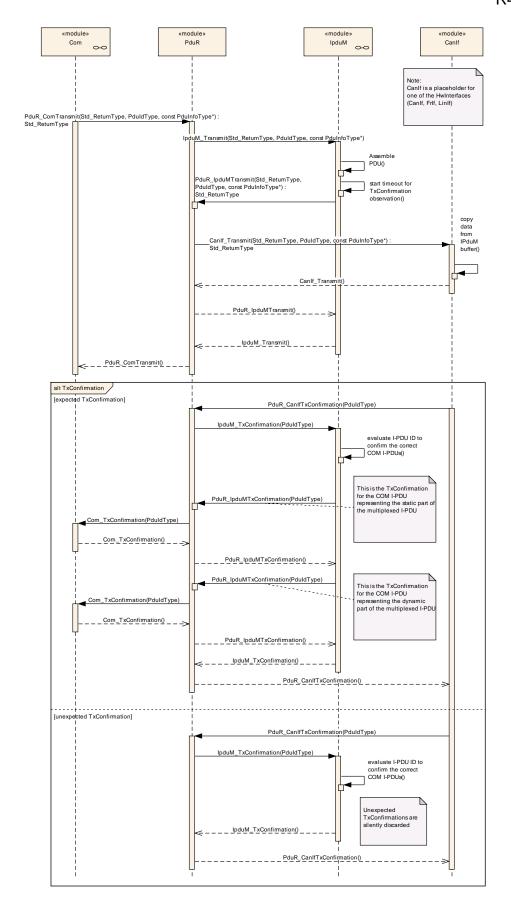


Figure 4 Transmission and confirmation of multiplexed I-PDU with triggering



9.2 Transmission of a multiplexed I-PDU without Trigger

The following sequence chart shows a transmit request initiated by the COM layer. Because of the configuration of the IpduM, no transmit request for the IpduM I-PDU takes place. For configuration see ECUC_lpudM_00052.

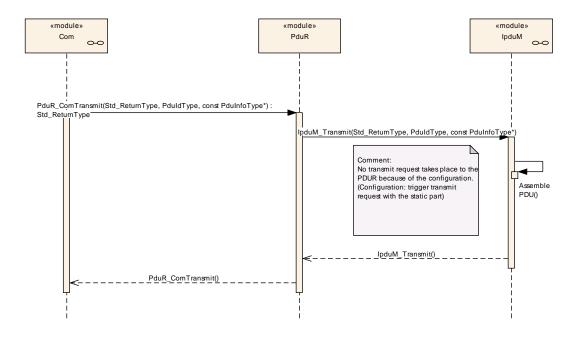


Figure 5 Transmission of a multiplexed I-PDU without triggering



9.3 Reception of the multiplexed I-PDU

The following sequence chart shows a reception of a multiplexed I-PDU. The I-PDU contains a static and a dynamic part and both are configured to create an RxIndication to the PDU-R module.

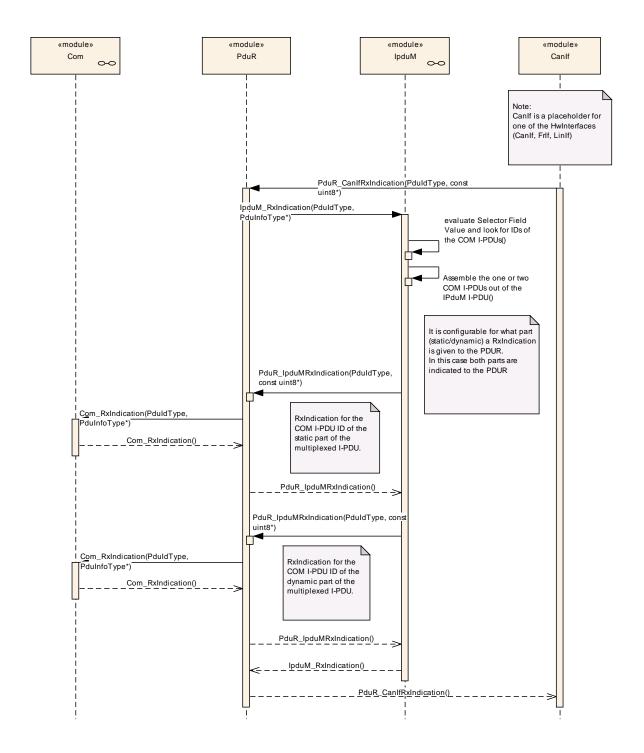


Figure 6 Reception of a multiplexed I-PDU



9.4 Trigger Transmit

The following sequence chart shows a Trigger Transmit request from an interface layer.

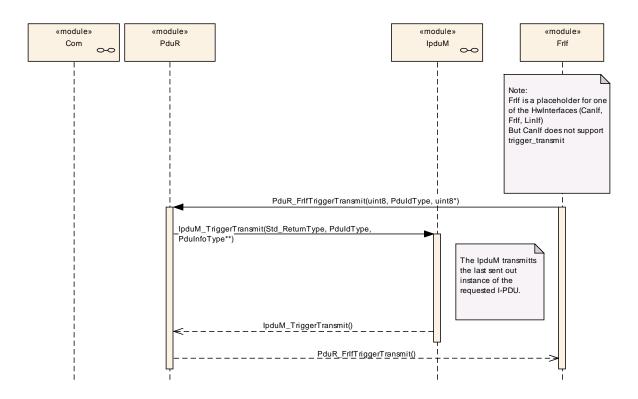


Figure 7 Trigger Transmit request from interface layer



9.5 Missing Transmit Confirmation

The following sequence chart shows the case that a TxConfirmation is not received by the IpduM module during the TX Confirmation timeout. After the timeout has elapsed, it is allowed to send the I-PDU again.

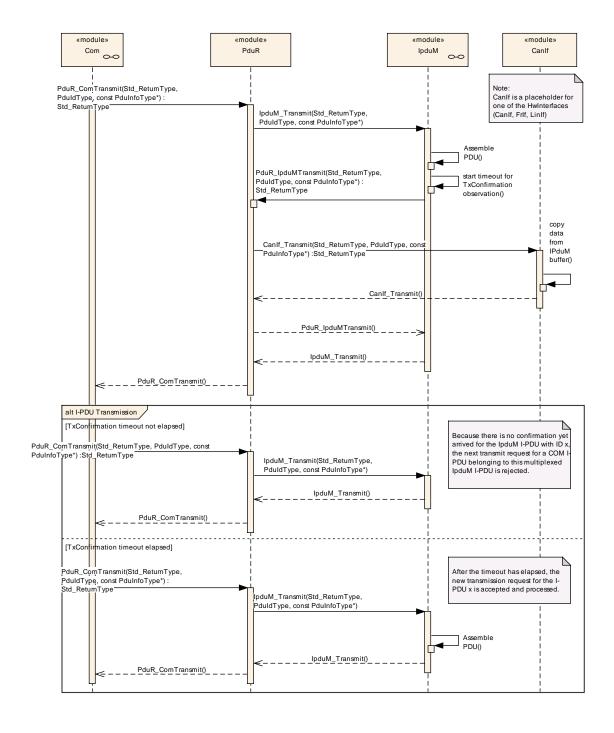


Figure 8 Missing Transmit Confirmation



10 Configuration specification

In general, this chapter defines configuration parameters and their clustering into containers.

Chapter 10.2 specifies the structure (containers) and the parameters of the module IpduM.

Chapter 10.3 specifies published information of the module IpduM.



10.1 How to read this chapter

For details, refer to the chapter 10.1 Introduction to configuration specification in SWS_BSWGeneral.



10.2 Containers and configuration parameters

The following chapters summarize all configuration parameters. The detailed meanings of the parameters describe Chapters 7 and Chapter 8.

10.2.1 Variants

There are three variants called: VARIANT-PRE-COMPILE, VARIANT-LINK-TIME and VARIANT-POST-BUILD.

The VARIANT-PRE_COMPILE is designed for modules that are purely configured at pre-compile time. In this variant, all configuration parameters are fixed at compile-time.

The VARIANT-LINK-TIME is designed for the use case where parameters that affect code generation are fixed at compile-time and all other configuration parameters are fixed at link-time.

The VARIANT-POST-BUILD is designed for parameters that affect code generation to be fixed at compile-time and all other parameters to be fixed at post build-time.

10.2.2 Configuration overview

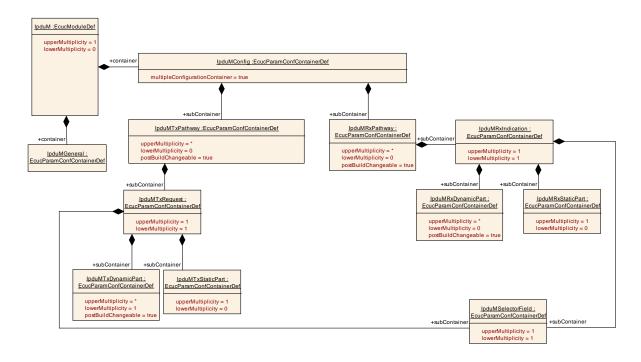


Figure 9 IpduM Configuration Overview



10.2.3 lpduM

Module Name	lpduM
Module Description	Configuration of the IpduM (Ipdu Multiplexer) module.

Included Containers					
Container Name Multipli		Scope / Dependency			
IpduMConfig	1	This container contains the sub containers of the IpduM module. The IpduMTxPathway subcontainer includes information about sent I-PDUs. The IpduMRxPathway includes information about received I-PDUs. This container is a MultipleConfigurationContainer, i.e. this container and its sub-containers exist once per configuration set.			
IpduMGeneral	1	Contains the general configuration parameters of IpduM.			
IpduMPublishedInformation	1	Additional published parameters not covered by CommonPublishedInformation container. Note that these parameters do not have any configuration class setting, since they are published information.			

10.2.4 IpduMConfig

SWS Item	ECUC_lpduM_00059:		
Container Name	IpduMConfig [Multi Config Container]		
Description	This container contains the sub containers of the IpduM module. The IpduMTxPathway subcontainer includes information about sent I-PDUs. The IpduMRxPathway includes information about received I-PDUs. This container is a MultipleConfigurationContainer, i.e. this container and its sub-containers exist once per configuration set.		
Configuration Parameters			

SWS Item	ECUC_lpduM_00166:	ECUC_lpduM_00166:			
Name	IpduMMaxTxBufferSize	lpduMMaxTxBufferSize			
Description		Maximum total size of all Tx buffers. This parameter is needed only in case of post-build loadable implementation using static memory allocation.			
Multiplicity	01	01			
Туре	EcucIntegerParamDef	EcucIntegerParamDef			
Range	0 65535	0 65535			
Default value					
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST- BUILD		
	Post-build time				
Scope / Dependency	scope: local				

SWS Item	ECUC_lpduM_00165:
Name	lpduMMaxTxPathwayCnt
	Maximum number of transmitted IPdus. This parameter is needed only in case of post-build loadable implementation using static memory allocation.
Multiplicity	01



Туре	EcucIntegerParamDef	EcucIntegerParamDef		
Range	0 65535	0 65535		
Default value				
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST- BUILD	
	Post-build time			
Scope / Dependency	scope: local			

Included Containers		
Container Name	Multiplicity	Scope / Dependency
IpduMRxPathway	0*	includes information about received I-PDUs
IpduMTxPathway	0*	includes information about sent I-PDUs

10.2.5 IpduMGeneral

SWS Item	ECUC_lpduM_00130:
Container Name	lpduMGeneral
Description	Contains the general configuration parameters of IpduM.
Configuration Parameters	

SWS Item	ECUC_lpduM_00131:				
Name	IpduMConfigurationTimeBase				
Description	The cycle time with which IpduM_MainFunction should be invoked (in seconds).				
Multiplicity	1	1			
Туре	EcucFloatParamDef				
Range	03600				
Default value					
ConfigurationClass	Pre-compile time	Χ	All Variants		
	Link time	1			
	Post-build time	-			
Scope / Dependency	scope: local	•			

SWS Item	ECUC_lpduM_00132:				
Name	IpduMDevErrorDetect	lpduMDevErrorDetect			
Description	Active/Deactivate the detection of development errors, for production code this parameter has to be False.				
	True: error detection activated False: error detection deactivated				
Multiplicity	1				
Туре	EcucBooleanParamDef				
Default value					
ConfigurationClass	Pre-compile time	Χ	All Variants		
	Link time				
	Post-build time	ŀ			
Scope / Dependency	scope: local				

SWS Item	ECUC_IpduM_00133:
Name	lpduMStaticPartExists
Description	This is to allow optimizations in the case the IpduM will never be used with a static part.
	Note that this is a pre-compile option. If this is set to False then it will not



	be possible to add static parts after compilation. True: A static part may exist. False: A static part will never exist.			
Multiplicity	1	1		
Туре	EcucBooleanParamDef			
Default value				
ConfigurationClass	Pre-compile time	X	All Variants	
	Link time			
	Post-build time			
Scope / Dependency	scope: local			

SWS Item	ECUC_lpduM_00134:	ECUC_lpduM_00134:		
Name	IpduMVersionInfoApi			
Description	Active/Deactivate the ve	rsion info	rmation API.	
	true: version information	true: version information activated false: version information deactivated		
Multiplicity	1	1		
Туре	EcucBooleanParamDef	EcucBooleanParamDef		
Default value				
ConfigurationClass	Pre-compile time	X	All Variants	
	Link time	Link time		
	Post-build time			
Scope / Dependency	scope: local			

d Conta	uded	Incl	No
---------	------	------	----

10.2.6 lpduMTxPathway

SWS Item	ECUC_lpduM_00070:
Container Name	lpduMTxPathway
Description	Contains the configuration parameters transmitted I-PDUs by the IpduM module.
	Attributes: postBuildChangeable=true
Configuration Parameters	

Included Containers		
Container Name	Multiplicity	Scope / Dependency
IpduMTxRequest	1	configuration for a TxRequest

10.2.7 IpduMTxRequest

SWS Item	ECUC_lpduM_00052:
Container Name	lpduMTxRequest
Description	This container is used to specify the configuration for Transmit requests. There will be one instance of this container for each I-PDU that can be requested for transmission (the outgoing I-PDUs) by the IpduM.
Configuration Parameters	



SWS Item	ECUC_lpduM_00162:			
Name	lpduMByteOrder			
Description	This parameter defines the ByteOrder for all segments (static and dynamic part) and for the selectorField within the MultiplexedPdu.			
	The absolute position of a segment in the MultiplexedIPdu is determined by the definition of the ByteOrder parameter: If BIG_ENDIAN is specified, the SegmentPosition indicates the bit position of the most significant bit in an IPDU. If LITTLE_ENDIAN is specified, the SegmentPosition indicates the bit position of the least significant bit in an IPDU.			
Multiplicity	1			
Туре	EcucEnumerationParamDef			
Range	BIG_ENDIAN			
	LITTLE_ENDIAN			
ConfigurationClass	Pre-compile time	X VARIANT-PRE-COMPILE		
	Link time	X VARIANT-LINK-TIME		
	Post-build time	X VARIANT-POST-BUILD		
Scope / Dependency	scope: local			

SWS Item	ECUC_lpduM_00121:	ECUC_lpduM_00121:		
Name	IpduMIPduUnusedArea	lpduMIPduUnusedAreasDefault		
Description	IpduM module fills not u	IpduM module fills not used areas of an I-PDU with this bit-pattern		
	If this attribute is omitte	d the IpduM module does not fill the I-PDU.		
Multiplicity	01	01		
Туре	EcucIntegerParamDef	EcucIntegerParamDef		
Range	0 255	0 255		
Default value				
ConfigurationClass	Pre-compile time	X VARIANT-PRE-COMPILE		
	Link time X VARIANT-LINK-TIME			
	Post-build time	X VARIANT-POST-BUILD		
Scope / Dependency	scope: local			

SWS Item	ECUC_lpduM_00158:				
Name	IpduMTxConfirmationPduId	lpduMTxConfirmationPduId			
Description		Handle Id used by the PduR for confirmation (IpduM_TxConfirmation) and for TriggerTransmit (IpduM_TriggerTransmit).			
		The existence of this parameter is essential for the PduR generation tool to actually find a symbolicNameValue for the OutgoingPdu.			
Multiplicity	01	01			
Туре	EcucIntegerParamDef (Syr	nbolic	Name generated for this parameter)		
Range	0 65535				
Default value					
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST- BUILD		
	Post-build time				
Scope / Dependency	scope: local				

SWS Item	ECUC_IpduM_00124:
Name	IpduMTxConfirmationTimeout
	This timeout (in seconds) defines the timeout period for monitoring the reception of the TxConfirmation.



	It is not used when an I-PDU is requested using the trigger transmit API.			
Multiplicity	01			
Туре	EcucFloatParamDef			
Range	0 3600			
Default value				
ConfigurationClass	Pre-compile time	Х		VARIANT-PRE-COMPILE
	Link time	Х		VARIANT-LINK-TIME
	Post-build time	Х		VARIANT-POST-BUILD
Scope / Dependency	scope: local			

SWS Item	ECUC_lpduM_00125:		
Name	lpduMTxTriggerMode		
Description	Selects whether to send the multiplexed I-PDU immediately or at some later date.		
Multiplicity	1		
Туре	EcucEnumerationParamDef		
Range	DYNAMIC_PART_TRIGGER	Writing the I-PDU representing the dynamic part does trigger a sending of the I-PDU.	
	NONE	Only the buffer in the IpduM are written but not send is triggered, used for IpduM I-PDUs which are requested by TriggerTransmit.	
	STATIC_OR_DYNAMIC_PART_TRIGGER	Writing the I-PDU representing the static or the dynamic part does trigger a sending of the I-PDU.	
	STATIC_PART_TRIGGER	Writing the I-PDU representing the static part does trigger a sending of the I-PDU.	
ConfigurationClass	Pre-compile time	X VARIANT-PRE-COMPILE	
	Link time	X VARIANT-LINK-TIME	
	Post-build time	X VARIANT-POST-BUILD	
Scope / Dependency	scope: local		

SWS Item	ECUC_lpduM_00157:			
Name	IpduMInitialDynamicPar	lpduMInitialDynamicPart		
Description	Reference to the dynam xed TX-I-PDU.	Reference to the dynamic part that shall be used to initialize this multiple- xed TX-I-PDU.		
Multiplicity	1	1		
Туре	Reference to [lpduMTx	Reference to [IpduMTxDynamicPart]		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	X	VARIANT-LINK-TIME	
	Post-build time	X	VARIANT-POST-BUILD	
Scope / Dependency	scope: local			

SWS Item	ECUC_lpduM_00120:			
Name	IpduMOutgoingPduRef	lpduMOutgoingPduRef		
Description	Reference to the PDU defin	Reference to the PDU defining the outgoing I-PDU.		
		When the outgoing I-PDU is sent this is the I-PDU ID to give it. It is the IpduM I-PDU ID of the assembled I-PDU.		
Multiplicity	1	1		
Туре	Reference to [Pdu]			
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	X	VARIANT-LINK-TIME	



	Post-build time	Χ	VARIANT-POST-BUILD
Scope / Dependency	scope: ECU		

Included Containers		
Container Name	Multiplicity	Scope / Dependency
IpduMSelectorField	1	Specifies the position of the selector field in the outgoing I-PDU.
IpduMTxDynamicPart	1*	This (These) included container(s) must exist for each unique selector field value for this outgoing IpduM I-PDU.
		The dynamic part of the multiplexed outgoing I-Pdu (referenced by IpduMOutgoingPduRef) can be separated into several segments. For each segment one IpduMTxDynamicSegment container
IpduMTxDynamicSegment	1*	shall be created that contains the location and the length of the segment.
		Please note that each configured segment will be copied out of the source I-Pdu that is referenced in the IpduMTxDynamicPart container and will be copied to the same location in the multiplexed outgoing I-Pdu. The segment layout for all dynamic Parts is always identical.
lpduMTxStaticPart	01	This included container configures the static part, if present.
lpduMTxStaticSegment	0*	The static part of the multiplexed outgoing I-Pdu (referenced by IpduMOutgoingPduRef) can be separated into several segments. For each segment one IpduMTxStaticSegment container shall be created that contains the location and the length of the segment.
		Please note that each segment in the source I-Pdu that is referenced in the IpduMTxStaticPart container will be copied to the same location in the multiplexed outgoing I-Pdu.

10.2.8 IpduMTxDynamicPart

SWS Item	ECUC_lpduM_00056:
Container Name	lpduMTxDynamicPart
Description	Configuration parameters for an instance of a TxRequest call into the IpduM. When a Tx Request with the IpduMTxDynamicHandleId is received by the IpduM, all segments (defined in the IpduMDynamicSegment container) are copied from the incoming I-PDU into the outgoing I-PDU buffer and then the send mode honored. This container is used by the dynamic part of a TxRequest configuration. Therefore, for each outgoing I-PDU there will be one instance of this container for the dynamic part. Attributes: postBuildChangeable=true
Configuration Parameters	

SWS Item	ECUC_lpduM_00167:
Name	lpduMJitUpdate
Description	If configured to true fetch the data of this part Just-In-Time via the trigger-



	Transmit API of the PduR.				
Multiplicity	01	01			
Туре	EcucBooleanParamDef	EcucBooleanParamDef			
Default value	false	false			
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE		
	Link time	X	VARIANT-LINK-TIME		
	Post-build time	X	VARIANT-POST-BUILD		
Scope / Dependency	scope: local				

SWS Item	ECUC_lpduM_00163:			
Name	IpduMTxDynamicConfirmation			
Description	A transmit request can be confirmed by the lower layer. If this parameter is set to true a confirmation of the I-PDU in COM representing the dynamic part is generated.			
Multiplicity	1			
Туре	EcucBooleanParamDef			
Default value				
ConfigurationClass	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time X VARIANT-LINK-TIME			
	Post-build time X VARIANT-POST-BUILD			
Scope / Dependency	scope: local			

SWS Item	ECUC_lpduM_00127:				
Name	IpduMTxDynamicHandleId				
Description	This defines an incoming handle id. When the handle of an incoming Tx Request matches this id, the configured dynamic segments are copied and the IpduMTxTriggerMode is honored.				
Multiplicity	1	1			
Type	EcucIntegerParamDef (Sym	EcucIntegerParamDef (Symbolic Name generated for this parameter)			
Range	0 65535	0 65535			
Default value					
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST- BUILD		
	Post-build time				
Scope / Dependency	scope: ECU				

SWS Item	ECUC_lpduM_00126:	ECUC_lpduM_00126:			
Name	IpduMTxDynamicPduR	ef			
Description		Reference to the Pdu representation in the ECU Configuration Description exchange file to be transmitted.			
Multiplicity	1	1			
Туре	Reference to [Pdu]	Reference to [Pdu]			
ConfigurationClass	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	Link time X VARIANT-LINK-TIME			
	Post-build time	Post-build time X VARIANT-POST-BUILD			
Scope / Dependency	scope: ECU				

Included Containers		
Container Name	Multiplicity	Scope / Dependency
IpduMSegment		This is a list of all segments to be copied from the incoming I-PDU to the outgoing I-PDU.



10.2.9 IpduMTxDynamicSegment

SWS Item	ECUC_lpduM_00168:
Container Name	IpduMTxDynamicSegment
	The dynamic part of the multiplexed outgoing I-Pdu (referenced by IpduMOutgoingPduRef) can be separated into several segments. For each segment one IpduMTxDynamicSegment container shall be created that contains the location and the length of the segment.
Description	Please note that each configured segment will be copied out of the source I-Pdu that is referenced in the IpduMTxDynamicPart container and will be copied to the same location in the multiplexed outgoing I-Pdu. The segment layout for all dynamic Parts is always identical.
	Attributes: postBuildChangeable=true
Configuration Parameters	

SWS Item	ECUC_lpduM_00114:				
Name	IpduMSegmentLength				
Description	Length of the segment in bit	S.			
Multiplicity	1				
Туре	EcucIntegerParamDef	EcucIntegerParamDef			
Range	1 2032	1 2032			
Default value					
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE		
	Link time X VARIANT-LINK-TIME				
	Post-build time X VARIANT-POST-BUILD				
Scope / Dependency	scope: local				

SWS Item	ECUC_lpduM_00159:	ECUC_lpduM_00159:			
Name	IpduMSegmentPosition	lpduMSegmentPosition			
Description	Segments bit position in	n the multi	plexed Pdu.		
Multiplicity	1				
Туре	EcucIntegerParamDef	EcucIntegerParamDef			
Range	0 2031	0 2031			
Default value					
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE		
	Link time	X	VARIANT-LINK-TIME		
	Post-build time	Post-build time X VARIANT-POST-BUILD			
Scope / Dependency	scope: local	-			

No Included Containers		

10.2.10 IpduMTxStaticPart

SWS Item	ECUC_lpduM_00082:
Container Name	IpduMTxStaticPart
Description	Configuration parameters for an instance of a Tx_Request call into the IpduM. When a Tx Request with the IpduMTxStaticHandleId is received by the IpduM, all segments (defined in the IpduMStaticSegment container) are copied from the incoming I-PDU into the outgoing I-PDU buffer and



	then the send mode honored. This container is used for the static part of a
	TxRequest configuration. Therefore, for each outgoing I-PDU there will be
	one instance of this container for the static part if it exists.
Configuration Parameters	

SWS Item	ECUC_lpduM_00167:				
Name	IpduMJitUpdate	lpduMJitUpdate			
Description	If configured to true fetch the data of this part Just-In-Time via the trigger- Transmit API of the PduR.				
Multiplicity	01	01			
Туре	EcucBooleanParamDef				
Default value	false	false			
ConfigurationClass	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	Link time X VARIANT-LINK-TIME			
	Post-build time	X	VARIANT-POST-BUILD		
Scope / Dependency	scope: local				

SWS Item	ECUC_lpduM_00164:	ECUC_lpduM_00164:			
Name	IpduMTxStaticConfirma	tion			
Description	A transmit request can be confirmed by the lower layer. If this parameter is set to true a confirmation of the I-PDU in COM representing the static part is generated.				
Multiplicity	1	1			
Туре	EcucBooleanParamDef				
Default value					
ConfigurationClass	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	Link time X VARIANT-LINK-TIME			
	Post-build time X VARIANT-POST-BUILD				
Scope / Dependency	scope: local				

SWS Item	ECUC_lpduM_00129:	ECUC_lpduM_00129:			
Name	IpduMTxStaticHandleId	lpduMTxStaticHandleId			
Description	Request matches this id	This defines an incoming handle id. When the handle of an incoming Tx Request matches this id, the configured static segments are copied and the IpduMTxTriggerMode is honored.			
Multiplicity	1	1			
Туре	EcucIntegerParamDef (EcucIntegerParamDef (Symbolic Name generated for this parameter)			
Range	0 65535	0 65535			
Default value					
ConfigurationClass	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST- BUILD		
	Post-build time				
Scope / Dependency	scope: ECU				

SWS Item	ECUC_lpduM_00128:				
Name	IpduMTxStaticPduRef	IpduMTxStaticPduRef			
Description	Reference to the Pdu representation in the ECU Configuration Description exchange file to be transmitted.				
Multiplicity	1				
Туре	Reference to [Pdu]				
ConfigurationClass	Pre-compile time X VARIANT-PRE-COMPILE				
	Link time X VARIANT-LINK-TIME				
	Post-build time X VARIANT-POST-BUILD				
Scope / Dependency	scope: ECU				



Included Containers		
Container Name	Multiplicity	Scope / Dependency
IpduMSegment	() "	This is a list of all segments to be copied from the incoming I-PDU to the outgoing I-PDU.

10.2.11 IpduMTxStaticSegment

SWS Item	ECUC_lpduM_00171:
Container Name	lpduMTxStaticSegment
Description	The static part of the multiplexed outgoing I-Pdu (referenced by IpduMOutgoingPduRef) can be separated into several segments. For each segment one IpduMTxStaticSegment container shall be created that contains the location and the length of the segment. Please note that each segment in the source I-Pdu that is referenced in the IpduMTxStaticPart container will be copied to the same location in the multiplexed outgoing I-Pdu.
	Attributes: postBuildChangeable=true
Configuration Parameters	

SWS Item	ECUC_lpduM_00114:				
Name	IpduMSegmentLength				
Description	Length of the segment in bit	S.			
Multiplicity	1				
Туре	EcucIntegerParamDef	EcucIntegerParamDef			
Range	1 2032	1 2032			
Default value					
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME		
	Post-build time X VARIANT-POST-BUILD				
Scope / Dependency	scope: local				

SWS Item	ECUC_lpduM_00159:	ECUC_lpduM_00159:			
Name	IpduMSegmentPosition				
Description	Segments bit position in	n the mult	iplexed Pdu.		
Multiplicity	1	1			
Туре	EcucIntegerParamDef	EcucIntegerParamDef			
Range	0 2031	0 2031			
Default value					
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE		
	Link time	X	VARIANT-LINK-TIME		
	Post-build time	X	VARIANT-POST-BUILD		
Scope / Dependency	scope: local	•			

No Included Containers



10.2.12 IpduMRxPathway

SWS Item	ECUC_lpduM_00071:
Container Name	lpduMRxPathway
	Contains the configuration parameters received I-PDUs by the IpduM module.
	Attributes: postBuildChangeable=true
Configuration Parameters	

Included Containers		
Container Name	Multiplicity	Scope / Dependency
IpduMRxIndication	1	configuration for RxIndication

10.2.13 IpduMRxIndication

SWS Item	ECUC_lpduM_00047:
Container Name	lpduMRxIndication
Description	Contains the configuration for incoming RxIndication calls.
Configuration Parameters	

SWS Item	ECUC_lpduM_00162:			
Name	lpduMByteOrder			
Description	This parameter defines the ByteOrder for all segments (static and dynamic part) and for the selectorField within the MultiplexedPdu.			
	The absolute position of a segment in the MultiplexedIPdu is determined by the definition of the ByteOrder parameter: If BIG_ENDIAN is specified, the SegmentPosition indicates the bit position of the most significant bit in an IPDU. If LITTLE_ENDIAN is specified, the SegmentPosition indicates the bit position of the least significant bit in an IPDU.			
Multiplicity	1			
Туре	EcucEnumerationParamDef			
Range	BIG ENDIAN			
	LITTLE_ENDIAN			
ConfigurationClass	Pre-compile time	Χ	VARIANT-PRE-COMPILE	
	Link time	Χ	VARIANT-LINK-TIME	
	Post-build time	Χ	VARIANT-POST-BUILD	
Scope / Dependency	scope: local			

SWS Item	ECUC_lpduM_00109:	ECUC_lpduM_00109:				
Name	IpduMRxHandleId	lpduMRxHandleId				
Description		This is the I-PDU ID of the incoming I-PDU. If an incoming RxIndication's I-PDU ID matches this value then it is unpacked according to the specification in this container.				
Multiplicity	1	1				
Туре	EcucIntegerParamDef (Sy	EcucIntegerParamDef (Symbolic Name generated for this parameter)				
Range	0 65535	0 65535				
Default value						
ConfigurationClass	Pre-compile time	VARIANT-PRE-COMPILE				
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-			



		BUILD
	Post-build time	
Scope / Dependency	scope: ECU	

SWS Item	ECUC_lpduM_00108:			
Name	lpduMRxIndicationPduRef			
Description	Reference to the received Pdu representation in the ECU Configuration Description exchange file.			
Multiplicity	1			
Туре	Reference to [Pdu]			
ConfigurationClass	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time X VARIANT-LINK-TIME			
	Post-build time X VARIANT-POST-BUILD			
Scope / Dependency	scope: ECU			

Included Containers		
Container Name	Multiplicity	Scope / Dependency
lpduMRxDynamicPart	0*	Each of these containers contains the configuration for one value of the selector field for the incoming I-PDU's dynamic part.
lpduMRxDynamicSegment	0*	The dynamic part of the multiplexed incoming I-Pdu (referenced by IpduMRxIndicationPduRef) can be separated into several segments. For each segment one IpduMRxDynamicSegment container shall be created that contains the location and the length of the segment. Please note that each configured segment will be copied into the destination I-Pdu that is referenced in the IpduMRxDynamicPart container and will be copied from the same location in the multiplexed incoming I-Pdu. The segment layout for all dynamic Parts is always identical.
lpduMRxStaticPart		This contains the configuration for the incoming I-PDU's static part. If the incoming I-PDU has no static part then this is omitted.
lpduMRxStaticSegment	0*	The static part of the multiplexed incoming I-Pdu (referenced by IpduMRxIndicationPduRef) can be separated into several segments. For each segment one IpduMRxStaticSegment container shall be created that contains the location and the length of the segment. Please note that each configured segment will be copied into the destination I-Pdu that is referenced in the IpduMRxStaticPart container and will be copied from the same location in the multiplexed incoming I-Pdu.
lpduMSelectorField	1	This contains the location of the selector field. At run-time, the selector field is used to select which dynamic part is unpacked.

10.2.14 IpduMRxDynamicPart

SWS Item	ECUC_lpduM_00048:
Container Name	lpduMRxDynamicPart



	This container contains the configuration for the dynamic part of incoming RxIndication calls. When an incoming received I-PDU's selector field matches the IpduMRxSelectorValue, the new outgoing I-PDU for the dynamic part is constructed as defined by the segments (defined in the IpduMDynamicSegment container) and sent out with the I-PDU ID referenced by IpduMOutgoingDynamicPduRef.
Description	In case no dynamic part shall be extracted from this received I-PDU this container does not exist. This use-case can occur in case a Multiple-xedIPdu is received by an ECU which is only interested in the static part of the MultiplexedIPdu.
	Attributes: postBuildChangeable=true
Configuration Parameters	

SWS Item	ECUC_lpduM_00113:				
Name	IpduMRxSelectorValue	lpduMRxSelectorValue			
Description	This is the selector value t	hat this	container refers to.		
Multiplicity	1	1			
Туре	EcucIntegerParamDef	EcucIntegerParamDef			
Range	0 255	0 255			
Default value					
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE		
	Link time	X	VARIANT-LINK-TIME		
	Post-build time	Х	VARIANT-POST-BUILD		
Scope / Dependency	scope: local				

SWS Item	ECUC_lpduM_00112:				
Name	IpduMOutgoingDynamicPo	lpduMOutgoingDynamicPduRef			
Description		When the new I-PDU is sent out it is sent with this I-PDU ID. Reference to the sent PDU representation in the ECU Configuration Description exchange file.			
Multiplicity	1	1			
Туре	Reference to [Pdu]	Reference to [Pdu]			
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE		
	Link time	X	VARIANT-LINK-TIME		
	Post-build time X VARIANT-POST-BUILD				
Scope / Dependency	scope: ECU				

Included Containers		
Container Name	Multiplicity	Scope / Dependency
IpduMSegment	() "	The DynamicPart can be separated in multiple segments within the multiplexed PDU.

10.2.15 IpduMRxDynamicSegment

SWS Item	ECUC_lpduM_00170:
Container Name	lpduMRxDynamicSegment
Description	The dynamic part of the multiplexed incoming I-Pdu (referenced by IpduMRxIndicationPduRef) can be separated into several segments. For each segment one IpduMRxDynamicSegment container shall be created



	that contains the location and the length of the segment.	
	Please note that each configured segment will be copied into the desti on I-Pdu that is referenced in the IpduMRxDynamicPart container and be copied from the same location in the multiplexed incoming I-Pdu. To segment layout for all dynamic Parts is always identical.	
	Attributes: postBuildChangeable=true	
Configuration Parameters		

SWS Item	ECUC_lpduM_00114:				
Name	IpduMSegmentLength	lpduMSegmentLength			
Description	Length of the segment in	bits.			
Multiplicity	1	1			
Туре	EcucIntegerParamDef				
Range	1 2032	1 2032			
Default value					
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE		
	Link time	X	VARIANT-LINK-TIME		
	Post-build time X VARIANT-POST-BUILD				
Scope / Dependency	scope: local				

SWS Item	ECUC_lpduM_00159:				
Name	IpduMSegmentPosition	lpduMSegmentPosition			
Description	Segments bit position in the	multip	lexed Pdu.		
Multiplicity	1	1			
Туре	EcucIntegerParamDef				
Range	0 2031	0 2031			
Default value					
ConfigurationClass	Pre-compile time	Χ	VARIANT-PRE-COMPILE		
	Link time	Χ	VARIANT-LINK-TIME		
	Post-build time	Χ	VARIANT-POST-BUILD		
Scope / Dependency	scope: local	•			

No Included Containers

10.2.16 IpduMRxStaticPart

SWS Item	ECUC_lpduM_00049:
Container Name	IpduMRxStaticPart
Description	This container contains the configuration for the static part of incoming RxIndication calls. On reception, the new outgoing I-PDU for the static part is constructed as defined by the segments (defined in the IpduMStaticSegment container) and sent out with the I-PDU ID referenced by IpduMOutgoingStaticPduRef.
Configuration Parameters	

SWS Item	ECUC_lpduM_00115:
Name	lpduMOutgoingStaticPduRef
	When the new I-PDU is sent out it is sent with this I-PDU ID. Reference to the sent Pdu representation in the ECU Configuration Description exchan-



	ge file.		
Multiplicity	1		
Туре	Reference to [Pdu]		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: ECU		

Included Containers		
Container Name	Multiplicity	Scope / Dependency
IpduMSegment	() "	The StaticPart can be separated in multiple segments within the multiplexed PDU.

10.2.17 IpduMRxStaticSegment

SWS Item	ECUC_lpduM_00169:
Container Name	lpduMRxStaticSegment
Description	The static part of the multiplexed incoming I-Pdu (referenced by IpduMR-xIndicationPduRef) can be separated into several segments. For each segment one IpduMRxStaticSegment container shall be created that contains the location and the length of the segment. Please note that each configured segment will be copied into the destination I-Pdu that is referenced in the IpduMRxStaticPart container and will be copied from the same location in the multiplexed incoming I-Pdu. Attributes: postBuildChangeable=true
Configuration Parameters	

SWS Item	ECUC_lpduM_00114:			
Name	IpduMSegmentLength			
Description	Length of the segment in b	its.		
Multiplicity	1			
Туре	EcucIntegerParamDef	EcucIntegerParamDef		
Range	1 2032	1 2032		
Default value				
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	X	VARIANT-LINK-TIME	
	Post-build time	Х	VARIANT-POST-BUILD	
Scope / Dependency	scope: local			

SWS Item	ECUC_lpduM_00159:	ECUC_lpduM_00159:		
Name	IpduMSegmentPosition	IpduMSegmentPosition		
Description	Segments bit position in the	multip	lexed Pdu.	
Multiplicity	1	1		
Туре	EcucIntegerParamDef	EcucIntegerParamDef		
Range	0 2031	0 2031		
Default value				
ConfigurationClass	Pre-compile time	Χ	VARIANT-PRE-COMPILE	
	Link time	Χ	VARIANT-LINK-TIME	
	Post-build time	Χ	VARIANT-POST-BUILD	



Scope / Dependency	scope: local		
			_
No Included Containers			

10.2.18 IpduMSegment

SWS Item	ECUC_lpduM_00053:
Container Name	lpduMSegment
	Please note that this container is deprecated and will be removed in the future.
Description	Old description: This contains the location and the length of a segment. A segment must fit inside the I-PDU. The segment in the source I-PDU that is located at the IpduMSegmentPosition is copied to the same position in the destination I-PDU.
	Attributes: postBuildChangeable=true
Configuration Parameters	

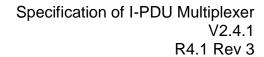
SWS Item	ECUC_lpduM_00114:	ECUC_lpduM_00114:		
Name	IpduMSegmentLength			
Description	Length of the segment in bit	S.		
Multiplicity	1			
Туре	EcucIntegerParamDef	EcucIntegerParamDef		
Range	1 2032	1 2032		
Default value				
ConfigurationClass	Pre-compile time	Χ	VARIANT-PRE-COMPILE	
	Link time	Χ	VARIANT-LINK-TIME	
	Post-build time	Χ	VARIANT-POST-BUILD	
Scope / Dependency	scope: local			

SWS Item	ECUC_lpduM_00159:	ECUC_lpduM_00159:			
Name	IpduMSegmentPosition				
Description	Segments bit position in	n the multi	plexed Pdu.		
Multiplicity	1				
Туре	EcucIntegerParamDef	EcucIntegerParamDef			
Range	0 2031	0 2031			
Default value					
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME		
	Post-build time	Х	VARIANT-POST-BUILD		
Scope / Dependency	scope: local				

Nο	Included	Containers
IIVO	mciuaea	Containers

10.2.19 lpduMSelectorField

SWS Item	ECUC_lpduM_00054:





Container Name	lpduMSelectorField
Description	This contains the location and the length of the selector field.
Configuration Parameters	

SWS Item	ECUC_lpduM_00160:		
Name	IpduMSelectorFieldLength		
Description	Length of the selector field in bits.		
Multiplicity	1		
Туре	EcucIntegerParamDef		
Range	1 8		
Default value			
ConfigurationClass	Pre-compile time	Χ	VARIANT-PRE-COMPILE
	Link time	Χ	VARIANT-LINK-TIME
	Post-build time	Χ	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	ECUC_lpduM_00161:			
Name	IpduMSelectorFieldPosition	IpduMSelectorFieldPosition		
Description	Selector field bit position in	Selector field bit position in the multiplexed Pdu.		
Multiplicity	1	1		
Туре	EcucIntegerParamDef	EcucIntegerParamDef		
Range	0 2031			
Default value				
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME	
	Post-build time	Х	VARIANT-POST-BUILD	
Scope / Dependency	scope: local			

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No Included Containers		
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10.3 Published Information

For details refer to the Chapter 10.3 Published Information in SWS_BSWGeneral.

10.3.1 IpduMPublishedInformation

SWS Item	ECUC_lpduM_00141:
Container Name	lpduMPublishedInformation
Description	Additional published parameters not covered by CommonPublishedInformation container. Note that these parameters do not have any configuration class setting, since they are published information.
Configuration Parameters	

SWS Item	ECUC_lpduM_00142:		
Name	lpduMRxDirectComInvocation		
Description	If set to TRUE the COM invocation optimization as defined in		
	IPDUM140 is implemented.		
Multiplicity	1		
Туре	EcucBooleanParamDef		
Default value			
ConfigurationClass	Published Information	Χ	All Variants
Scope / Dependency	scope: local		

No Included Containers	
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10.4 Configuration Rules

10.4.1 Selector Field

[SWS_lpduM_00155] [The selector fields shall not cross any byte-boundary within the I-PDU.] (SRS_lpduM_02802)

Restricting the selector field to be within one byte helps avoiding endianness related problems regarding the selector field.

[SWS_lpduM_00011] [The number of values used of the selector field, i.e. values used to distinguish between different I-PDU layouts, does not have to be the whole range of possible values.] (SRS_lpduM_02803)

Example: The size of a selector field with 3 bits leads to 2³ possible selector field values; it shall be allowed to use only an arbitrary subset of these values. The used subset needs no to be contiguous.

10.4.2 Byte Order

The byte order of all segments and the selector field of a multiplexed I-PDU is restricted to be the same, see ECUC_lpduM_00162. Any necessary byte order conversion shall be handled within the COM module. The multiplexed I-PDUs in COM and lpduM have to be configured consistently to have the same endianness.

[SWS_lpduM_00166] [The endianness of signals of the de-multiplexed I-PDUs configured in COM must match the endianness of the corresponding multiplexed I-PDU in IpduM as configured per IpduMByteOrder (ECUC_lpduM_00162).] ()

The above configuration rule also restricts all COM signals of a multiplexed attribute to have the same endianness.



11 Not applicable requirements

[SWS_lpduM_00999] 「These requirements are not applicable to this specification.」 (SRS_BSW_00171, SRS_BSW_00375, SRS_BSW_00437, SRS_BSW_00168, SRS_BSW_00423, SRS_BSW_00427, BSW00431, SRS_BSW_00432, SRS_BSW_00433, BSW00434, SRS_BSW_00336, SRS_BSW_00339, SRS_BSW_00422, SRS_BSW_00417, SRS_BSW_00386, SRS_BSW_00162, SRS_BSW_00005, SRS_BSW_00164, SRS_BSW_00325, SRS_BSW_00326, SRS_BSW_00314, SRS_BSW_00377)