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# **1** Introduction and functional overview

This specification describes the functionality, APIs and the configuration of the AUTOSAR Basic Software module I-PDU Multiplexer IpduM.

PDU multiplexing means using the same PCI (Protocol Control Information) of a PDU (Protocol Data Unit) with more than one unique layout of its SDU (Service Data Unit). A selector field is a part of the SDU of the multiplexed PDU. It is used to distinguish the contents of the multiplexed PDUs from each other.

Multiplexing of PDUs is currently known from CAN, but is not restricted to this communication system.

On sender-side, the I-PDU Multiplexer module is responsible to combine appropriate I-PDUs from COM to new, multiplexed I-PDUs and send them back to the PDU-Router. On receiver-side, it is responsible to interpret the content of multiplexed I-PDUs and provide COM with its appropriate separated I-PDUs taking into account the value of the selector field.



# 2 Acronyms and abbreviations

Abbreviation / Acronym:	Description:	
IpduM	I-PDU Multiplexer	
Dynamic part	see [6]	
Static part	see [6]	
Selector field	see [6]	
Signal	see [7]	
Signal group	see [7]	
Sub part	The static or dynamic part may consist of more than one element. These	
	sub-elements are called sub-parts; see also IPDUM006 and Figure 2.	
COM I-PDU	I-PDU assembled in the COM module out of COM Signals	
IpduM I-PDU	I-PDU assembled in the IpduM module out of two COM I-PDUs	
Multiplexed I-PDU	see IpduM I-PDU	
Instance	IpduM I-PDU with one specific layout and content	



# 3 Related documentation

## 3.1 Input documents

- [1] List of Basic Software Modules AUTOSAR\_BasicSoftwareModules.pdf
- [2] Layered Software Architecture AUTOSAR\_LayeredSoftwareArchitecture.pdf
- [3] General Requirements on Basic Software Modules AUTOSAR\_SRS\_General.pdf
- [4] Specification of ECU Configuration AUTOSAR\_ECU\_Configuration.pdf
- [5] Specification of BSW Scheduler AUTOSAR\_SWS\_BSW\_Scheduler.pdf
- [6] AUTOSAR Requirements on I-PDU Multiplexer AUTOSAR\_SRS\_IPDUM.pdf
- [7] AUTOSAR Specification of Communication AUTOSAR\_SWS\_COM.pdf
- [8] AUTOSAR Basic Software Module Description Template, AUTOSAR\_BSW\_Module\_Description.pdf

# 3.2 Related standards and norms

None



# 4 Constraints and assumptions

## 4.1 Limitations

For transmission of multiplexed I-PDUs, minimum delay time observation cannot be taken into account. For more details, see [7] and 7.4.1.

# 4.2 Applicability to car domains

No restrictions.

## 4.3 Applicability to safety related environments

This document has been created in absence of a safety case and a safety plan. Thus, the direct results of this document can only be used within safety relevant systems after repeating certain process steps as required in the IEC 61508.



# 5 Dependencies to other modules

This chapter lists all the features from other modules that are used by the AUTOSAR IpduM and functionalities that are provided by AUTOSAR IpduM to other modules. Because of the position of the IpduM module in the layered architecture, it has only interfaces to the PDU-Router. See also 7.2.

Because the IpduM module deals with PDUs that are either sourced or sunk by other modules, care must be taken that shared configuration items are consistent between the modules.

# 5.1 AUTOSAR OS

**IPDUM107:** The IpduM shall not directly access the AUTOSAR OS.

## 5.2 BSW Scheduler

IpduM shall use the BSW-Scheduler to schedule its main functions, see also [5].

## 5.3 PDU-Router

The following summarizes the functionality IpduM needs from the PDU-Router (for more details see Chapter 8.6):

- Indication of incoming multiplexed I-PDUs
- Sending interface for outgoing I-PDUs
- Confirmation of I-PDUs which went out

The following list summarizes the functionality provided by the IpduM module for the PDU-Router module:

- Indication interface for incoming I-PDUs, which are de-multiplexed
- Sending interface for to be multiplexed I-PDUs
- Confirmation interface for transmitted I-PDUs



# 5.4 File structure

## 5.4.1 Code file structure

Note: This IpduM SWS does not define the code file structure completely.

**IPDUM095:** The module IpduM shall provide a file IpduM\_Lcfg.c containing the link-time configurable parameters.

**IPDUM096:** The module IpduM shall provide a file IpduM\_PBcfg.c containing the post-build time configurable parameters.

## 5.4.2 Header file structure

**IPDUM002**: The IpduM module shall comply with the following include-file structure:

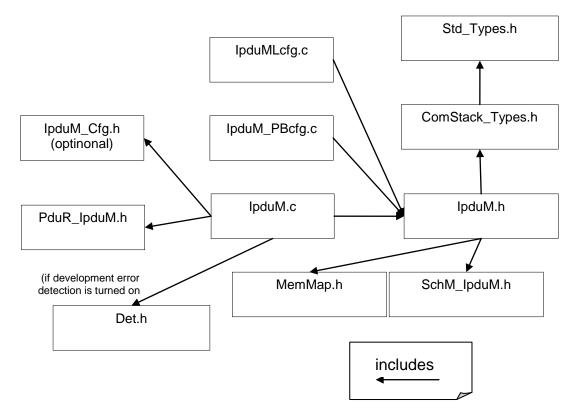


Figure 1 Header File Structure

## 5.4.3 Design Rules

**IPDUM073**: The code of the IpduM module, as long as it is written in C, shall conform to the HIS subset of the MISRA C Standard.

**IPDUM074**: The code of the IpduM module shall avoid direct use of compiler and platform specific keywords.



**IPDUM075**: The code of the IpduM module shall indicate all global data with readonly purposes by explicitly assigning the const keyword.

**IPDUM076**: The IpduM module can use macros instead of functions where source code is used and runtime is critical.

**IPDUM077**: The IpduM module shall not define global data in the header files. If global variables are used, the definition shall take place in the C file.

**IPDUM078**: The source code of the IpduM module shall not be processor and compiler dependent.



# 6 Requirements traceability

Document: AUTOSAR requirements on Basic Software [3]

Requirement         [BSW00344]         Reference to link-time configuration         [BSW00404]         Reference to post build time configuration         [BSW00405]	Satisfied by         Chapter 10.2.2, IPDUM032         Chapter 10.2         IPDUM032
Reference to link-time configuration [BSW00404] Reference to post build time configuration	Chapter 10.2
[BSW00404] Reference to post build time configuration	
Reference to post build time configuration	
	IPDUM032
Reference to multiple configuration sets	
[BSW00345]	Chapter 10.2.2, IPDUM059, IPDUM047,
Pre-compile-time configuration	<u>IPDUM048</u> , <u>IPDUM049</u> , <u>IPDUM050</u> , <u>IPDUM051</u> ,
	<u>IPDUM052</u> , <u>IPDUM053</u> , <u>IPDUM056</u>
[BSW159]	not scope of this specification
Tool-based configuration	Refers to Configuration WP.
[BSW167]	not scope of this specification
Static configuration checking	Refers to Configuration WP.
[BSW171]	not applicable
Configurability of optional functionality	(there is no optional functionality)
[BSW170]	not scope of this specification
Data for reconfiguration of AUTOSAR SW-	Refers to Configuration WP.
Components	
[BSW00380]	IPDUM095, IPDUM096
Separate C-Files for configuration parameters	implementation specific
[BSW00419]	Chapter 5.4
Separate C-Files for pre-compile time	implementation specific
configuration parameters	
[BSW00381]	Chapter 5.4
Separate configuration header file for pre-compile	
time parameters	
[BSW00412]	Chapter 5.4
Separate H-File for configuration parameters	implementation specific
[BSW00383]	not scope of this specification
List dependencies of configuration files	
[BSW00384]	Chapter 5, IPDUM104, IPDUM105
List dependencies to other modules	
[BSW00387]	Chapter 8.5
Specify the configuration class of callback functio	
[BSW00388]	Chapter 10.2, IPDUM070, IPDUM071, IPDUM082,
Introduce containers	IPDUM130
[BSW00389]	Chapter 10.2
Containers shall have names	
[BSW00390]	Chapter 10.2
Parameter content shall be unique within the	
module	
[BSW00391]	Chapter 10.2
Parameter shall have unique names	
[BSW00392]	Chapter 10.2
Parameters shall have a type	
[BSW00393]	Chapter 10.2
Parameters shall have a range	
[BSW00394]	Chapter 10.2
Specify the scope of the parameters	
[BSW00395]	All parameter in Chapter 10.2 are required.
List the required parameters (per parameter)	
[BSW00396]	Chapter 10.2
Configuration classes	
[BSW00395] List the required parameters (per parameter)	



[BC]W(00207]	Chapter 40.0
[BSW00397]	Chapter 10.2
Pre-compile-time parameters	
[BSW00398]	Chapter 10.2
Link-time parameters	
[BSW00399]	Chapter 10.2
Loadable Post-build time parameters	
[BSW00400]	Chapter 10.2
Selectable Post-build time parameters	
[BSW00438] Post Build Configuration Data	Chapter 10.2.1
Structure	
[BSW00402]	Chapter 10.3
	Chapter 10.5
Published information	
[BSW00375]	not applicable
Notification of wake-up reason	(this layer can not perform a wake-up)
[BSW101]	IPDUM032, IPDUM033, IPDUM034, IPDUM035,
Initialization interface	IPDUM064, IPDUM065, IPDUM092
[BSW00416]	not scope of this specification
Sequence of Initialization	refere to Mode Management Specification.
[BSW00406]	IPDUM083, IPDUM084
Check module initialization	
	not applicable (not readed)
[BSW00437] NoInit—Area in RAM	not applicable (not needed)
[BSW168]	not applicable
Diagnostic interface	(not diagnostic interface included)
[BSW00407]	<u>IPDUM037</u>
Function to read out published parameters	
[BSW00423]	not applicable
Usage of SW-C template to describe BSW	(this module has no connection to the RTE)
modules with AUTOSAR Interfaces	
[BSW00424]	not scope of this specification
BSW main processing function task allocation	Implementation specific
[BSW00425]	<u>IPDUM103, IPDUM131</u>
Trigger conditions for schedulable objects	
[BSW00426]	not scope of this specification
Exclusive areas in BSW modules	Implementation specific
[BSW00427]	not applicable
ISR description for BSW modules	(module does not provide ISRs)
[BSW00428]	Chapter 8.6
Execution order dependencies of main processing	
functions	
[BSW00429]	IPDUM107
Restricted BSW OS functionality access	
	n at ann Baabla
[BSW00431] The DSW Scheduler module implements took	not applicable
The BSW Scheduler module implements task	(requirement for the scheduler)
bodies	
[BSW00432]	not applicable
Modules should have separate main processing	(transmit and receive functions are called
functions for read/receive and write/transmit data	synchronous by the adjacent layers)
path	
[BSW00433]	not applicable
Calling of main processing functions	(requirement for the scheduler)
[BSW00434]	not applicable
The Schedule Module shall provide an API for	(requirement for the scheduler)
exclusive areas	
[BSW00336]	not applicable
Shutdown interface	(not needed)
[BSW00337]	<u>IPDUM026, IPDUM106</u>
Classification of errors	
[BSW00338]	IPDUM027, IPDUM028, IPDUM059, IPDUM132
Detection and Reporting of development errors	, <u></u> , <u></u> , <u></u> , <u></u>



[DCW002C0]	
[BSW00369]	IPDUM032, IPDUM037, IPDUM040, IPDUM043,
Do not return development error codes via API	
[BSW00339]	<u>IPDUM029, IPDUM030</u>
Reporting of production relevant errors and	
exceptions	
[BSW00422] Pre—de—bouncing of production	not applicable
relevant error status	(not scope of this specification)
[BSW00417]	not applicable
Reporting of Error Events by Non-Basic Software	(this module is part of the basic software)
[BSW00323]	IPDUM028
API parameter checking	
[BSW004]	IPDUM057, IPDUM038, IPDUM039, IPDUM059,
Version check	IPDUM134
[BSW00409]	Figure 1
Header files for production code error IDs	5
[BSW00385]	IPDUM026
List possible error notifications	
[BSW00386]	not applicable
Configuration for detecting an error	(implementation specific)
[BSW161]	IPDUM074, IPDUM078
Microcontroller abstraction	
[BSW162]	not applicable
ECU layout abstraction	(not scope of this specification)
[BSW005]	not applicable
No hard coded horizontal interfaces within MCAL	(not scope of this specification)
[BSW00415]	IPDUM002
User dependent include files	
[BSW164]	not applicable
Implementation of interrupt service routines	(module does not provide ISRs)
[BSW00325]	not applicable
Runtime of interrupt service routines	(module does not provide ISRs)
[BSW00326]	not applicable
Transition from ISRs to OS tasks	(module does not provide ISRs)
[BSW00342]	Chapter 10.2
Usage of source code and object code	Chapter 10.2
[BSW00343]	Chapter 10.2
	Chapter 10.2
Specification and configuration of time	Chapter 10.2
[BSW160]	Chapter 10.2
Human-readable configuration data	
[BSW007]	<u>IPDUM073</u>
HIS MISRA C	
[BSW00300]	Figure 1
Module naming convention	
[BSW00413]	not scope of this specification
Accessing instances of BSW modules	implementation specific
[BSW00347]	not scope of this specification
Naming separation of different instances of BSW	implementation specific
drivers	
[BSW00305]	Chapter 8.3.1
Self-defined data types naming convention	
[BSW00307]	not scope of this specification
Global variables naming convention	implementation specific
[BSW00310]	Chapter 8.4 and 8.5
API naming convention	
[BSW00373]	Chapter 8.6
Main processing function naming convention	
[BSW00327]	IPDUM026
Error values naming convention	
[BSW00335]	not scope of this specification



Status values naming convention	implementation specific
[BSW00350]	IPDUM027
Development error detection keyword	
[BSW00408]	Chapter 10.2
Configuration parameter naming convention	'
[BSW00410]	not scope of this specification
Compiler switches shall have defined values	implementation specific
[BSW00411]	IPDUM039
Get version info keyword	
[BSW00346]	Figure 1
Basic set of module files	5
[BSW158]	Figure 1
Separation of configuration from implementation	C
[BSW00314]	not applicable
Separation of interrupt frames and service	(module does not provide ISRs)
routines	
[BSW00370]	Chapter 8.5
Separation of callback interface from API	
[BSW00435] Module Header File Structure for the	Figure 1.
Basic Software Scheduler	
[BSW00436] Module Header File Structure for the	Figure 1.
Basic Software Memory Mapping	
[BSW00348]	Figure 1
Standard type header	
[BSW00353]	not scope of this specification
Platform specific type header	implementation specific
[BSW00361]	not scope of this specification
Compiler specific language extension header	implementation specific
[BSW00301]	not scope of this specification
Limit imported information	implementation specific
[BSW00302]	not scope of this specification
Limit exported information	implementation specific
[BSW00328]	not scope of this specification
Avoid duplication of code	implementation specific
[BSW00312]	not scope of this specification
Shared code shall be reentrant	implementation specific
[BSW006]	not scope of this specification
Platform independency	implementation specific
[BSW00357]	Chapter 8, <u>IPDUM102</u>
Standard API return type	unt nun Kantula
[BSW00377] Madula apacific A Di ratura turca	not applicable
Module specific API return types	(no specific return types)
[BSW00304] AUTOSAR integer data types	Figure 1
	implementation specific
[BSW00355]	Chapter 8.3
Do not redefine AUTOSAR integer data types	implementation specific
[BSW00378]	not scope of this specification
AUTOSAR boolean type	implementation specific
[BSW00306]	not scope of this specification
Avoid direct use of compiler and platform specific	implementation specific
keywords	
[BSW00308]	not scope of this specification
Definition of global data	implementation specific
[BSW00309]	IPDUM075, IPDUM077
Global data with read-only constraint	
[BSW00371]	Chapter 8.4 and 8.5
Do not pass function pointers via API	
[BSW00358]	Chapter 8.4.1
Return type of init functions	



[BSW00414]	Chapter 8.4.1
Parameter of init function	
[BSW00376]	Chapter 8.6
Return type and parameters of main processing	
functions	
[BSW00359]	Chapter 8.5
Return type of callback functions	
[BSW00360]	Chapter 8.5
Parameters of callback functions	
[BSW00329]	Chapter 8
Avoidance of generic interfaces	
[BSW00330]	IPDUM076, IPDUM085
Usage of macros / inline functions instead of	
functions	
[BSW00331]	Chapter 8
Separation of error and status values	
[B\$W009]	not scope of this specification
Module User Documentation	implementation specific
[BSW00401]	Chapter 10.2
Documentation of multiple instances of	
configuration parameters	
[BSW172]	not scope of this specification
Compatibility and documentation of scheduling	implementation specific
strategy	
[BSW010]	not scope of this specification
Memory resource documentation	implementation specific
[BSW00333]	not scope of this specification
Documentation of callback function context	implementation specific
[BSW00374]	Chapter 10.3
Module vendor identification	
[BSW00379]	Chapter 10.3
Module identification	
[BSW003]	IPDUM037, IPDUM057, IPDUM059
Version identification	······································
[BSW00318]	Chapter 10.3
Format of module version numbers	
[BSW00321]	not scope of this specification
Enumeration of module version numbers	implementation specific
[BSW00341]	not scope of this specification
Microcontroller compatibility documentation	implementation specific
[BSW00334]	not scope of this specification
Provision of XML file	Refers to Configuration WP

# Document: AUTOSAR requirements on Basic Software cluster IPDUM [6]

Requirement	Satisfied by
[BSW02800]	IPDUM004, IPDUM007
Exactly one selector field per PDU	
[BSW02801]	IPDUM009, IPDUM052
Size of the selector field	
[BSW02802]	<u>IPDUM005</u>
Position of the selector field	
[BSW02815]	IPDUM052
Compile Time configuration of the selector field	
[BSW02803]	IPDUM011
Unused values of the selector field	
[BSW02804]	IPDUM006, IPDUM008
Support for static and dynamic parts of the PDU	



Requirement	Satisfied by
[BSW02808]	IPDUM004, IPDUM133
Support of multiplexed PDUs with a static part of	
length "zero"	
[BSW02809]	IPDUM013, IPDUM069, IPDUM068, IPDUM067,
Initialization of multiplexed PDUs	<u>IPDUM098, IPDUM099</u>
[BSW02806]	IPDUM010
Semantic of the multiplexer	
[BSW02810]	IPDUM063, IPDUM089, IPDUM090, IPDUM091,
Routing of multiplexed PDUs on sender side	<u>IPDUM112,</u>
[BSW02816]	<u>IPDUM015</u> , <u>IPDUM017</u> , <u>IPDUM114</u> , <u>IPDUM120</u> ,
Combining of multiplexed PDUs on sender side	IPDUM121, IPDUM122, IPDUM123, IPDUM124,
	<u>IPDUM125, IPDUM126, IPDUM127, IPDUM128,</u>
	IPDUM129, IPDUM167, IPDUM168, IPDUM169
[BSW02811]	<u>IPDUM021</u> , <u>IPDUM052</u>
Triggering condition on sender side	
[BSW02812]	IPDUM041, IPDUM042, IPDUM086, IPDUM108,
Routing of multiplexed PDUs on receiver side	<u>IPDUM109</u>
[BSW02817]	IPDUM040, IPDUM113, IPDUM114, IPDUM115,
De-multiplexing PDUs on receiver side	<u>IPDUM170</u>
[BSW02813]	IPDUM022, IPDUM050, IPDUM072, IPDUM101,
Routing of Send Confirmations	<u>IPDUM117</u>
[BSW02818]	IPDUM022, IPDUM050, IPDUM051, IPDUM118,
Confirmation replication of multiplexed PDUs	IPDUM119
[BSW02814]	IPDUM023, IPDUM024, IPDUM019, IPDUM020,
Correct confirmation handling of multiplexed	IPDUM087,IPDUM088
PDUs	
[BSW02807]	<u>IPDUM097</u>
No Runtime Overhead for systems without PDU	
multiplexing	
[BSW02819]	<u>IPDUM020, IPDUM023</u>
No queuing of transmission requests on sender	
side	



# 7 Functional specification

## 7.1 Introduction and definitions

I-PDU multiplexing means using the same I-PDU ID transferred from the PDU-Router to the Communication Hardware Abstraction Layer with more than one unique layout of this I-PDU; see also [2].

**IPDUM004:** A multiplexed I-PDU consists of a static part and a dynamic part, where the static part consists of zero or more signals or signal groups. The dynamic part consists of the selector field and one or more signals or signal groups; see Figure 2.

**Note:** The dynamic part of an I-PDU is comparable with a union in "C". With help of the selector field inside the I-PDU, the actual layout of the I-PDU is selected.

**IPDUM005**: The position of the static and the dynamic part of the multiplexer shall be arbitrary and has to be configurable per I-PDU; see Figure 2, for configuration see Chapter 10.2.2.

**IPDUM006**: It shall be possible that the static and the dynamic part consist of more than one element. These elements of the static or dynamic parts are called *sub parts*.

**IPDUM007**: There shall be only one selector field within one multiplexed I-PDU.

**IPDUM008**: The value of the selector field shall define how the content of the dynamic part of the I-PDU shall be interpreted.

**IPDUM009**: The selector field of one I-PDU shall have a configurable size between one and eight contiguous bits.

**IPDUM010**: The position of the selector field within the I-PDU shall be defined by configuration.



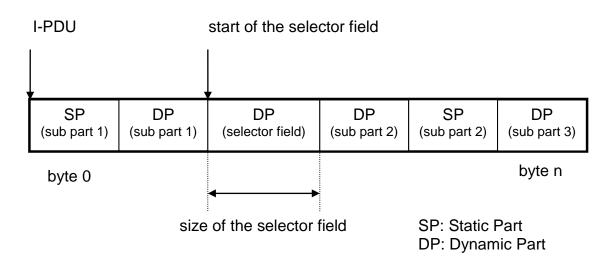


Figure 2 Possible layout of a multiplexed I-PDU

**IPDUM011**: The number of values used of the selector field, i.e. values used to distinguish between different I-PDU layouts, does not have to be the whole range of possible values.

**Example:** The size of a selector field with 3 bits leads to 2<sup>3</sup> possible selector field values; it shall be allowed to use only a part of these values.

**Note:** Multiplexing of PDUs is currently only known from CAN, but it is not restricted to this communication system.

However, because the module is layered next to the PDU-Router above the interface layer (Communication Hardware Abstraction) in the AUTOSAR layer architecture this feature also could be used with LIN or FlexRay.

## 7.2 Overview

The IpduM is arranged next to the PDU-Router in the layered architecture of AUTOSAR; see [2] and Figure 3.

**IPDUM097:** The IpduM shall be implemented so that no other modules depend on it and that it is be possible to build a system without the IpduM module if it is not needed.

**IPDUM013:** The configuration of COM shall be such that each part of a multiplexed I-PDU, the static part and the different dynamic parts, are configured as different I-PDUs in COM.



**Note:** There is one COM I-PDU for the static part and one COM I-PDU for each layout of the dynamic part of one IpduM I-PDU, so the IpduM always combines only two I-PDUs of COM.

**IPDUM098:** The IpduM module shall not set the selector field.

**IPDUM099:** The configuration of COM shall be such that the selector field is part of the COM I-PDU for the dynamic part.

**Note:** This could be realized by defining a signal for the selector field in each instance of the dynamic part. This signal is initialized with the default value by the configuration of COM but never written during runtime.

For a detailed description of the transmission and reception of a multiplexed I-PDU see Chapter 7.4 and 7.5.

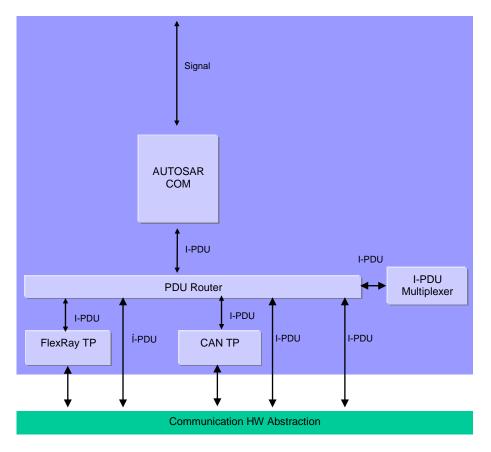


Figure 3 I-PDU Multiplexer in the Autosar Architecture

It should be allowed to optimize the receive and TxConfirmation path from the IpduM module via the PDU-Router module to the COM layer to call the COM API directly from the IpduM module without including the PDU-Router.



# 7.3 Initialization

The IpduM module provides an initialization function IpduM\_Init defined in IPDUM032. This function initializes all internal global variables and the buffers of the IpduM I-PDUs. For more details, see Chapter 8.3.1.

**IPDUM092:** The environment of the IpduM shall call IpduM\_Init before calling any other function of the IPDUM module.

For the I-PDU data transmission pathway through the IpduM module a buffer is allocated inside the IpduM module. This buffer needs to be initialized in case it is transmitted before it has been fully populated with data by COM. The initialization data for this buffer is arrived at as follows using configuration data from the IpduM\_Tx\_Request container.

- 1) **IPDUM067**: The buffer is first filled with the pattern defined in the configuration parameter IpduMIPduUnsuedAerasDefault.
- 2) **IPDUM068**: The initial selector field IpduMInitialSelectorValue is used to determine from COM's configuration the initial value of the dynamic part. The initial value of the static part is determined by COM's initial value for the incoming I-PDU.
- 3) **IPDUM069**: Finally, the selector field, indicated by the IpduMBitField container is filled with the value in the configuration parameter IpduMInitialSelectorValue.

For optimization, the initial bit pattern for the buffer can be worked out at configuration-time and then copied at run-time.

# 7.4 Transmission

Inside COM, there are separated I-PDUs for the static part and one for each dynamic part of a multiplexed I-PDU.

The static part and the dynamic parts are treated in COM as separate I-PDUs with their own I-PDU IDs.

**IPDUM063**: The configuration of the PDU-Router module (e.g. look-up tables) shall be such that the I-PDUs, which belong to multiplexed I-PDUs and represent a static or a dynamic part of a multiplexed I-PDU, are routed to the IpduM module.

**IPDUM015**: The IpduM module shall merge the two I-PDUs (the static part and the last received dynamic part) into one single I-PDU with a new unique I-PDU ID, which is sent out to the PDU-Router module.

For details about the trigger of the transmission, see Chapter 7.4.2.



**Note:** All control functionalities like deadline monitoring of the COM I-PDUs and update-bit evaluation are out of the scope of the IpduM and have to be done by the COM layer. For details about the timing-behavior of the new combined I-PDU see Chapter 7.4.2.

## 7.4.1 Transmission request

The IpduM module provides an IpduM\_Transmit function so that the PDU-R is able to initiate the transmission of an I-PDU; see <u>IPDUM043</u>.

**IPDUM017**: The function IpduM\_Transmit (called with a COM I-PDU) shall assemble the related IpduM I-PDU, using the related static and dynamic part, and transmit it according to the trigger conditions.

As defined in Chapter 7.3, each outgoing I-PDU has an initial value so that, should an I-PDU be transmitted by the IpduM module before both static and dynamic parts have been sent from COM to the IpduM, a value defined by the configuration is transmitted.

**IPDUM019**: The configuration of the IpduM shall contain a dedicated timeout for each IpduM I-PDU within the IpduM module in the configuration parameter IpduMTxConfirmationTimeout.

This timeout defines until when the transmission confirmation for this I-PDU has to be received after the transmission. For transmission confirmation see Chapter 7.4.3.

**Note:** The timeout period shall take into account the delays in the lower layers.

**IPDUM020**: As long as the timeout (defined in the configuration parameter IpduMTxConfirmationTimeout) has not elapsed and as long as no transmission confirmation for the IpduM I-PDU is received, the function IpduM\_Transmit shall not allow a new transmission request from the upper layer with a COM I-PDU that belongs to the same IpduM I-PDUs. In that case, the function IpduM\_Transmit shall return with E\_NOT\_OK.

**Note:** It maybe useful to configure the IpduM transmission confirmation timeout depended of the transmission deadline monitoring timeouts for the single COM I-PDUs of the COM layer configuration; see also [7].

### 7.4.2 Transmission trigger

The IpduM module receives the static and the dynamic part of a multiplexed I-PDU by separated two transmission requests as two single COM I-PDUs from the PDU-Router module.

**IPDUM021:** The IpduM module shall be configurable to send a transmission request for the new multiplexed I-PDU to the PDU-Router because of

• receiving a static part



- receiving a dynamic part
- receiving a static or a dynamic part
- does not trigger transmission because of receiving anything

of this I-PDU.

For configuration, see IPDUM052.

**Note:** By this mechanism, it is possible to control the transmission mode of the new assembled I-PDU by the transmission modes of the single I-PDUs sent by COM, see also [7].

**Note:** By this realization, it is not possible to guarantee the minimum delay time between consecutive transmissions of different instances of multiplexed I-PDUs, because if the transmission is triggered by static and dynamic part or only by the dynamic part, COM does not take care for the minimum delay time. COM treats the static part and the different dynamic parts as stand-alone I-PDUs, which are not connected together.

**Note:** The configuration "does not trigger transmission because of receiving anything" is needed if an I-PDU is only sent out because of a TriggerTransmit of a lower layer.

With the API lpduM\_TriggerTransmit it is possible for lower layers to trigger a send out of an I-PDU.

### 7.4.3 Just-In-Time update of parts

Sometimes it may be unwanted that the IpduM module not just sends out the locally stored parts, since these parts may contain outdated information e.g. update-bits. Therefore, the IpduM supports a per part configurable just-in-time update mechanism.

**IPDUM168**: In case the transmission of a multiplexed I-PDU is triggered by the update of one part and IpduMJitUpdate is configured to *true* for the second part, the IpduM module shall update the second part via PduR\_IpduMTriggerTransmit before the multiplexed I-PDU is sent out via PduR\_IpduMTransmit.

**IPDUM169**: In case the contents of a multiplexed I-PDU is requested via IpduM\_TriggerTransmit, the IpduM module shall update all parts which have IpduMJitUpdate configured to *true* before returning the contents of the multiplexed I-PDU.

### 7.4.4 Transmission confirmation

Transmission confirmations are given to the IpduM module by the PDU-Router according to the configuration of the I-PDUs in the PDU-Router module look-up tables.



**IPDUM022**: If the IpduM receives a TxConfirmation for a specific IpduM I-PDU, it shall translate this confirmation into the corresponding confirmations for the COM I-PDUs, which were contained in the last sent out multiplexed IpduM I-PDU.

**Note:** Depending on the configuration there are zero, one or two confirmations given to COM for one send request.

**IPDUM023**: If the TxConfirmation is not received within the configured timeout IpduMTxConfirmationTimeout the IpduM shall allow new transmission requests for this specific I-PDU after timeout is elapsed.

**IPDUM024**: The IpduM shall discard unexpected TxConfirmations silently. This may happen if a previously requested transmit has been timed out, but is confirmed now.

**Note:** There need not to be an error entry in the case of timeout violation because this is already done in COM, if needed. In the case of a proper configuration of the communication stack, the timeout violation in the IpduM modules occurs at the same time than the Deadline Monitoring violation in the COM module.

# 7.5 Reception

Every I-PDU which is received by the Hardware Abstraction Layer (CAN Interface, Lin Interface, Flexray Interface) is given to the PDU-Router. The PDU-Router routes multiplexed I-PDUs to the IpduM module. The IpduM module separately routes the static and dynamic parts of the multiplexed I-PDU to their destinations.

It is known at configuration-time which incoming I-PDU IDs correspond to multiplexed I-PDUs with a static part configured. The I-PDU ID is all that is necessary to work out if there is a static part present.

As all multiplexed I-PDUs contain a dynamic part this part always has to be routed.

There are no requirements to handle or notify wrongly configured parts. Hence, if the received I-PDU contains segments not configured for reception on this ECU, they will be ignored silently. Furthermore, if an I-PDU is configured with a PduLength of 0, it will also be ignored silently, since no meaningful processing can be configured.

This situation might occur in a gateway setting, if a multiplexed I-PDU is always routed onto another bus by the PDU Router, but contains a signal in one dynamic part that must be passed to the application. In this case, the multiplexed I-PDU would have to be routed to the IpduM as well.

## 7.6 Error classification

**IPDUM026:** The following errors and exceptions shall be detectable by the IpduM module depending on its build version (development/production mode):

Type or errorRelevanceRelated error codeValue [hex]
---



API service called with wrong parameter	Development	IPDUM_E_PARAM	10
API service used without module initialization	Development	IPDUM_E_UNINIT	20

**IPDUM106:** Development error values are of type uint8.

## 7.7 Error detection

**IPDUM027:** The detection of development errors is configurable (ON / OFF) at precompile time. The switch IpduMDevErrorDetect (see Chapter 10) shall activate or deactivate the detection of all development errors.

**IPDUM028:** If the IpduMDevErrorDetect switch is enabled API parameter checking is enabled. The detailed description of the detected errors can be found in Chapter 7.6 and Chapter 8.

**IPDUM029:** The detection of production code errors cannot be switched off.

**Note:** Actually, there are no production errors defined for the IpduM.

## 7.8 Error notification

**IPDUM030:** The IpduM module shall report detected development errors to the error hook of the Development Error Tracer (DET) if the pre-processor switch IpduMDev-ErrorDetect is set, see Chapter 10.



# 8 API specification

## 8.1 Imported types

This chapter lists all imported types and the corresponding header files.

### IPDUM102:

Module	Imported Type
ComStack_Types	PduldType
	PduInfoType
Std_Types	Std_ReturnType
	Std_VersionInfoType

## 8.2 Type definitions

### 8.2.1 IpduM\_ConfigType

· · · · ·	
Name:	IpduM_ConfigType
Туре:	Structure
Range:	Implementation specific.
Description:	This is the type of the data structure containing the initialization data for the I-PDU multiplexer.

## 8.3 Function definitions

This is a list of functions provided for upper layer modules.

## 8.3.1 IpduM\_Init

### IPDUM032:

Service name:	lpduM_Init		
Syntax:	void IpduM_Init(		
	const IpduM_ConfigType* config		
Service ID[hex]:	0x00		
Sync/Async:	Synchronous		
Reentrancy:	Non Reentrant		
Parameters (in):	config Implementation specific structure with configuration parameters.		
Parameters	None		
(inout):			
Parameters (out):	None		
Return value:	None		
Description:	Initializes the I-PDU Multiplexer.		

**IPDUM033:** The function IpduM\_Init shall initialize all module-related global variables.

**IPDUM034:** The function IpduM\_Init shall initialize all I-PDUs with the default values.



**IPDUM035:** The function IpduM\_Init shall initialize the default value of the selector field with a configurable value.

**IPDUM064:** The function IpduM\_Init shall initialize the states of the timeout monitors.

**IPDUM065:** The function IpduM\_Init shall initialize the state of the TxConfirmation IDs.

**IPDUM083:** In case, the configuration parameter IpduMDevErrorDetect equals TRUE: if the parameter config does not correspond to a valid configuration, the function IpduM\_Init shall raise the development error IPDUM E PARAM.

**IPDUM084:** The behavior of the IpduM is unspecified until a correct call to IpduM\_Init is made.

### 8.3.2 IpduM\_GetVersionInfo

#### IPDUM037:

Service name:	IpduM_GetVersionInfo		
Syntax:	void IpduM_GetVersionInfo( Std_VersionInfoType* versioninfo )		
Service ID[hex]:	0x01		
Sync/Async:	Synchronous		
Reentrancy:	Non Reentrant		
Parameters (in):	None		
Parameters (inout):	None		
Parameters (out):	versioninfo Pointer to where to store the version information of this module.		
Return value:	None		
Description:	Service returns the version information of this module.		

**IPDUM038:** The function IpduM\_GetVersionInfo shall return the version information of this module. The version information includes:

- Module ID
- Vendor ID
- Vendor specific version numbers (BSW00407).

**IPDUM039:** The function IpduM\_GetVersionInfo shall be pre compile time configurable On/Off by the configuration parameter: IpduMVersionInfoApi

**IPDUM085:** If source code for caller and callee of the function IpduM\_GetVersionInfo are available, the module IpduM should realize this function as a macro, defined in the module's header file.

## 8.3.3 IpduM\_Transmit

#### IPDUM043:



Service name:	lpduM_Transmit	
Syntax:	Std_ReturnType IpduM_Transmit( PduIdType PdumTxPduId, const PduInfoType* PduInfoPtr	
Service ID[hex]:	0x03	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant for the same PDU-ID. Reentrant for different PDU-ID.	
Parameters (in):	PdumTxPduld PduInfoPtr	ID of I-PDU to be transmitted. Range: 0(maximum number of I-PDU IDs which are mutliplexed) - 1 A pointer to a structure with I-PDU related data that shall be transmitted: data length and pointer to I-SDU buffer
Parameters (inout):	None	
Parameters (out):	None	
Return value:	Std_ReturnTypeE_OK: Transmit request is accepted E_NOT_OK: Transmit request is not accepted	
Description:	Service is called by the PDU-Router to request a transmission.	

For a detailed description read Chapter 7.4.1.

## 8.4 Call-back notifications

### 8.4.1 IpduM\_RxIndication

#### **IPDUM040:**

Service name:	IpduM_RxIndication		
Syntax:	void IpduM_RxIndication(		
	PduIdType PdumRxPduId,		
	const PduInfoType* PduInfoPtr		
Service ID[hex]:	0x02		
Sync/Async:	Synchronous		
Reentrancy:	Non Reentrant for the same PDU-ID. Reentrant for different PDU-ID.		
	PdumRxPduId ID of I-PDU that has been received.		
Parameters (in):	PduInfoPtr	Contains the length (SduLength) of the received I-PDU and a pointer to a buffer (SduDataPtr) containing the I-PDU.	
Parameters (inout):	None		
Parameters (out):	None		
Return value:	None	None	
Description:	Service is called when a multiplexed SDU has to be de-multiplexed.		

**IPDUM041:** If there is a static part configured in a multiplexed SDU received from the PDU-R the function IpduM\_RxIndication transforms the incoming I-PDU ID into the correct I-PDU ID for the static part's destination and then forwards the SDU via the PDU-R, see PduR\_IpduMRxIndication in the PDU-R SWS.

**IPDUM042:** When a multiplexed I-PDU is received from the PDU-R the function IpduM\_RxIndication uses the incoming I-PDU ID and the selector field to find out the



correct I-PDU ID for the dynamic part's destination and then forwards the I-PDU via the PDU-R, see PduR\_IpduMRxIndication in the PDU-R SWS.

**IPDUM170:** Within the function IpduM\_RxIndication, the IpduM module shall check the received data length (PduInfoPtr->SduLength) and process only completely received static or dynamic parts.

**Note:** The selector field is part of the dynamic part. Therefore, a dynamic part can only be received, if the selector field is also received.

**IPDUM086:** The function IpduM\_RxIndication shall be callable in interrupt context, e.g. from receive interrupt.

### 8.4.2 IpduM\_TxConfirmation

#### IPDUM044:

Service name:	IpduM_TxConfirmation		
Syntax:	void IpduM_TxConfirmation( PduIdType PdumTxPduId )		
Service ID[hex]:	0x04		
Sync/Async:	Synchronous		
Reentrancy:	Non Reentrant for the same PDU-ID. Reentrant for different PDU-ID.		
Parameters (in):	PdumTxPduId ID of multiplexed I-PDU that has been transmitted. Range: 0(maximum number of I-PDU IDs which are multiplexed) - 1		
Parameters (inout):	None		
Parameters (out):	None		
Return value:	None		
Description:	This function is called by the lower layer after the I-PDU has been transmitted on the network.		

**IPDUM088:** The function IpduM\_TxConfirmation shall translate the confirmation received from the PDU-Router into confirmations for the I-PDUs which where contained in the sent multiplexed I-PDU.

**Note:** These confirmations are given again to the PDU-Router that has to route them to COM.

**IPDUM087:** The function IpduM\_TxConfirmation shall be callable in interrupt context, e.g. from transmit interrupt.

### 8.4.3 IpduM\_TriggerTransmit

#### IPDUM060:

Service name:	IpduM_TriggerTransmit
Syntax:	Std_ReturnType IpduM_TriggerTransmit( PduIdType PdumTxPduId,



	PduInfoType* PduInfoPtr		
	)		
Service ID[hex]:	0x05		
Sync/Async:	Synchronous	Synchronous	
Reentrancy:	Non Reentrant for the same PDU-ID. Reentrant for different PDU-ID.		
Parameters (in):	PdumTxPduld	ID of IpduM I-PDU that is requested to be transmitted by IpduM.	
Parameters (inout):		Contains a pointer to a buffer (SduDataPtr) to where the SDU shall be copied to. On return, the service will indicate the length of the copied SDU data in SduLength.	
Parameters (out):	None		
Return value:		E_OK: SDU has been copied and SduLength indicates the number of copied bytes. E_NOT_OK: No SDU has been copied. SduLength has not been set.	
Description:	Service is called	by the lower layer when an IpduM I-PDU shall be transmitted.	

**IPDUM090:** The function IpduM\_TriggerTransmit shall copy the contents of its I-PDU transmit buffer to the I-PDU buffer given by SduPtr.

**IPDUM091:** The IpduM shall take care about the data consistency during providing the data.

**Use case:** This function is used e.g. by the LIN Master for sending out a LIN frame. In this case, the trigger transmit can be initiated by the Master schedule table itself or a received LIN header.

This function is also used by the FlexRay Interface for requesting PDUs to be sent in static part (synchronous to the FlexRay global time).

**IPDUM089:** The function IpduM\_TriggerTransmit shall be callable in interrupt context.

# 8.5 Scheduled functions

Most of the functions of the IpduM module are called synchronous in the context of the upper layer (for transmission) and in the context of the lower layer (for reception). However, for the TxConfirmation timeout timer a scheduled function is needed.

### IPDUM103:

Service name:	IpduM_MainFunction	
Syntax:	void IpduM_MainFunction(	
Service ID[hex]:	0x10	
Timing:	FIXED_CYCLIC_WITH_PRECONDITION	
Description:	Performs the processes of the activities that are not directly initiated by the calls from PDU-R.	

**IPDUM101:** The function IpduM\_MainFunction shall perform the processing of the IpduM activities that are not directly initiated by the calls from PDU-R. This includes at least the TxConfirmation time observation.



**IPDUM072:** The configuration of the BSWM Scheduler shall be such that the cycle time is equal to the smallest IpduMTxConfirmationTimeout.



## 8.6 Expected Interfaces

In this chapter, all interfaces required from other modules are listed.

### 8.6.1 Mandatory Interfaces

This chapter defines all interfaces that are required to fulfill the core functionality of the module.

#### IPDUM104:

API function	Description
PduR_IpduMRxIndication	Rx indicator for the IpduM
PduR_IpduMTxConfirmation	Tx confirmation for the IpduM

#### 8.6.2 Optional Interfaces

This chapter defines all interfaces that are required to fulfill an optional functionality of the module.

#### IPDUM105:

API function	Description
Det_ReportError	Service to report development errors.
PduR_lpduMTransmit	Requests a transmission for the IpduM
PduR_IpduMTriggerTransmit	pduM requests the buffer of the SDU for transmission from the PduR.

### 8.6.3 Configurable interfaces

Not applicable



# 9 Sequence diagrams

## 9.1 Transmission of a multiplexed I-PDU and Transmit confirmation

The following sequence chart shows a transmit request initiated by the COM layer. The transmit request is for an I-PDU which has to be transmitted within a multiplexed I-PDU. In the IpduM module is configured that this transmitted I-PDU triggers the sending of the multiplexed I-PDU.



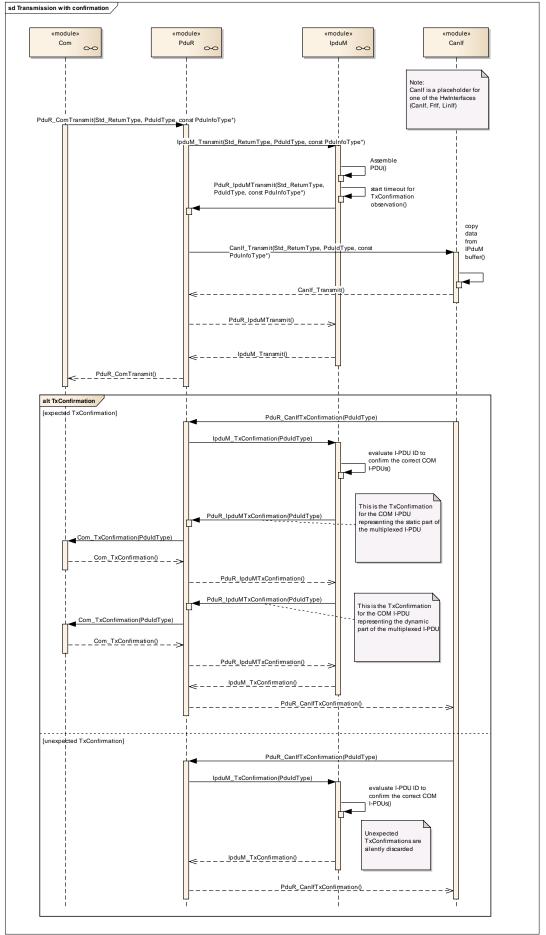




Figure 4 Transmission and confirmation of multiplexed I-PDU with triggering



# 9.2 Transmission of a multiplexed I-PDU without Trigger

The following sequence chart shows a transmit request initiated by the COM layer. Because of the configuration of the IpduM, no transmit request for the IpduM I-PDU takes place. For configuration see <u>IPDUM052</u>.

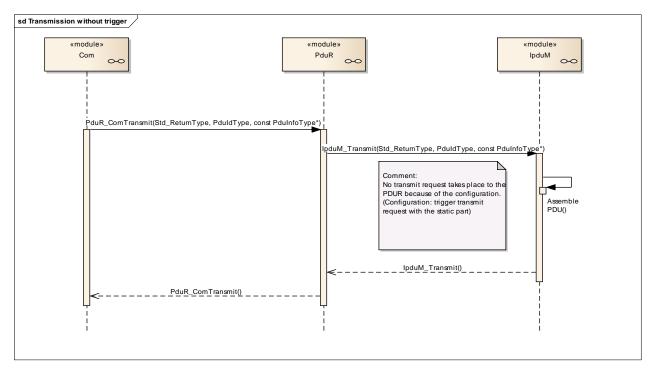


Figure 5 Transmission of a multiplexed I-PDU without triggering



# 9.3 Reception of the multiplexed I-PDU

The following sequence chart shows a reception of a multiplexed I-PDU. The I-PDU contains a static and a dynamic part and both are configured to create an RxIndication to the PDU-R module.

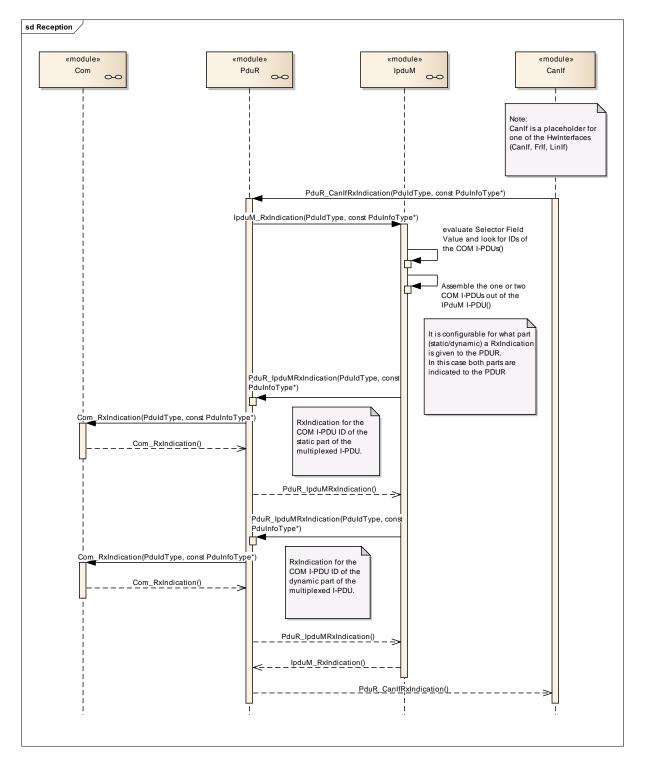


Figure 6 Reception of a multiplexed I-PDU



# 9.4 Trigger Transmit

The following sequence chart shows a Trigger Transmit request from an interface layer.

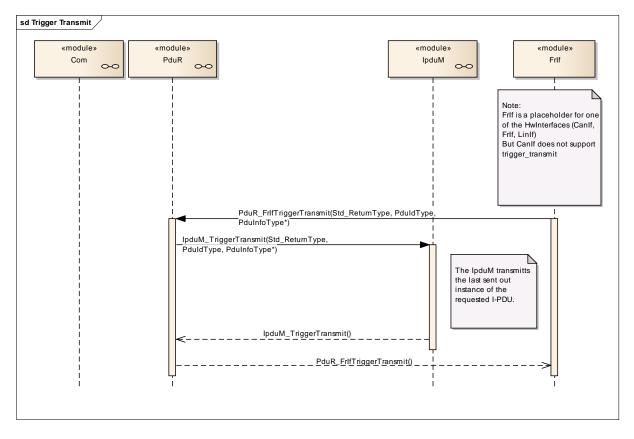


Figure 7 Trigger Transmit request from interface layer



# 9.5 Missing Transmit Confirmation

The following sequence chart shows the case that a TxConfirmation is not received by the IpduM module during the TX Confirmation timeout. After the timeout has elapsed, the I-PDU is allowed to be sent again.

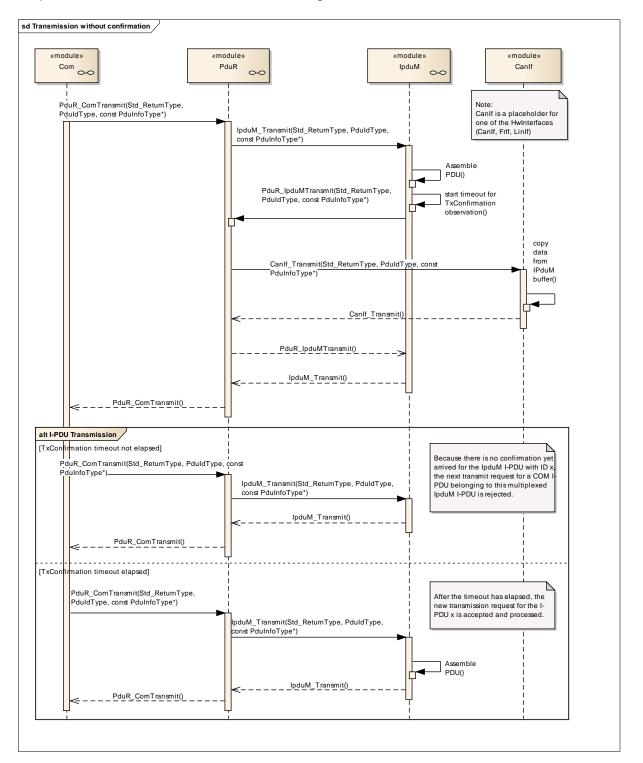


Figure 8 Missing Transmit Confirmation



# **10** Configuration specification

In general, this chapter defines configuration parameters and their clustering into containers. In order to support the specification Chapter 10.1 describes fundamentals. It also specifies a template (table) you shall use for the parameter specification. We intend to leave Chapter 10.1 in the specification to guarantee comprehension.

Chapter 10.2 specifies the structure (containers) and the parameters of the module IpduM.

Chapter 10.3 specifies published information of the module IpduM.

# **10.1** How to read this chapter

In addition to this section, it is highly recommended to read the documents:

- AUTOSAR Layered Software Architecture [2]
- AUTOSAR ECU Configuration Specification [4]
- This document describes the AUTOSAR configuration methodology and the AUTOSAR configuration Metamodel in detail.

The following is only a short survey of the topic and it will not replace the ECU Configuration Specification document.

### **10.1.1** Configuration and configuration parameters

Configuration parameters define the variability of the generic part(s) of an implementation of a module. This means that only generic or configurable module implementation can be adapted to the environment (software/hardware) in use during system and/or ECU configuration.

The configuration of parameters can be achieved at different times during the software process: before compile time, before link time or after build time. In the following, the term "configuration class" (of a parameter) shall be used in order to refer to a specific configuration point in time.

### 10.1.2 Containers

Containers structure the set of configuration parameters. This means:

- all configuration parameters are kept in containers.
- (sub-) containers can reference (sub-) containers. It is possible to assign a multiplicity to these references. The multiplicity then defines the possible number of instances of the contained parameters.



# **10.2 Containers and configuration parameters**

The following chapters summarize all configuration parameters. The detailed meanings of the parameters describe Chapters 7 and Chapter 8.

### 10.2.1 Variants

The IpduM module has the following three configuration variants:

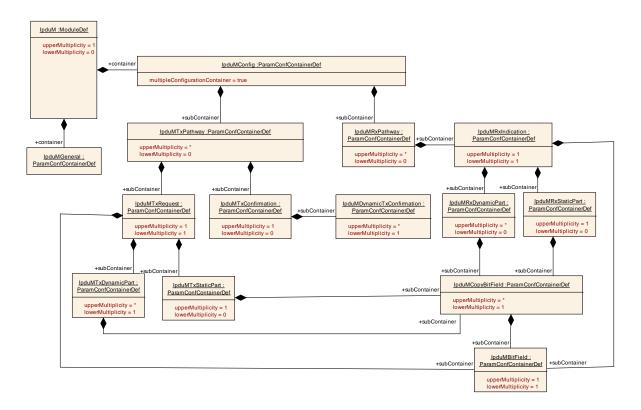
- VARIANT-PRE-COMPILE
- VARIANT-LINK-TIME
- VARIANT-POST-BUILD

The VARIANT-PRE-COMPILE is designed to support the use-case where all parameters are fixed at compile-time.

The VARIANT-LINK-TIME is designed for the use case where parameters that affect code generation are fixed at compile-time and all other configuration parameters are fixed at link-time.

The VARIANT-POST-BUILD is designed for parameters that affect code generation to be fixed at compile-time and all other parameters to be fixed at post build-time.

### 10.2.2 Configuration overview







### 10.2.3 IpduM

Module Name	IpduM
Module Description	Configuration of the IpduM (Ipdu Multiplexer) module.

Included Containers				
Container Name Multiplicity Scope / Dependency				
lpduMConfig	1	This container contains the sub containers of the IpduM module. The IpduMTxPathway subcontainer includes information about sent I-PDUs. The IpduMRxPathway includes information about received I-PDUs. This container is a MultipleConfigurationContainer, i.e. this container and its sub- containers exist once per configuration set.		
IpduMGeneral	1	Contains the general configuration parameters of IpduM.		

### 10.2.4 IpduMGeneral

SWS Item	IPDUM130 :
Container Name	IpduMGeneral
Description	Contains the general configuration parameters of IpduM.
Configuration Parameters	

SWS Item	IPDUM131 :			
Name	IpduMConfigurationTimeBas	IpduMConfigurationTimeBase		
Description	The period between success	ive ticks of AUTOSAR	COM in seconds.	
Multiplicity	1	1		
Туре	FloatParamDef			
Range	-INF INF			
Default value				
ConfigurationClass	Pre-compile time	Х	All Variants	
-	Link time			
	Post-build time			
Scope / Dependency	scope: local			

SWS Item	IPDUM132 :			
Name	IpduMDevErrorDetect			
Description	Active/Deactivate the detection of development errors, for production code this parameter has to be False. True: error detection activated False: error detection deactivated			
Multiplicity	1			
Туре	BooleanParamDef			
Default value				
ConfigurationClass	Pre-compile X All Variants time			
	Link time			
	Post-build			
	time			
Scope / Dependency	scope: local			

SWS Item	IPDUM133 :
Name	IpduMStaticPartExists
	This is to allow optimizations in the case the IpduM will never be used with a static part. Note that this is a pre-compile option. If this is set to False then it will not be possible to add static parts after compilation. True: A static part may exist. False: A static part will never exist.
Multiplicity	1



Туре	BooleanParamD	ef		
Default value				
ConfigurationClass	Pre-compile	Х	All Variants	
	time			
	Link time			
	Post-build			
	time			
Scope / Dependency	scope: local			

SWS Item	IPDUM134 :				
Name	IpduMVersionInf	IpduMVersionInfoApi			
Description	Active/Deactivate the version information API. true: version information activated false: version information deactivated				
Multiplicity	1				
Туре	BooleanParamDef				
Default value					
ConfigurationClass	Pre-compile X All Variants time				
	Link time	Link time			
	Post-build				
	time				
Scope / Dependency	scope: local				

No Included Containers

### 10.2.5 IpduMTxPathway

	~ )
SWS Item	IPDUM070 :
Container Name	IpduMTxPathway
Description	Contains the configuration parameters transmitted I-PDUs by the IpduM module.
Configuration Parameters	

Included Containers			
Container Name	Multiplicity	Scope / Dependency	
IpduMTxConfirmation	01	configuration for a TxConfirmation	
IpduMTxRequest	1	configuration for a TxRequest	

### 10.2.6 IpduMTxRequest

SWS Item	IPDUM052 :
Container Name	IpduMTxRequest
Description	This is used to specify the configuration for Transmit requests. There will one instance of this container for each I-PDU that can be requested for transmission (the outgoing I-PDUs) by the IpduM.
Configuration Paramet	ers

# SWS Item IPDUM162 : Name IpduMByteOrder Description This parameter defines the ByteOrder for all IpduMSegments (static and dynamic part) and for the selectorField within the MultiplexedPdu. The absolute position of a segment in the MultiplexedIPdu is determined by the definition of the ByteOrder parameter: If BIG\_ENDIAN is specified, the SegmentPosition indicates the bit position of the most significant bit in an IPDU. If LITTLE\_ENDIAN is specified, the SegmentPosition indicates the bit position of the least significant bit in an IPDU. Multiplicity 1



Туре	EnumerationParamDef		
Range	BIG_ENDIAN		
	LITTLE_ENDIAN		
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item IPDUM121 : Name IpduMIPduUnusedAreasDefault IpduM module fills not used areas of an I-PDU with this bit-pattern If this attribute Description is omitted the IpduM module does not fill the I-PDU. Multiplicity 0..1 IntegerParamDef Туре Range 0 .. 255 Default value ConfigurationClass Pre-compile time VARIANT-PRE-COMPILE Х Link time Х VARIANT-LINK-TIME Post-build time Х VARIANT-POST-BUILD Scope / Dependency scope: local

SWS Item	IPDUM122 :		
Name	IpduMInitialSelectorValue	;	
Description	This value is used by the initialization function to set the initial value of the selector field.		
Multiplicity	1		
Туре	IntegerParamDef		
Range	0 255		
Default value			
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	IPDUM123 :		
Name	IpduMSize		
Description	The size of the I-PDU in bytes. The maximum size is limited by the underlying communication interface. 0-8 for CAN and LIN 0-254 for FlexRay		
Multiplicity	1		
Туре	IntegerParamDef		
Range	0 254		
Default value			
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	IPDUM124 :	
Name	IpduMTxConfirmationTimeout	
Description	This timeout (in seconds) defines the timeout period for monitoring the reception of the TxConfirmation. It is not used when an I-PDU is requested using the trigger transmit API.	
Multiplicity	01	
Туре	FloatParamDef	
Range	-INF INF	
Default value		



ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Scone / Dependency	scope: local		

Scope / Dependency scope: local

SWS Item	IPDUM125 :		
Name	IpduMTxTriggerMode		
Description	Selects whether to send the multiplexed I-PDL	J immediately	or at some later date.
Multiplicity	1		
Туре	EnumerationParamDef		
Range	DYNAMIC_PART_TRIGGER		PDU representing the t does trigger a ne I-PDU.
	NONE	written but nu used for Ipdu	fer in the IpduM are ot send is triggered, uM I-PDUs which are / TriggerTransmit.
	STATIC_OR_DYNAMIC_PART_TRIGGER	static or the	PDU representing the dynamic part does ding of the I-PDU.
	STATIC_PART_TRIGGER		PDU representing the bes trigger a sending .
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE- COMPILE
	Link time	Х	VARIANT-LINK- TIME
	Post-build time	Х	VARIANT-POST- BUILD
Scope / Dependency	scope: local		-

SWS Item	IPDUM120 :			
Name	IpduMOutgoing P	PduRef		
Description	Reference to the PDU defining the outgoing I-PDU. When the outgoing I-PDU is sent this is the I-PDU ID to give it. It is the IpduM I-PDU ID of the assembled I-PDU.			
Multiplicity	1			
Туре	Reference to [ Pdu ]			
ConfigurationClass	Pre-compile X VARIANT-PRE-COMPILE			
	Link time	Link time X VARIANT-LINK-TIME		
	Post-build X VARIANT-POST-BUILD			
	time			
Scope / Dependency	scope: external			

Included Containers		
Container Name	Multiplicity	Scope / Dependency
lpduMBitField		This specifies the bits that are reserved for the selector field. There can only be 18 bits specified.
IpduMTxDynamicPart	1*	This (These) included container(s) must exist for each unique selector field value for this outgoing IpduM I-PDU.
IpduMTxStaticPart		This included containers configures the static part, if present.

### 10.2.7 IpduMTxDynamicPart



Container Name	IpduMTxDynamicPart		
Description	Configuration parameters for an instance of a TxRequest call into the IpduM. When a Tx Request with the IpduMTxDynamicHandleld is received by the IpduM, the bit fields in the incoming I-PDU are packed into the outgoing I-PDU buffer and then the send mode honored. This container is used by the dynamic part of a TxRequest configuration. Therefore, for each outgoing I-PDU there will be one instance of this container for the dynamic part.		
Configuration Parameters			

SWS Item	IPDUM167 :		
Name	IpduMJitUpdate		
	If configured to true fetch the data of this part Just-In-Time via the triggerTransmit API of the PduR.		
Multiplicity	01		
Туре	BooleanParamDef		
Default value	false		
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time X VARIANT-LINK-TIME		
	Post-build X VARIANT-POST-BUILD		
	time		
Scope / Dependency	scope: local		

SWS Item	IPDUM127 :		
Name	IpduMTxDynamicHandleId		
	This is an incoming handle id. When the handle of an incoming Tx Request matches this, the bits fields (see IpduM_CopyBitField) are copied and the IpduMTxTriggerMode is honored.		
Multiplicity	1		
Туре	IntegerParamDef (Symbolic Name generated for this parameter)		
Range			
Default value			
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE
-	Link time X VARIANT-LINK-TIME		
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: External		

SWS Item	IPDUM126 :		
Name	IpduMTxDynam	icPduRef	
Description	Reference to the Pdu representation in the ECU Configuration Description exchange file to be transmitted.		
Multiplicity	1		
Туре	Reference to [ Pdu ]		
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build	Х	VARIANT-POST-BUILD
	time		
Scope / Dependency	scope: external		

Included Containers			
Container Name	Multiplicity	Scope / Dependency	
lpduMCopyBitField	1*	This is a list of bit fields to copy from the incoming I-PDU to the outgoing I-PDU. This bit fields represent the subparts of the I-PDU.	



### 10.2.8 IpduMTxStaticPart

SWS Item	IPDUM082 :
Container Name	IpduMTxStaticPart
Description	Configuration parameters for an instance of a Tx_Request call into the IpduM. When a Tx Request with the IpduMTxStaticHandleld is received by the IpduM, the bit fields in the incoming I-PDU are packed into the outgoing I-PDU buffer and then the send mode honored. This container is used for the static part of a TxRequest configuration. Therefore, for each outgoing I-PDU there will be one instance of this container for the static part if it exists.
<b>Configuration Parame</b>	ters

SWS Item	IPDUM167 :			
Name	IpduMJitUpdate			
Description	If configured to true fetch the data of this part Just-In-Time via the triggerTransmit API of the PduR.			
Multiplicity	01	01		
Туре	BooleanParamDef			
Default value	false			
ConfigurationClass	Pre-compile X VARIANT-PRE-COMPILE time			
	Link time X VARIANT-LINK-TIME			
	Post-build X VARIANT-POST-BUILD			
	time			
Scope / Dependency	scope: local			

SWS Item	IPDUM129 :			
Name	IpduMTxStaticHandleId	lpduMTxStaticHandleId		
	This is an incoming handle id. When the handle of an incoming Tx Request matches this, the bits fields (see IpduMCopyBitField) are copied and the IpduMTxTriggerMode is honored.			
Multiplicity	1			
Туре	IntegerParamDef (Symbolic	IntegerParamDef (Symbolic Name generated for this parameter)		
Range				
Default value				
ConfigurationClass	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time X VARIANT-LINK-TIME			
	Post-build time X VARIANT-POST-BUILD			
Scope / Dependency	scope: External			

SWS Item	IPDUM128 :				
Name	IpduMTxStaticPduRef				
-	Reference to the Pdu representation in the ECU Configuration Description exchange file to be transmitted.				
Multiplicity	1	1			
Туре	Reference to [ Pdu ]				
ConfigurationClass	Pre-compile X VARIANT-PRE-COMPILE				
	time	time			
	Link time	Link time X VARIANT-LINK-TIME			
	Post-build X VARIANT-POST-BUILD				
	time				
Scope / Dependency	scope: external				

Included Containers	
Container Name	Multiplicity Scope / Dependency



IpduMCopyBitField	1*	Specifies the source bit fields and the destination bit position, so that the bits in the source can be copied to the bits in the destination. Within one I-PDU multiple instances of this container are used to specify the bit fields in that I-PDU. Adjacent bit fields could be merged in order to reduce the number of instances of this container.
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### 10.2.9 IpduMTxConfirmation

SWS Item	IPDUM050 :	
Container Name	IpduMTxConfirmation	
Description	A transmit request can be confirmed by the lower layer. This container is used to generate the matching confirmations for the static and dynamic parts of a multiplexed I-PDU. When an I-PDU is transmitted by the IpduM, the selector field value in that PDU needs to be stored in the IpduM so that the confirmation for the correct dynamic part can be generated. This is state internal to the IpduM at run-time. For the purposes of this container and IpduMDynamicTxConfirmation this stored state is called Stored_Selector.	
<b>Configuration Parameters</b>		

SWS Item	IPDUM117 :				
Name	IpduMStaticTxC	IpduMStaticTxConfirmationIPduRef			
Description		This references the I-PDU to use in the TxConfirmation for the static part. This entity does not appear if there is no static part.			
Multiplicity	01	01			
Туре	Reference to [ F	Reference to [ Pdu ]			
ConfigurationClass	Pre-compile X VARIANT-PRE-COMPILE				
	Link time	Link time X VARIANT-LINK-TIME			
	Post-build X VARIANT-POST-BUILD				
	time				
Scope / Dependency	scope: local				

Included Containers			
Container Name	Multiplicity	Scope / Dependency	
IpduMDynamicTxConfirmatio n	1*	This defines the dynamic parts that also need confirmation.	

### 10.2.10 IpduMDynamicTxConfirmation

SWS Item	IPDUM051 :		
Container Name	IpduMDynamicTxConfirmation		
Description	The dynamic part of an I-PDU can have more than one I-PDU IDs for confirmations. The correct I-PDU ID for the confirmation is found from the selector field value of a previously transmitted I-PDU. It is assumed that this selector field is stored in some internal value called Stored_Selector. When a transmit confirmation is received the Stored_Selector is used to select an instance of IpduMDynamicTxConfirmation by matching the Stored_Selector with the IpduMSelectorValue.		
<b>Configuration Parameters</b>			

 SWS Item
 IPDUM119 :

 Name
 IpduMSelectorValue

 Description
 When the selector field of the confirmed I-PDU matches the value in here then generate a TxConfirmation for the I-PDU referenced by IpduMDynamicTxConfirmIPduRef.



Multiplicity	1		
Туре	IntegerParamDef		
Range	0 255		
Default value			
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	IPDUM118 :			
Name	IpduMDynamicTxConfirmIPduRef			
Description	This is the I-PDU ID to use in the outgoing confirmation (confirmation for the COM I-PDU) when an incoming confirmation (for an IpduM I-PDU) is received and matches the stored Stored_Selector.			
Multiplicity	1			
Туре	Reference to [ P	Reference to [ Pdu ]		
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE	
	Link time	Link time X VARIANT-LINK-TIME		
	Post-build X VARIANT-POST-BUILD			
	time			
Scope / Dependency	scope: local			

No Included Containers

### 10.2.11 IpduMRxPathway

	,
SWS Item	IPDUM071 :
Container Name	IpduMRxPathway
Description	Contains the configuration parameters received I-PDUs by the IpduM module.
Configuration Parameters	

Included Containers		
Container Name	Multiplicity	Scope / Dependency
IpduMRxIndication	1	configuration for RxIndication

### 10.2.12 IpduMRxIndication

SWS Item	IPDUM047 :
Container Name	IpduMRxIndication
Description	Contains the configuration for incoming RxIndication calls.
Configuration Parameters	

SWS Item	IPDUM162 :	
Name	IpduMByteOrder	
Description	This parameter defines the ByteOrder for all IpduMSegments (static and dynamic part) and for the selectorField within the MultiplexedPdu. The absolute position of a segment in the MultiplexedIPdu is determined by the definition of the ByteOrder parameter: If BIG_ENDIAN is specified, the SegmentPosition indicates the bit position of the most significant bit in an IPDU. If LITTLE_ENDIAN is specified, the SegmentPosition indicates the bit position of the least significant bit in an IPDU.	
Multiplicity	1	
Туре	EnumerationParamDef	
Range	BIG_ENDIAN LITTLE_ENDIAN	



ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	IPDUM109 :		
Name	IpduMRxHandleId		
Description	This is the I-PDU ID of the incoming I-PDU. If an incoming RxIndication's I-PDU ID matches this value then it is unpacked according to the specification in this container.		
Multiplicity	1		
Туре	IntegerParamDef (Symbolic Name generated for this parameter)		
Range			
Default value			
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time X VARIANT-POST-BUILD		
Scope / Dependency			

SWS Item	IPDUM108 :		
Name	IpduMRxIndicationPduRef		
Description	Reference to the received Pdu representation in the ECU Configuration Description exchange file.		
Multiplicity	1		
Туре	Reference to [ Pdu ]		
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: external		

Included Containers			
Container Name	Multiplicity	Scope / Dependency	
lpduMBitField	1	This contains the location in the incoming I-PDU of the bit field that contains the selector field. At run-time, the selector field is used to select which dynamic part is unpacked.	
lpduMRxDynamicPart	Each of these containers contains the configuration for 0* value of the selector field for the incoming I-PDU's dyna part.		
lpduMRxStaticPart	01	This contains the configuration for the incoming I-PDU's static part. If the incoming I-PDU has no static part then this is omitted.	

# 10.2.13 IpduMRxDynamicPart

SWS Item	IPDUM048 :		
Container Name	IpduMRxDynamicPart		
Description	This container contains the configuration for the dynamic part of incoming RxIndication calls. When an incoming received I-PDU's selector field matches the IpduMRxSelectorValue, the new outgoing I-PDU for the dynamic part is constructed as defined by the segments of this container and sent out with the I-PDU ID referenced by IpduMOutgoingDynamicPduRef. In case no dynamic part shall be extracted from this received I-PDU this container does not exist. This use-case can occur in case a MultiplexedIPdu is received by an ECU which is only interested in the		



static part of the MultiplexedIPdu.

**Configuration Parameters** 

SWS Item	IPDUM113 :		
Name	IpduMRxSelectorValue		
Description	This is the selector value that	at this container refe	ers to.
Multiplicity	1		
Туре	IntegerParamDef		
Range	0 255		
Default value			
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE
-	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	IPDUM112 :		
Name	IpduMOutgoingDynamicPduRef		
	When the new I-PDU is sent out it is sent with this I-PDU ID. Reference to the sent PDU representation in the ECU Configuration Description exchange file.		
Multiplicity	1		
Туре	Reference to [ Pdu ]		
ConfigurationClass	Pre-compile X VARIANT-PRE-COMPILE		
	time		
	Link time X VARIANT-LINK-TIME		
	Post-build	Х	VARIANT-POST-BUILD
	time		
Scope / Dependency	scope: external		

Included Containers		
Container Name	Multiplicity	Scope / Dependency
IpduMCopyBitField		Contains the list of bit fields that need to be copied from the incoming I-PDU to the outgoing I-PDU.

### 10.2.14 IpduMRxStaticPart

SWS Item	IPDUM049 :
Container Name	IpduMRxStaticPart
Description	This container contains the information on how to unpack the static part of an incoming I-PDU.
Configuration Parameters	

SWS Item	IPDUM115 :		
Name	IpduMOutgoingS	StaticPduRef	
Description	When the new I-PDU is sent out it is sent with this I-PDU ID. Reference to the sent Pdu representation in the ECU Configuration Description exchange file.		
Multiplicity	1		
Туре	Reference to [ Pdu ]		
ConfigurationClass	Pre-compile X VARIANT-PRE-COMPILE		
	time		
	Link time	Х	VARIANT-LINK-TIME
	Post-build	Х	VARIANT-POST-BUILD
	time		
Scope / Dependency	scope: external		

Included Containers	
Container Name	Multiplicity Scope / Dependency



IpduMCopyBitField	1 ^	Contains the list of bit fields that need to be copied from the incoming I-PDU to the outgoing I-PDU.
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### 10.2.15 IpduMBitField

SWS Item	IPDUM054 :
Container Name	lpduMBitField
	This is used to specify a contiguous range of bits within an I-PDU. The range is inclusive.
Configuration Parameters	

SWS Item	IPDUM110 :		
Name	IpduMEndBit		
Description	Position of the end bit in the	I-PDU.	
Multiplicity	1		
Туре	IntegerParamDef		
Range	0 2031		
Default value			
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	IPDUM111 :		
Name	IpduMStartBit		
Description	Position of the start bit in the	e I-PDU.	
Multiplicity	1		
Туре	IntegerParamDef		
Range	0 2031		
Default value			
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

No Included Containers

### 10.2.16 lpduMCopyBitField

SWS Item	IPDUM053 :
Container Name	IpduMCopyBitField
Description	Specifies the source bit fields and the destination bit position, so that the bits in the source can be copied to the bits in the destination. Within one I-PDU multiple instances of this container are used to specify the bit fields in that I-PDU. Adjacent bit fields could be merged in order to reduce the number of instances of this container.
O	

Configuration Parameters

SWS Item	IPDUM114 :
Name	IpduMDestinationBit
	Bit position in an I-PDU of the start of the destination bit field for the copy. The resulting destination field must fit inside the I-PDU.
Multiplicity	1
Туре	IntegerParamDef
Range	0 2031



Default value			
ConfigurationClass	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

Included Containers		
Container Name	Multiplicity	Scope / Dependency
lpduMBitField	1	Source bit field.

### 10.2.17 IpduMConfig

SWS Item	IPDUM059 :
Container Name	IpduMConfig [Multi Config Container]
Description	This container contains the sub containers of the IpduM module. The IpduMTxPathway subcontainer includes information about sent I-PDUs. The IpduMRxPathway includes information about received I-PDUs. This container is a MultipleConfigurationContainer, i.e. this container and its sub-containers exist once per configuration set.
Configuration Parameters	

Included Containers		
Container Name	Multiplicity	Scope / Dependency
IpduMRxPathway	0*	includes information about received I-PDUs
IpduMTxPathway	0*	includes information about sent I-PDUs



# **10.3 Published Information**

Published information contains data defined by the implementer of the SW module that does not change when the module is adapted (i.e. configured) to the actual HW/SW environment. It thus contains version and manufacturer information.

The standard common published information like

vendorld (<Module>\_VENDOR\_ID), moduleID (<Module>\_MODULE\_ID), arMajorVersion (<Module>\_AR\_MAJOR\_VERSION), arMinorVersion (<Module>\_ AR\_MINOR\_VERSION), arPatchVersion (<Module>\_ AR\_PATCH\_VERSION), swMajorVersion (<Module>\_SW\_MAJOR\_VERSION), swMinorVersion (<Module>\_ SW\_MINOR\_VERSION), swPatchVersion (<Module>\_ SW\_PATCH\_VERSION), vendorApiInfix (<Module>\_VENDOR\_API\_INFIX)

is provided in the BSW Module Description Template (see 3.1 Figure 4.1 and Figure 7.1).

Additional published parameters are listed below if applicable for this module.