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## 1 Introduction and functional overview

This specification is the AUTOSAR COM Software Specification. It is based on the AUTOSAR COM SRS [7]. It specifies how the requirements of the AUTOSAR COM SRS shall be realized. That means that the functionality and the API of the AUTOSAR COM module are described in this document.

Within the AUTOSAR Layered Architecture the COM module is placed between RTE and the PDU Router, see [1].

AUTOSAR COM is derived from [17]. For details see Chapter 7.2.1.

AUTOSAR COM provides signal gateway functionality. For details see Chapter 7.2.4.

Main Features:

- Provision of signal oriented data interface for the RTE
- Packing of AUTOSAR signals to I-PDUs to be transmitted
- Unpacking of received I-PDUs and provision of received signals to RTE
- Routing of signals from received I-PDUs into I-PDUs to become transmitted
- Routing of signal groups from received I-PDUs into I-PDUs to become transmitted
- Communication transmission control (start/ stop of I-PDU groups)
- Replications of send requests
- Guarantee of minimum distances between transmit I-PDUs
- Monitoring of receive signals (signals timeout)
- Filter mechanisms for incoming signals
- Different notification mechanisms
- Provision of init values and update indications
- Byte order conversion
- Sign extension
- Support of two different transmission modes per I-PDU
- Signal based gateway



## 2 Acronyms, abbreviations and definitions

### 2.1 Acronyms and abbreviations

Acronym:	Description
AUTOSAR COM	AUTOSAR COM is derived from OSEK COM [17]. For details see Chapter 7.2.1.
DM	Deadline Monitoring. For details see Chapter 7.4.5.5.
IL	Interaction Layer. A detailed description can be found in [17].
I-PDU	Interaction Layer Protocol Data Unit An I-PDU carries signals and is defined in [17].
LOM	Listen only mode
L-PDU	Data Link Layer PDU. In AUTOSAR the Data Link Layer is equivalent to the Communication Hardware Abstraction and Microcontroller Abstraction Layer.
MDT	Minimum Delay Timer. A detailed description can be found in [17]. See also chapter 7.4.5.5.
OSEK COM	Open systems and the corresponding interfaces for automotive electronics – communication [17]
PCI	Protocol Control Information For a description see [1] page 04-51 ff.
PDU Router	Module that transfers I-PDUs from one module to another module. The PDU Router can be utilized for gateway operations and for internal routing purposes.
SDT	Specification of System Template [12]
SDU	Service Data Unit For a description see [1] Chapter 4.
TM	Transmission Mode
TMC	Transmission Mode Condition, see Chapter 7.4.3.5
TMS	Transmission Mode Selector, see Chapter 7.4.3.5

#### 2.1.1 Definitions

Acronym:	Description:
Confirmation	Lower layer reports that a request by COM has been completed successfully. It's a reaction to a request of COM. E.g. when a PDU has been successfully transmitted.
Data Invalid Value	Value sent by the AUTOSAR COM to indicate that the sender side AUTOSAR Software Component is not able to provide a valid value.
Group signal	A group signal is a signal that is contained in a signal group.
Indication	Asynchronous information from lower layer to COM, e.g. when something has been received.
Init Value	I-PDUs and signals are set to the Init Value by AUTOSAR COM after start-up. This value is used until it is overwritten.
I-PDU group	An I-PDU group contains zero or more I-PDUs or I-PDU groups. For a detailed description see [7].
Inter-ECU communication	Communication between two or more ECU for example via a CAN network.
Intra-ECU communication	Communication between Software components that reside on the same ECU.
Message	OSEK-COM uses always the synonym <i>message</i> . In AUTOSAR, <i>message</i> is replaced by <i>signal</i> but with the same meaning.
Notification	Information by COM to upper layer, e.g. when new data is available, an

	error occurred.
Signal	A description can be found in [7].
Signal groups	<p>In AUTOSAR, so called <i>complex data types</i> are used. Inside a complex data type, there are one or more data elements (primitive data types), like in a C-struct. The data consistency of such complex data types must be ensured</p> <p>The RTE decomposes the complex data type in single signals and sends them to the AUTOSAR COM module. As these signals altogether have to be treated consistently, they are called <i>signal group</i>.</p> <p>See also [7].</p>
Update-bits	A mechanism supported by AUTOSAR COM with that the receiver of a signal/ signal group can identify whether the sender has updated the data in this signal/ signal group before sending. See Chapter 7.7.

### 3 Related documentation

#### 3.1 Deliverables of AUTOSAR

- [1] Layered Software Architecture  
AUTOSAR\_LayeredSoftwareArchitecture.pdf
- [2] Specification of Communication Stack Types  
AUTOSAR\_SWS\_ComStackTypes.pdf
- [3] General Requirements on Basic Software Modules  
AUTOSAR\_SRS\_General.pdf
- [4] Basic Software UML Model  
AUTOSAR\_UML\_Model.eap
- [5] Specification of Standard Types  
AUTOSAR\_SWS\_StandardTypes.pdf
- [6] Specification of the Virtual Functional Bus  
AUTOSAR\_VirtualFunctionBus.pdf
- [7] Requirements on Communication  
AUTOSAR\_SRS\_COM.pdf
- [8] Software Component Template  
AUTOSAR\_SoftwareComponentTemplate.pdf
- [9] Requirements on Gateway  
AUTOSAR\_SRS\_Gateway.pdf
- [10] Specification of PDU Router  
AUTOSAR\_SWS\_PDU\_Router.pdf
- [11] Specification of Operating System  
AUTOSAR\_SWS\_OS.pdf
- [12] Specification of System Template  
AUTOSAR\_SystemTemplate.pdf
- [13] Specification of RTE Software  
AUTOSAR\_SWS\_RTE.pdf
- [14] Specification of ECU Configuration  
AUTOSAR\_ECU\_Configuration.pdf

[15] Specification of Generic Network Management  
AUTOSAR\_SWS\_Generic\_NM.pdf

[16] Specification of Communication Manager  
AUTOSAR\_SWS\_ComManager.pdf

AUTOSAR Basic Software Module Description Template,  
AUTOSAR\_BSW\_Module\_Description.pdf

### **3.2 Related standards and norms**

[17] OSEK/ VDX Communication Version 3.0.3  
<http://www.osek-vdx.org>  
OSEKCOM303.pdf

[18] OSEK implementation language Version 2.5  
<http://www.osek-vdx.org>  
oil25.pdf

## 4 Constraints and assumptions

This document is applicable for AUTOSAR release 3.0. Features for later AUTOSAR releases are not yet included.

### 4.1 Limitations

AUTOSAR COM is based on [17]. Nevertheless not all features of [17] are included and some features are different. See COM013 for a list of not included features.

Within the AUTOSAR COM Stack the I-PDUs of COM are passed via the PDU Router directly to the communication interfaces. Therefore the maximum length of an I-PDU depends of the maximum length of the L-PDU of the underlying communication interface. For CAN and LIN the maximum L-PDU length is 8 bytes. For FlexRay the maximum L-PDU length is 254 bytes.

For AUTOSAR release 3.0 there is no special treatment in COM to handle *floating point* data types. However, they may be handled with existing COM functionality.

The number of IPDU-groups is limited to 64, see COM187.

### 4.2 Applicability to car domains

No restrictions.

## 5 Dependencies to other modules

This chapter lists all the features from other modules which are used by the AUTOSAR COM module and functionalities which are provided by AUTOSAR COM to other modules. For the placement of AUTOSAR COM in the communication stack see Figure 1.

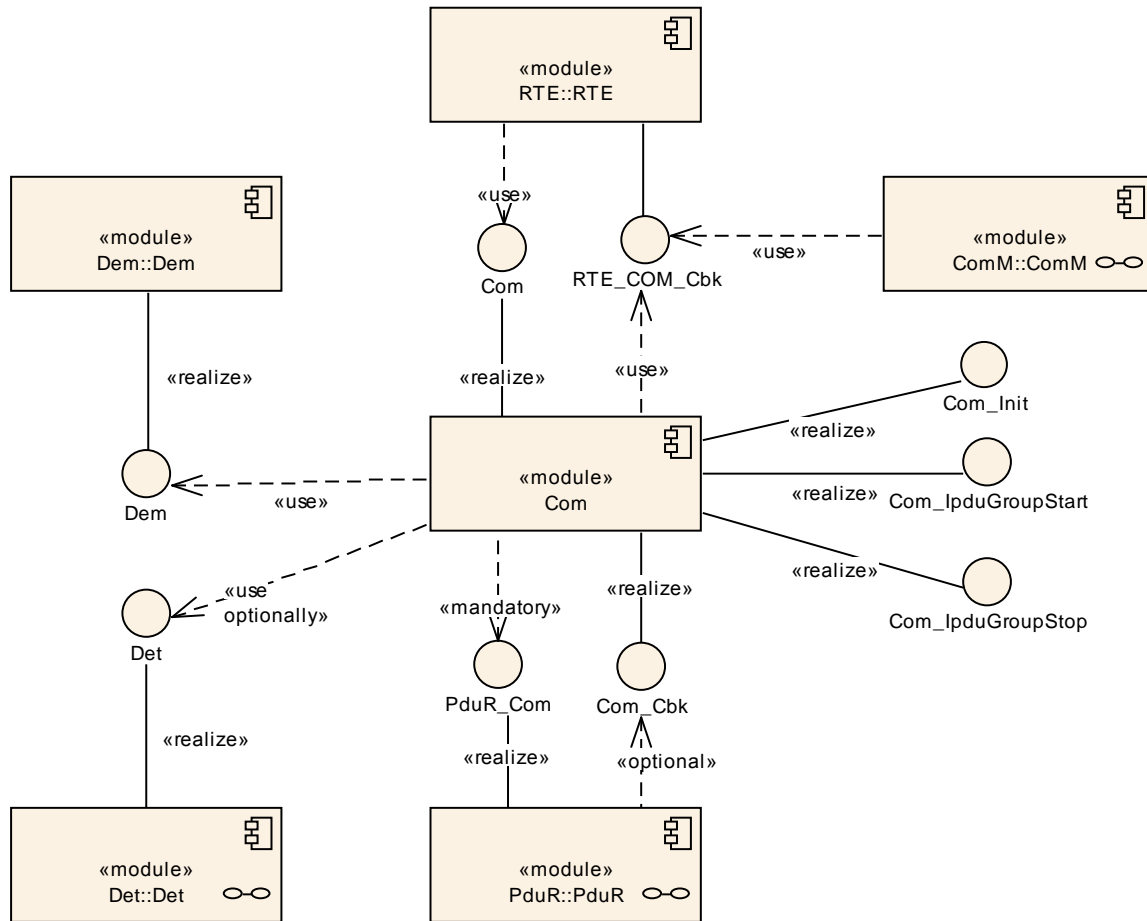


Figure 1: AUTOSAR COM context view

**Note:** RTE\_COM\_Cbk denotes the interface provided by the RTE that is used by COM to notify about transmission acknowledgements and errors. This must not necessarily result in an RTE\_COM\_Cbk.h file.

### 5.1 PDU router

The following summarizes the functionality AUTOSAR COM needs from the underlying layer PDU Router:

- Indication of incoming I-PDUs
- Sending interface for outgoing I-PDUs including the confirmation if an I-PDU has been send by the communication controller.
- Trigger interface to enable the PDU router to cause a transmission from AUTOSAR COM

A detailed description of the interface to the lower layer can be found in Chapter 7.6 and in Chapter 9.1. For further information see [10].

## 5.2 Runtime Environment (RTE)

RTE uses the capability to send and receive signals via AUTOSAR COM. In AUTOSAR the RTE is the higher layer above COM. For further information see [13].

## 5.3 COM Manager (ComM)

The COM Manager controls the start and stop of sending and receiving I-PDUs via AUTOSAR COM. For further information see [16].

## 5.4 File structure

### 5.4.1 Code file structure

The code file structure is not completely defined within this specification.

**COM430:** The code-file structure shall include the following files named:

- COM.c – module source file
- COM\_Cfg.c – pre-compile-time configurable constant parameters
- COM\_Lcfg.c – link-time configurable parameters
- COM\_PBcfg.c – post-build time configurable parameters

### 5.4.2 Header file structure

**COM005:** AUTOSAR COM shall offer a header file Com.h which includes all user relevant information and another header file Com\_Cbk.h which declares the callback functions and the I-PDU callout prototype.

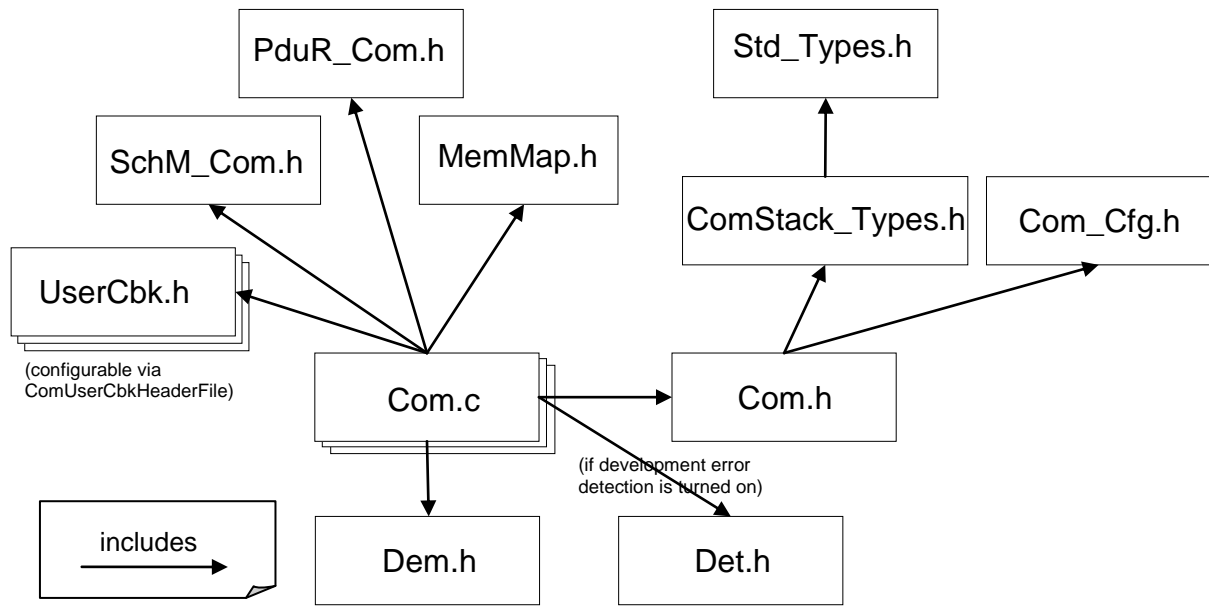


Figure 2: Include file structure

**COM220:** The include file structure regarding the specifics of the COM shall be constructed as shown in Figure 2.

**COM431:** The module shall include the **Dem.h** file. By this inclusion, the APIs to report errors as well as the required Event ID symbols are included. This specification defines the name of the Event ID symbols, which are provided by XML to the DEM configuration tool. The DEM configuration tool assigns ECU dependent values to the Event ID symbols and publishes the symbols in **Dem\_IntErrId.h**.



## 6 Requirements traceability

Document: General Requirements on Basic Software Modules [3]

Requirement	Satisfied by
[BSW00344] Reference to link-time configuration	Chapter 10.2.1.2 COM432, COM430
[BSW00404] Reference to post build time configuration	Chapter 10.2, COM375, COM432
[BSW00405] Reference to multiple configuration sets	COM432
[BSW00345] Pre-compile-time configuration	Chapter 10.2.1.1 COM430
[BSW159] Tool-based configuration	not applicable (not in scope of this spec)
[BSW167] Static configuration checking	not applicable (not scope of this spec)
[BSW171] Configurability of optional functionality	not applicable (COM module has no features switches for optional functionality)
[BSW170] Data for reconfiguration of AUTOSAR SW-Components	not applicable (not in scope of this spec)
[BSW00380] Separate C-files for configuration parameters	COM430
[BSW00419] Separate C-files for pre-compile time configuration parameters	COM430
[BSW00381] Separate configuration header file for pre-compile time parameters	COM220
[BSW00412] Separate H-file for configuration parameters	COM220
[BSW00383] List dependencies of configuration files	not applicable (implementation specific)
[BSW00384] List dependencies to other modules	Chapter 5
[BSW00387] Specify the configuration class of callback function	Chapter 8.4
[BSW00388] Introduce containers	Chapter 10.2, COM541
[BSW00389] Containers shall have names	Chapter 10.2
[BSW00390] Parameter content shall be unique within the module	Chapter 10.2
[BSW00391] Parameter shall have unique names	Chapter 10.2
[BSW00392] Parameters shall have a type	Chapter 10.2
[BSW00393] Parameters shall have a range	Chapter 10.2
[BSW00394] Specify the scope of the parameters	Chapter 10.2
[BSW00395]	Chapter 10

List the required parameters (per parameter)	(scope and dependency fields)
[BSW00396] Configuration classes	Chapter 10.2
[BSW00397] Pre-compile-time parameters	Chapter 10.2
[BSW00398] Link-time parameters	Chapter 10.2
[BSW00399] Loadable post-build time parameters	Chapter 10.2
[BSW00400] Selectable post-build time parameters	Chapter 10.2
[BSW00402] Published information	Chapter 10.2.22
[BSW00375] Notification of wake-up reason	not applicable (not in scope of this spec)
[BSW101] Initialization interface	COM128, COM328, COM015, COM098, COM117, COM170, COM217, COM059, COM432
[BSW00416] Sequence of Initialization	not applicable (not in scope of this spec)
[BSW00406] Check module initialization	COM433
[BSW00437] NoInit-Area in RAM	not applicable (not in scope of this spec)
[BSW168] Diagnostic interface	not applicable (not in scope of this spec)
[BSW00407] Function to read out published parameters	COM426
[BSW00423] Usage of SW-C template to describe BSW modules with AUTOSAR Interfaces	not applicable (not valid for AUTOSAR COM module)
[BSW00424] BSW main processing function task allocation	not applicable (implementation specific)
[BSW00425] Trigger conditions for schedulable objects	COM398, COM399, COM400, COM359
[BSW00426] Exclusive areas in BSW modules	not applicable (implementation specific)
[BSW00427] ISR description for BSW modules	not applicable (not valid for AUTOSAR COM module)
[BSW00428] Execution order dependencies of main processing functions	not applicable (not valid for AUTOSAR COM module)
[BSW00429] Restricted BSW OS functionality access	not applicable (AUTOSAR COM has no interface to OS)
[BSW00431] The BSW Scheduler module implements task bodies	not applicable (not in scope of this spec)
[BSW00432] Modules should have separate main processing functions for read/receive and write/transmit data path	COM398, COM399, COM400, COM359, COM466
[BSW00433] Calling of main processing functions	not applicable (not in scope of this spec)
[BSW00434] The schedule module shall provide an API for exclusive areas	not applicable (not in scope of this spec)
[BSW00336] Shutdown interface	COM129, COM130
[BSW00337]	Chapter 7.10

Classification of errors	
[BSW00338] Detection and reporting of development errors	COM024, COM028, COM442  Configuration: COM141
[BSW00369] Do not return development error codes via API	COM442, COM459, Chapter 8
[BSW00339] Reporting of production relevant error status	COM459, COM428
[BSW00417] Reporting of error events by non-basic software	not applicable (not in scope of this spec)
[BSW00323] API parameter checking	COM024, COM028
[BSW004] Version check	COM026, COM337
[BSW00409] Header files for production code error IDs	COM431
[BSW00385] List possible error notifications	COM442, COM459
[BSW00386] Configuration for detecting an error	not applicable (not in scope of this spec)
[BSW161] Microcontroller abstraction	not applicable (not in scope of this spec)
[BSW162] ECU layout abstraction	not applicable (not in scope of this spec)
[BSW005] No hard coded horizontal interfaces within MCAL	not applicable
[BSW00415] User dependent include files	Chapter 5.4, COM005, COM220, COM831
[BSW164] Implementation of interrupt service routines	not applicable (not in scope of this spec)
[BSW00325] Runtime of interrupt service routines	not applicable (not in scope of this spec)
[BSW00326] Transition from ISRs to OS tasks	not applicable (not in scope of this spec)
[BSW00342] Usage of source code and object code	Chapter 10.2
[BSW00343] Specification and configuration of time	Chapter 10.2
[BSW160] Human-readable configuration data	Chapter 10.2
[BSW007] HIS MISRA C	API is MISRA conform other issues are implementation specific
[BSW00300] Module naming convention	COM005, COM220, COM540
[BSW00413] Accessing instances of BSW modules	not applicable (not in scope of this spec)
[BSW00347] Naming separation of different instances of BSW drivers	not applicable (not in scope of this spec)
[BSW00305] Self-defined data types naming convention	see Chapter 8.2
[BSW00307] Global variables naming convention	not applicable (implementation specific)
[BSW00310] API naming convention	Chapter 0 and 8.4
[BSW00373] Main processing function naming convention	Chapter 8.5

[BSW00327] Error values naming convention	COM442, COM459
[BSW00335] Status values naming convention	Chapter 8.2.1
[BSW00350] Development error detection keyword	COM028
[BSW00408] Configuration parameter naming convention	Chapter 10.2
[BSW00410] Compiler switches shall have defined values	not applicable (implementation specific)
[BSW00411] Get version info keyword	COM425
[BSW00346] Basic set of module files	COM005, COM220
[BSW158] Separation of configuration from implementation	COM005, COM220
[BSW00314] Separation of interrupt frames and service routines	not applicable (not in scope of this spec)
[BSW00370] Separation of callback interface from API	Chapter 8
[BSW00435] Module header file structure for the basic software scheduler	COM220
[BSW00436] Module header file Structure for the basic software memory mapping	COM220
[BSW00348] Standard type header	COM220
[BSW00353] Platform specific type header	not applicable (implementation specific)
[BSW00361] Compiler specific language extension header	not applicable (implementation specific)
[BSW00301] Limit imported information	not applicable (implementation specific)
[BSW00302] Limit exported information	not applicable (implementation specific)
[BSW00328] Avoid duplication of code	not applicable (implementation specific)
[BSW00312] Shared code shall be reentrant	COM320, COM321
[BSW006] Platform independency	not applicable (implementation specific)
[BSW00357] Standard API return type	Chapter 8
[BSW00377] Module specific API return types	Chapter 7.10, COM459
[BSW00304] AUTOSAR integer data types	COM220, (implementation specific)
[BSW00355] Do not redefine AUTOSAR integer data types	Chapter 7.10 and Chapter 8.2
[BSW00378] AUTOSAR boolean type	not applicable (implementation specific)
[BSW00306] Avoid direct use of compiler and platform specific keywords	not applicable (implementation specific)
[BSW00308] Definition of global data	not applicable (implementation specific)
[BSW00309]	not applicable

Global data with read-only constraint	(implementation specific)
[BSW00371] Do not pass function pointers via API	Chapter 8
[BSW00358] Return type of init functions	COM432
[BSW00414] Parameter of init function	COM432
[BSW00376] Return type and parameters of main processing functions	Chapter 8.5
[BSW00359] Return type of callback functions	COM468, COM491, COM536, COM554, COM555, COM556
[BSW00360] Parameters of callback functions	COM468, COM491, COM536, COM554, COM555, COM556
[BSW00329] Avoidance of generic interfaces	Chapter 8
[BSW00330] Usage of macros / inline functions instead of functions	COM434
[BSW00331] Separation of error and status values	Chapter 8, COM194
[BSW009] Module user documentation	not applicable (implementation specific)
[BSW00401] Documentation of multiple instances of Configuration parameters	Chapter 10
[BSW172] Compatibility and documentation of scheduling strategy	see Chapter 8.5, COM298 further item are implementation specific
[BSW010] Memory resource documentation	not applicable (implementation specific)
[BSW00333] Documentation of callback function context	not applicable (not in scope of this spec)
[BSW00374] Module vendor identification	COM208
[BSW00379] Module identification	COM417
[BSW003] Version identification	COM426, COM425, COM424, COM026, COM337, COM141, COM208, COM417, COM418, COM419, COM420, COM421, COM422, COM423, COM438
[BSW00318] Format of module version numbers	COM026
[BSW00321] Enumeration of module version numbers	not applicable (not in scope of this spec)
[BSW00341] Microcontroller compatibility documentation	not applicable (not in scope of this spec)
[BSW00334] Provision of XML file	not applicable (not in scope of this spec)

Document: Requirements on Communication [7]

Requirement	Satisfied by
[BSW02037] AUTOSAR COM shall be based on the functionality and APIs of OSEK COM 3.0.3	COM010, COM011, COM012, COM013, COM396
[BSW02078] Support of endianness conversion	COM007, COM221, COM352, COM472, COM473
[BSW02086] Support of sign-extension for received signals	COM008, COM353, COM352
[BSW02042] Initialization of not used areas of an I-PDU	COM015
[BSW02040] AUTOSAR COM configuration language	COM006, Chapter 10
[BSW177] Configuration of communication parameters	Chapter 10.2, COM795, COM796
[BSW02067] Rules for checking the consistency of Configuration input	COM101, COM102, COM319, COM365, COM373, COM384, COM310, COM401, COM402, COM443, COM474, COM489, COM535, COM553
[BSW02046] Configuration of signal notification	COM298, COM300, COM301, COM393
[BSW02089] Timeout indication mechanism on receiver-side [approved]	[17]  COM292, COM290, COM291, COM393, COM738, COM744  Configuration: COM186, COM263, COM264, COM333, COM552
[BSW02088] Value substitution in case of a signal timeout [approved]	COM393
[BSW02083] Transmission modes [approved]	COM329, COM330, COM135, COM276, COM305, COM392, COM277, COM278, COM307, COM308, COM467, COM478, COM494, COM739  Configuration: COM351, COM178, COM137, COM180, COM281, COM282
[BSW02082] Two different transmission modes	COM032, COM239, COM244, COM238, COM495, COM582 Configuration: COM454, COM455, COM465
[BSW02084] Transmission mode selection	COM274, COM283, COM241, COM245, COM284, COM255, COM032, COM763
[BSW02080] Re-triggering of repetitions of I-PDUs	COM279
[BSW02077] Signal invalidation mechanism on sender-side	COM097, COM099, COM286  API: COM203, COM288, COM557  Configuration: COM314, COM315, COM391, COM501
[BSW02079] Signal invalidation mechanism on receiver-side	COM680, COM681, COM682, COM683, COM717, COM718, COM736, COM737
[BSW02087]	COM412, COM470, COM500

Substitution of invalid value by configurable data value	
[BSW218] Separate start/stop AUTOSAR COM for separate groups of I-PDUs	COM085, COM114, COM222, COM223, COM228, COM229, COM334, COM090, COM115, COM311, COM187, COM444, COM476, COM479, COM684, COM685, COM733, COM740, COM771  API: COM190, COM191  Configuration: COM341, COM126, COM184, COM185, COM710
[BSW192] Disable reception deadline monitoring	COM225, COM772  API: COM192,
[BSW02081] Re-enable reception deadline monitoring	COM224, COM486, COM534, COM772  API: COM193
[BSW02041] Consistent transfer of complex data types	COM042, COM043, COM047, COM049, COM050, COM051, COM052, COM053, COM327, COM326, COM461, COM464  API: COM199, COM200, COM201, COM202  Configuration: COM345, COM044, COM513, COM520, COM521
[BSW02043] Indication service Com_RxIndication	COM574, COM575, COM794 API: COM123
[BSW02044] Confirmation service Com_TxConfirmation	COM260  API: COM124
[BSW02045] Function Com_TriggerTransmit	API: COM001, COM260, COM475
[BSW02030] Identify if a signal is updated by the sender	COM054, COM055, COM056, COM057, COM059, COM061, COM062, COM067, COM076, COM324, COM117, COM310  Configuration: COM257
[BSW02058] Deadline monitoring of receiving updated signals	COM292, COM290, COM291, COM117, COM393

Document: OSEK/ VDX Communication Version 3.0.3 [17]

Requirement	Satisfied by
Filtering (Section 2.2.2 in [17])	COM325, COM380, COM272, COM273, COM132, COM230, COM302, COM303, COM231, COM439, COM480, COM764  Configuration: COM339, COM235, COM312, COM313, COM146, COM147, COM317, COM318
Reception deadline monitoring (Section 2.5.1 in [17])	COM292, COM290, COM291
Transmission deadline monitoring (Section 2.5.2 in [17])	COM304, COM445, COM481, COM696, COM697
I-PDU callout (Section 2.9.3.2, Appendix C in [17])	COM381, COM346, COM347, COM395, COM388, COM492  API: COM348
OSEK APIs	COM197, COM198, COM469, COM562  Configuration: COM340, COM174, COM175, COM176, COM017, COM181, COM119, COM387, COM206, COM233, COM234, COM157, COM158, COM259, COM183, COM263, COM264, COM333, COM344, COM163, COM165, COM232, COM170, COM127, COM169, COM275, COM437, COM471, COM493, COM496, COM497, COM518, COM519
Notifications	API: COM123, COM124  Configuration: COM498, COM499

Document: Requirements on Gateway [9]

Requirement	Satisfied by
Interface between AUTOSAR COM and the lower layer (PDU-Router)	COM138
[BSW06002] Updateable Configuration	COM373, COM357, COM361, COM544, COM545, COM546, COM547, COM548, COM549, COM550, COM551
[BSW06097] Configuration identification	COM374, COM375, COM394, COM487
[BSW06003] Static Routing Rules	COM376  Configuration: COM355, COM358
[BSW06055] Signal Based Gateway	COM377, COM539
[BSW06056] Gateway of Signal Groups	COM361, COM383, COM735
[BSW06061] Routing operation on Signals	COM371, COM360, COM361, COM362
[BSW06098]	COM024, COM442, COM459



Signal Gateway Error Handling at signal routing	
[BSW06099] Signal Gateway Error Handling at signal routing	COM024, COM442, COM459
[BSW06077] Routing of multiple signals of the same PDU	COM371
[BSW06089] Timeout handling	COM381, COM377, COM568, COM569, COM570, COM571, COM572, COM573
[BSW06064] Signal gateway scalability	COM370

## 7 Functional specification

### 7.1 Introduction

#### 7.1.1 Signal values

The signals sent by AUTOSAR COM respectively received by AUTOSAR COM could have the values defined in Table 1.

Signal value	Remark
init value	See Chapter 7.4.1.4 for details.
data invalid value	See Chapter 7.4.3.8 for details.
<value>	This is the normal case: A valid value after initialization phase which is sent by AUTOSAR COM respectively received by AUTOSAR COM.

Table 1: Possible signal values

### 7.2 General functionality

#### 7.2.1 OSEK-COM

OSEK COM 3.0.3 is the functional basis of AUTOSAR COM.

**COM010:** AUTOSAR COM shall implement all the functionality and all the APIs of OSEK/ VDX Communication Version 3.0.3 [17] except the features and APIs mentioned in COM013.

**COM011:** If this specification defines functionality in a different way compared to definitions in [17], the definitions made in this AUTOSAR COM specification shall be used.

**COM012:** AUTOSAR COM shall in addition implement all those features, that are defined in this specification and that are not part of [17].

**COM013:** AUTOSAR COM needs *not* to implement the following features of [17]. If they are implemented in a specific AUTOSAR COM configuration the configuration shall by default disable them. This also applies for all other additional features a specific implementation may offer.

OSEK-COM feature	Rationale	related OSEK COM API
Mapping of a received network message (within an I-PDU) to more than one message data objects (1:n splitting mechanism)	not required, done by the RTE, see [13]	none
Mapping of an internal message to more than one message data objects (1:n splitting mechanism)	not required, done by the RTE, see [13]	none

Mapping an only locally send message to both an external send message object and an internal receive message object (1:n splitting mechanism)	not required, done by the RTE, see [13]	none
M:1 sending; mapping of messages from multiple senders to one and the same message object	not required, ensured by RTE, see [13]	SendMessage
Queued messages	not required, done by the RTE, see [13]	GetMessageStatus
Zero size messages	it is possible to set up communication without them  functionality is partly covered by Com_TriggerTransmit	SendZeroMessage
Dynamic size messages	were introduced for diagnostics, no use case in AUTOSAR	SendDynamicMessage, ReceiveDynamicMessage
Notification mechanisms TASK, FLAG and EVENT	not required, done by the RTE, see [13]	none
Overlapping messages in an I-PDU	no use case, dangerous concept	none
Usage of OIL	not the OSEK OIL shall be used to configure the AUTOSAR COM	none
Application modes	not needed	GetApplicationMode
Start-up behavior	replaced by <ul style="list-style-type: none"> <li>• Com_Init</li> <li>• Com_Delnit</li> <li>• Com_IpduGroupStart</li> <li>• Com_IpduGroupStop</li> </ul>	StartCOM, StopCOM, StartCOMExtensions, InitMessage
Start and stop of periodic messages	no use case, is realized by I-PDU group mechanism	StartPeriodic, StopPeriodic
Reentrancy	Not all of the AUTOSAR API calls are reentrant. See Chapter 0.	See Chapter 0.
Interface to OSEK indirect NM	not needed	I_MessageTransfer, I_MessageTimeout
Sender side filtering	no use case, the filter conditions are still used in the selection of the transmission mode but there is no signal filtering	none
Network-order message callout CPU-order message callout	Only I-PDU callouts with a defined AUTOSAR interface are supported by AUTOSAR COM. This is to avoid proprietary solutions.	none
Error hook routine	AUTOSAR COM will use a direct interface to DEM/DET instead of using the OSEK COM error hook	COMErrorHook COMError_Name1_Name2 macros COMErrorGetServiceId
Interface for callback routines	The signatures for the used callback function in AUTOSAR COM will be explicitly defined within AUTOSAR COM.	COMCallback
Internal communication	not required, ensured by RTE, see [13]	SendMessage, ReceiveMessage

Table 2: Excluded OSEK COM features in AUTOSAR COM

## 7.2.2 Endianness conversion and sign extension

**COM007:** To support the required AUTOSAR data types (signed- and unsigned integer, ASCII, enum, opaque bitfield) the AUTOSAR COM layer shall provide support for endianness conversion of all integer types. Other data types (ASCII, enum, opaque<sup>1</sup>) are either treated as signed or unsigned integer or nothing has to be done, i.e. their contents is not interpreted by the AUTOSAR COM layer.

The supported data types of AUTOSAR COM are:

- boolean
- uint8
- uint16
- uint32
- sint8
- sint16
- sint32
- uint8[n]

**COM472:** Opaque data shall always be of uint8[n] and shall always be mapped to an n-bytes sized signal.

**Note:** For opaque data (see [13]) endianness conversion shall be configured to *Opaque* (see COM157).

**COM473:** If the endianness conversion is configured to *Opaque* (see COM157) the parameter ComSignalBitPosition (see COM259) shall define the bit0 of the first byte like in little endian byte order.

**Remark:** [17] Chapter 2.4 defines the endianness conversion for unsigned data types. This endianness conversion shall be extended to signed data types. The associated configurations can be found in the configuration chapter. See also COM127 and COM157.

**COM008:** To map negative values of signed data correctly, the received data shall be extended to the size of the receiver (sign extension). The platform specific representation of signed data shall be taken into account.

**Example:** A 10-Bit signed signal is received and shall be copied by Com\_Receive-Signal to a 16-Bit signed integer variable. If  $(-3)_{\text{decimal}}$  is received the received 10-Bit

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<sup>1</sup> This Data type represents an array of exactly numberOfBits bits. It is called *opaque* because this array of bits should be transported "as is" by the AUTOSAR communication stack.

signal has a value of 1111111101b. While copying it to the 16-Bit integer variable the value has to be extended to 1111111111111101b.

**COM353:** On sender side there shall be no sign extensions.

**COM221:** Endianness conversion shall take place before the I-PDU callout on the sender side. (For an overview see Chapter 7.12).

**COM352:** Sign extensions and endianness conversion shall take place before configuration filtering and notification detection on receiver side.

### 7.2.3 Filtering

**COM272:** Each filtering condition shall either evaluate to true or false. Filtering out signals shall only take place at receiver side. On sender side the mechanisms are still used for Transmission Mode Conditions (TMC) but no signal filtering shall take place.

**Note:** For Transmission Mode Selection (TMS) see Chapters 7.4.3.6 and 7.4.3.5.

**COM480:** AUTOSAR COM shall only provide the following filter types which are defined in [17]

- ALWAYS
- MASKED\_NEW\_DIFFERS\_MASKED\_OLD
- MASKED\_NEW\_DIFFERS\_X
- MASKED\_NEW\_EQUALS\_X
- NEVER
- NEW\_IS\_OUTSIDE
- NEW\_IS\_WITHIN
- ONE EVERY\_N

**Note:** Some filters defined in [17] are removed from AUTOSAR COM to reduce complexity. The removed filters were either obsolete or special cases of other filters. For example the filter *NEW\_IS\_DIFFERENT* is a special case of *MASKED\_NEW\_DIFFERS\_MASKED\_OLD* with a fully set mask.

**COM325:** All filter mechanisms defined in COM480 shall be supported for all data types listed in COM007; considering the exceptions defined in COM380 and COM439.

**COM380:** For the type uint8[n] only the filters *ALWAYS* and *NEVER* shall be supported.

**COM439:** For the type boolean only the following filters shall be supported:

- ALWAYS
- NEVER
- MASKED\_NEW\_EQUALS\_X

- *MASKED\_NEW\_DIFFERS\_X*
- *MASKED\_NEW\_DIFFERS\_MASKED\_OLD*
- *ONE\_EVERY\_N*

**COM764:** For signals and group signals with ComBitSize configured to 0, the AUTOSAR COM module shall not support the filter algorithm *MASKED\_NEW\_DIFFERS\_MASKED\_OLD*.

**COM273:** If a signal is filtered out on receiver side (i.e. filter condition evaluates to FALSE), it shall be discarded and not be further processed. See also COM303.

**COM327:** Filtering out of signals as specified in COM273 shall not be applied to group signals.

**Note:** Conditions for TMS may be applied to group signals, see COM326.

**COM132:** The filtering mechanisms, defined in [17] and in Chapter 7.4.3.5 shall also be supported for signed data types.

In the case a filter is evaluated before a signal has been written to by a send-API, there needs to be a way to determine the filter state of this signal. Some of the filters require a *new\_value* to evaluate the filter. However, this is only available after the signal has been updated using a send-API. So it is necessary to define the value used by the filter for *new\_value* in the period before the first send takes place.

**COM230:** The *old\_value* of the filtering mechanisms is set during start-up to the init-value, see [17]. Up to the point in time where the application has not updated the value, for the *new\_value* also the init-value shall be used.

The next two requirements shall clarify the definitions of [17] according to the update of the *old\_value* of filters.

**COM302:** If a filter is evaluated to true (value is not filtered out) then the value is placed into *old\_value* (as defined in [17]).

**COM303:** When a value is being filtered, if the filter does not allow the passage of the value (i.e. the filter evaluates to false) then the value is not placed into *old\_value* (as defined in [17]).

**COM231:** In the case of the filter *ONE\_EVERY\_N*,

- OCCURRENCE shall be set to zero by Com\_IpduGroupStart
- FILTER shall be set true when OCCURRENCE == OFFSET
- OCCURRENCE shall be incremented after filter processing
- When OCCURRENCE == PERIOD, OCCURRENCE shall be set to zero.

For definition of OCCURRENCE, FILTER, OFFSET and PERIOD see [17].

This definition of the filter *ONE\_EVERY\_N* has the effect that the signal is passed by the filter (i.e. the filter returns true) once every *PERIOD* call of the filter. If the *OFFSET* parameter is zero then the first time the filter is used the signal is allowed to

pass (i.e. filter returns true). If the *OFFSET* is greater than zero then more than one message must pass through the filter before it returns true.

This definition exists to clarify the description of the *ONE EVERY N* filter in [17].

The associated configuration items can be found in the configuration chapter, see COM339.

**[COM793]** [For a signal with a configured reception filter *MASKED\_NEW\_DIFFERS\_MASKED\_OLD*, the AUTOSAR COM module shall treat the first value received for this signal after a reception deadline monitoring timeout occurred for this signal the same way as if the value has passed the filter criteria.] ()

Hence, the AUTOSAR COM module will let pass any value for the filter *MASKED\_NEW\_DIFFERS\_MASKED\_OLD* after an RX deadline timeout for the associated I-PDU.

## 7.2.4 Signal Gateway

AUTOSAR COM provides a signal gateway for forwarding signals and signal groups in a 1:n manner.

Signals and signal groups to be routed by the signal gateway are identified and configured by unique static names. The signal gateway determines the destination of a signal or of a signal group by using its name and a configuration table.

**COM370:** Furthermore the signal gateway should scale down to no size if no signal routing functionality is needed.

**COM371:** The signal gateway is placed as shown in Figure 3, Figure 13, Figure 14 and Figure 15.

## 7.3 Configuration

See Chapter 10.

## 7.4 Normal operation

### 7.4.1 Start-up behavior

This chapter describes the actions which shall be performed during *Com\_Init*.

**COM217:** The I-PDU init value (Chapter 7.4.1.3) and the signal / update-bit init value (Chapter 7.4.1.4) together result in one init value for each I-PDU. During *Com\_Init* this init value shall be used to initialize the I-PDU.

#### 7.4.1.1 Preconditions

**Note:** The C initialization code (also known as *start-up code*) which initializes global and static variables with the initial values shall be executed before any call of an AUTOSAR COM service.

#### 7.4.1.2 Initialization

**COM128:** The AUTOSAR COM module's initialization function `Com_Init` (COM432) shall initialize all internal data that is not yet initialized by the *start-up code* e.g. C-structs.

**Note:** The concrete initialization process is implementation specific.

**COM328:** The AUTOSAR COM initialization routine shall not enable Inter-ECU communication. Inter-ECU communication requires a separate start (see Chapter 7.4.5 for details).

The API function is defined by COM432.

**Note:** This initialization chapter is not complete. Details about initialization of some COM features are described within the different feature chapters.

#### 7.4.1.3 Initialization of not used areas of an I-PDU

**COM015:** AUTOSAR COM shall fill not used areas within an I-PDU with a value configurable at configuration-time, e.g. 0xFF.

See also COM017 for the associated configuration element.

#### 7.4.1.4 Initialization of signals and Update-bits

**COM098:** AUTOSAR COM shall initialize all signals on sender and receiver side with the configured init values which shall be the same value as used for the initialization of the signal in the related I-PDU (see COM217). For configuration see COM170 in the configuration chapter.

The signal init values may be identical to the AUTOSAR COM data invalid values. These may be different for each signal. For the related configuration items see COM391 and COM501.

**COM117:** AUTOSAR COM shall clear all update-bits during initialization. See also COM059.

#### 7.4.1.5 Initialization of I-PDU groups

**COM444:** By default all I-PDU groups shall be in the state 'stopped' and they shall not be started automatically while AUTOSAR COM initialization.



## 7.4.2 Shutdown behavior

### 7.4.2.1 De-initialization

**COM129:** AUTOSAR COM shall provide a functionality to de-initialize the layer. This means that after de-initialization of the layer no communication via AUTOSAR COM is possible and all started I-PDU groups are stopped.

The API function is defined by COM130.

## 7.4.3 Communication modes

This chapter defines the signal flow in AUTOSAR COM and how the different transmission modes in AUTOSAR COM are defined. Chapter 7.4.3.8 shows exemplary communication use cases that can be solved with AUTOSAR COM. Chapter 7.4.3.5 defines a mechanism to switch between two transmission modes for one I-PDU. The replication of signals is defined in Chapter 7.4.3.7.

### 7.4.3.1 Transfer Properties and I-PDU Transmission Modes

#### 7.4.3.2 Signals

[17] distinguishes between:

- Transfer properties (applies for signals)
- Transmission modes (applies for I-PDUs).

The following two tables are based on the corresponding tables in [17].

<i>TRANSFER PROPERTY</i> (per signal)	<i>Description</i>
<i>PENDING</i>	The <i>PENDING</i> transfer property does not cause transmission of an I-PDU.
<i>TRIGGERED</i>	<b>COM329:</b> At any send request of a signal with ComTransferProperty <i>TRIGGERED</i> assigned to an I-PDU with ComTxModeMode <i>DIRECT</i> or <i>MIXED</i> , the AUTOSAR COM module shall initiate ComTxModeNumberOfRepetitions transmissions of the assigned I-PDU within the next main function at the latest.
<i>TRIGGERED_ON_CHANGE</i>	<b>COM563:</b> At a send request of a signal with ComTransferProperty <i>TRIGGERED_ON_CHANGE</i> assigned to an I-PDU with ComTxModeMode <i>DIRECT</i> or <i>MIXED</i> , the AUTOSAR COM module shall immediately (within the next main function by the latest) initiate ComTxModeNumberOfRepetitions transmissions of the assigned I-PDU if the new value of the sent signal differs to the locally stored (last sent or init) value.
<i>TRIGGERED_ - WITHOUT_REPETITION</i>	<b>COM767:</b> At any send request of a signal with ComTransferProperty <i>TRIGGERED_WITHOUT_REPETITION</i> assigned to an I-PDU with ComTxModeMode <i>DIRECT</i> or <i>MIXED</i> , the AUTOSAR COM module shall immediately (within the next main

	function by the latest) initiate one transmission (as if ComTxModeNumberOfRepetitions would be 0) of the assigned I-PDU.
<i>TRIGGERED_ON_CHANGE_WITHOUT_REPETITION</i>	<b>COM768:</b> At a send request of a signal with ComTransferProperty <i>TRIGGERED_ON_CHANGE_WITHOUT_REPETITION</i> assigned to an I-PDU with ComTxModeMode <i>DIRECT</i> or <i>MIXED</i> , the AUTOSAR COM module shall immediately (within the next main function by the latest) initiate one transmission (as if ComTxModeNumberOfRepetitions would be 0) of the assigned I-PDU if the new value of the sent signal differs to the locally stored (last sent or init) value.

**Table 3: Transfer Properties defined for signals**

**COM762:** The AUTOSAR COM module shall not support the transfer property *TRIGGERED\_ON\_CHANGE* and *TRIGGERED\_ON\_CHANGE\_WITHOUT\_REPETITION* for signals and group signals with ComBitSize configured to 0.

**Note:** A pending signal associated with an I-PDU is transmitted if either a signal with a triggering transfer property within the same I-PDU is sent or the I-PDU is sent because of a timer (Periodic / Mixed transmission mode).

<i>Transmission mode</i> (per I-PDU)	<i>Description</i>
<i>DIRECT</i> (N-Times)	<b>COM330:</b> The transmission of an I-PDU with transmission mode <i>DIRECT</i> can be caused by a send request of a signal with one of the transfer properties: <ul style="list-style-type: none"> <li>• <i>TRIGGERED</i> (see COM329)</li> <li>• <i>TRIGGERED_ON_CHANGE</i> (see COM563)</li> <li>• <i>TRIGGERED_WITHOUT_REPETITION</i> (see COM767)</li> <li>• <i>TRIGGERED_ON_CHANGE_WITHOUT_REPETITION</i> (see COM768)</li> </ul>
<i>PERIODIC</i>	In Periodic transmission mode, AUTOSAR COM issues periodic transmission requests for an I-PDU to the underlying layer.
<i>MIXED</i>	Mixed transmission mode is a combination of the “Direct/N-Times” and the Periodic transmission modes.
<i>NONE</i>	<b>COM135:</b> In transmission mode <i>NONE</i> no transmission is initiated by AUTOSAR COM. It shall only be possibly to request I-PDUs with Com_TriggerTransmit (see COM001). The configuration is defined by COM137.

**Table 4: Transmission modes defined for I-PDUs**

On the one hand the timing of bus messages can be controlled by send requests of the upper layer in combination with the transmission mode and the transfer property as described above. On the other hand it can be controlled by the lower layer (esp. for FlexRay and LIN) with the service Com\_TriggerTransmit. In this case the lower layer requests I-PDUs that have to be provided by COM.

**COM260:** It shall be possible to use Com\_TriggerTransmit to request the transmission of any I-PDU with any transmission mode.

**Note:** This allows LIN and FlexRay to use all the available transmission modes, particularly for sporadic communication. This mechanism is also used by the NM to send user data.

### 7.4.3.3 Signal Groups

In AUTOSAR COM also signal groups and group signals may have a transfer property, defining in combination with the transmission mode, if the I-PDU is sent out in case of an update of a signal group or group signal, respectively.

<b>TRANSFER PROPERTY</b> <i>(per signal group)</i>	<b>Description</b>
<i>TRIGGERED</i>	<b>COM564 :</b> The triggered transfer property causes immediate transmission (within the next main function by the latest) of the I-PDU, except if transmission mode <i>PERIODIC</i> or transmission mode <i>NONE</i> is defined for the I-PDU (see Table 4).
<i>PENDING</i>	<b>COM565 :</b> The “Pending” transfer property does not cause transmission of an I-PDU.
<i>TRIGGERED_ON_CHANGE</i>	At a send request of a signal group with ComTransferProperty <i>TRIGGERED_ON_CHANGE</i> assigned to an I-PDU with ComTxModeMode <i>DIRECT</i> or <i>MIXED</i> two cases shall be distinguished:  <b>COM566:</b> If none of the signal group’s group signals has a ComTransferProperty specified, the AUTOSAR COM module shall immediately (within the next main function by the latest) initiate ComTxModeNumberOfRepetitions transmissions of the assigned I-PDU, if at least one new value of the signal group’s group signals differs to the locally stored (last sent or init) value.  <b>COM567:</b> If at least one group signal of a signal group has the ComTransferProperty configured, all other group signals of that signal group shall have configured ComTransferProperty as well. If the ComTransferProperty is set to <i>PENDING</i> : a change of the value of this group signal shall not trigger the transmission of the assigned I-PDU. If the “ComTransferProperty” is set to <i>TRIGGERED_ON_CHANGE</i> , a change of the value of this group signal shall trigger the transmission of the assigned I-PDU.
<i>TRIGGERED_WITHOUT_REPETITION</i>	<b>COM769:</b> At any send request of a signal group with ComTransferProperty <i>TRIGGERED_WITHOUT_REPETITION</i> assigned to an I-PDU with ComTxModeMode <i>DIRECT</i> or <i>MIXED</i> , the AUTOSAR COM module shall immediately (within the next main function by the latest) initiate one transmission of the assigned I-PDU.
<i>TRIGGERED_ON_CHANGE_WITHOUT_REPETITION</i>	<b>COM770:</b> At a send request of a signal group with ComTransferProperty <i>TRIGGERED_ON_CHANGE_WITHOUT_REPETITION</i> assigned to an I-PDU with ComTxModeMode <i>DIRECT</i> or <i>MIXED</i> , the AUTOSAR COM module shall immediately (within the next main function by the latest) initiate one transmission of the assigned I-PDU if the new value of the sent signal differs to the locally stored (last sent or init) value.

#### 7.4.3.4 Link to the VFB specification

**Note:** This chapter is just an illustration how the transfer mode relates to the VFB specification and links to a non normative part of the VFB specification.

Because, from the point of view of the AUTOSAR SW Component, it is not known at implementation time, which communication media is used, all bus specific replications of send requests by a SW component to underlying layers as well as all bus specific timing behavior must be done either by AUTOSAR COM or by the appropriate bus interfaces and drivers.

AUTOSAR COM implements the replication of transmission requests and the bus specific timing behavior by a combination of transfer properties and transmission modes, which is shown in the table below. The entries in the table correspond to the VFB's send modes:

<i>Transfer property (horizontal) Transmission mode (vertical)</i>	<i>TRIGGERED/ TRIGGERED ON CHANGE</i>	<i>PENDING</i>
<i>Direct/N-Times</i>	<i>N-Times</i>	--
<i>Periodic</i>	--	<i>Cyclic</i>
<i>Mixed</i>	<i>N-Times</i>	<i>Cyclic</i>
<i>None</i>	--	--

**Table 5: Mapping of transfer property and transmission Mode (I-PDU) to send modes defined in the AUTOSAR Specification of the Virtual Functional Bus [6]**

#### 7.4.3.5 Selection of the Transmission Mode for one specific I-PDU

Signals are carried by I-PDUs. Because an I-PDU can contain more than one signal, in the following, a method is defined to derive the I-PDU's transmission mode from the state of the signals that are contained in one specific I-PDU.

AUTOSAR COM allows configuring statically two different transmission modes for each I-PDU (see COM032). The transmission mode of an I-PDU that is valid at a specific point in time is selected using only the values of the signals that are mapped to this I-PDU.

The signals of one I-PDU that contribute to the selection of one of the two transmission modes as well as the conditions used for the selection of the transmission mode are configured statically.

**COM326:** For the selection of the transmission mode the group signals shall be treated like normal signals. Therefore each group signal shall contribute, depending on its configuration, to the evaluation of the transmission mode.

The following definitions give an overview about terms used in the following specification articles.

<b>Definitions</b>	
$s_i$	Signal in AUTOSAR COM
$IPDU_k$	I-PDU in AUTOSAR COM
$C(s_i, IPDU_k)$	Transmission Mode Condition (TMC), condition attached to a signal ( $s_i$ ) within an I-PDU ( $IPDU_k$ )
$S_k$	The set of all signals ( $s_i$ ) within one I-PDU ( $IPDU_k$ )
$M_k$	The set of all signals ( $s_i$ ) within one I-PDU ( $IPDU_k$ ) which contribute according to their configuration to the selection of the transmission mode. $M_k$ has to be a subset of $S_k$ .
$TMS_k$	The Transmission Mode Selector (TMS) is calculated from the evaluation of all $C(s_i, IPDU_k)$ for all $s_i$ in $M_k$

**Table 6: Definitions for transmission mode selection**

**COM274:** To each signal ( $s_i$ ) mapped to a specific I-PDU ( $IPDU_k$ ) a condition  $C(s_i, IPDU_k)$  shall be associated (see COM275).

**COM283:** The conditions  $C(s_i, IPDU_k)$  available shall be the same as provided for the filter mechanism (see COM272 and COM480). The definitions made in COM230 and COM231 shall also be applied for the evaluation of the TMS.

**Definition:** (see also [17])

For each I-PDU ( $IPDU_k$ ) a Transmission Mode Selector ( $TMS_k$ ) is defined.  $TMS_k$  is calculated by evaluating the conditions  $C(s_i, IPDU_k)$  for a configurable subset of signals  $M_k$  (see COM275) of the set of all signals  $S_k$  mapped to the  $IPDU_k$ .

$TMS_k$  is defined to be true, if at least one  $C(s_i, IPDU_k)$  in  $M_k$  evaluates to true and is defined to be false, if all  $C(s_i, IPDU_k)$  in  $M_k$  evaluate to false.

$$TMS_k = \begin{cases} \text{true, if at least one } C(s_i, IPDU_k) \equiv \text{true for all } s_i \in M_k \\ \text{false, if } C(s_i, IPDU_k) \equiv \text{false for all } s_i \in M_k \end{cases}$$

**Table 7: Calculation of transmission mode selector**

**COM241:** AUTOSAR COM shall be able to define and calculate a TMS for each I-PDU as defined in the definition given above.

**COM245:** The TMS of each I-PDU containing a specific signal shall be re-calculated within a call of `Com_SendSignal` respective `Com_SendSignalGroup` by the upper layers for that specific signal.

**COM763:** For the calculation of the transmission mode with the configured condition `MASKED_NEW_DIFFERS_MASKED_OLD`, the AUTOSAR COM module shall use the least significant `ComBitSize` bits only.

**COM826:** For the calculation of the transmission mode with a configured condition `MASKED_NEW_DIFFERS_X`, `MASKED_NEW_EQUALS_X`, `NEW_IS_OUTSIDE` or

NEW\_IS\_WITHIN, the AUTOSAR COM module shall use all bits of the configured ComSignalType.

**COM284:** AUTOSAR COM must provide the mechanisms to specify which signals shall contribute to the evaluation of TMS, i.e. to define the set of signals  $M_k$  that contribute to the evaluation of the  $TMS_k$ .

For the configuration see COM275.

**COM255:** If no signal within an I-PDU is configured to contribute to the calculation of the TMS, the TMS shall be set to true.

**Comment:** Note that a signal with  $C(s_i, IPDU_k)$  ALWAYS – if it contributes to the selection of the transmission mode – will always set the TMS of the respective I-PDU to true. Therefore, care must be taken when defining the signals that contribute to the TMS.

**COM032:** On sender-side two independent transmission modes shall be configured for each I-PDU. One of those transmission modes shall be valid if the TMS evaluates to true, the other transmission mode shall be valid, if the TMS evaluates to false.

The transmission modes, which can be configured separately for each evaluation result, are defined in the configuration chapter, see COM233 and COM234.

**COM238:** In each of the two TMS states, the rules for combination of transfer properties of signals and transmission modes of I-PDUs shall apply as defined in [17], Section 2.3.

**COM239:** When the TMS state for an I-PDU changes, the AUTOSAR COM module shall use the now valid transmission mode immediately (within the next main function by the latest). That means, first the AUTOSAR COM module shall perform the mode change and after that, the AUTOSAR COM module shall execute any resulting calls to PduR\_ComTransmit caused by mode change.

**COM244:** If a change of the TMS causes a change of the transmission mode for an I-PDU, then the AUTOSAR COM module shall restart the timer for the cycle time of the transmission mode PERIODIC and MIXED.

**COM495:** If a send request of a signal or signal group causes a change of the transmission mode of the assigned I-PDU to the transmission mode PERIODIC or MIXED, then the AUTOSAR COM module shall start the new transmission cycle with a call to PduR\_ComTransmit within the next main function at the latest. The transmission shall be initiated regardless of the transfer property of the signal or signal group that caused the transmission mode switch. The MDT shall still be respected. See also Figure 6.

**COM582:** If a change of the TMS causes a change to the transmission mode DIRECT, an immediate (within the next main function by the latest unless shifted due to the MDT) direct/ n-times transmission to the underlying layer shall be initiated.

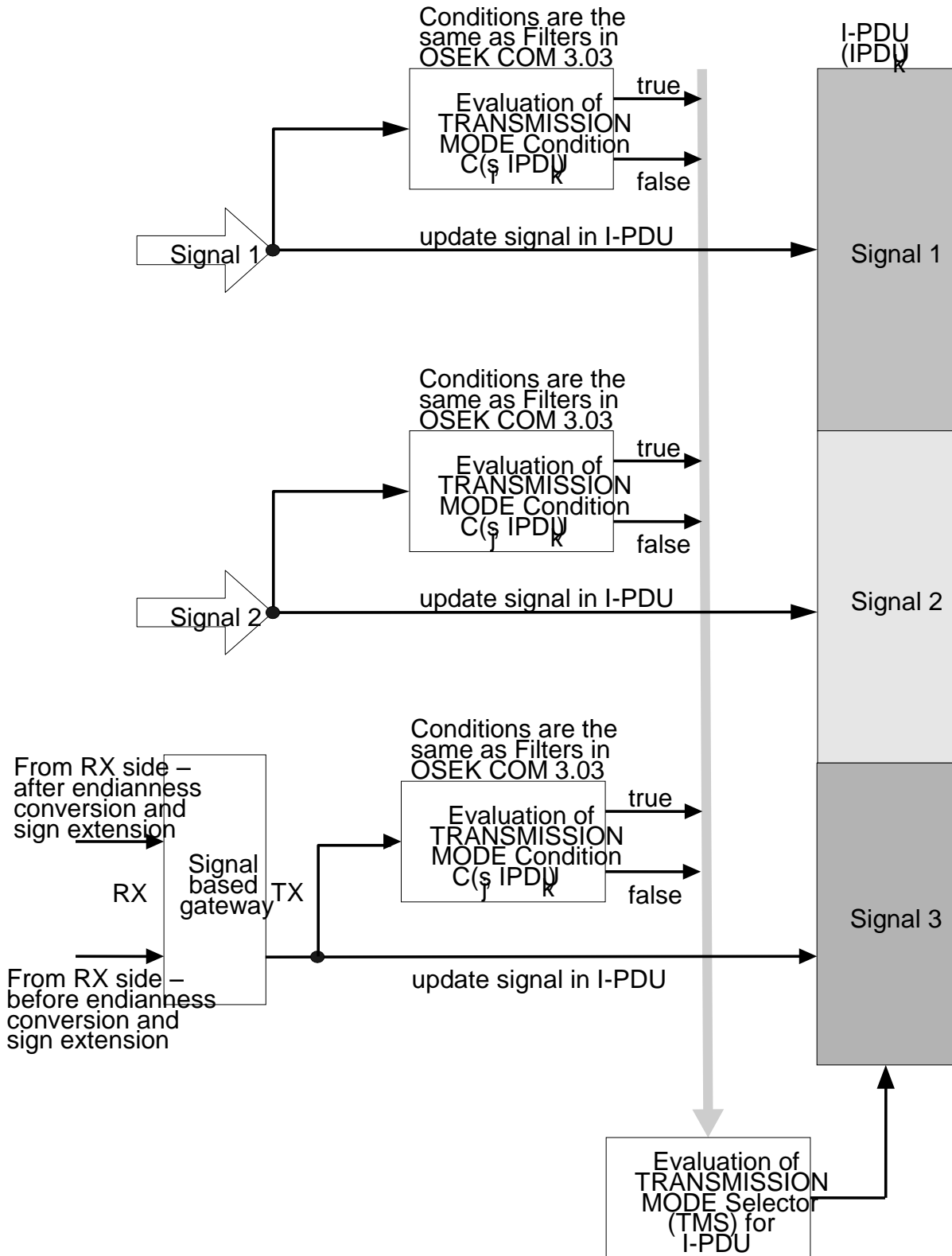
**Remark:** In case the TMS evaluates to false, it shall be possible to configure the transmission mode in that way that no transmission takes place (transmission mode None). This prevents the I-PDU to be transmitted and shall be the default. For the configuration see COM234.

**COM478:** An I-PDU shall be sent out at most once while one call to Com\_MainFunctionTx.

#### 7.4.3.6 Signal flow and Transmission Mode Selection

After a send request from an upper layer for a specific signal the signal is written to the appropriate I-PDU buffer as defined by configuration and the selection of the transmission mode of the I-PDUs is done according to Chapter 7.4.3.5.

Figure 3 shows the signal flow:



**Figure 3: Logical signal flow in AUTOSAR COM shown for two signals (Signal1 and Signal2) that are mapped to one I-PDU (IPDU<sub>k</sub>)**



#### 7.4.3.7 Replication of Signal Transmission Requests

**COM276:** In the Direct/N-Times and Mixed transmission modes AUTOSAR COM shall be able to send  $n$  transmission requests ( $n = 0, 1 \dots m, m \leq 255$ ) to the lower layer for each send request by an upper layer. See also the matching configuration requirement COM281.

**COM467:** If `ComRetryFailedTransmitRequests` is not set to `TRUE` and an I-PDU with `ComTxModeMode` `DIRECT` or `MIXED` and `ComTxModeNumberOfRepetitions` set to 0 is triggered for sending, the AUTOSAR COM module shall invoke `PduR_ComTransmit` for this I-PDU just once, independently of the result of the confirmation.

Configuring `ComTxModeNumberOfRepetitions` to 0 imitates the original OSEK direct transmission mode.

**COM279:** If a new send request is received from an upper layer while sending  $n$  transmissions belonging together (e.g. after the 3<sup>rd</sup> of 5 repetitions, see COM276) AUTOSAR COM shall cancel the outstanding transmission repetitions and start processing the new request immediately, see Figure 4.

**COM305:** The confirmation behavior to the upper layer in the Direct/N-Times transmission mode with  $n > 0$  shall be according to the following definition:

- 1) When an I-PDU is sent by the application with Direct/N-Times transmission mode,  $n$  is put into a counter in COM.
- 2) COM sends to the underlying layer an N-Times I-PDU periodically as long as the counter is non-zero.
- 3) Whenever a TX confirmation is received and the counter is greater than 0, the counter is decremented. When the counter is 0, transmission confirmations for that I PDU are ignored.
- 4) When the counter reaches 0 the transmission confirmation is send to the upper layer and transmission deadline monitoring is cancelled (if configured). See COM392 and Chapter 7.4.6.2.

**Note:** The definition in COM305 shall not define a concrete implementation. But every implementation shall implement the confirmation behavior according to the above definition.

**Note:** This solution allows the violation of the period in certain extreme circumstances when the confirmations arrive late in the period.

This solution requires that CAN does not have a queue for these L-PDUs.

There is a race condition in the interaction between the CAN driver, interface and hardware that may cause an extra transmission to occur in certain unlikely circumstances.

**Note:** If the underlying layer returns `E_NOT_OK` while an N-Times transmission is in progress this error notification shall be ignored (as defined in COM428). As COM305 specifies only confirmed transmissions are counted for the N-Times transmission, erroneous send request can safely be ignored.

**Note:** If the N-Times transmission is requested in Mixed transmission mode after a Cyclic transmission of the Mixed transmission mode with a pending confirmation, the confirmation of the cyclic transmission will be assigned to the N-Times transmission. In this case only  $n-1$  transmissions of the new value of the N-Times request are made, if no confirmation gets lost. The transmission deadline monitoring timer will then be reset earliest after the N-Times request is completed. This must be respected when configuring the transmission deadline monitoring timer in conjunction with the Mixed transmission mode and N-Times transmission.

**COM494:** If within the Mixed transmission mode an N-Times transmission request overlaps with the cyclic part of the Mixed transmission the Cyclic transmission shall be counted as the corresponding transmission of the N-Times transmission request.

**COM392:** If a transmission deadline monitoring timeout occurs before the N-Times transmission is complete, the N-Times transmission shall be abandoned.

**Note:** The minimum delay time shall always be taken into account as defined in [17].

**Note:** To avoid bursts in start-up a time offset can be configured per I-PDU. For details see COM180.

**COM277:** The number of repetitions ( $n$ ) shall be configurable (see COM281).

**COM278:** The time between two repetitions shall be configurable (see COM282).

**Note:** If the transmission mode change leads to the start of the Mixed transmission mode by sending a triggered signal and `ComTxModeNumberOfRepetitions` is configured  $> 1$  then there will be at least  $n$  transmission requests to the lower layer at the beginning of the Mixed transmission mode. See also COM276.

**COM310:** It shall not be possible to use/configure update-bits for signals that are transmitted within I-PDUs having the Direct/N-Times transmission mode with  $n \geq 1$ . (I.e. only  $n=0$  is allowed).

**Note:** There is no common understanding how update-bits and N-Times transmission can be combined. It is unclear when update-bits shall be set and cleared respecting the replication. Therefore this is currently forbidden.

#### 7.4.3.8 Retry Failed Transmission Requests

**COM773:** If `ComRetryFailedTransmitRequests` is set to TRUE the return value of `PduR_ComTransmit` shall be evaluated. If the return value of `PduR_ComTransmit` is not equal to `E_OK`, the AUTOSAR COM Module shall invoke `PduR_ComTransmit` for the not sent I-PDU again within the next `Com_MainFunctionTx`.

If the I-PDU is updated in between, the new data will be sent.

COM773 may lead to multiple retries for the same failed transmission request.

COM773 is not affected by transmission mode changes.

COM773 has no influence on a potential repetition period. Any repetitions will occur as if no retry had taken place.

**COM774:** The AUTOSAR COM module shall start the transmission deadline monitoring independently of possible retries. Subsequent retries shall not affect transmission deadline monitoring.

**COM775:** If ComRetryFailedTransmitRequests is set to True and a transmission deadline monitoring timeout occurs for an I-PDU, the AUTOSAR COM module shall expire any pending transmission request for this I-PDU.




**COM776:** The cycle timer for a cyclic transmission shall always start with the first transmit attempt.

**COM779:** If ComRetryFailedTransmitRequests is set to TRUE the return value of PduR\_ComTransmit shall be evaluated according to COM773, even though it is otherwise stated in a note to COM305.

**7.4.3.9 Use Cases for communication modes**

This chapter shows use cases which have to be realizable by the transmission modes and transfer properties specified in AUTOSAR COM.

**Note:** For a more detailed discussion of the following use cases see Appendix A.

<b>Use case diagram legend</b>	
$t_c, t_{c1}, t_{c2}$	Cycle times
$t_d$	Cycle time of N-Times send signals
$t_{r, min}$	Minimum SW reaction time of COM-Layer, e.g. due to internal cycle time
V	Value: x stands for an arbitrary value / value range, a...w for specific values / value ranges, defined by the user, with a <> b, range a is disjoint from range b.
	Request from upper layers (RTE) to the COM-Layer
	Request from COM-Layer to lower layers (PDU-Router)
	Potential but skipped request from COM-Layer to lower layers (e.g. because of a new send request by upper layers or delayed due to minimum delay time)
dt	Minimum distance between two requests to lower layers (minimum delay time), dt can be set per I-PDU.
w/o TMS switch	Without switching of the TMS (see 7.4.3.5) from true to false or vice versa.
w TMS switch	With switching of the TMS (see 7.4.3.5) from true to false or vice versa (from TM 1 to TM 2) One TM is named before the "+" and one behind in the description.

**Table 8: Legend for use case diagrams.**

Use case diagrams:

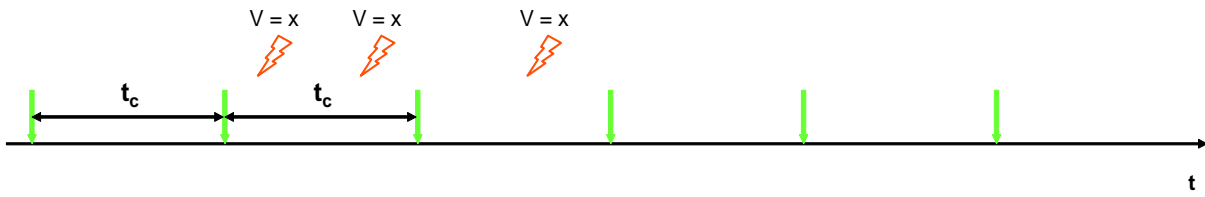


Figure 4: Use case 1, TM Periodic (without TMS switch)

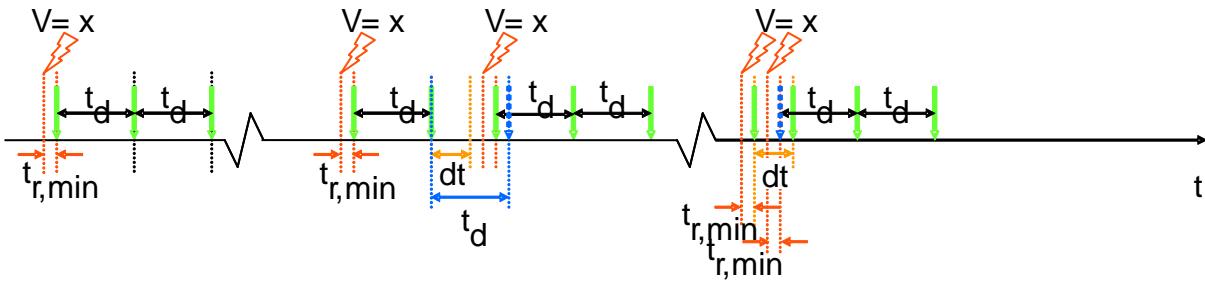


Figure 5: Use case 2, TM Direct/N-Times, here  $n = 3$  (without TMS switch)

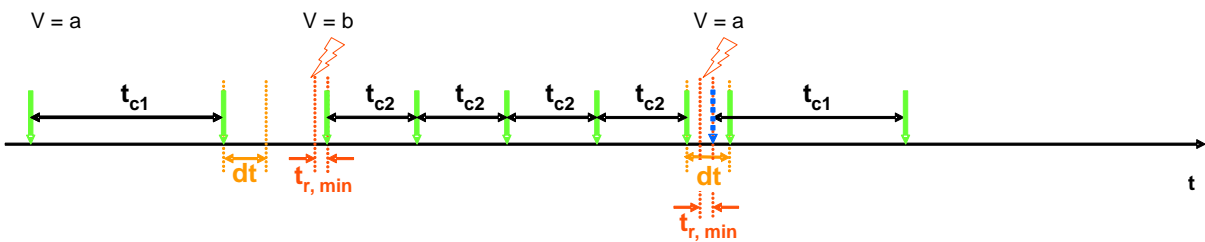


Figure 6: Use case 3, TM Periodic + Periodic (with TMS switch)

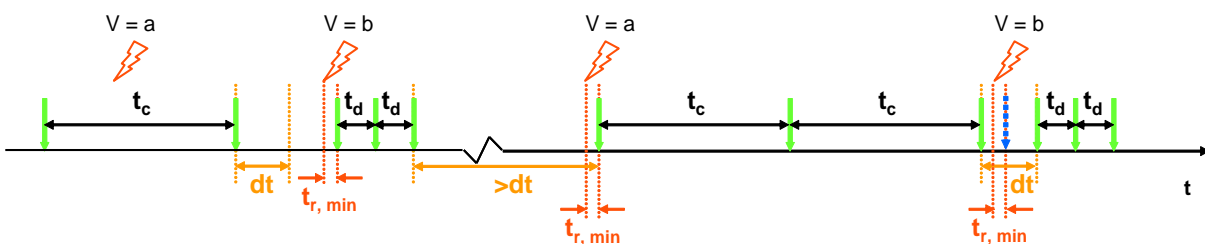


Figure 7: Use case 4a, TM Periodic + Direct/N-Times, here n = 3 (with TMS switch)

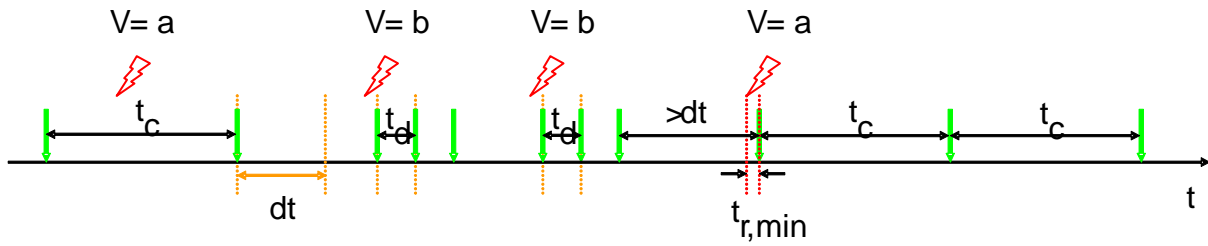


Figure 8: Use case 4b, TM Periodic + Direct/N-Times, here n = 3 (with TMS switch)

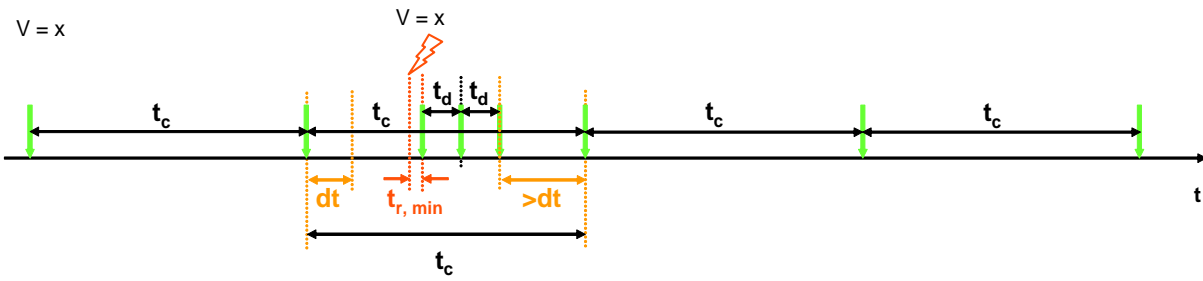


Figure 9: Use case 5a, TM Mixed, here n = 3 (without TMS switch)

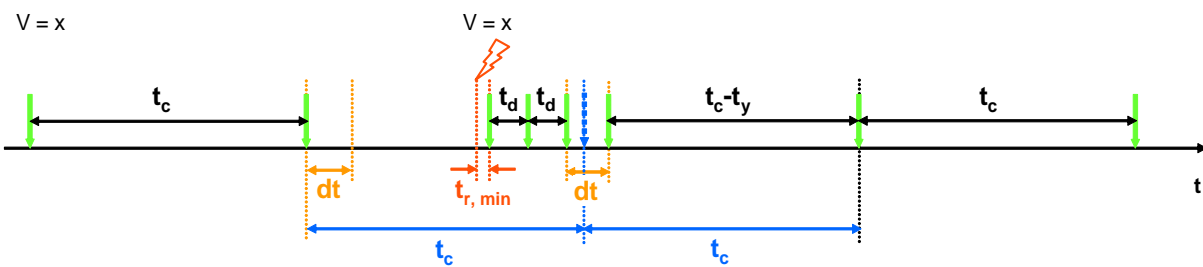


Figure 10: Use case 5b, TM Mixed, here n = 3 (without TMS switch)

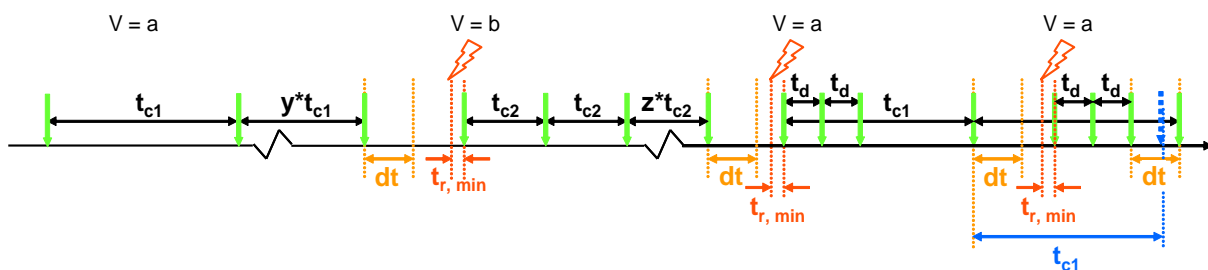


Figure 11: Use case 6, TM Mixed, here  $n= 3 + \text{Periodic (with TMS switch)}$ 

#### 7.4.4 Signal invalidation mechanism

**COM097:** It shall be possible for the sender side to indicate AUTOSAR COM that it is not able to provide a valid value for a corresponding signal (e.g. sensor is faulty). It shall be possible during configuration to define a *data invalid value* (for configuration see COM501).

##### 7.4.4.1 Transmission of an invalidated signal

**COM099:** AUTOSAR COM shall replace the current value of a signal by the data invalid value if the AUTOSAR software component indicates that it is not able to provide a valid value, see also Com\_InvalidateSignal. AUTOSAR COM shall internally perform a Com\_SendSignal with the configured data invalid value. For the associated configuration elements see COM501. Therefore the transmission of the data invalid value on the bus is determined by the transfer property and the transmission mode.

**Note:** The internally performed Com\_SendSignal with the data invalid value leads to data invalid value to be used as current value for filters and TMS.

**COM286:** By a call of Com\_InvalidateShadowSignal AUTOSAR COM shall replace the current value of the signal with the given SignalId within the associated signal group by the configured data invalid value. By this call no send request shall be initiated.

**Note:** Compared to Com\_InvalidateSignal, there is no send request associated with Com\_InvalidateShadowSignal.

**Note:** The RTE has to call Com\_InvalidateShadowSignal for each signal inside a signal group.

Example with 2 signals signal\_a and signal\_b which belong to group\_x:

```
/* invalidate signal a in shadow buffer with configured data invalid value */  
Com_InvalidateShadowSignal (signal_a);  
  
/* invalidate signal b in shadow buffer with configured data invalid value */  
Com_InvalidateShadowSignal (signal_b);  
  
/* copy shadow buffer to I-PDU */  
Com_SendSignalGroup (group_x);
```

The data invalid values are configured per group signal see COM391.

**Note:** The invalidation of the whole signal group results in a consistent state of the signal group during transmission.

**Note:** The VFB defines only one attribute for a complex data type. Therefore the best mapping of an invalidated complex data type to an invalidated signal group is to invalidate all group signals of a signal group.

#### 7.4.4.2 Reception of an invalidated signal

**COM680:** If the configured ComSignalDataInvalidValue (COM391) is received for a signal and the ComDataInvalidAction (COM314) is configured to **NOTIFY** for this signal, the AUTOSAR COM module shall notify the RTE via the configured ComInvalidNotification function (COM315). In this case, no other signal processing like filtering or the normal signal indication shall take place.

**Note:** The reception deadline monitoring timer is also restarted in case of receiving an invalid signal or signal group, see COM738.

**COM681:** If the configured ComSignalDataInvalidValue (COM391) is received for a signal and the ComDataInvalidAction (COM314) is configured to **REPLACE** for this signal, the AUTOSAR COM module shall replace the signal's value by its configured ComSignalInitValue (COM170). After the replacement, the normal signal processing like filtering and notification shall take place as if the ComSignalInitValue would have been received instead of the ComSignalDataInvalidValue.

**COM736:** In case **no** ComDataInvalidAction is configured for a (group) signal, the AUTOSAR COM module, shall handle a reception of this signal always like a reception of a valid value.

**COM682:** If the configured ComSignalDataInvalidValue (COM391) is received for at least one group signal of a signal group and the ComDataInvalidAction (COM314) is configured to **NOTIFY** for this signal group, the AUTOSAR COM module shall notify the RTE via the configured ComInvalidNotification function (COM315). In this case, no other signal group/ group signal processing and no normal indication shall take place.

**COM683:** If the configured ComSignalDataInvalidValue (COM391) is received for at least one group signal of a signal group and the ComDataInvalidAction (COM314) is configured to **REPLACE** for this signal group, the AUTOSAR COM module shall replace all group signals of this signal group by their configured ComSignalInitValue values. After the replacement, the normal signal group/ group signal processing and notification shall take place as if the ComSignalInitValue would have been received for all group signals.

**COM737:** In case **no** ComDataInvalidAction is configured for a signal group, the AUTOSAR COM module, shall handle a reception of this signal group always like a reception of valid signal group.

**COM717:** If the configured ComSignalDataInvalidValue is received for a signal and its ComDataInvalidAction is configured to **NOTIFY**, the AUTOSAR COM module shall not store the received ComSignalDataInvalidValue into the signal object.

The next call to Com\_ReceiveSignal will return the last valid reserved signal or the ComSignalInitValue in case no signal was received yet respectively.

**COM718:** If the configured ComSignalDataInvalidValue is received for at least one group signal of a signal group and its ComDataInvalidAction is configured to **NOTIFY**, the AUTOSAR COM module shall not store any of the received group signals into the signal objects.

The next call to Com\_ReceiveSignalGroup will copy the last valid reserved group signals or the ComSignalInitValues in case the signal group was not received yet respectively into the shadow buffer.

## 7.4.5 Handling of I-PDUs

### 7.4.5.1 I-PDU group definitions

For I-PDUs and I-PDU groups the following rules apply:

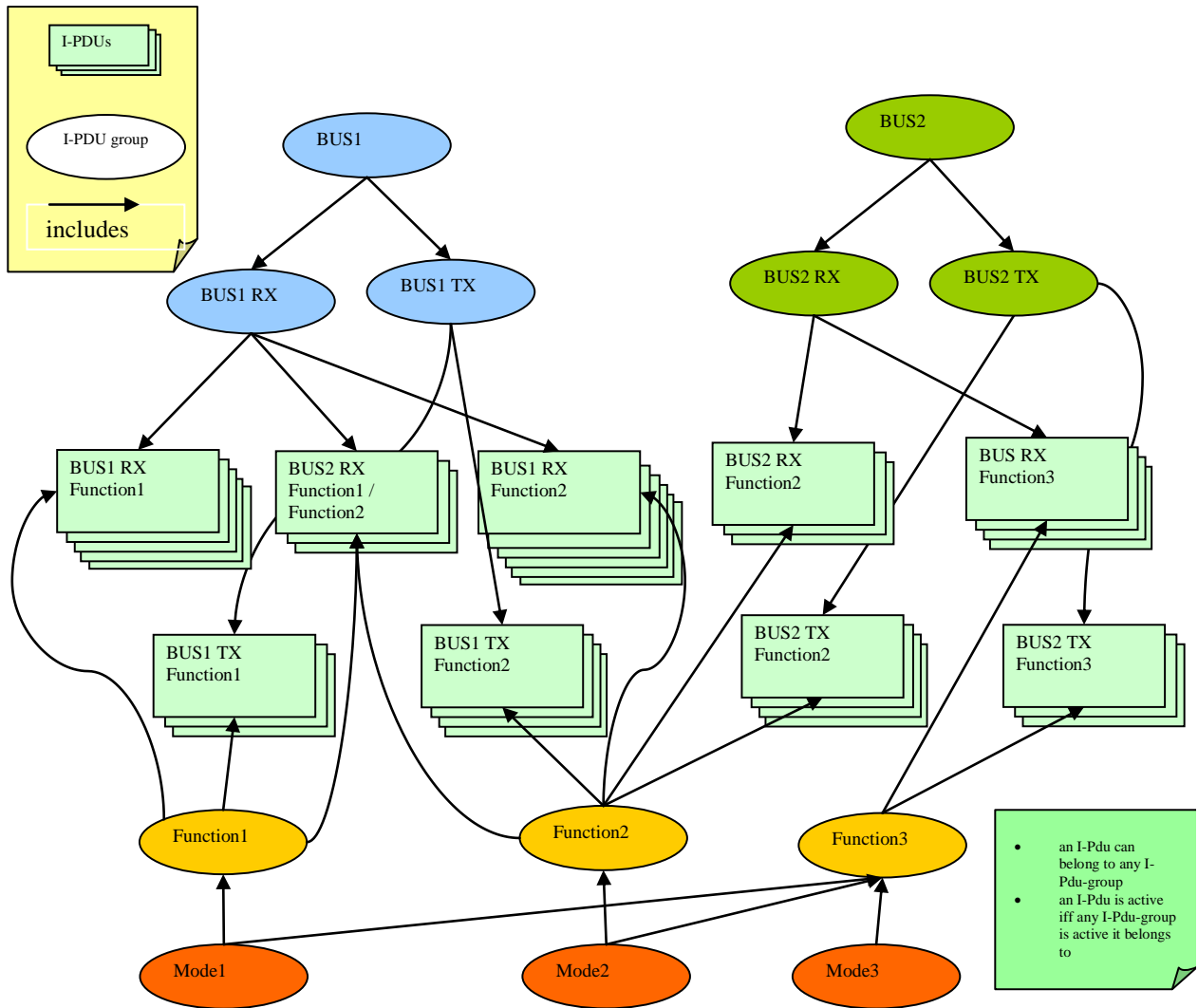
1. An I-PDU can belong to any I-PDU group.
2. **COM771:** An I-PDU is **active (started)** if and only if at least one I-PDU group is active (started) it belongs to.
3. The maximum number of I-PDU groups is pre-compile configurable.

The maximum number of supported I-PDU groups can be configured via ComSupportedIpdugroups (COM710\_Conf).

Up to the definitions above, an I-PDU is named **activated/ started**, if any of the I-PDU groups containing this I-PDU is activated/ started. If an I-PDU is not started, it is called to be **stopped** or **deactivated**. An I-PDU must belong to at least one I-PDU group in order to be able to get started.

The nesting of I-PDU groups is purely conceptual and must be resolved by the configuration tool. Thus, if an I-PDU “*BUS1 RX Function1*” belongs to I-PDU group “*BUS1 RX*” and I-PDU group “*BUS1 RX*” is included in I-PDU group “*BUS1*” then I-PDU “*BUS1 RX Function1*” must also be included in I-PDU group “*BUS1*”. Such dependencies have to be resolved at configuration time.





**Figure 12: Grouping of I-PDUs and I-PDU groups**

### 7.4.5.2 Starting of I-PDU groups

By default all I-PDUs and all I-PDU groups are stopped, see COM444. A call to Com\_IpduGroupStart starts an I-PDU group if it was previously stopped.

**COM114:** If an I-PDU is started as result of a call to Com\_IpduGroupStart, the AUTOSAR COM module shall permit to transmit/ receive its signals and signal groups, see also Table 10.

**COM222:** If an I-PDU is started as result of a call to `Com_IpduGroupStart` with parameter *Initialize* set to *true*, the AUTOSAR COM module shall initialize the following attributes of this I-PDU:

- 1) initialize the minimum delay time supervision of this I-PDU (see `ComTxIPdu-MinimumDelayTimeFactor`), so that a new sending of this I-PDU is allowed regardless of the last sent-time of this I-PDU.
- 2) start a new transmission period (see `ComTxModeTimePeriodFactor`) for the periodic part of the *Periodic* and *Mixed* transmission mode after the delay of periodic time offset (see `ComTxModeTimePeriodFactor`).
- 3) start the transmission/ reception deadline monitoring anew with respecting the first timeout (see `ComFirstTimeoutFactor`).
- 4) clear all included update-bits.
- 5) reset the counted *occurrence* of the *ONE\_EVERY\_N* filter algorithm.

**COM223:** If an I-PDU is started as result of a call to `Com_IpduGroupStart`, the AUTOSAR COM module shall determine its transmission mode according to its current data content.

**COM228:** In some cases, an I-PDU is started as result of a call to `Com_IpduGroupStart` before all its contained signals have been written. In this case, the AUTOSAR COM module shall use the `ComSignalInitValue` for the missing signal data. The AUTOSAR COM module shall determine the transmission mode of the started I-PDU according to its signal data content.

**COM229:** When an I-PDU is started and one or more signals in that I-PDU have already been written via one of the send APIs by the upper layer, the AUTOSAR COM module shall use the most recently sent values to determine the TMS of the I-PDU.

**COM733:** If an I-PDU is started as result of a call to `Com_IpduGroupStart` and the I-PDU contains signals that have deadline monitoring configured (`COM183`, `COM263`), the AUTOSAR COM module shall start the deadline monitoring for these signals independently of the value of the *initialize* parameter.

**COM740:** If an I-PDU is started as result of a call to `Com_IpduGroupStart` for the first time after `Com_Init` and the parameter *initialize* is set to *false*, the AUTOSAR COM module shall start this I-PDU as if it was started with *initialize* set to *true*.

### 7.4.5.3 Stopping of I-PDU groups

A call to `Com_IpduGroupStop` stops an I-PDU group if it was previously started.

In order to disable the transmission of an I-PDU, all I-PDU groups containing this I-PDU have to be stopped. Hence, to implement *listen-only-mode*, all I-PDU groups containing transmission I-PDUs must be stopped. Receiving of I-PDUs may also be stopped.

**COM334:** By a call to the functions: `Com_SendSignal`, `Com_UpdateShadowSignal`, `Com_SendSignalGroup`, `Com_InvalidateSignal`, or `Com_InvalidateShadowSignal`, the AUTOSAR COM module shall update the values of its internal buffers even for stopped I-PDUs. See also Table 9.

**Note:** If a signal written to a stopped I-PDU would trigger the transmission of this I-PDU if it were not stopped, then this trigger is not stored. After re-starting the corresponding I-PDU group, such an old trigger does not lead to an immediate transmission of the I-PDU.

**COM777:** If an I-PDU is stopped as result of a call to `Com_IpduGroupStop`, the AUTOSAR COM module shall cancel any outstanding transmission requests for this I-PDU. This includes cancelling any potential retries with respect to *Retry Failed Transmission Requests*.

**COM115:** If an I-PDU is stopped as result of a call to `Com_IpduGroupStop`, the AUTOSAR COM module shall cancel deadline monitoring for all pending confirmations and ignore any transmit confirmations.

The AUTOSAR COM module cannot prohibit the invocation of the `Com_TriggerTransmit` function.

**COM684:** If an I-PDU is stopped as result of a call to `Com_IpduGroupStop`, the AUTOSAR COM module shall disable its reception processing.

**COM685:** If an I-PDU is stopped as result of a call to `Com_IpduGroupStop`, the AUTOSAR COM module shall cancel its deadline monitoring.

**COM479:** If an I-PDU is stopped as result of a call to `Com_IpduGroupStop`, the AUTOSAR COM module shall immediately invoke the configured `Com_ErrorNotification` (COM499), for outstanding not confirmed transmitted signals/ signal groups of the stopped I-PDU.

Table 9 gives an overview of the behavior of stopped I-PDUs:

<b>Behavior on stopping an I-PDU</b>	
<b>Receiver side (RX)</b>	<b>Transmitter side (TX)</b>
<ul style="list-style-type: none"> <li>• disable RX deadline monitoring</li> <li>• no action on a <code>Com_RxIndication</code> to RTE, no storing of the I PDU</li> <li>• return code <code>COM_SERVICE_NOT_AVAILABLE</code> on <code>Com_ReceiveSignal</code> and <code>Com_ReceiveSignalGroup</code> and the last known value (or init value) is given back as data</li> <li>• normal reaction on <code>Com_ReceiveShadowSignal()</code></li> </ul>	<ul style="list-style-type: none"> <li>• disable sending</li> <li>• disable TX deadline monitoring</li> <li>• <code>Com_TxConfirmation</code>:               <ul style="list-style-type: none"> <li>if it is for timeout ignore it</li> <li>if it is used by the RTE ignore it.</li> </ul> </li> <li>• on a call of <code>Com_SendSignal</code>, <code>Com_UpdateShadowSignal</code>, <code>Com_SendSignalGroup</code>, <code>Com_InvalidSignal</code> and <code>Com_InvalidShadowSignal</code> the values in the COM internal buffers are still up-dated but the return code <code>COM_SERVICE_NOT_AVAILABLE</code> is returned</li> <li>• outstanding transmission request (e.g. N-Times) shall be cancelled</li> <li>• normal reaction on <code>Com_TriggerTransmit</code></li> </ul>
	<b>For periodic (TX)</b>
	do not send any more

**Table 9: Behavior of stopped I-PDUs**

Table 10 gives an overview of the behavior of started I-PDU:

<b>Behavior on starting an I-PDU</b>	
<b>Receiver side (RX)</b>	<b>Transmitter side (TX)</b>
<ul style="list-style-type: none"> <li>reinitialize timeouts if Initialize==true (ComSignalFirstTimeoutFactor, ComSignalTimeoutFactor, ComSignalGroupFirstTimeoutFactor, ComSignalGroupTimeoutFactor)</li> <li>normal reaction on Com_RxIndication</li> <li>normal reaction on Com_ReceiveSignal, Com_ReceiveShadowSignal and Com_ReceiveSignalGroup</li> <li>deadline monitoring is enabled</li> </ul>	<ul style="list-style-type: none"> <li>normal reaction on Com_InvalidSignal, Com_InvalidShadowSignal, Com_SendSignal, Com_SendSignalGroup, Com_UpdateShadowSignal and Com_SendSignalGroup</li> <li>no transmission timeout notification until next send</li> <li>normal reaction on Com_TxConfirmation</li> <li>normal reaction on Com_TriggerTransmit</li> <li>deadline monitoring is enabled</li> </ul>
	<b>For periodic (TX)</b>
	Start at 0

**Table 10 Behavior of started I-PDUs**

#### 7.4.5.4 Signal indication (Unpacking of I-PDUs)

**COM298:** In order to support both interrupt-driven and polled system, it shall be configurable when the signal indication takes place. There shall be two configurable signal indication modes:

**Immediate:**

The signal indications/ confirmations are performed in Com\_RxIndication/ Com\_TxConfirmation

**Deferred:**

Signal indication/ confirmations are deferred for example to a cyclic task

**COM300:** In Immediate mode the signal notification shall be done in Com\_RxIndication.

**COM301:** If ComIPduSignalProcessing for an I-PDU is configured to DEFERRED, the AUTOSAR COM module shall first copy the I-PDU's data within the Com\_RxIndication function from the PduR into COM. Then the AUTOSAR COM module shall invoke the configured ComNotifications for the included signals and signal groups asynchronously, during the next call to Com\_MainFunctionRx.

**Note:** If in Deferred mode a call to Com\_ReceiveSignal is made before the deferred unpacking takes place the previous (not updated) values are returned.

A sequence chart with both indication options can be found in Chapter 9.3. The configuration of these modes is defined in COM119.

**COM574:** The AUTOSAR COM module shall check the received data length (Pdu-InfoPtr->SduLength) and unpack and notify only completely received signals via ComNotification.

**COM794:** In case the reception of a smaller I-PDU than expected results into receiving a signal without its configured update-bit, the AUTOSAR COM module shall treat this signal as if its update bit was set and interpret such a signal as updated.

**Note:** If the received I-PDU length is smaller than the configured/ expected I-PDU length, it shall be prevented that signals are updated partially. On the other hand all completely received signals shall be received and notified to the upper layer.

**COM575:** The AUTOSAR COM module shall check the received data length (Pdu-InfoPtr->SduLength) and in case a signal group is received only partially, such a signal group and all included group signals shall not be unpacked or notified via ComNotification.

**Note:** The above requirement prevents inconsistently received signal groups and therefore inconsistently received complex data types.

**Note:** The AUTOSAR COM module does not copy or handle additional received data for not configured signals in case the received data length is greater than expected.

#### 7.4.5.5 Minimum Delay Timer (MDT)

The minimum delay timer shall be defined as in [17].

**Note:** When an I PDU group is started the MDT eventually is re-initialized, depending on the 'Initialize' parameter of Com\_IpduGroupStart, see COM222. Therefore the MDT can be violated by stopping and starting I-PDU groups rapidly.

**Note:** As defined in [17] the MDT is started when the confirmation of the sent I-PDU is received. Therefore exists a time-slot between the send-call and the confirmation where an (erroneous) application could create a burst of I-PDUs by sending rapidly.

**Note:** The behavior of the transmission deadline monitoring timer shall not be affected by any transmission delay caused by the minimum delay time supervision.

#### 7.4.6 Deadline Monitoring

Deadline monitoring for signals is defined in [17].

In the context of deadline monitoring a signal group shall be handled like a signal. The deadline monitoring parameters can be configured via ComFirstTimeoutFactor and ComTimeoutFactor in configuration container ComSignal or ComSignalGroup respectively.

The corresponding error notification callback functions can be configured via configuration parameter ComErrorNotification in configuration container ComSignal or ComSignalGroup respectively.

**COM562:** If ComTxIPduMinimumDelayTimeFactor (COM181) of an I-PDU is configured greater than 0, the AUTOSAR COM module shall load and start the minimum delay time counter upon transmission of that I-PDU to the PDU Router via PduR\_ComTransmit.

**COM469:** If ComTxIPduMinimumDelayTimeFactor of an I-PDU is configured greater than 0, the AUTOSAR COM module shall (re-)load the already running minimum delay time counter with ComTxIPduMinimumDelayTimeFactor for that I-PDU when Com\_TxConfirmation is invoked and the minimum delay time counter of that I-PDU, started at PduR\_ComTransmit, is not already elapsed.

The running minimum delay timer is reloaded upon the reception of the TX-confirmation of that I-PDU, unless the transmission was already delayed longer than ComTxIPduMinimumDelayTime at the reception of the confirmation. In normal case, there will be no further transmission of that I-PDU by the AUTOSAR COM module unless the loaded and started minimum delay has expired. See also Figures 2-4, 2-5 and 2-7 in [17]. However, some exception exists: According to COM475 Com\_TriggerTransmit does not interfere with the minimum delay timer. Further, the minimum delay timer is reset if the transmission deadline monitoring timer expires; see Chapter 2.3.4 in [17]. In addition, starting an I-PDU group resets the minimum delay time timer of the included I-PDUs.

#### 7.4.6.1 Reception Deadline Monitoring

The reception deadline monitoring is enabled and disabled by the control of I-PDU groups analogous to Chapter 7.4.5.

**COM772:** The reception deadline monitoring of an I-PDU is enabled if and only if it is contained in an I-PDU group that has reception deadline monitoring enabled. Otherwise, the reception deadline monitoring of the I-PDU is disabled.

**COM292:** In the case where reception deadline monitoring is used on signals with update-bits, there shall be a separate reception deadline monitoring for each signal/signal group with an update-bit. For configuration see COM263 and COM264.

**COM290:** There shall be an I-PDU based reception deadline monitoring for signals without an update-bit.

**COM291:** For all signals/ signal groups without update-bits within the same I-PDU, the smallest configured timeout parameter (ComSignalFirstTimeoutFactor, ComSignalGroupFirstTimeoutFactor / ComSignalTimeoutFactor, ComSignalGroupTimeoutFactor) of the associated signals is chosen as timeout parameter for the reception deadline monitoring of the I-PDU.

**Note:** If all signals within an I-PDU have an update-bit configured, no reception deadline monitoring on I-PDU base needs to be performed.

**COM393:** In case of an Rx-timeout it shall be configurable whether COM replaces the signal/ signal group value with the initial value or keeps it as it is. In case of replacement the *old\_value* of the corresponding filter-object (if configured) shall not be replaced.

**Note:** Rx-timeout-indication can be combined and configured separately from COM393.

**COM738:** The reception deadline monitoring timer mechanism shall not take the values of the signals into account. Hence, the AUTOSAR COM module shall restart the reception monitoring timer also in case of receiving an invalid value.

#### 7.4.6.1.1 En-/Disable Reception Deadline Monitoring

When reception deadline monitoring of an I-PDU is disabled and the reception deadline monitoring timer expires, no error indication will be given to the RTE.

Disabling reception deadline monitoring does not stop the reception of an I-PDU.

**COM224:** If the reception deadline monitoring state of an I-PDU is changed by a call to `Com_EnableReceptionDM` from disabled to enabled, the AUTOSAR COM module shall reset the reception deadline monitoring timer `ComSignalFirstTimeoutFactor` and `ComSignalGroupFirstTimeoutFactor`.

**COM486:** The AUTOSAR COM module shall silently ignore setting the reception deadline monitoring of an I-PDU to enabled by a call to `Com_EnableReceptionDM`, in case the reception deadline monitoring is already enabled for this I-PDU.

Enabling reception deadline monitoring implies that error indications of deadline monitoring expiry are notified to the RTE for an I-PDU.

**COM534:** If `Com_EnableReceptionDM` is invoked on an I-PDU group containing only/ also Tx-I-PDUs, then the Tx-I-PDUs shall be silently ignored.

**COM225:** The AUTOSAR COM module shall silently ignore setting the reception deadline monitoring of an I-PDU to disabled by a call to `Com_DisableReceptionDM`, in case the reception deadline monitoring is already disabled for this I-PDU.

#### 7.4.6.2 Transmission Deadline Monitoring

For transmission deadline monitoring there is no difference between signals with update-bits and signals without update-bits. Therefore transmission deadline monitoring can be performed on I-PDU base. Nevertheless notification about detected transmission deadline violations on sender side is done per signal. See [17] for further details.

**COM481:** Transmission deadline monitoring shall not distinguish between signals with Pending or Triggered transfer property. It shall be performed for all signals and

all transmission modes as defined for signals with Triggered transfer property in [17] if it is configured.

**COM445:** If different ComTimeoutFactor parameters of the associated signals/ signal groups of an I-PDU are configured the smallest value shall be used as timeout parameter for the transmission deadline monitoring of the I-PDU.

**Note:** Transmission deadline monitoring should only be configured in COM if the lower layer supports the generation of transmit confirmations. Otherwise the transmission deadline monitoring would always notify a transmission error.

**COM696:** In case transmission deadline monitoring is configured for an I-PDU with transmission mode NONE only, the AUTOSAR COM module shall start the transmission deadline monitoring timer for this I-PDU upon the start of the I-PDU group to which the I-PDU belongs to.

**Note:** In case transmission deadline monitoring is configured for an I-PDU with transmission mode NONE and another transmission mode, the transmission deadline monitoring shall be disabled whenever the transmission mode NONE is active.

**COM697:** In case transmission deadline monitoring is configured for an I-PDU with transmission mode NONE only, the AUTOSAR COM module shall reset the transmission deadline monitoring timer for this I-PDU upon each transmission confirmation via Com\_TxConfirmation for this I-PDU.

**Note:** The PDUR does not support transmit confirmations for PDUs that are configured to be fanned out by the PDUR to multiple receivers.

**Note:** In case of a signal group it is only possible to configure transmission deadline monitoring for the whole signal group and not for group signals, see COM345 and COM520.

#### 7.4.6.2.1 Clarification of the OSEK COM specification

The following requirement COM304 states the behavior of the transmission deadline monitoring in the Mixed transmission mode defined in [17] more precisely.

**COM304:** If the transmission does not occur, i.e. if there is no confirmation of the I-PDU's transmission by the underlying layer, the time-out occurs and the application shall be notified using the appropriate notification mechanism.

**Note:** If the transmission deadline monitoring timer runs out there shall be an error notification regardless of the reason. Even if it was postponed because of the MDT or it was filtered out via an I-PDU callout.

**Note:** In the case that there are any contradictions between text and diagrams in [17] the text is the normative part.



**Note:** In [17] is defined that in Direct transmission mode (here Direct/N-times with  $n == 0$ ): “The monitoring timer is started upon completion of the call to the SendMessage, SendDynamicMessage or SendZeroMessage API service.”

Clarification: The transmission deadline monitoring timer shall only be reset if the corresponding signal has transmission deadline monitoring timeouts configured. Signals that have not configured transmission deadline monitoring shall not interfere in the I-PDU based monitoring process.

#### 7.4.6.2.2 Transmission Deadline Monitoring with N-Times Transmission Mode

**Note:** As defined in [17] the monitoring timer shall be started upon completion of a call to Com\_SendSignal or Com\_SendSignalGroup if transmission deadline monitoring is configured for the corresponding signal or signal group respectively.

**COM307:** In Direct/N-Times transmission mode it must be ensured that all  $n$  requests can be made within the configured time period, see Chapter 7.4.3.7.

As defined in [17], if the monitoring timer expires the upper layer is notified with the configured notification mechanism about that failure.

**COM308:** For an I-PDU with ComTxModeMode *DIRECT* and ComTxModeNumberOfRepetitions  $> 0$ , the AUTOSAR COM module shall cancel the transmission deadline monitoring timer after the  $n$ -th received confirmation.

**Note:** If the timer is cancelled after the  $n$ -th confirmation, the transmission was successful and then the transmission confirmation is send to the RTE. See also COM305.

**COM739:** For an I-PDU with ComTxModeMode *DIRECT* and ComTxModeNumberOfRepetitions  $> 0$ , the AUTOSAR COM module shall reset an already running timer in case another send request for this I-PDU is initiated.

## 7.5 Map Complex Data Types to I-PDUs – Signal Groups

**COM042:** To support the AUTOSAR concept of complex data types the AUTOSAR COM layer provides signal groups (see Chapter 2). A signal group shall be transmitted and received consistently providing the data consistency for complex data types.

**COM043:** Signal groups are configured statically. For each signal group a symbolic name shall be provided. See COM345 and COM044 for the configuration details.

**COM047:** The consistency of a signal group shall be achieved by means of a shadow buffer mechanism, i.e. the upper layer uses the group signals in the shadow buffer. If the shadow buffer needs to be synchronized with the I-PDU this is triggered explicitly by the upper layer. Synchronization shall be performed atomically.

### 7.5.1 Initialization

**COM484:** The shadow buffer of a signal group on sender-side shall be initialized by a call to Com\_Init.

**Note:** Since it is not suspected that a well-formed SWC tries to read a group signal before a call to Com\_ReceiveSignalGroup COM484 applies to the sender side only.

### 7.5.2 Transmission

**COM049:** A group signal in the shadow buffer shall be updated by the call of the service Com\_UpdateShadowSignal.

**COM050:** If Com\_SendSignalGroup is called for the signal group the AUTOSAR COM layer shall copy the shadow buffer atomically to the I-PDU buffer.

Example with 2 group signals signal\_a and signal\_b which belong to group\_x:

```
/* copy a to shadow buffer */  
Com_UpdateShadowSignal (signal_a, &a);  
  
/* copy b to shadow buffer */  
Com_UpdateShadowSignal (signal_b, &b);  
  
/* copy shadow buffer to I-PDU */  
Com_SendSignalGroup (group_x);
```

### 7.5.3 Reception

**COM051:** If Com\_ReceiveSignalGroup is called for the signal group the AUTOSAR COM layer shall copy the data atomically from the I-PDU buffer to the shadow buffer.

**COM052:** A group signal shall be received from the shadow buffer by means of the service Com\_ReceiveShadowSignal.

Example with 2 group signals signal\_a and signal\_b which belong to group\_x:

```
/* copy I-PDU to shadow buffer */  
Com_ReceiveSignalGroup (group_x);  
  
/* copy a from shadow buffer */  
Com_ReceiveShadowSignal (signal_a, &a);  
  
/* copy b from shadow buffer */  
Com_ReceiveShadowSignal (signal_b, &b);
```

### 7.5.4 Notifications

It is only possible to configure the signal and error notifications (on sender and receiver side) for the whole signal group.

**COM053:** The notifications shall be sent to the RTE if a whole signal group has been sent to / received or detected to be invalid from the lower layer. See COM345 and COM520 for the configuration details.

### 7.5.5 Collection of the attributes of a signal group

Table 11 gives an overview of the attributes of a signal group:

<i>Attribute</i>	<i>Per group signal</i>	<i>Per signal group</i>
Update-bit	No	Yes, associated on the whole group (see 7.7)
Signal Notification (sender side)	No	Yes
Signal Notification (receiver side)	No	Yes
Error Notification (sender side)	No	Yes
Error Notification (receiver side)	No	Yes
Invalid Notification (receiver side)	Yes (see COM683)	Yes (see COM683)
Data access (receiver side)	Yes, with ReceiveSignal API (see 0)	Yes, via shadow buffer (see 8.3.2.5 and 8.3.2.6)
Data access (sender side)	No	Yes, via shadow buffer (see 0 and 8.3.2.4)
Data Filtering (receiver side)	No (see 7.2.3)	No
Data Filtering (sender side)	No	No
TMS on sender side	Each signal, according to TMS selection definition. (see 7.4.3.5)	No

**Table 11: Attributes of signal groups**

## 7.6 Interface between AUTOSAR COM and the lower layer (PDU-Router)

OSEK COM leaves the interface between OSEK COM and the lower layers undefined. In AUTOSAR the only lower layer that AUTOSAR COM interfaces to is the PDU Router.

The interaction diagram in Chapter 9.1 shows the interaction between the PDU Router and AUTOSAR COM.

A detailed description can be found in the API chapter see Com\_RxIndication, Com\_TxConfirmation and Com\_TriggerTransmit.

**COM138:** When AUTOSAR COM wants to send out an I-PDU, AUTOSAR COM shall use the PduR\_ComTransmit function.

## 7.7 Signal status information

### 7.7.1 Identify if a signal is updated by the sender

**COM054:** To enable the receiver of a signal/ signal group to identify whether the sender has updated the data in this signal/ signal group before sending, AUTOSAR COM shall support *update-bits*.

The update-bit shall indicate whether upper layers on sender-side have updated a signal value before lower layers have fetched the I-PDU containing that signal for transmission or before AUTOSAR COM has handed over the I-PDU to lower layers for transmission.

**Note:** Update-bits are not allowed if Direct/N-Times transmission mode with  $n > 1$  is used (see COM310).

**COM055:** By configuration on sender- and on receiver-side, it shall be possible to add separately for each signal and/or separately for each signal group at most one additional bit (= update-bit). The update-bit is not part of the signal or signal group itself and shall only be used by AUTOSAR COM itself. The update-bit shall not be visible to or accessible by the AUTOSAR Software Component.

**COM056:** The position of the update-bit shall be configurable. For configuration parameter see COM257.

**COM057:** A signal/ signal group and the corresponding update-bit shall always be part of the same I-PDU.

**COM059:** The interpretation of the update-bit shall be as follows:

<i>Update-BIT</i>	
0	cleared
1	set

**Table 12 update-bit interpretation**

If the value of the update-bit is set, data has been updated; if the value of the update-bit is cleared it has not been updated.

### 7.7.1.1 Sender Side

The initialization of the update-bit is defined in the Chapter 7.4.1 by COM117.

**COM061:** If upper layers update the value of a signal by calling the AUTOSAR COM API `Com_SendSignal`, the update-bit for this signal shall be set. For signal groups, the update-bit shall be set, if the upper layers call the AUTOSAR COM API `Com_SendSignalGroup`.

**COM062:** If the parameter `ComTxIPduClearUpdateBit` of an I-PDU is configured to *Transmit*, the AUTOSAR COM module shall clear all update-bits of all contained signals and signal groups after this I-PDU was sent out via `PduR_ComTransmit` and `PduR_ComTransmit` returned `E_OK`.

**COM577:** If the parameter `ComTxIPduClearUpdateBit` of an I-PDU is configured to *Confirmation*, the AUTOSAR COM module shall clear all update-bits of all contained signals and signal groups after this I-PDU was sent out via `PduR_ComTransmit`, `PduR_ComTransmit` returned `E_OK` and the I-PDU was successfully confirmed.

For confirmation-handling of I-PDUs with `ComTxModeMode` *DIRECT* and `ComTxModeNumberOfRepetitions` > 0, the confirmation behavior as defined in COM305 must be respected.

**COM578:** If the parameter `ComTxIPduClearUpdateBit` of an I-PDU is configured to *TriggerTransmit*, the AUTOSAR COM module shall clear all update-bits of all contained signals and signal groups after the contents of this I-PDU was requested by a call to `Com_TriggerTransmit`.

### 7.7.1.2 Receiver Side

**COM324:** On receiver-side, if there is an update-bit attached to a signal/signal group, AUTOSAR COM shall only process this signal (i.e. filter, notification, signal based, byte swapping), if the signal has been updated. If the signal has not been updated AUTOSAR COM shall discard the signal.

**Note:** If the signals has not been updated the signal will not be routed via the signal gateway. It will only be discarded.

**Remark:** If the upper layer reads a signal with an associated cleared update-bit, the init value or the last received value is returned.

**COM067:** A signal/ signal group shall be interpreted as *updated* if the signal has an update-bit attached and the value of the update-bit is set.

For the behavior of deadline monitoring on signals with update-bits, see Chapter 7.4.5.5.

## 7.8 Callouts

As stated in COM013 *Network-order message callout* and *CPU-order message callout* are not supported in AUTOSAR COM. The only callout method in AUTOSAR COM therefore is the I-PDU callout. AUTOSAR COM supports I-PDU callouts on sender and on receiver side.

### 7.8.1 I-PDU Callout

**COM719:** In case a ComIPduCallout is configured for an I-PDU with ComIPduDirection configured to SEND, the AUTOSAR COM module shall invoke this I-PDU callout directly before the I-PDU is transmitted via PduR\_ComTransmit.

**COM766:** In case a ComIPduTriggerTransmitCallout is configured for an I-PDU, the AUTOSAR COM module shall invoke this I-PDU callout within every execution of Com\_TriggerTransmit for this I-PDU.

**COM395:** When Com\_TriggerTransmit is called, the AUTOSAR COM module shall ignore the return value from the ComIPduTriggerTransmitCallout.

**COM381:** The AUTOSAR COM module shall not support that other AUTOSAR COM module's APIs than Com\_TriggerIPDUSend, Com\_SendSignal, Com\_SendSignalGroup and Com\_UpdateShadowSignal can be called out of an I-PDU callout.

**COM780:** For ComSignals, ComSignalGroups or ComGroupSignals that are updated inside an I-PDU callout, the ComTransferProperty shall not be configured to TRIGGERED or TRIGGERED\_ON\_CHANGE.

**COM781:** For ComSignals, ComSignalGroups and ComGroupSignals that are updated inside an I-PDU callout, the ComFilter shall be configured to ALWAYS, NEVER or omitted.

**COM346:** The I-PDU-Callout API shall be defined as:

boolean <IPDU\_CalloutName>(PduIdType ID, PduInfoType\* PduInfoPtr)

where <IPDU\_CalloutName> has to be substituted with the concrete I-PDU callout name.

**Note:** For callouts on the receiver side the PDU-IDs are defined by the COM module. On the transmission side the PDU-IDs defined by the PduR module have to be used.

**Note:** As specified in OSEK COM if the I-PDU callout returns false the I-PDU shall not be processed any further.

**COM347:** It shall be possible to configure separate I-PDU callout function for each I-PDU. Therefore the I-PDU callout function shall be configurable per I-PDU if used.

For configuration see COM387.

## 7.9 Signal Gateway

The signal gateway is an integrated part of COM. The signal gateway can't be accessed by any external modules, except the cyclic task call.

The signal gateway is working on (group) signals and signal groups.

**COM376:** The signal gateway only supports static routing: All routes shall be used independent of the content of the signals and signal groups to be routed. The destination of a signal or signal group shall only depend on the name of the received signal respectively signal group.

**COM377:** The signal gateway shall copy the value of signals respectively signal groups to be routed to the signals respectively signal groups for transmission according to configuration.

**COM358:** It shall be possible to route a signal/ signal group from one source signal/ signal group to zero (no signal gateway functionality) or more destinations (1:n).

### 7.9.1 Dealing with signals

**COM357:** COM shall forward signals to be routed from received I-PDUs to transmit I-PDUs. For configuration see configuration container ComGwMapping (COM544).

**COM360:** If the endianness of a received signal to be routed differs from the endianness of a related destination signal, its endianness shall be converted using the applicable COM mechanisms.

### 7.9.2 Dealing with signal groups

**COM361:** COM shall forward signal groups to be routed from received I-PDUs to transmit I-PDUs. For configuration see configuration container ComGwMapping (COM544).

**COM383:** The AUTOSAR COM module shall route signal groups in a consistent manner. Therefore, it must be guaranteed that the AUTOSAR COM module transfers the data of the signal group as one consistent set of data during the whole routing operation.

**COM735:** The AUTOSAR COM module shall support routing consistently a subset of group signals of a source signal group into a reduced target signal group.

**COM362:** It shall be possible to change the endianness of signals contained in signal groups to be routed by signal gateway. The signal gateway shall use the applicable COM mechanisms to do so.

### 7.9.3 Routing of out timed signals and signal groups

**COM568:** The AUTOSAR COM module's signal gateway shall route signal and signal groups even if any configured reception deadline monitoring timeout expired.

In case of a not in time received signal or signal group the AUTOSAR COM module's signal gateway will route these signal or signal group anyway.

#### 7.9.3.1 Handling of update-bits

**COM569:** If both, the received signal/ signal group and the destination signal/ signal group have an update-bit (ComUpdateBitPosition) configured and the update-bit of the received signal/ signal group is set, the AUTOSAR COM module shall route the signal/ signal group with the set update-bit and clear the update-bit of the destination signal/ signal group after it was sent.

**COM570:** If the received signal/ signal group and the destination signal/ signal group have an update-bit (ComUpdateBitPosition) configured, and the update-bit of the received signal/ signal group is not set, the AUTOSAR COM module shall not route this signal/ signal group.

**COM571:** If the received signal/ signal group has an update-bit (ComUpdateBitPosition) configured, but the destination signal has no update-bit configured, and the update-bit is set, the AUTOSAR COM module shall route this signal/ signal group without the update-bit.

**COM572:** If the received signal/ signal group has an update-bit (ComUpdateBitPosition) configured, but the destination signal has no update-bit configured, and the update-bit is not set, the AUTOSAR COM module shall not route this signal/ signal group.

**COM573:** If the received signal/ signal group has no update-bit (ComUpdateBitPosition) configured and the destination signal/ signal group has an update-bit configured, the AUTOSAR COM module shall set the update-bit of the destination signal when a new signal/ signal group was received and clear it after sending of the destination signal/ signal group.

### 7.9.4 Decoupling signal gateway

To protect interrupt routines (used for I-PDU reception) from incalculable (and perhaps expensive) time usage, it is necessary to decouple the signal gateway from interrupt routines.

**COM359:** The functions of the signal gateway shall be executed during a separate function call only. During this function call the signal gateway checks received and to be routed signals and signal groups and forwards them from the related receive I-PDUs to the related transmit I-PDUs (see COM400).



**COM466:** Within Com\_MainFunctionRouteSignals the evaluation of transfer properties and transmission mode must be performed in the following sequence (see also Figure 3):

- Copy all gated signals from the source to the target I-PDUs
- Evaluate the TMC of all gated signals
- Evaluate the TMS for the target I-PDUs
- For any target I-PDU containing gated signals with Triggered transfer property send it according to its transmission mode

**COM539:** An I-PDU shall be sent out at most once while one call to Com\_MainFunctionRouteSignals.

## 7.10 Error classification

### 7.10.1 Development Errors

**COM024:** All input parameters shall be checked for validity during development. The parameter check shall be not contained in the production code. For the configuration of this feature see COM028.

**COM442:** When a development error is detected the function Det\_ReportError of the development error tracer shall be called with:

- the COM moduleID (see COM417)
- the COM instanceID
- the service ID of the COM API the error is detected (see Com\_ServiceIdType)
- the error ID as defined in Table 13

Type of development error	Related error code	Value [hex]
API service called with wrong parameter	COM_E_PARAM	0x01
Error code if any other API service is called before COM was initialized with Com_Init or after a call to Com_Deinit	COM_E_UNINIT	0x02

**Table 13: Mapping of COM development error IDs**

### 7.10.2 Production Errors

Actually no production errors are defined in AUTOSAR COM. If production errors will be defined in later versions AUTOSAR COM shall report them directly to the DEM.

### 7.10.3 Return Codes

AUTOSAR COM does not define a special COM return type. The API services return errors either by using the Std\_ReturnType as defined in [5] or via a uint8 value mapped according to Table 14.

**COM459:** Return codes of AUTOSAR Com shall be defined according Table 14.

Name	Description	Type	Value	Defined in
E_OK	the service has been accepted	#define	0x00	Std_Types.h
COM_SERVICE_NOT_AVAILABLE	the service is currently not available e.g. the corresponding I-PDU group is stopped (or a development error has been detected)	#define	0x80	Com.h
COM_TIMEOUT	a timeout has occurred	#define	0x81	Com.h

Table 14: Mapping of AUTOSAR COM return codes

### 7.11 Error handling

**COM428:** If not stated otherwise AUTOSAR COM will ignore all errors from the underlying communication layer.

**Note:** AUTOSAR COM supervises the communication with deadline monitoring if configured. The specific error codes from the underlying layer therefore can be ignored. In case of update-bits this error codes are handled see COM062.

### 7.12 AUTOSAR COM interaction model

This chapter corresponds to the chapter *Functional Model of Interaction Layer* of [17]. The following figures illustrate the behavior of the Interaction layer for external reception and external transmission. The complete functionality is shown but it depends on the configuration what parts are present/ used in a concrete implementation.

**COM396:** A received signal can be configured to have filtering, data invalidation and notification. The order of execution (if configured) is:

- 1) Data invalidation
- 2) Filtering
- 3) Notification

**COM744:** In case both a ComRxDataTimeoutAction and a ComTimeoutNotification is configured for a ComSignal or a ComSignalGroup, the AUTOSAR COM module shall

first call the configured ComRxDataTimeoutAction and then call the configured ComTimeoutNotification."

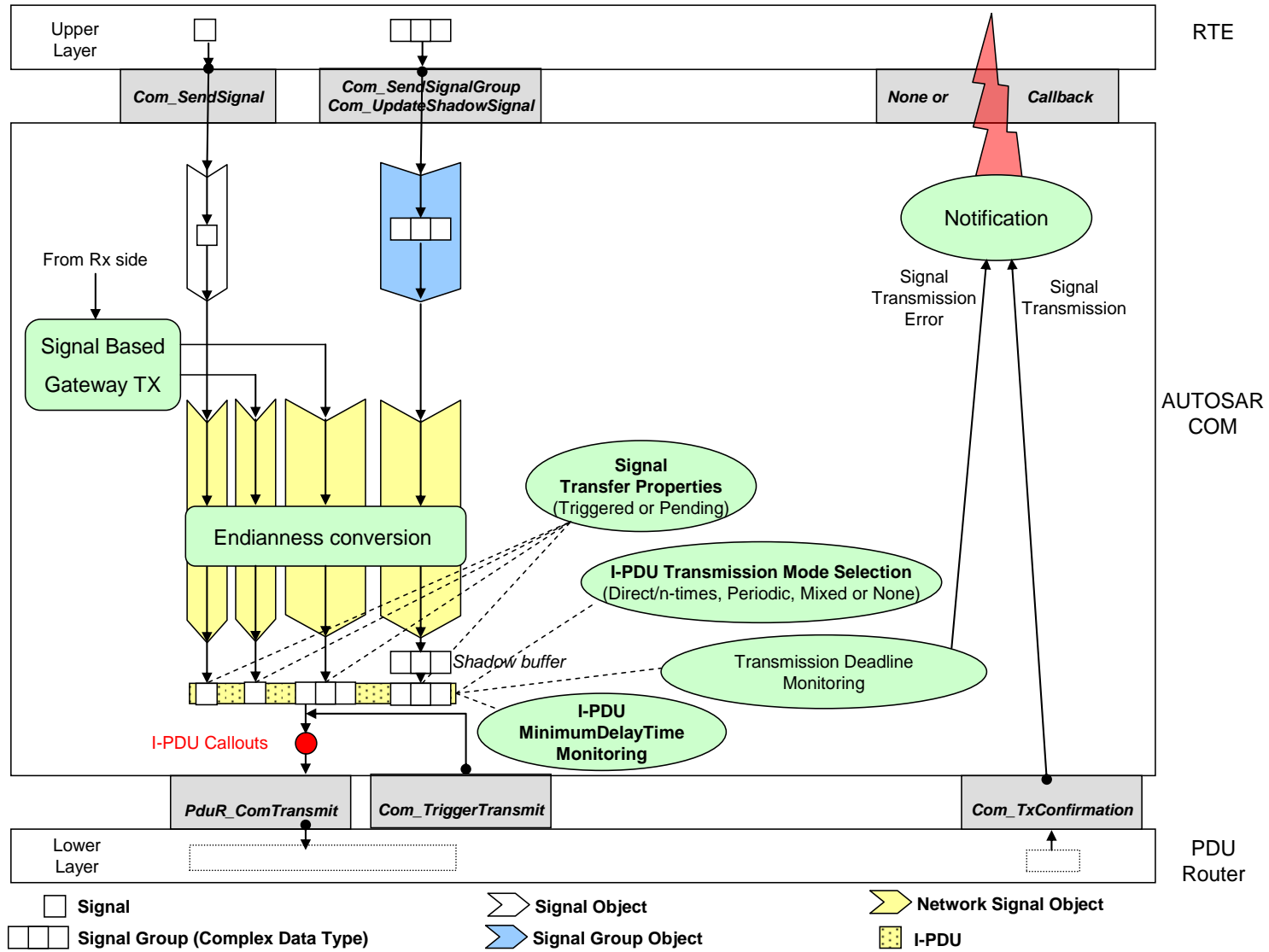


Figure 13 AUTOSAR COM interaction model for transmission

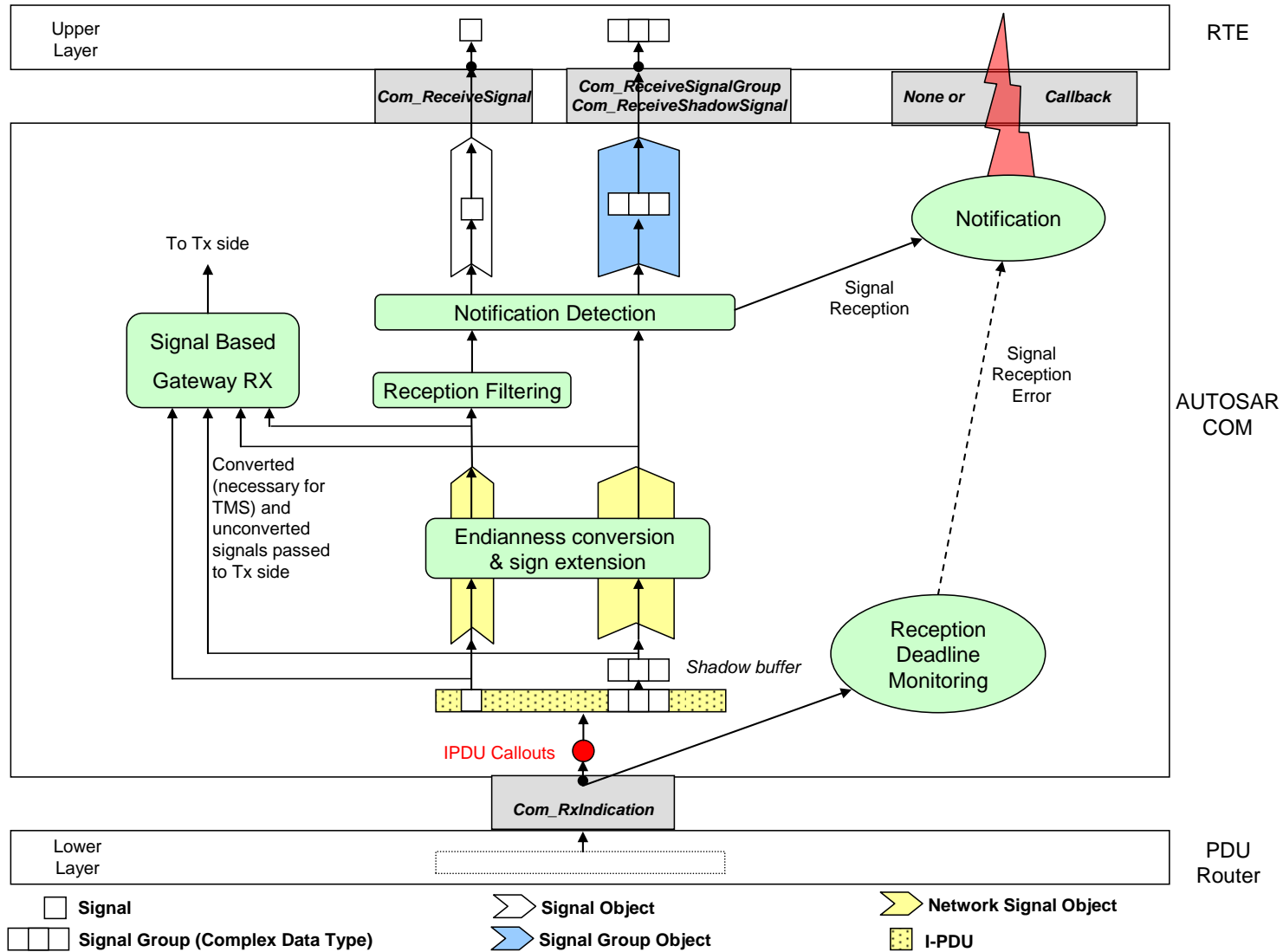


Figure 14 AUTOSAR COM interaction model for reception

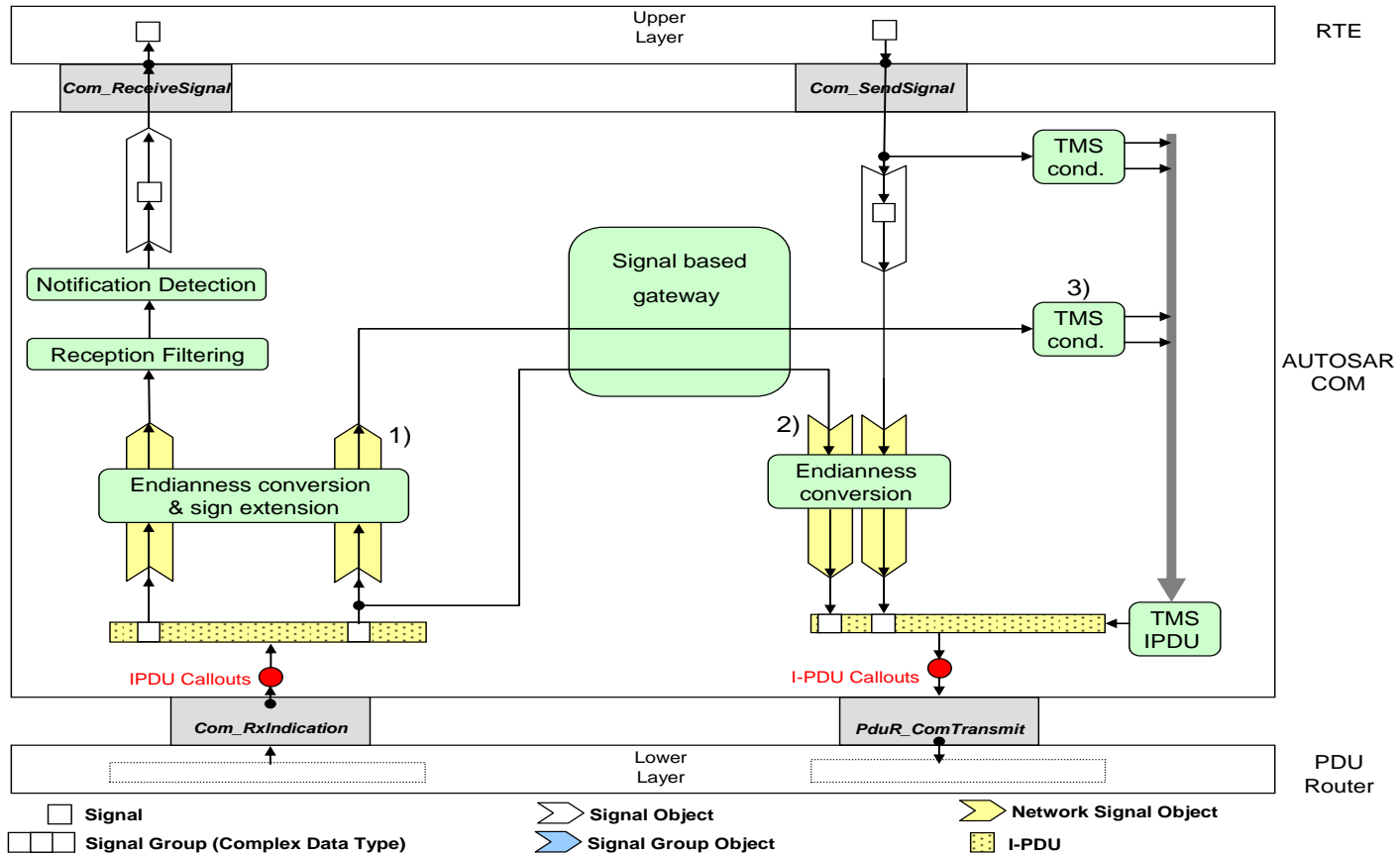


Figure 15: AUTOSAR COM-interaction model for integrated Signal Gateway

The endianness conversion and sign extension on receiver side is needed to feed the TMS with a correct data format. This endianness conversion is only necessary if the endianness of the Rx-bus differs from the endianness of the CPU. The endianness conversion on the sender side is only necessary if the endianness of the Rx-bus differs from the endianness of the Tx-bus. If a gated signal should not always trigger the associated IPDU to be sent out, one of the configured transmission modes must be None.

## 8 API specification

### 8.1 Imported types

<i>Module</i>	<i>Imported Type</i>
ComStack_Types	PduldType
	PdulInfoType
Dem	Dem_EventIdType
Std_Types	Std_ReturnType
	Std_VersionInfoType

#### 8.1.1 PduldType

The definition of the PduldType can be found in [2].

#### 8.1.2 Std\_ReturnType

The definition of the Std\_ReturnType can be found in [5].

#### 8.1.3 Std\_VersionInfoType

The definition of the Std\_VersionInfoType can be found in [5].

## 8.2 Type definitions

### 8.2.1 Com\_StatusType

<b>Name:</b>	Com_StatusType	
<b>Type:</b>	Enumeration	
<b>Range:</b>	COM_UNINIT	The AUTOSAR COM module is not initialized or not usable. This shall be the default value after reset. This status shall have the value 0.
	COM_INIT	The AUTOSAR COM Module is initialized and usable.
<b>Description:</b>	This is a status value returned by the API service Com_GetStatus().	

### 8.2.2 Com\_SignalIdType

<b>Name:</b>	Com_SignalIdType	
<b>Type:</b>	uint16	
<b>Range:</b>	0..<SignalIdmax>	-- Zero-based integer number
<b>Description:</b>	AUTOSAR COM signal object identifier.	

### 8.2.3 Com\_SignalGroupIdType

<b>Name:</b>	Com_SignalGroupIdType		
<b>Type:</b>	uint16		
<b>Range:</b>	0..<SignalGroupIdmax>	--	Zero-based integer number
<b>Description:</b>	AUTOSAR COM signal group object identifier.		

### 8.2.4 Com\_PduGroupIdType

<b>Name:</b>	Com_PduGroupIdType		
<b>Type:</b>	uint8		
<b>Range:</b>	0..<PduGroupId-max>	--	Zero-based integer number
<b>Description:</b>	AUTOSAR COM PDU group object identifier.		

### 8.2.5 Com\_ServiceIdType

<b>Name:</b>	Com_ServiceIdType		
<b>Type:</b>	uint8		
<b>Range:</b>	COMServiceId_Init	0x01	--
	COMServiceId_DelInit	0x02	--
	COMServiceId_IpduGroupStart	0x03	--
	COMServiceId_IpduGroupStop	0x04	--
	COMServiceId_DisableReceptionDM	0x05	--
	COMServiceId_EnableReceptionDM	0x06	--
	COMServiceId_GetStatus	0x07	--
	COMServiceId_GetConfigurationId	0x08	--
	COMServiceId_GetVersionInfo	0x09	--
	COMServiceId_SendSignal	0x0A	--
	COMServiceId_ReceiveSignal	0x0B	--
	COMServiceId_UpdateShadowSignal	0x0C	--
	COMServiceId_SendSignalGroup	0x0D	--
	COMServiceId_ReceiveSignalGroup	0x0E	--
	COMServiceId_ReceiveShadowSignal	0x0F	--
	COMServiceId_InvalidateSignal	0x10	--
	COMServiceId_ErrorGetServiceId	0x11	--
	COMServiceId_Error_<Name1>_<Name2>Macros	0x12	--
	COMServiceId_TriggerTransmit	0x13	--
	COMServiceId_RxIndication	0x14	--
	COMServiceId_TxConfirmation	0x15	--
	COMServiceId_InvalidateShadowSignal	0x16	--
	COMServiceId_TriggerIPDU Send	0x17	--
	COMServiceId_MainFunctionRx	0x18	--
	COMServiceId_MainFunctionTx	0x19	--
	COMServiceId_MainFunctionRouteSignals	0x1A	--
	COMServiceId_InvalidateSignalGroup	0x1B	--
<b>Description:</b>	Unique identifier of an AUTOSAR COM service. Example: COMServiceId_SendSignal 0x0A.		



### 8.2.6 Com\_ConfigType

<b>Name:</b>	Com_ConfigType	
<b>Type:</b>	Structure	
<b>Range:</b>	implementation specific	The content of the initialization data structure is implementation specific
<b>Description:</b>	This is the type of the data structure containing the initialization data for COM.	

## 8.3 Function definitions

**COM320:** If a function is marked as non-reentrant the caller of that function shall ensure that this function must not be called while it is running.

**COM321:** Non-reentrant functions do not have to check if they are called reentrant.

**COM434:** It is allowed to use macros instead of functions where source code is used and runtime is critical.

### 8.3.1 Start up and control services

#### 8.3.1.1 Com\_Init

##### COM432:

<b>Service name:</b>	Com_Init	
<b>Syntax:</b>	void Com_Init( const Com_ConfigType* config )	
<b>Service ID[hex]:</b>	0x01	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Non Reentrant	
<b>Parameters (in):</b>	config	Pointer to the COM configuration data.
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	None	
<b>Description:</b>	This service initializes internal and external interfaces and variables of the AUTOSAR COM layer for the further processing. After calling this function the inter-ECU communication is still disabled.	

**COM433:** If the config parameter does not correspond to a valid configuration then the development error COM\_E\_PARAM is generated. The behavior of AUTOSAR COM is unspecified until a correct call to Com\_Init is made.

**Caveats:** Com\_Init shall not pre-empt any COM function. The rest of the system must guarantee that Com\_Init is not called in such a way.

#### 8.3.1.2 Com\_Delnit

##### COM130:

<b>Service name:</b>	Com_Delnit
<b>Syntax:</b>	void Com_Delnit( )
<b>Service ID[hex]:</b>	0x02
<b>Sync/Async:</b>	Synchronous
<b>Reentrancy:</b>	Non Reentrant
<b>Parameters (in):</b>	None
<b>Parameters (in-out):</b>	None
<b>Parameters (out):</b>	None
<b>Return value:</b>	None
<b>Description:</b>	This service stops the inter-ECU communication. All started I-PDU groups are stopped and have to be started again, if needed, after Com_Init is called. By a call to ComDelnit COM is put into an not initialized state.

**Caveats:** Com\_Delnit shall not pre-empt any COM function. The rest of the system must guarantee that Com\_Delnit is not called in such a way.

### 8.3.1.3 Com\_IpduGroupStart

#### COM191:

<b>Service name:</b>	Com_IpduGroupStart	
<b>Syntax:</b>	void Com_IpduGroupStart( Com_PduGroupIdType IpduGroupId, boolean Initialize )	
<b>Service ID[hex]:</b>	0x03	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Reentrant for different I-PDU groups. Non reentrant for the same I-PDU group.	
<b>Parameters (in):</b>	IpduGroupId	Id of I-PDU group to be started
	Initialize	flag to request initialization of the data in the I-PDUs of this I-PDU group
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	None	
<b>Description:</b>	Starts a preconfigured I-PDU group. For example, cyclic I-PDUs will be sent out cyclically after the call of Com_IpduGroupStart(). See Chapter 7.4.5 for details.  If Initialize is true all I-PDUs of the I-PDU group shall be (re-)initialized before the I-PDU group is started. That is they shall behave like after a start-up of COM, for example the old_value of the filter objects and shadow buffers of signal groups have to be (re-)initialized.	

**Caveats:** A call to Com\_IpduGroupStart shall not be interrupted by another call to Com\_IpduGroupStart or a call to Com\_IpduGroupStop. Note that this function is not only called by the COMM but also from other modules e.g. diagnosis.

**Configuration:** An I PDU group must be configured before this call. See COM206 and COM341 for details.

### 8.3.1.4 Com\_IpduGroupStop

#### COM190:

<b>Service name:</b>	Com_IpduGroupStop
<b>Syntax:</b>	void Com_IpduGroupStop( Com_PduGroupIdType IpduGroupId )
<b>Service ID[hex]:</b>	0x04
<b>Sync/Async:</b>	Synchronous
<b>Reentrancy:</b>	Reentrant for different I-PDU groups. Non reentrant for the same I-PDU group.
<b>Parameters (in):</b>	IpduGroupId      Id of I-PDU group to be stopped
<b>Parameters (in-out):</b>	None
<b>Parameters (out):</b>	None
<b>Return value:</b>	None
<b>Description:</b>	Stops a preconfigured I-PDU group. For example, cyclic I-PDUs will be stopped after the call of Com_IpduGroupStop(). See Chapter 7.4.5 for details.

**Caveats:** A call to Com\_IpduGroupStop shall not be interrupted by another call to Com\_IpduGroupStop or a call to Com\_IpduGroupStart. Note that this function is not only called by the COMM but also from other modules e.g. diagnosis.

**Configuration:** An I PDU group must be configured before this call. See COM206 and COM341 for details.

### 8.3.1.5 Com\_DisableReceptionDM

#### COM192:

<b>Service name:</b>	Com_DisableReceptionDM
<b>Syntax:</b>	void Com_DisableReceptionDM( Com_PduGroupIdType IpduGroupId )
<b>Service ID[hex]:</b>	0x05
<b>Sync/Async:</b>	Synchronous
<b>Reentrancy:</b>	Reentrant for different I-PDU groups. Non reentrant for the same I-PDU group.
<b>Parameters (in):</b>	IpduGroupId      Id of I-PDU group where reception DM shall be disabled.
<b>Parameters (in-out):</b>	None
<b>Parameters (out):</b>	None
<b>Return value:</b>	None
<b>Description:</b>	Disables the reception deadline monitoring for the I-PDUs within the given I-PDU group.

**Configuration:** An I PDU group must be configured before this call. See COM206 and COM341 for details.

### 8.3.1.6 Com\_EnableReceptionDM

#### COM193:

<b>Service name:</b>	Com_EnableReceptionDM
<b>Syntax:</b>	void Com_EnableReceptionDM( Com_PduGroupIdType IpduGroupId )

	)
<b>Service ID[hex]:</b>	0x06
<b>Sync/Async:</b>	Synchronous
<b>Reentrancy:</b>	Reentrant for different I-PDU groups. Non reentrant for the same I-PDU group.
<b>Parameters (in):</b>	IpdugroupId   Id of I-PDU group where reception DM shall be enabled.
<b>Parameters (in-out):</b>	None
<b>Parameters (out):</b>	None
<b>Return value:</b>	None
<b>Description:</b>	Enables the reception deadline monitoring for the I-PDUs within the given I-PDU group.

**Configuration:** An I-PDU group must be configured before this call. See COM206 and COM341 for details.

### 8.3.1.7 Com\_GetStatus

#### COM194:

<b>Service name:</b>	Com_GetStatus	
<b>Syntax:</b>	Com_StatusType Com_GetStatus(  )	
<b>Service ID[hex]:</b>	0x07	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Reentrant	
<b>Parameters (in):</b>	None	
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	Com_StatusType	COM_UNINIT: AUTOSAR COM is not initialized and not usable COM_INIT: AUTOSAR COM is initialized and usable
<b>Description:</b>	Returns the status of the AUTOSAR COM module.	

### 8.3.1.8 Com\_GetConfigurationId

#### COM375:

<b>Service name:</b>	Com_GetConfigurationId	
<b>Syntax:</b>	uint32 Com_GetConfigurationId(  )	
<b>Service ID[hex]:</b>	0x08	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Non Reentrant	
<b>Parameters (in):</b>	None	
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	uint32	configured ConfigurationID, see COM394
<b>Description:</b>	Provides the unique identifier of the configuration.	

**Configuration:** The provided Identification shall be set during configuration process and can't be changed by COM.

### 8.3.1.9 Com\_GetVersionInfo

#### COM426:

<b>Service name:</b>	Com_GetVersionInfo	
<b>Syntax:</b>	void Com_GetVersionInfo( Std_VersionInfoType* versioninfo )	
<b>Service ID[hex]:</b>	0x09	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Non Reentrant	
<b>Parameters (in):</b>	None	
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	versioninfo	Pointer to where to store the version information of this module.
<b>Return value:</b>	None	
<b>Description:</b>	Returns the version information of this module.	

**COM424:** This service returns the version information of this module. The version information includes:

- 1) Module ID
- 2) Vendor ID
- 3) Vendor specific version numbers (BSW00407).

**COM425:** This function shall be pre compile time configurable On/Off by the configuration parameter: COM\_VERSION\_INFO\_API.

**Note:** If source code for caller and called of this function is available, this function should be realized as a macro. The macro should be defined in the modules header file.

Configuration: see COM026

## 8.3.2 Communication services

### 8.3.2.1 Com\_SendSignal

#### COM197:

<b>Service name:</b>	Com_SendSignal	
<b>Syntax:</b>	uint8 Com_SendSignal( Com_SignalIdType SignalId, const void* SignalDataPtr )	
<b>Service ID[hex]:</b>	0x0a	
<b>Sync/Async:</b>	Asynchronous	
<b>Reentrancy:</b>	Non Reentrant for the same signal. Reentrant for different signals.	
<b>Parameters (in):</b>	SignalId	Id of signal to be sent.
	SignalDataPtr	Reference to the signal data to be transmitted.

<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	uint8	E_OK: service has been accepted COM_SERVICE_NOT_AVAILABLE: corresponding I-PDU group was stopped (or service failed due to development error)
<b>Description:</b>	<p>The service Com_SendSignal updates the signal object identified by SignalId with the signal referenced by the SignalDataPtr parameter.</p> <p>If the signal has the Triggered transfer property, the update is followed by immediate transmission (within the next main function at the latest) of the I-PDU associated with the signal except when the signal is packed into an I-PDU with Periodic transmission mode; in this case, no transmission is initiated by the call to this service.</p> <p>If the signal has the Pending transfer property, no transmission is caused by the update.</p>	

### 8.3.2.2 Com\_ReceiveSignal

#### COM198:

<b>Service name:</b>	Com_ReceiveSignal	
<b>Syntax:</b>	uint8 Com_ReceiveSignal( Com_SignalIdType SignalId, void* SignalDataPtr )	
<b>Service ID[hex]:</b>	0x0b	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Non Reentrant for the same signal. Reentrant for different signals.	
<b>Parameters (in):</b>	SignalId	Id of signal to be received.
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	SignalDataPtr	Reference to the signal data in which to store the re-ceived data.
<b>Return value:</b>	uint8	E_OK: service has been accepted COM_SERVICE_NOT_AVAILABLE: corresponding I-PDU group was stopped (or service failed due to development error)
<b>Description:</b>	The service Com_ReceiveSignal updates the signal referenced by SignalDataPtr with the data in the signal object identified by SignalId.	

### 8.3.2.3 Com\_UpdateShadowSignal

#### COM199:

<b>Service name:</b>	Com_UpdateShadowSignal	
<b>Syntax:</b>	void Com_UpdateShadowSignal( Com_SignalIdType SignalId, const void* SignalDataPtr )	
<b>Service ID[hex]:</b>	0x0c	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Non Reentrant for the same group signal. Reentrant for different group signals.	
<b>Parameters (in):</b>	SignalId	Id of group signal to be updated.
<b>Parameters (in-out):</b>	SignalDataPtr	Reference to the group signal data to be updated.
<b>Parameters (in):</b>	None	

<b>out):</b>	
<b>Parameters (out):</b>	None
<b>Return value:</b>	None
<b>Description:</b>	The service Com_UpdateShadowSignal updates a group signal with the data, referenced by SignalDataPtr. The update of the group signal data is done in the shadow buffer, not in the I-PDU. To send out the shadow buffer, Com_SendSignalGroup has to be called.  Sign extension and byte swapping are performed as the group signal is inserted into the shadow buffer.

**Configuration:** A signal group must be configured before this call. See COM345 for details.

### 8.3.2.4 Com\_SendSignalGroup

#### COM200:

<b>Service name:</b>	Com_SendSignalGroup	
<b>Syntax:</b>	uint8 Com_SendSignalGroup( Com_SignalGroupIdType SignalGroupId )	
<b>Service ID[hex]:</b>	0x0d	
<b>Sync/Async:</b>	Asynchronous	
<b>Reentrancy:</b>	Non Reentrant for the same group signal. Reentrant for different group signals.	
<b>Parameters (in):</b>	SignalGroupId	Id of signal group to be send.
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	uint8	E_OK: service has been accepted COM_SERVICE_NOT_AVAILABLE: corresponding I-PDU group was stopped (or service failed due to development error)
<b>Description:</b>	The service Com_SendSignalGroup copies the content of the associated shadow buffer to the associated I-PDU. Prior to this call, all group signals should be updated in the shadow buffer by the call of Com_UpdateShadowSignal.	

**Configuration:** A signal group must be configured before this call. See COM345 for details.

### 8.3.2.5 Com\_ReceiveSignalGroup

#### COM201:

<b>Service name:</b>	Com_ReceiveSignalGroup	
<b>Syntax:</b>	uint8 Com_ReceiveSignalGroup( Com_SignalGroupIdType SignalGroupId )	
<b>Service ID[hex]:</b>	0x0e	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Non Reentrant for the same group signal. Reentrant for different group signals.	
<b>Parameters (in):</b>	SignalGroupId	Id of signal group to be received.
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	uint8	E_OK: service has been accepted

		COM_SERVICE_NOT_AVAILABLE: corresponding I-PDU group was stopped (or service failed due to development error)
<b>Description:</b>	The service Com_ReceiveSignalGroup copies the received signal group from the I-PDU to the shadow buffer. After this call, the group signals could be copied from the shadow buffer to the upper layer by a call of Com_ReceiveShadowSignal.	

**COM461:** The AUTOSAR COM module shall always copy the last known data, or the ComSignalInitValue(s) if not yet written, of the I-PDU to the shadow buffer by a call to Com\_ReceiveSignalGroup even if the I PDU is stopped and COM\_SERVICE\_NOT\_AVAILABLE is returned.

**Configuration:** A signal group must be configured before this call. See COM345 for details.

### 8.3.2.6 Com\_ReceiveShadowSignal

#### COM202:

<b>Service name:</b>	Com_ReceiveShadowSignal	
<b>Syntax:</b>	void Com_ReceiveShadowSignal( Com_SignalIdType SignalId, void* SignalDataPtr )	
<b>Service ID[hex]:</b>	0x0f	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Non Reentrant for the same group signal. Reentrant for different group signals.	
<b>Parameters (in):</b>	SignalId	Id of group signal to be received.
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	SignalDataPtr	Reference to the group signal data in which to store the received data.
<b>Return value:</b>	None	
<b>Description:</b>	The service Com_ReceiveShadowSignal updates the group signal which is referenced by SignalDataPtr with the data in the shadow buffer. The data in the shadow buffer should be updated before the call of Com_ReceiveShadowSignal by a call of the service Com_ReceiveSignalGroup.	

### 8.3.2.7 Com\_InvalidateSignal

#### COM203:

<b>Service name:</b>	Com_InvalidateSignal	
<b>Syntax:</b>	uint8 Com_InvalidateSignal( Com_SignalIdType SignalId )	
<b>Service ID[hex]:</b>	0x10	
<b>Sync/Async:</b>	Asynchronous	
<b>Reentrancy:</b>	Non Reentrant for the same signal. Reentrant for different signals.	
<b>Parameters (in):</b>	SignalId	Id of signal to be invalidated.
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	uint8	E_OK: service has been accepted



		COM_SERVICE_NOT_AVAILABLE: corresponding I-PDU group is stopped, no ComSignalDataInvalidValue is configured for the given signalId or service fails due to development error
<b>Description:</b>	Sender side AUTOSAR Software Component indicates via the RTE to AUTOSAR COM that it is not able to provide a valid value for the corresponding signal (e.g. sensor is faulty). After invalidating the actual signal data a Com_SendSignal is performed internally, for details see COM097 and COM099.	

**Configuration:** For processing, a Data Invalid Value must have been configured, see COM501.

### 8.3.2.8 Com\_InvalidateShadowSignal

#### COM288:

<b>Service name:</b>	Com_InvalidateShadowSignal	
<b>Syntax:</b>	void Com_InvalidateShadowSignal( Com_SignalIdType SignalId )	
<b>Service ID[hex]:</b>	0x16	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Non Reentrant for the same signal. Reentrant for different signals.	
<b>Parameters (in):</b>	SignalId	Id of signal to be sent.
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	None	
<b>Description:</b>	Sender side AUTOSAR Software Component indicates via the RTE to AUTOSAR COM that it is not able to provide a valid value for the corresponding group signal, e.g. sensor is faulty. See also COM047. The RTE has to call this function for each group signal of a signal group. To send out the invalidated signal group Com_SendSignalGroup must be called separately.	

**Configuration:** For processing, a ComSignalDataInvalidValue must have been configured.

### 8.3.2.9 Com\_InvalidateSignalGroup

#### COM557:

<b>Service name:</b>	Com_InvalidateSignalGroup	
<b>Syntax:</b>	uint8 Com_InvalidateSignalGroup( Com_SignalGroupIdType SignalGroupId )	
<b>Service ID[hex]:</b>	0x1b	
<b>Sync/Async:</b>	Asynchronous	
<b>Reentrancy:</b>	Non Reentrant for the same signal group. Reentrant for different signal groups.	
<b>Parameters (in):</b>	SignalGroupId	Id of signal group to be invalidated.
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	uint8	E_OK: service has been accepted COM_SERVICE_NOT_AVAILABLE: corresponding I-PDU group

	was stopped (or service failed due to development error)
<b>Description:</b>	Sender side AUTOSAR Software Component indicates via the RTE to AUTOSAR COM that it is not able to provide a valid value for the corresponding signal group. After invalidating the actual signal group data a Com_SendSignalGroup is performed internally,

### 8.3.2.10 Com\_TriggerIPDUSend

#### COM348:

<b>Service name:</b>	Com_TriggerIPDUSend	
<b>Syntax:</b>	void Com_TriggerIPDUSend( PduldType ComTxPduld )	
<b>Service ID[hex]:</b>	0x17	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Non Reentrant	
<b>Parameters (in):</b>	ComTxPduld	The I-PDU-ID if the I-PDU that shall be triggered for sending
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	None	
<b>Description:</b>	By a call to Com_TriggerIPDUSend the I-PDU with the given ID is triggered for transmission.	

**COM388:** When an I-PDU is sent out because of this API only the minimum delay time has to be taken into account. That is postpone transmissions if necessary and reset the minimum delay timer in case of transmissions. All other transmission mode related parameters like N-Times shall not be taken into account.

**COM492:** If an I-PDU triggered by Com\_TriggerIPDUSend has a configured I-PDU-callout this I-PDU-Callout shall also be called.

**Caveats:** Shall only be used from within an I PDU callout.

## 8.4 Callback notifications

### 8.4.1 Com\_TriggerTransmit

#### COM001:

<b>Service name:</b>	Com_TriggerTransmit	
<b>Syntax:</b>	Std_ReturnType Com_TriggerTransmit( PduldType ComTxPduld, PdulInfoType* PdulInfoPtr )	
<b>Service ID[hex]:</b>	0x13	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Non reentrant for the same PDU-ID. Reentrant for different PDU-ID.	
<b>Parameters (in):</b>	ComTxPduld	ID of AUTOSAR COM I-PDU that is requested to be transmitted by AUTOSAR COM.
<b>Parameters (in-out):</b>	PdulInfoPtr	Contains a pointer to a buffer (SduDataPtr) to where the SDU shall be copied to. On return, the service will indicate the length

		of the copied SDU data in SduLength.
<b>Parameters (out):</b>	None	
<b>Return value:</b>	Std_ReturnType	E_OK: SDU has been copied and SduLength indicates the number of copied bytes. E_NOT_OK: No SDU has been copied. PdulInfoPtr must not be used since it may contain a NULL pointer or point to invalid data.
<b>Description:</b>	This function is called by the lower layer when an AUTOSAR COM I-PDU shall be transmitted. Within this function, AUTOSAR COM shall copy the contents of its I-PDU transmit buffer to the L-PDU buffer given by SduDataPtr.	

**COM475:** Com\_TriggerTransmit is not interfered by the I-PDU minimum delay time and shall not reset the minimum delay timer, see COM181.

**Use case:** This function is used e.g. by the LIN Master for sending out a LIN frame. In this case, the trigger transmit can be initiated by the Master schedule table itself or a received LIN header.

This function is also used by the FlexRay Interface for requesting PDUs to be sent in static part (synchronous to the FlexRay global time).

Once the I PDU has been successfully sent by the lower layer (PDU Router), the lower layer must call Com\_TxConfirmation.

**Caveats:** This function might be called in interrupt context.

## 8.4.2 Com\_RxIndication

### COM123:

<b>Service name:</b>	Com_RxIndication	
<b>Syntax:</b>	void Com_RxIndication( PduIdType ComRxPduId, const PdulInfoType* PdulInfoPtr )	
<b>Service ID[hex]:</b>	0x14	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Non reentrant for the same PDU-ID. Reentrant for different PDU-ID.	
<b>Parameters (in):</b>	ComRxPduId	ID of AUTOSAR COM I-PDU that has been received. Identifies the data that has been received.  Range: 0..(maximum number of I-PDU IDs received by AUTOSAR COM) - 1
	PdulInfoPtr	Contains the length (SduLength) of the received I-PDU and a pointer to a buffer (SduDataPtr) containing the I-PDU.
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	None	
<b>Description:</b>	This function is called by the lower layer after an I-PDU has been received.	

**Caveats:** This function might be called in interrupt context. Therefore, data consistency must be ensured.

### 8.4.3 Com\_TxConfirmation

#### COM124:

<b>Service name:</b>	Com_TxConfirmation
<b>Syntax:</b>	void Com_TxConfirmation( PduIdType ComTxPduId )
<b>Service ID[hex]:</b>	0x15
<b>Sync/Async:</b>	Synchronous
<b>Reentrancy:</b>	Non reentrant for the same PDU-ID. Reentrant for different PDU-ID.
<b>Parameters (in):</b>	ComTxPduId ID of AUTOSAR COM I-PDU that has been transmitted. Range: 0..(maximum number of I-PDU IDs transmitted by AUTOSAR COM) - 1
<b>Parameters (in-out):</b>	None
<b>Parameters (out):</b>	None
<b>Return value:</b>	None
<b>Description:</b>	This function is called by the lower layer after the PDU has been transmitted on the network.  A confirmation that is received for an I-PDU that does not require a confirmation is silently discarded.

**Caveats:** This function might be called in interrupt context (e.g. from transmit interrupt).

## 8.5 Scheduled Functions

### 8.5.1 Com\_MainFunctionRx

#### COM398:

<b>Service name:</b>	Com_MainFunctionRx
<b>Syntax:</b>	void Com_MainFunctionRx( )
<b>Service ID[hex]:</b>	0x18
<b>Timing:</b>	FIXED_CYCLIC
<b>Description:</b>	This function shall perform the processing of the AUTOSAR COM receive processing that are not directly initiated by the calls from the RTE and PDU-R.  A call to Com_MainFunctionRx shall simply return if COM was not previously initialized with a call to Com_Init.

Configuration: see COM186.

### 8.5.2 Com\_MainFunctionTx

#### COM399:

<b>Service name:</b>	Com_MainFunctionTx
<b>Syntax:</b>	void Com_MainFunctionTx( )

<b>Service ID[hex]:</b>	0x19
<b>Timing:</b>	FIXED_CYCLIC
<b>Description:</b>	This function shall perform the processing of the AUTOSAR COM transmission activities that are not directly initiated by the calls from the RTE and PDU-R.  A call to Com_MainFunctionTx shall simply return if COM was not previously initialized with a call to Com_Init.

Configuration: see COM186.

### 8.5.3 Com\_MainFunctionRouteSignals

#### COM400:

<b>Service name:</b>	Com_MainFunctionRouteSignals
<b>Syntax:</b>	void Com_MainFunctionRouteSignals(  )
<b>Service ID[hex]:</b>	0x1a
<b>Timing:</b>	FIXED_CYCLIC
<b>Description:</b>	Calls the signal gateway part of COM to forward received signals to be routed. The insertion of this call is necessary for decoupling receive interrupts and signal gateway tasks.  A call to Com_MainFunctionRouteSignals shall simply return if COM was not previously initialized with a call to Com_Init.

**Caveat:** The time between to consecutive calls (perhaps the related task/thread cycle) affects directly the signal gateway latency.

**Configuration:** A cyclic task/thread to call this function cyclical shall be configured. The cycle of this task/thread directly affects the latency of the signal gateway, see COM186.

## 8.6 Expected Interfaces

### 8.6.1 Mandatory Interfaces

This chapter defines all interfaces which are required to fulfill the core functionality of the module.

<b>API function</b>	<b>Description</b>
Dem_ReportErrorStatus	Reports errors to the DEM.
PduR_ComTransmit	Requests a transmission for the AUTOSAR COM Module

### 8.6.2 Optional Interfaces

This chapter defines all interfaces that are required to fulfill an optional functionality of the module.

<b>API function</b>	<b>Description</b>
Det_ReportError	Service to report development errors.

### 8.6.3 Configurable interfaces

**Caveats:** A callback routine runs either on interrupt level or on task level. Thus, the OS restrictions of usage of system functions for interrupt service routines as well as for tasks apply.

#### COM468:

<b>Service name:</b>	Com_CbkTxAck
<b>Syntax:</b>	void Com_CbkTxAck( )
<b>Sync/Async:</b>	Synchronous
<b>Reentrancy:</b>	don't care
<b>Parameters (in):</b>	None
<b>Parameters (in-out):</b>	None
<b>Parameters (out):</b>	None
<b>Return value:</b>	None
<b>Description:</b>	<p>This callback represents notification class 2 of [17]. It is called immediately after successful transmission of the I-PDU containing the message.</p> <p>Com_CbkTxAck is called on sender side only. It can be configured for signals and signal groups. Com_CbkTxAck corresponds to Rte_COMCbTack_&lt;sn&gt; or Rte_COMCbTack_&lt;sg&gt; respectively.</p> <p>For configuration of the callback function names, see COM498.</p>

#### COM491:

<b>Service name:</b>	Com_CbkTxErr
<b>Syntax:</b>	void Com_CbkTxErr( )
<b>Sync/Async:</b>	Synchronous
<b>Reentrancy:</b>	don't care
<b>Parameters (in):</b>	None
<b>Parameters (in-out):</b>	None
<b>Parameters (out):</b>	None
<b>Return value:</b>	None
<b>Description:</b>	<p>This callback corresponds to notification class 4 of [17]. It is called in case the transmission is not possible because the corresponding I-PDU group is stopped.</p> <p>Com_CbkTxErr is called on sender side only. This callback function corresponds to Rte_COMCbTErr_&lt;sn&gt; or Rte_COMCbTErr_&lt;sg&gt; respectively.</p> <p>For configuration of the callback function name, see COM499.</p>

#### COM554:

<b>Service name:</b>	Com_CbkTxTOut
<b>Syntax:</b>	void Com_CbkTxTOut( )

	)
<b>Sync/Async:</b>	Synchronous
<b>Reentrancy:</b>	don't care
<b>Parameters (in):</b>	None
<b>Parameters (in-out):</b>	None
<b>Parameters (out):</b>	None
<b>Return value:</b>	None
<b>Description:</b>	<p>This callback corresponds to notification class 4 of [17]. It is called immediately after a message transmission error has been detected by the deadline monitoring mechanism.</p> <p>Com_CbkTxTOut is called on sender side only. It can be configured for signals and signal groups. This callback function corresponds to Rte_COMCbktOut_&lt;sn&gt; or Rte_COMCbktOut_&lt;sg&gt; respectively.</p> <p>For configuration of the callback function names, see COM552.</p>

### COM555:

<b>Service name:</b>	Com_CbkRxAck
<b>Syntax:</b>	void Com_CbkRxAck( )
<b>Sync/Async:</b>	Synchronous
<b>Reentrancy:</b>	don't care
<b>Parameters (in):</b>	None
<b>Parameters (in-out):</b>	None
<b>Parameters (out):</b>	None
<b>Return value:</b>	None
<b>Description:</b>	<p>This callback represents notification class 1 of [17]. It is called immediately after the message has been stored in the receiving message object.</p> <p>Com_CbkRxAck is called on receiver side only . It can be configured for signals and signal groups. Com_CbkRxAck corresponds to Rte_COMCb�_&lt;sn&gt; or Rte_COMCb�_&lt;sg&gt; respectively.</p> <p>For configuration of the callback function names, see COM498.</p>

### COM556:

<b>Service name:</b>	Com_CbkRxTOut
<b>Syntax:</b>	void Com_CbkRxTOut( )
<b>Sync/Async:</b>	Synchronous
<b>Reentrancy:</b>	don't care
<b>Parameters (in):</b>	None
<b>Parameters (in-out):</b>	None
<b>Parameters (out):</b>	None
<b>Return value:</b>	None
<b>Description:</b>	This callback corresponds to notification class 3 of [17]. It is called immediately

	<p>after a message reception error has been detected by the deadline monitoring mechanism.</p> <p>Com_CbkRxTOut is called on receiver side only. It can be configured for signals and signal groups. This callback function corresponds to Rte_COMCbTOut_&lt;sn&gt; or Rte_COMCbTOut_&lt;sg&gt; respectively.</p> <p>For configuration of the callback function names, see COM552.</p>
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### COM536:

<b>Service name:</b>	Com_CbkInv
<b>Syntax:</b>	void Com_CbkInv(  )
<b>Sync/Async:</b>	Synchronous
<b>Reentrancy:</b>	don't care
<b>Parameters (in):</b>	None
<b>Parameters (in-out):</b>	None
<b>Parameters (out):</b>	None
<b>Return value:</b>	None
<b>Description:</b>	<p>This callback function is called after reception of an invalid signal or signal group respectively.</p> <p>Com_CbkInv is called on receiver side only. It can be configured for signals, group signals and signal groups. This callback function corresponds to Rte_COMCbInv_&lt;sn&gt; (for signals and group signals) and Rte_COMCbInv_&lt;sg&gt; respectively.</p> <p>For configuration of the callback function names, see COM315.</p>

**Note:** The naming conventions for the RTE callback routines are defined in [13] in Chapter “Naming convention of callbackRoutineName”.

**Note:** AUTOSAR COM uses no direct interface of RTE beside the callback functions.



## 9 Sequence diagrams

A sequence diagram of the underlying OSEK COM communication stack can be found in [17].

### 9.1 Interface between AUTOSAR COM and the lower layer (PDU Router)

The following chart shows the communication between AUTOSAR COM and the PDU Router.

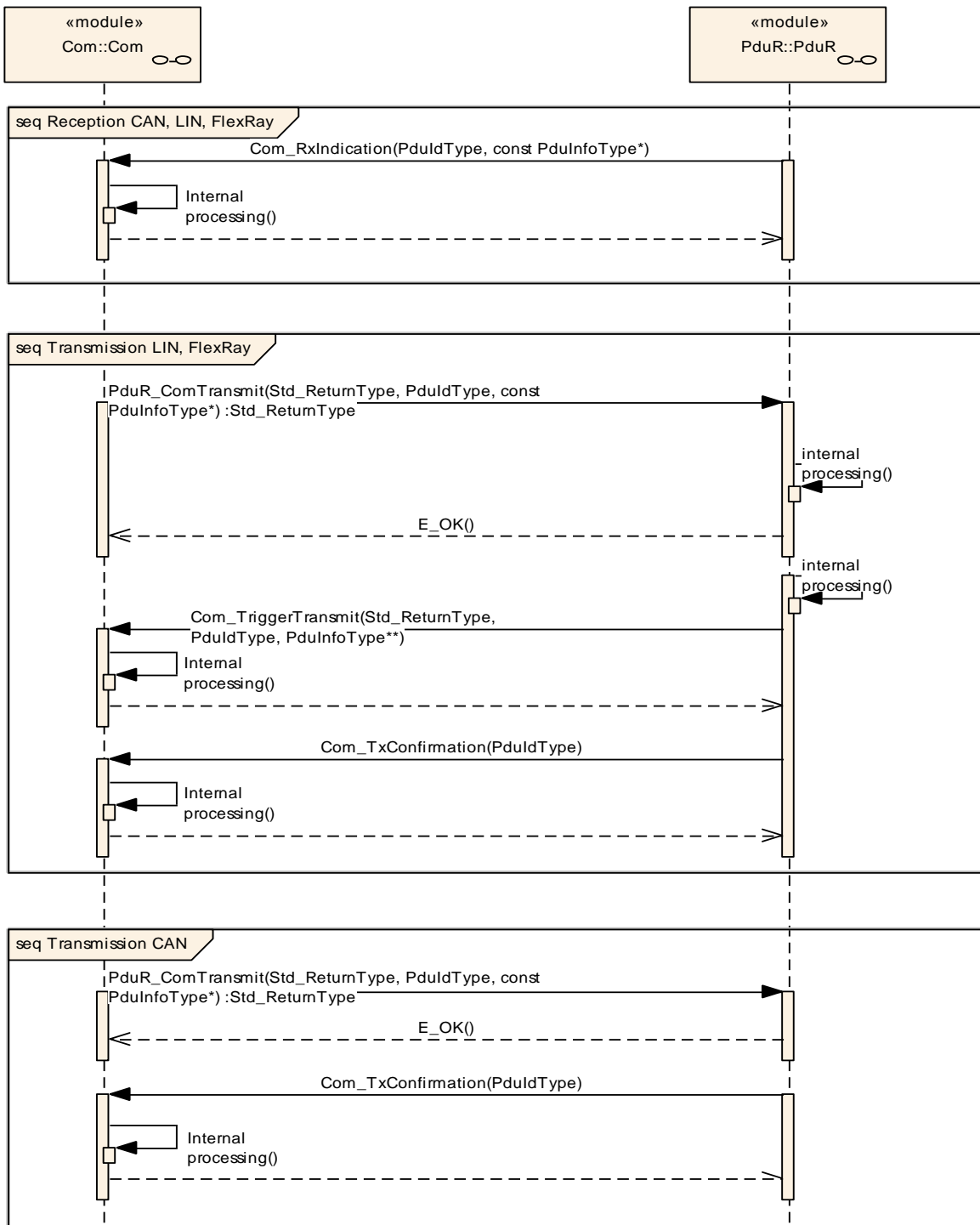


Figure 16: Interactions between AUTOSAR COM and the PDU router

## 9.2 Confirmation handling between PDUR, COM and RTE

The following chart shows the confirmation handling with respect to the two different IPDU-processing modes. (See also Chapter 7.4.5.4.)

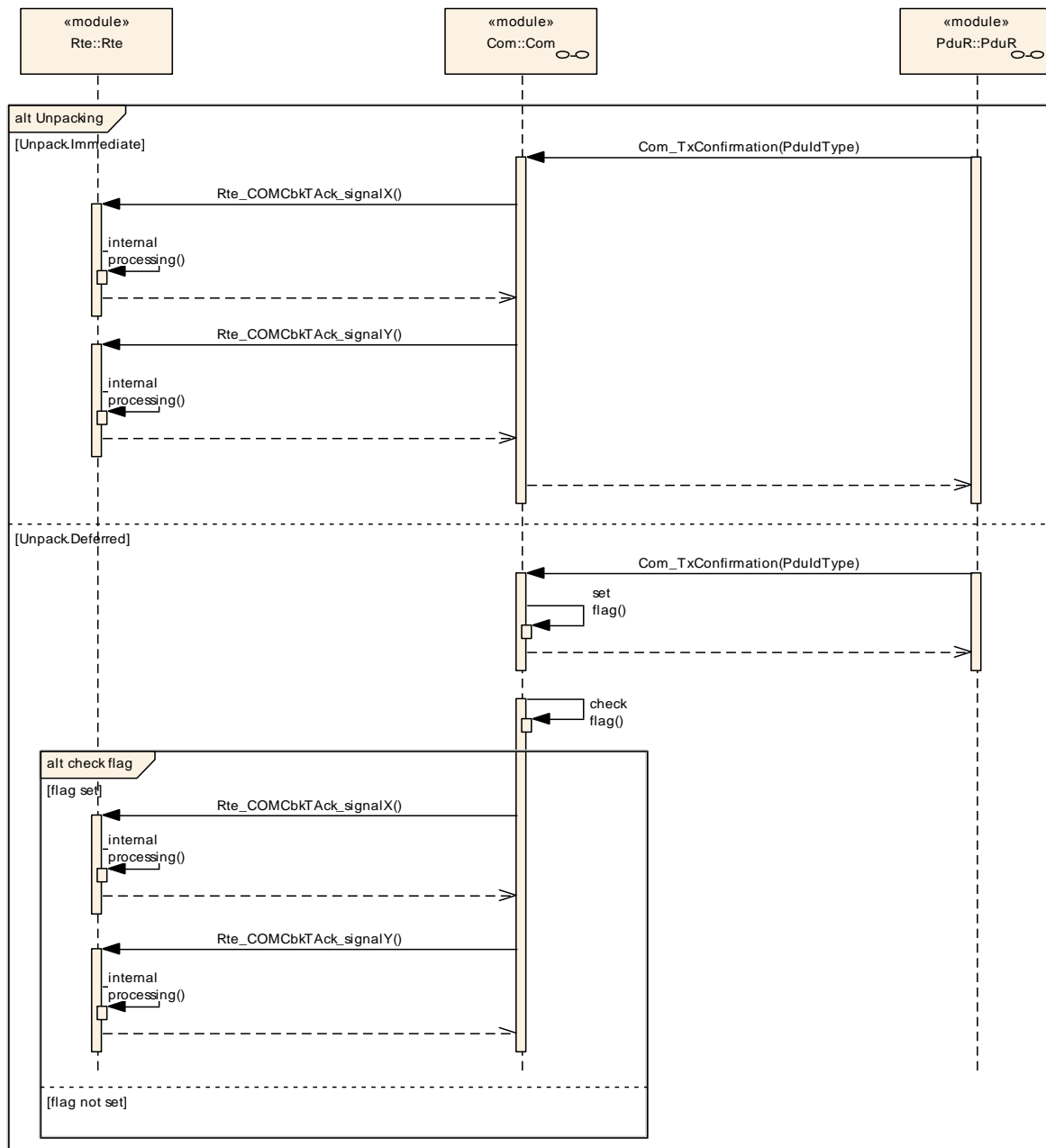
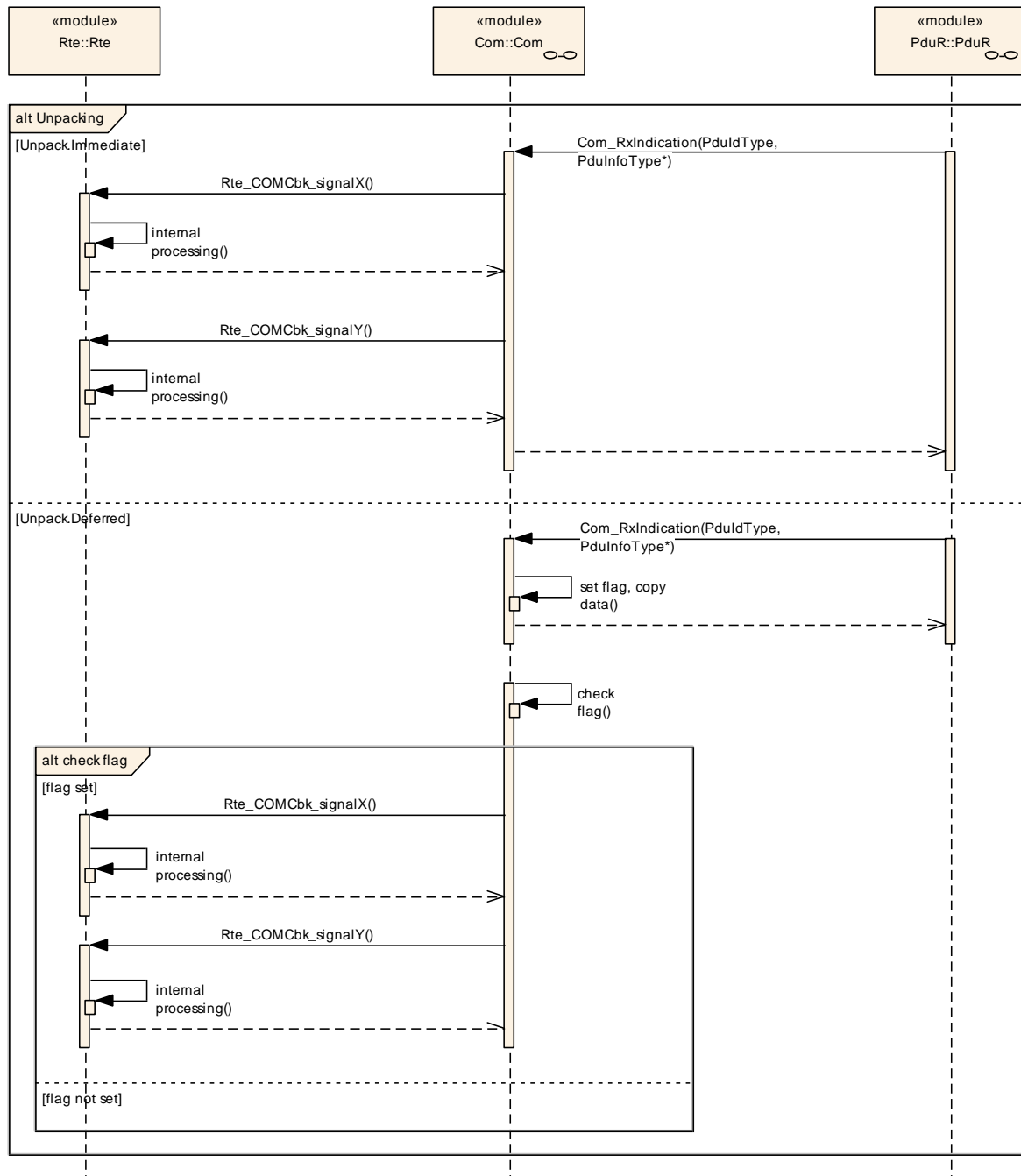


Figure 17: Confirmation handling between PDUR, COM and RTE

### 9.3 Indication handling between PDUR, COM and RTE

The following chart shows the indication handling with respect to the two different unpacking modes. (See also Chapter 7.4.5.4.)



**Figure 18: Indication handling between PDUR, COM and RTE**

## 10 Configuration specification

### 10.1 How to read this chapter

In addition to this section, it is highly recommended to read the documents:

- AUTOSAR Layered Software Architecture [1]
- AUTOSAR ECU Configuration Specification [14]  
This document describes the AUTOSAR configuration methodology and the AUTOSAR configuration meta model in detail.

The following is only a short survey of the topic and it will not replace the ECU Configuration Specification document.

#### 10.1.1 Configuration and configuration parameters

Configuration parameters define the variability of the generic part(s) of an implementation of a module. This means that only generic or configurable module implementation can be adapted to the environment (software/ hardware) in use during system and/ or ECU configuration.

The configuration of parameters can be achieved at different times during the software process: before compile time, before link time or after build time. In the following, the term **configuration class** (of a parameter) shall be used in order to refer to a specific configuration point in time.

**COM006:** The configuration parameters are based on [18]. All parameters have to be stored in an XML format.

#### 10.1.2 Containers

Containers structure the set of configuration parameters. This means: *all* configuration parameters are kept in containers. (sub-) containers can reference (sub-) containers. It is possible to assign a multiplicity to these references. The multiplicity then defines the possible number of instances of the contained parameters.

### 10.2 Containers and configuration parameters

The following chapters summarize all configuration parameters. The detailed meanings of the parameters describe Chapter 7 and Chapter 8.

#### 10.2.1 Variants

Currently three configuration variants for AUTOSAR COM are defined.

**COM374:** All configuration sets shall be identifiable by a unique identifier, see COM394.

#### **10.2.1.1 VARIANT-PRE-COMPILE**

VARIANT-PRE-COMPILE only supports pre-compile configurable parameters. Parameters below that are marked as Pre-compile configurable shall be configurable in a pre-compile manner, for example as #defines. A VARIANT-PRE-COMPILE module is most likely delivered as source code.

**Remark:** Even though the module is delivered as source code the implementation might use techniques similar to link time, i.e. table driven configuration.

#### **10.2.1.2 VARIANT-LINK-TIME**

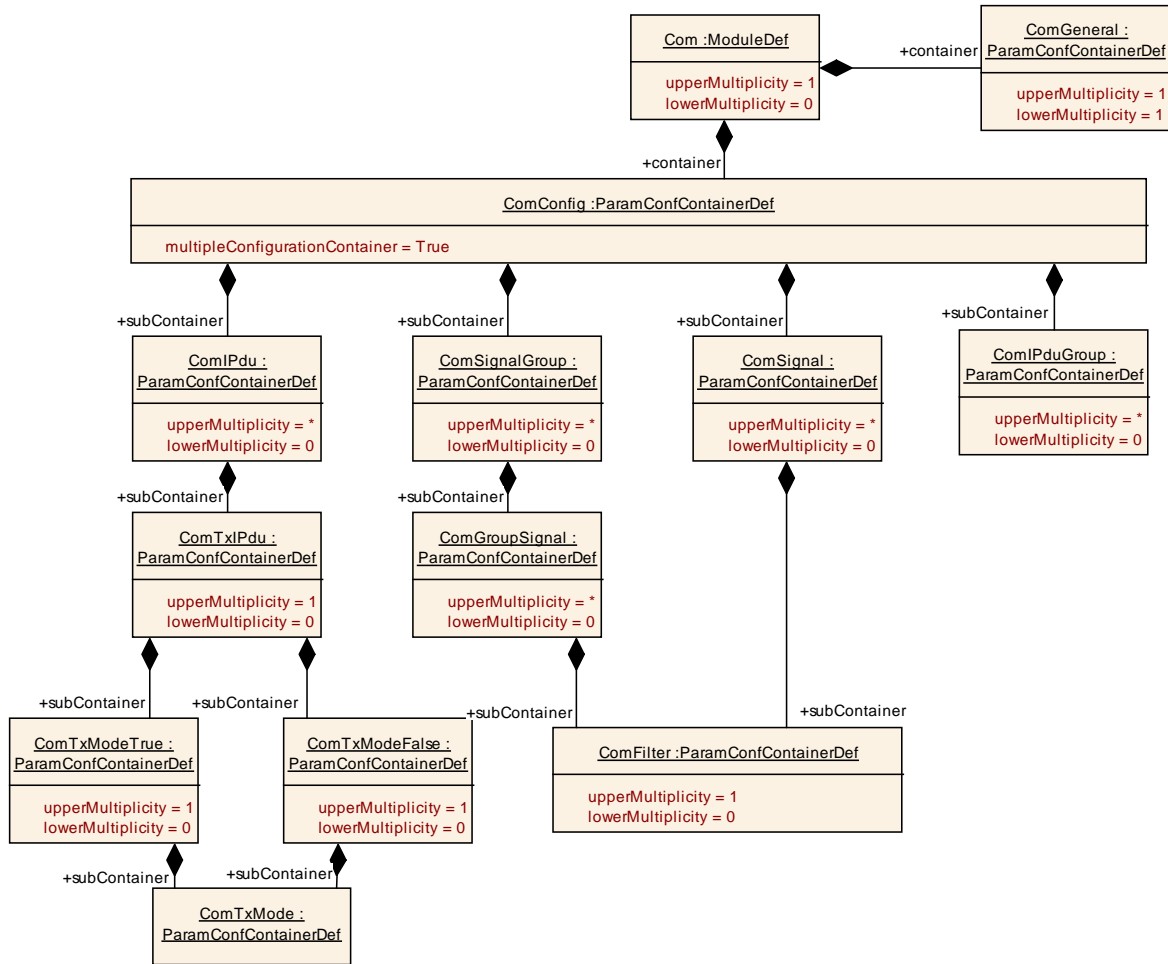
VARIANT-LINK-TIME includes mainly link-time and some pre-compile configurable parameters. All parameters defined below as link-time configurable shall be configurable at link time for example by linking a special configured parameter object file. A VARIANT-LINK-TIME module is most likely delivered as object code.

#### **10.2.1.3 VARIANT-POST-BUILD**

VARIANT-POST-BUILD includes post-build-time, link-time and some pre-compile configurable parameters. All parameters defined below as post build configurable shall be configurable post build for example by flashing configuration data. A VARIANT-POST-BUILD configurable module is most likely delivered as object code.

### 10.2.2 Configuration of the AUTOSAR COM Layer

For an overview of the COM Configuration see Figure 19:



**Figure 19: Com Configuration Overview**

### 10.2.3 Com

<b>Module Name</b>	Com
<b>Module Description</b>	COM540: Configuration of the Com module.

<b>Included Containers</b>		
<b>Container Name</b>	<b>Multiplicity</b>	<b>Scope / Dependency</b>
ComConfig	1	This container contains the configuration parameters and sub containers of the COM module. This container is a Multiple-ConfigurationContainer, i.e. this container and its sub-containers exist once per configuration set.
ComGeneral	1	Contains the general configuration parameters of the Com module.

### 10.2.4 ComConfig

<b>SWS Item</b>	<b>COM337 :</b>
<b>Container Name</b>	ComConfig [Multi Config Container]
<b>Description</b>	This container contains the configuration parameters and sub containers of the COM module. This container is a MultipleConfigurationContainer, i.e. this container and its sub-containers exist once per configuration set.
<b>Configuration Parameters</b>	

<b>SWS Item</b>	<b>COM394 :</b>		
<b>Name</b>	ComConfigurationId		
<b>Description</b>	This ID is returned by a call to Com_GetConfigurationId.		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>Included Containers</b>		
<b>Container Name</b>	<b>Multiplicity</b>	<b>Scope / Dependency</b>
ComGwMapping	0..*	Each instance of this container defines one mapping of the integrated Signal Gateway.
ComIPdu	0..*	COM404: If there is no such container included no I-PDU is defined. In this case no communication is possible.
ComIPduGroup	0..*	COM405: If there is no such container included then no I-PDU group is defined. In this case no communication is possible.
ComSignal	0..*	COM407: If there is no ComSignal container included no single signals are defined.
ComSignalGroup	0..*	COM408: If there is no such container included no signal groups are defined.



### 10.2.5 ComGeneral

<b>SWS Item</b>	<b>COM541 :</b>
<b>Container Name</b>	ComGeneral
<b>Description</b>	Contains the general configuration parameters of the Com module.
<b>Configuration Parameters</b>	

<b>SWS Item</b>	<b>COM186 :</b>		
<b>Name</b>	ComConfigurationTimeBase		
<b>Description</b>	If no "ComTimeBase" container is specified this value defines the period between successive calls to the Main Functions (Rx, Tx, Routing) of AUTOSAR COM in seconds. In this case this "ComConfigurationTimeBase" value is used by the COM generator to take the values of the Tx/Rx/Routing related timing configuration parameters of the COM module to internal implementation specific counter or tick values. The COM module's internal timing handling is implementation specific. If additionally a "ComTimeBase" container and its mandatory parameters ComTxTimeBase, ComRxTimeBase and ComGwTimeBase are specified this value defines the time base for all timing configuration parameters (which are specified as factors of this "ComConfigurationTimeBase"). In this case the time base parameters from "ComTimeBase" container are used by the COM generator to transform the values of the Tx/Rx/Routing related timing configuration parameters of the COM module to internal implementation specific counter or tick values to support the possibly different time bases for Tx/Rx/Routing. The COM module's internal timing handling is implementation specific.		
<b>Multiplicity</b>	1		
<b>Type</b>	FloatParamDef		
<b>Range</b>	-INF .. INF		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM141 :</b>		
<b>Name</b>	ComConfigurationUseDet		
<b>Description</b>	The error hook shall contain code to call the Det. If this parameter is configured COM_DEV_ERROR_DETECT shall be set to ON as output of the configuration tool. (as input for the source code), see COM028.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	BooleanParamDef		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM780_Conf :</b>		
<b>Name</b>	ComRetryFailedTransmitRequests		
<b>Description</b>	If this Parameter is set to true, retry of failed transmission requests is enabled. If this Parameter is not present, the default value is assumed.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	BooleanParamDef		
<b>Default value</b>	false		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>		

	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM710 :</b>		
<b>Name</b>	ComSupportedIPduGroups		
<b>Description</b>	Defines the maximum number of supported I-PDU groups.		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	0 .. 65535		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM831 :</b>		
<b>Name</b>	ComUserCbkJHeaderFile		
<b>Description</b>	Defines header files for callback functions which shall be included by the COM module. The minimum length for this StringParamDef is 1. The maximum length for this StringParamDef is 32.		
<b>Multiplicity</b>	0..*		
<b>Type</b>	StringParamDef		
<b>Default value</b>	--		
<b>regularExpression</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>COM438 :</b>		
<b>Name</b>	ComVersionInfoApi		
<b>Description</b>	Activate/Deactivate the version information API (Com_GetVersionInfo). True: version information API activated False: version information API deactivated		
<b>Multiplicity</b>	1		
<b>Type</b>	BooleanParamDef		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>Included Containers</b>		
<b>Container Name</b>	<b>Multiplicity</b>	<b>Scope / Dependency</b>
ComTimeBase	0..1	Contains the timebase parameters for Tx, Rx and routing.

### 10.2.6 ComTimeBase

<b>SWS Item</b>	:
<b>Container Name</b>	ComTimeBase
<b>Description</b>	Contains the timebase parameters for Tx, Rx and routing.
<b>Configuration Parameters</b>	

<b>SWS Item</b>	<b>COM729 :</b>		
<b>Name</b>	ComGwTimeBase		
<b>Description</b>	The period between successive calls to Com_MainFunctionRouteSignals in seconds. This parameter may be used by the COM generator to transform the values of the signal gateway related timing configuration parameters of the COM module to internal implementation specific counter or tick values. The COM module's internal timing handling is implementation specific. The COM module (generator) might rely on the fact that Com_MainFunctionRouteSignals is scheduled according to the value configured here.		
<b>Multiplicity</b>	1		
<b>Type</b>	FloatParamDef		
<b>Range</b>	-INF .. INF		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM728 :</b>		
<b>Name</b>	ComRxTimeBase		
<b>Description</b>	The period between successive calls to Com_MainFunctionRx in seconds. This parameter may be used by the COM generator to transform the values of the reception related timing configuration parameters of the COM module to internal implementation specific counter or tick values. The COM module's internal timing handling is implementation specific. The COM module (generator) may rely on the fact that Com_MainFunctionRx is scheduled according to the value configured here.		
<b>Multiplicity</b>	1		
<b>Type</b>	FloatParamDef		
<b>Range</b>	-INF .. INF		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM730 :</b>		
<b>Name</b>	ComTxTimeBase		
<b>Description</b>	The period between successive calls to Com_MainFunctionTx in seconds. This parameter may be used by the COM generator to transform the values of the transmission related timing configuration parameters of the COM module to internal implementation specific counter or tick values. The COM module's internal timing handling is implementation specific. The COM module (generator) may rely on the fact that Com_MainFunctionTx is scheduled according to the value configured here.		
<b>Multiplicity</b>	1		
<b>Type</b>	FloatParamDef		
<b>Range</b>	-INF .. INF		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	All Variants

	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

**No Included Containers**

### 10.2.7 ComFilter

<b>SWS Item</b>	<b>COM339 :</b>		
<b>Container Name</b>	ComFilter		
<b>Description</b>	This container contains the configuration parameters of COM Filters. Note: On sender side the container is used to specify the transmission mode conditions.		
<b>Configuration Parameters</b>			

<b>SWS Item</b>	<b>COM146 :</b>		
<b>Name</b>	ComFilterAlgorithm		
<b>Description</b>	The range of values is specified in the [17] specification, chapter 2.2.2, Reception Filtering.		
<b>Multiplicity</b>	1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	ALWAYS		
	MASKED_NEW_DIFFERS_MASKED_OLD		
	MASKED_NEW_DIFFERS_X		
	MASKED_NEW_EQUALS_X		
	NEVER		
	NEW_IS_OUTSIDE		
	NEW_IS_WITHIN		
	ONE_EVERY_N		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM235 :</b>		
<b>Name</b>	ComFilterMask		
<b>Description</b>	The name of this attribute corresponds to the parameter name in the [17] specification of Reception Filtering. Only the least significant 32 bits are significant.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM317 :</b>		
-----------------	-----------------	--	--

<b>Name</b>	ComFilterMax		
<b>Description</b>	The name of this attribute corresponds to the parameter name in the [17] specification of Reception Filtering. Only the least significant 32 bits are significant.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM318 :</b>		
<b>Name</b>	ComFilterMin		
<b>Description</b>	The name of this attribute corresponds to the parameter name in the [17] specification of Reception Filtering. Only the least significant 32 bits are significant.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM313 :</b>		
<b>Name</b>	ComFilterOffset		
<b>Description</b>	The name of this attribute corresponds to the parameter name in the [17] specification of Reception Filtering. Only the least significant 32 bits are significant. Range = 0..(ComFilterPeriodFactor-1)		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local dependency: COM312		

<b>SWS Item</b>	<b>COM312 :</b>		
<b>Name</b>	ComFilterPeriodFactor		
<b>Description</b>	The name of this attribute corresponds to the parameter name in the [17] specification of Reception Filtering. Only the least significant 32 are significant.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM147 :</b>		
<b>Name</b>	ComFilterX		
<b>Description</b>	The name of this attribute corresponds to the parameter name in the [17] specification of Reception Filtering. Only the least significant 32 bits are significant.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

**No Included Containers**

### 10.2.8 ComIPdu

<b>SWS Item</b>	<b>COM340, COM174 :</b>		
<b>Container Name</b>	ComIPdu		
<b>Description</b>	Contains the configuration parameters of Com I-Pdus. COM174: The shortName is used as the symbolic name (ComIpduName) of this I-Pdu when communicating with the PduR. This parameter is only stored in the XML file, and must not be used within the implementation.		
<b>Configuration Parameters</b>			

<b>SWS Item</b>	<b>COM387 :</b>		
<b>Name</b>	ComIPduCallout		
<b>Description</b>	If there is a callout defined for this I-PDU this parameter contains the name of the callout function..		
<b>Multiplicity</b>	0..1		
<b>Type</b>	FunctionNameDef		
<b>Default value</b>	--		
<b>regularExpression</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM175 :</b>		
<b>Name</b>	ComIPduRxHandleId		
<b>Description</b>	The numerical value used as the ID of this I-PDU. The Com_IPduRxHandleId is required by the API calls to receive I-PDUs from the PduR. It is only present for I-PDU is received from the PduR, because Com is the starting module for Tx I-PDUs and there is no need to define IDs for Tx I-PDUs in the Com module.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef (Symbolic Name generated for this parameter)		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE

	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: external, depends on configuration process		

<b>SWS Item</b>	<b>COM119 :</b>		
<b>Name</b>	ComIPduSignalProcessing		
<b>Description</b>	For the definition of the two modes Immediate and Deferred, see COM298.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	DEFERED IMMEDIATE		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM176 :</b>		
<b>Name</b>	ComIPduSize		
<b>Description</b>	The size of the I-PDU in bytes. The maximum size is limited by the underlying communication interface. 0-8 for CAN and LIN 0-254 for FlexRay		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	0 .. 254		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM765 :</b>		
<b>Name</b>	ComIPduTriggerTransmitCallout		
<b>Description</b>	If there is a trigger transmit callout defined for this I-PDU this parameter contains the name of the callout function.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	FunctionNameDef		
<b>Default value</b>	--		
<b>regularExpression</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM493 :</b>		
<b>Name</b>	ComIpduDirection		
<b>Description</b>	The direction defines if this I-PDU, and therefore the contributing signals and signal groups, shall be send or received.		
<b>Multiplicity</b>	1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	RECEIVE SEND		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD

<b>Scope / Dependency</b>	scope: local dependency: If configured to Send also a ComTxIpdu container shall be included, see COM496
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<b>SWS Item</b>	<b>COM206 :</b>		
<b>Name</b>	ComIPduGroupRef		
<b>Description</b>	Reference to all I-PDU groups including this I-PDU.		
<b>Multiplicity</b>	0..*		
<b>Type</b>	Reference to [ ComIPduGroup ]		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM519 :</b>		
<b>Name</b>	ComIPduSignalGroupRef		
<b>Description</b>	References to all signal groups contained in this I-Pdu		
<b>Multiplicity</b>	0..*		
<b>Type</b>	Reference to [ ComSignalGroup ]		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>COM518 :</b>		
<b>Name</b>	ComIPduSignalRef		
<b>Description</b>	References to all signals contained in this I-PDU.		
<b>Multiplicity</b>	0..*		
<b>Type</b>	Reference to [ ComSignal ]		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	:		
<b>Name</b>	PduIdRef		
<b>Description</b>	Reference to the "global" Pdu structure to allow harmonization of handle IDs in the COM-Stack.		
<b>Multiplicity</b>	1		
<b>Type</b>	Reference to [ Pdu ]		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>			

<b>Included Containers</b>		
<b>Container Name</b>	<b>Multiplicity</b>	<b>Scope / Dependency</b>



ComTxIPdu	0..1	COM496: This container must be included if COM_IPDU_DIRECTION is configured to SEND.
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**COM497:** A ComTxIPdu container must be included if ComIpdudirection is configured to Send.

### 10.2.9 ComTxIPdu

<b>SWS Item</b>	<b>COM496 :</b>	
<b>Container Name</b>	ComTxIPdu	
<b>Description</b>	This container contains additional transmission related configuration parameters of COM I-PDUs	
<b>Configuration Parameters</b>		

<b>SWS Item</b>	<b>COM576 :</b>		
<b>Name</b>	ComTxIPduClearUpdateBit		
<b>Description</b>	Defines when the update-bits of signals or signal groups, contained in this I-PDU, will be cleared.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	Confirmation	The update-bits are cleared when the transmission of the I-PDU was confirmed. In case of Direct/N-Times transmission mode the update bits will be cleared with respect to the confirmation behaviour of COM305.	
	Transmit	The update-bits are cleared directly after the invocation of PduR_ComTransmit.	
	TriggerTransmit	The update-bits are cleared after the I-PDU was fetched via Com_TriggerTransmit.	
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM181, COM471 :</b>		
<b>Name</b>	ComTxIPduMinimumDelayTimeFactor		
<b>Description</b>	COM181: Minimum delay between successive transmissions of this I-PDU, independent of the transmission mode. There is only one minimum delay time parameter for the I-PDU. This minimum delay time does not change with mode changes. Neither is the timer reset. This means that mode changes are not allowed to violate the minimum delay time. It is not possible to monitor the minimum delay time for I-PDUs that are requested using the Com_TriggerTransmit API. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter. COM471: No minimum delay time monitoring shall take place, if ComTxIPduMinimumDelayTimeFactor is omitted or configured to 0.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>COM017 :</b>		
<b>Name</b>	ComTxIPduUnusedAreasDefault		
<b>Description</b>	AUTOSAR COM fills not used areas of an I-PDU with this bit-pattern. This attribute is mandatory to avoid undefined behaviour. This byte-pattern will be repeated throughout the I-PDU.		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	0 .. 255		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>Included Containers</b>		
<b>Container Name</b>	<b>Multiplicity</b>	<b>Scope / Dependency</b>
ComTxModeFalse	0..1	COM234: The referenced transmission mode object that is used when the filtering state for this I-PDU evaluates to false. The default is transmission mode None.
ComTxModeTrue	0..1	COM233: The referenced transmission mode object that is used when the filtering state for this I-PDU evaluates to true.

ComTxModeTrue: COM233: The referenced transmission mode object (see section 10.2.2.8) that is used when the filtering state for this I-PDU evaluates to true.

ComTxModeFalse: COM234: The referenced transmission mode object (see section 10.2.2.8) that is used when the filtering state for this I-PDU evaluates to false.

The default is transmission mode None.

### 10.2.10 ComIPduGroup

<b>SWS Item</b>	<b>COM341, COM126 :</b>		
<b>Container Name</b>	ComIPduGroup		
<b>Description</b>	Contains the configuration parameters of Com I-Pdu groups. COM126: The shortName is used as the symbolic name of the I-Pdu group (ComIpduGroupName). This parameter is only stored in the XML file, and must not be used within the implementation.		
<b>Configuration Parameters</b>			

<b>SWS Item</b>	<b>COM184 :</b>		
<b>Name</b>	ComIPduGroupHandleId		
<b>Description</b>	The numerical value used as the ID of this I-PDU Group . The ComIPduGroupHandleId is required by the API calls to start and stop I-PDU Groups. For the rational for the range see COM187.		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef (Symbolic Name generated for this parameter)		
<b>Range</b>	0 .. 65535		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	

<b>Scope / Dependency</b>	scope: external, depends on configuration process
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<b>SWS Item</b>	<b>COM185 :</b>		
<b>Name</b>	ComIPduGroupGroupRef		
<b>Description</b>	References to all I-PDU groups including this I-PDU group. If this reference is omitted, this I-PDU group is not included in another I-PDU group.		
<b>Multiplicity</b>	0..*		
<b>Type</b>	Reference to [ ComIPduGroup ]		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>No Included Containers</b>
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### 10.2.11 ComSignal

<b>SWS Item</b>	<b>COM344, COM163 :</b>		
<b>Container Name</b>	ComSignal		
<b>Description</b>	Contains the configuration parameters of Com signals. COM163: The shortName is used as the symbolic name of the signal (ComSignalName). This name is also used as the handle name for the signal. This parameter is only stored in the XML file, and must not be used within the implementation.		
<b>Configuration Parameters</b>			

<b>SWS Item</b>	<b>COM259 :</b>		
<b>Name</b>	ComBitPosition		
<b>Description</b>	Starting position within the I-PDU. This parameter refers to the position in the I-PDU and not in the shadow buffer.		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	0 .. 2031		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM158 :</b>		
<b>Name</b>	ComBitSize		
<b>Description</b>	Size in bits.		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	0 .. 64		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM314 :</b>		
<b>Name</b>	ComDataInvalidAction		
<b>Description</b>	This parameter defines the action performed upon reception of an invalid signal. Relating to signal groups the action in case if one of the included signals is an invalid signal. If Replace is used the ComSignalInitValue will be used for the replacement.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	NOTIFY		
	REPLACE	Literal for DataInvalidAction	
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM499 :</b>		
<b>Name</b>	ComErrorNotification		
<b>Description</b>	Only valid on sender side: Name of Com_CbkTxErr callback function to be called. If this parameter is omitted no error notification shall take place.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	FunctionNameDef		
<b>Default value</b>	--		
<b>regularExpression</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>COM183 :</b>		
<b>Name</b>	ComFirstTimeoutFactor		
<b>Description</b>	Defines the first timeout period for the deadline monitoring. Details can be found in [17]. Note: See also COM263 for the configuration of the remaining timeout periods. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM165 :</b>		
<b>Name</b>	ComHandleId		
<b>Description</b>	The numerical value used as the ID. For signals it is required by the API calls Com_UpdateShadowSignal, Com_ReceiveShadowSignal and Com_InvalidShadowSignal. For signals groups it is required by the Com_SendSignalGroup and Com_ReceiveSignalGroup calls.		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef (Symbolic Name generated for this parameter)		

<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: external, depends on configuration process		

<b>SWS Item</b>	<b>COM795 :</b>		
<b>Name</b>	ComInitialValueOnly		
<b>Description</b>	If set to true this parameter defines that the respective signal's initial value shall be put into the respective Pdu but there will not be any update of the value through the RTE. Thus the Com implementation does not need to expect any API calls for this signal.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	BooleanParamDef		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM315 :</b>		
<b>Name</b>	ComInvalidNotification		
<b>Description</b>	Only valid on receiver side: Name of Com_CbkRxInv callback function to be called. Name of the function which notifies the RTE about the reception of an invalidated signal/ signal group. Only applicable if ComSignalDataInvalidAction is configured to Notify.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	FunctionNameDef		
<b>Default value</b>	--		
<b>regularExpression</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM498 :</b>		
<b>Name</b>	ComNotification		
<b>Description</b>	On sender side: Name of Com_CbkTxAck callback function to be called. On receiver side: Name of Com_CbkRxAck callback function to be called. If this parameter is omitted no notification shall take place.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	FunctionNameDef		
<b>Default value</b>	--		
<b>regularExpression</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build</b>	--	

	<i>time</i>		
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM412, COM470, COM500, COM513 :</b>		
<b>Name</b>	ComRxDataTimeoutAction		
<b>Description</b>	COM412: This parameter defines the action performed upon a reception timeout violation. COM500: If this parameter is omitted or configured to None no replacement shall take place. COM470: Relating to signals: When this parameter is set to Replace, the replacement value used shall be the ComInitValue. COM513: Relating to signal groups: When this parameter is set to Replace, all included signals shall be set to their ComInitValue.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	NONE	Literal for DataTimeoutAction	
	REPLACE	Literal for DataTimeoutAction	
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM391, COM501 :</b>		
<b>Name</b>	ComSignalDataInvalidValue		
<b>Description</b>	COM391: On receiver side: When this value is received it is recognized as the invalid value and the appropriate invalid action (as specified by ComDataInvalidAction) is performed. COM501: On sender side: This configures the data invalid value that is used by a call to Com_InvalidateSignal.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM157 :</b>		
<b>Name</b>	ComSignalEndianness		
<b>Description</b>	Defines the endianness of the signal's network representation.		
<b>Multiplicity</b>	1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	BIG_ENDIAN		
	LITTLE_ENDIAN		
	OPAQUE		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM170, COM483 :</b>		
<b>Name</b>	ComSignalInitValue		
<b>Description</b>	COM170: Initial value for this signal. The default value is 0. The lower n-bits of the configured Integer shall be used as init-value for an n-bit sized signal type. COM483: If the signal is of type UINT[n], the Integer's least significant byte shall be assigned to the byte array's last byte. The second-least significant byte shall		

	be assigned to the byte array's last but one byte, and so on.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	0		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local dependency: IpduM		

<b>SWS Item</b>	<b>COM437 :</b>		
<b>Name</b>	ComSignalLength		
<b>Description</b>	The ComSignalLength specifies the n (in Bytes: 1..8) of the type UINT8[n]. For other types it will be ignored.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	1 .. 8		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM127 :</b>		
<b>Name</b>	ComSignalType		
<b>Description</b>	The AUTOSAR type of the signal. Whether or not the signal is signed or unsigned can be found by examining the value of this attribute. This type could also be used to reserved appropriate storage in AUTOSAR COM.		
<b>Multiplicity</b>	1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	BOOLEAN		
	SINT16		
	SINT32		
	SINT8		
	UINT16		
	UINT32		
	UINT8		
	UINT8_N		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM263, COM264, COM333 :</b>		
<b>Name</b>	ComTimeoutFactor		
<b>Description</b>	COM263: Defines the timeout period for the deadline monitoring. Details can be found in [17]. Note: The period for the ComFirstTimeoutFactor could differ from the ComTimeoutFactor. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter. COM264: If deadline monitoring is used on a signal with an update-bit this defines the timeout for deadline monitoring. COM333: If the timeout is omitted or configured to 0 than no timeout monitoring shall take place. In this case ComFirstTimeoutFactor shall be ignored.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		

<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM552 :</b>		
<b>Name</b>	ComTimeoutNotification		
<b>Description</b>	On sender side: Name of Com_CbkTxTOut callback function to be called. On receiver side: Name of Com_CbkRxTOut callback function to be called.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	FunctionNameDef		
<b>Default value</b>	--		
<b>regularExpression</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM232 :</b>		
<b>Name</b>	ComTransferProperty		
<b>Description</b>	Defines if a write access to this signal can trigger the transmission of the corresponding I-PDU. If the I-PDU is triggered, depends also on the transmission mode of the corresponding I-PDU. TRIGGERED: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU. PENDING: A write access to this signal never triggers the transmission of the corresponding I-PDU. TRIGGERED_ON_CHANGE: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU, but only in case the written value is different to the locally stored (last written or init) value. TRIGGERED_WITHOUT_REPETITION: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU just once without a repetition. TRIGGERED_ON_CHANGE_WITHOUT_REPETITION: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU just once without a repetition, but only in case the written value is different to the locally stored (last written or init) value.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	PENDING		
	TRIGGERED		
	TRIGGERED_ON_CHANGE		
	TRIGGERED_ON_CHANGE_WITHOUT_REPETITION		
	TRIGGERED_WITHOUT_REPETITION		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		



<b>SWS Item</b>	<b>COM257 :</b>		
<b>Name</b>	ComUpdateBitPosition		
<b>Description</b>	Bit position of update-bit inside I-PDU. If this attribute is omitted then there is no update-bit. This setting must be consistently on sender and on receiver side.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	0 .. 2031		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	:		
<b>Name</b>	SystemTemplateSystemSignalRef		
<b>Description</b>	Reference to the ISignalToIPduMapping that contains a reference to the ISignal (System Template) which this ComSignal (or ComGroupSignal) represents.		
<b>Multiplicity</b>	1		
<b>Type</b>	Foreign reference to [ ISignalToIPduMapping ]		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	--	
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: system configuration		

<b>Included Containers</b>		
<b>Container Name</b>	<b>Multiplicity</b>	<b>Scope / Dependency</b>
ComFilter	0..1	This container contains the configuration parameters of COM Filters. Note: On sender side the container is used to specify the transmission mode conditions.

**ComFilter: COM169:** On receiver side:

The name of the filter type as defined in the filter object in section 11.3.1.

**ComFilter: COM275:** On sender side:

Reference to a filter object which is used to determine the transmission mode selector of the I PDU the signal belongs to.

If this attribute is omitted, the signal does not contribute to the evaluation of the transmission mode of the I PDU the signal belongs to.

### 10.2.12 ComSignalGroup

<b>SWS Item</b>	<b>COM345, COM044 :</b>	
<b>Container Name</b>	ComSignalGroup	
<b>Description</b>	Contains the configuration parameters of Com signal groups. COM044: The shortName is used as the symbolic name of the signal group (ComSignalGroupName). This name is also used as the handle name for the signal group. This parameter is only stored in the XML file, and must not be used within the implementation.	
<b>Configuration Parameters</b>		

<b>SWS Item</b>	<b>COM314 :</b>	
<b>Name</b>	ComDataInvalidAction	

<b>Description</b>	This parameter defines the action performed upon reception of an invalid signal. Relating to signal groups the action in case if one of the included signals is an invalid signal. If Replace is used the ComSignalInitValue will be used for the replacement.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	NOTIFY		
	REPLACE	Literal for DataInvalidAction	
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM499 :</b>		
<b>Name</b>	ComErrorNotification		
<b>Description</b>	Only valid on sender side: Name of Com_CbkTxErr callback function to be called. If this parameter is omitted no error notification shall take place.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	FunctionNameDef		
<b>Default value</b>	--		
<b>regularExpression</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>COM183 :</b>		
<b>Name</b>	ComFirstTimeoutFactor		
<b>Description</b>	Defines the first timeout period for the deadline monitoring. Details can be found in [17]. Note: See also COM263 for the configuration of the remaining timeout periods. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM165 :</b>		
<b>Name</b>	ComHandleId		
<b>Description</b>	The numerical value used as the ID. For signals it is required by the API calls Com_UpdateShadowSignal, Com_ReceiveShadowSignal and Com_InvalidShadowSignal. For signals groups it is required by the Com_SendSignalGroup and Com_ReceiveSignalGroup calls.		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef (Symbolic Name generated for this parameter)		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE

	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: external, depends on configuration process		

<b>SWS Item</b>	<b>COM796 :</b>		
<b>Name</b>	ComInitialValueOnly		
<b>Description</b>	If set to true this parameter defines that the initial values of all group signals of the ComSignalGroup shall be put into the respective Pdu but there will not be any update of the values through the RTE. Thus the Com implementation does not need to expect any API calls for this signal group.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	BooleanParamDef		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM315 :</b>		
<b>Name</b>	ComInvalidNotification		
<b>Description</b>	Only valid on receiver side: Name of Com_CbkRxInv callback function to be called. Name of the function which notifies the RTE about the reception of an invalidated signal/ signal group. Only applicable if ComSignalDataInvalidAction is configured to Notify.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	FunctionNameDef		
<b>Default value</b>	--		
<b>regularExpression</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM498 :</b>		
<b>Name</b>	ComNotification		
<b>Description</b>	On sender side: Name of Com_CbkTxAck callback function to be called. On receiver side: Name of Com_CbkRxAck callback function to be called. If this parameter is omitted no notification shall take place.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	FunctionNameDef		
<b>Default value</b>	--		
<b>regularExpression</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM412, COM470, COM500, COM513 :</b>		
<b>Name</b>	ComRxDataTimeoutAction		
<b>Description</b>	COM412: This parameter defines the action performed upon a reception timeout violation. COM500: If this parameter is omitted or configured to None no replacement shall take place. COM470: Relating to signals: When this parameter is set to Replace, the replacement value used shall be the ComInitValue. COM513: Relating to signal groups: When this parameter is set to Replace, all included signals shall be set to their ComInitValue.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	NONE	Literal for DataTimeoutAction	
	REPLACE	Literal for DataTimeoutAction	
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM263, COM264, COM333 :</b>		
<b>Name</b>	ComTimeoutFactor		
<b>Description</b>	COM263: Defines the timeout period for the deadline monitoring. Details can be found in [17]. Note: The period for the ComFirstTimeoutFactor could differ from the ComTimeoutFactor. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter. COM264: If deadline monitoring is used on a signal with an update-bit this defines the timeout for deadline monitoring. COM333: If the timeout is omitted or configured to 0 than no timeout monitoring shall take place. In this case ComFirstTimeoutFactor shall be ignored.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM552 :</b>		
<b>Name</b>	ComTimeoutNotification		
<b>Description</b>	On sender side: Name of Com_CbkTxTOut callback function to be called. On receiver side: Name of Com_CbkRxTOut callback function to be called.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	FunctionNameDef		
<b>Default value</b>	--		
<b>regularExpression</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM232 :</b>		
<b>Name</b>	ComTransferProperty		
<b>Description</b>	Defines if a write access to this signal can trigger the transmission of the corresponding I-PDU. If the I-PDU is triggered, depends also on the transmission mode		

	of the corresponding I-PDU. TRIGGERED: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU. PENDING: A write access to this signal never triggers the transmission of the corresponding I-PDU. TRIGGERED_ON_CHANGE: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU, but only in case the written value is different to the locally stored (last written or init) value. TRIGGERED_WITHOUT_REPETITION: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU just once without a repetition. TRIGGERED_ON_CHANGE_WITHOUT_REPETITION: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU just once without a repetition, but only in case the written value is different to the locally stored (last written or init) value.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	PENDING		
	TRIGGERED		
	TRIGGERED_ON_CHANGE		
	TRIGGERED_ON_CHANGE_WITHOUT_REPETITION		
	TRIGGERED_WITHOUT_REPETITION		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM257 :</b>		
<b>Name</b>	ComUpdateBitPosition		
<b>Description</b>	Bit position of update-bit inside I-PDU. If this attribute is omitted then there is no update-bit. This setting must be consistently on sender and on receiver side.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	0 .. 2031		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	:		
<b>Name</b>	SystemTemplateSignalGroupRef		
<b>Description</b>	Reference to the ISignalToIPduMapping that contains a reference to the ISignal (SystemTemplate) which this ComSignalGroup represents.		
<b>Multiplicity</b>	1		
<b>Type</b>	Foreign reference to [ ISignalToIPduMapping ]		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	--	
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: system configuration		

<b>Included Containers</b>		
<b>Container Name</b>	<b>Multiplicity</b>	<b>Scope / Dependency</b>
ComGroupSignal	0..*	COM520: This container contains the configuration parameters

		of group signals. I.e. signals that are included within a signal group. COM521: The shortName is used as the symbolic name of the signal (ComSignalName). This name is also used as the handle name for the signal. This parameter is only stored in the XML file, and must not be used within the implementation.
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### 10.2.13 ComGroupSignal

<b>SWS Item</b>	<b>COM520, COM521 :</b>		
<b>Container Name</b>	ComGroupSignal		
<b>Description</b>	COM520: This container contains the configuration parameters of group signals. I.e. signals that are included within a signal group. COM521: The shortName is used as the symbolic name of the signal (ComSignalName). This name is also used as the handle name for the signal. This parameter is only stored in the XML file, and must not be used within the implementation.		
<b>Configuration Parameters</b>			

<b>SWS Item</b>	<b>COM259 :</b>		
<b>Name</b>	ComBitPosition		
<b>Description</b>	Starting position within the I-PDU. This parameter refers to the position in the I-PDU and not in the shadow buffer.		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	0 .. 2031		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM158 :</b>		
<b>Name</b>	ComBitSize		
<b>Description</b>	Size in bits.		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	0 .. 64		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM165 :</b>		
<b>Name</b>	ComHandleId		
<b>Description</b>	The numerical value used as the ID. For signals it is required by the API calls Com_UpdateShadowSignal, Com_ReceiveShadowSignal and Com_InvalidShadowSignal. For signals groups it is required by the Com_SendSignalGroup and Com_ReceiveSignalGroup calls.		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef (Symbolic Name generated for this parameter)		

<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: external, depends on configuration process		

<b>SWS Item</b>	<b>COM391, COM501 :</b>		
<b>Name</b>	ComSignalDataInvalidValue		
<b>Description</b>	COM391: On receiver side: When this value is received it is recognized as the invalid value and the appropriate invalid action (as specified by ComDataInvalidAction) is performed. COM501: On sender side: This configures the data invalid value that is used by a call to Com_InvalidateSignal.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM157 :</b>		
<b>Name</b>	ComSignalEndianness		
<b>Description</b>	Defines the endianness of the signal's network representation.		
<b>Multiplicity</b>	1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	BIG_ENDIAN		
	LITTLE_ENDIAN		
	OPAQUE		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM170, COM483 :</b>		
<b>Name</b>	ComSignalInitValue		
<b>Description</b>	COM170: Initial value for this signal. The default value is 0. The lower n-bits of the configured Integer shall be used as init-value for an n-bit sized signal type. COM483: If the signal is of type UINT[n], the Integer's least significant byte shall be assigned to the byte array's last byte. The second-least significant byte shall be assigned to the byte array's last but one byte, and so on.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	0		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local dependency: IpduM		

<b>SWS Item</b>	<b>COM437 :</b>		
<b>Name</b>	ComSignalLength		

<b>Description</b>	The ComSignalLength specifies the n (in Bytes: 1..8) of the type UINT8[n]. For other types it will be ignored.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	1 .. 8		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM127 :</b>		
<b>Name</b>	ComSignalType		
<b>Description</b>	The AUTOSAR type of the signal. Whether or not the signal is signed or unsigned can be found by examining the value of this attribute. This type could also be used to reserved appropriate storage in AUTOSAR COM.		
<b>Multiplicity</b>	1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	BOOLEAN		
	SINT16		
	SINT32		
	SINT8		
	UINT16		
	UINT32		
	UINT8		
	UINT8_N		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM560 :</b>		
<b>Name</b>	ComTransferProperty		
<b>Description</b>	Optionally defines whether this group signal shall contribute to the TRIGGERED_ON_CHANGE transfer property of the signal group. If at least one group signal of a signal group has the "ComTransferProperty" configured all other group signals of that signal group shall have the attribute configured as well. PENDING: a change of the value of this group signal shall not be considered in the evaluation of the signal groups ComTransferProperty. TRIGGERED_ON_CHANGE: a change of the value of this group signal shall be considered in the in the evaluation of the signal groups ComTransferProperty.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	PENDING		
	TRIGGERED_ON_CHANGE		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	:		
<b>Name</b>	SystemTemplateSystemSignalRef		
<b>Description</b>	Reference to the ISignalToIPduMapping that contains a reference to the ISignal (System Template) which this ComSignal (or ComGroupSignal) represents.		



<b>Multiplicity</b>	1		
<b>Type</b>	Foreign reference to [ ISignalToIPduMapping ]		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	--	
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: system configuration		

<b>Included Containers</b>		
<b>Container Name</b>	<b>Multiplicity</b>	<b>Scope / Dependency</b>
ComFilter	0..1	This container contains the configuration parameters of COM Filters. Note: On sender side the container is used to specify the transmission mode conditions.

### 10.2.14 ComTxMode

<b>SWS Item</b>	<b>COM351 :</b>
<b>Container Name</b>	ComTxMode
<b>Description</b>	This container contains the configuration parameters of COM transmission modes.
<b>Configuration Parameters</b>	

<b>SWS Item</b>	<b>COM137 :</b>		
<b>Name</b>	ComTxModeMode		
<b>Description</b>	The available transmission modes described in [18] shall be extended by the additional mode None. The transmission mode None shall not have any further sub-attributes in the ComTxMode object.		
<b>Multiplicity</b>	1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	DIRECT		
	MIXED		
	NONE		Literal for TxMode
	PERIODIC		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM281 :</b>		
<b>Name</b>	ComTxModeNumberOfRepetitions		
<b>Description</b>	Defines the number of repetitions for the Direct/N-Times transmission mode and the event driven part of Mixed transmission mode.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	0 .. 255		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM282 :</b>		
<b>Name</b>	ComTxModeRepetitionPeriodFactor		

<b>Description</b>	Period of the repetition of the n transmission for the Direct/NTimes transmission mode and the event driven part of the Mixed transmission mode. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM180 :</b>		
<b>Name</b>	ComTxModeTimeOffsetFactor		
<b>Description</b>	Time until first transmission of this I-PDU. ComTxModeTimeOffsetFactor defines the time between Com_IpduGroupStart and the first transmission of the cyclic part of this transmission request for this I-PDU. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM178 :</b>		
<b>Name</b>	ComTxModeTimePeriodFactor		
<b>Description</b>	Period of the repetition of cyclic transmissions. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

**No Included Containers**

### 10.2.15 ComTxModeTrue

<b>SWS Item</b>	<b>COM455 :</b>		
<b>Container Name</b>	ComTxModeTrue		
<b>Description</b>	This container contains the configuration parameters of COM transmission modes in the case the ComFilter evaluates to true.		
<b>Configuration Parameters</b>			

<b>Included Containers</b>		
<b>Container Name</b>	<b>Multiplicity</b>	<b>Scope / Dependency</b>

ComTxMode	1	This container contains the configuration parameters of COM transmission modes.
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### 10.2.16 ComTxModeFalse

<b>SWS Item</b>	<b>COM454 :</b>	
<b>Container Name</b>	ComTxModeFalse	
<b>Description</b>	This container contains the configuration parameters of COM transmission modes in the case the ComFilter evaluates to false.	
<b>Configuration Parameters</b>		

<b>Included Containers</b>		
<b>Container Name</b>	<b>Multiplicity</b>	<b>Scope / Dependency</b>
ComTxMode	1	This container contains the configuration parameters of COM transmission modes.

### 10.2.17 ComGwMapping

<b>SWS Item</b>	<b>COM544 :</b>	
<b>Container Name</b>	ComGwMapping	
<b>Description</b>	Each instance of this container defines one mapping of the integrated Signal Gateway.	
<b>Configuration Parameters</b>		

<b>Included Containers</b>		
<b>Container Name</b>	<b>Multiplicity</b>	<b>Scope / Dependency</b>
ComGwDestination	1..*	Each instance of this choice container allows to define one routing destination either by reference to an already configured COM signal / signal group or by a destination description container.
ComGwSource	1	This choice container allows the definition of the gateway source signal either by reference to an already configured COM signal / signal group or by a source description container.

### 10.2.18 ComGwSource

<b>SWS Item</b>	<b>COM545 :</b>	
<b>Choice container Name</b>	ComGwSource	
<b>Description</b>	This choice container allows the definition of the gateway source signal either by reference to an already configured COM signal / signal group or by a source description container.	

<b>Container Choices</b>		
<b>Container Name</b>	<b>Multiplicity</b>	<b>Scope / Dependency</b>
ComGwSignal	0..1	This container allows specifying a gateway source or destination respectively with a reference to a ComSignal, a ComGroupSignal or a ComSignalGroup.

ComGwSourceDescription	0..1	Description of a gateway source. This container allows defining a gateway source without the configuration of a complete COM signal. This allows adding / changing gateway relations post build without the configuration of new signals.
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### 10.2.19 ComGwSourceDescription

<b>SWS Item</b>	<b>COM548 :</b>		
<b>Container Name</b>	ComGwSourceDescription		
<b>Description</b>	Description of a gateway source. This container allows defining a gateway source without the configuration of a complete COM signal. This allows adding / changing gateway relations post build without the configuration of new signals.		
<b>Configuration Parameters</b>			

<b>SWS Item</b>	<b>COM259 :</b>		
<b>Name</b>	ComBitPosition		
<b>Description</b>	Starting position within the I-PDU. This parameter refers to the position in the I-PDU and not in the shadow buffer.		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	0 .. 2031		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM158 :</b>		
<b>Name</b>	ComBitSize		
<b>Description</b>	Size in bits.		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	0 .. 64		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM157 :</b>		
<b>Name</b>	ComSignalEndianness		
<b>Description</b>	Defines the endianness of the signal's network representation.		
<b>Multiplicity</b>	1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	BIG_ENDIAN		
	LITTLE_ENDIAN		
	OPAQUE		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM127 :</b>		
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<b>Name</b>	ComSignalType		
<b>Description</b>	The AUTOSAR type of the signal. Whether or not the signal is signed or unsigned can be found by examining the value of this attribute. This type could also be used to reserved appropriate storage in AUTOSAR COM.		
<b>Multiplicity</b>	1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	BOOLEAN		
	SINT16		
	SINT32		
	SINT8		
	UINT16		
	UINT32		
	UINT8		
	UINT8_N		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM257 :</b>		
<b>Name</b>	ComUpdateBitPosition		
<b>Description</b>	Bit position of update-bit inside I-PDU. If this attribute is omitted then there is no update-bit. This setting must be consistently on sender and on receiver side.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	0 .. 2031		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM550 :</b>		
<b>Name</b>	ComGwIPduRef		
<b>Description</b>	Symbolic reference to an I-PDU of a Signal Gateway source or destination description.		
<b>Multiplicity</b>	1		
<b>Type</b>	Reference to [ ComIPdu ]		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>			

**No Included Containers**

### 10.2.20 ComGwDestination

<b>SWS Item</b>	<b>COM546 :</b>		
<b>Choice container Name</b>	ComGwDestination		
<b>Description</b>	Each instance of this choice container allows to define one routing destination either by reference to an already configured COM signal / signal group or by a destination description container.		

<b>Container Choices</b>		
<b>Container Name</b>	<b>Multiplicity</b>	<b>Scope / Dependency</b>
ComGwDestinationDescription	0..1	Description of a gateway destination. This container allows defining a gateway destination without the configuration of a complete COM signal. This allows adding / changing gateway relations post build without the configuration of new signals.
ComGwSignal	0..1	This container allows specifying a gateway source or destination respectively with a reference to a ComSignal, a ComGroupSignal or a ComSignalGroup.

### 10.2.21 ComGwDestinationDescription

<b>SWS Item</b>		<b>COM549 :</b>
<b>Container Name</b>	ComGwDestinationDescription	
<b>Description</b>	Description of a gateway destination. This container allows defining a gateway destination without the configuration of a complete COM signal. This allows adding / changing gateway relations post build without the configuration of new signals.	
<b>Configuration Parameters</b>		

<b>SWS Item</b>		<b>COM259 :</b>	
<b>Name</b>	ComBitPosition		
<b>Description</b>	Starting position within the I-PDU. This parameter refers to the position in the I-PDU and not in the shadow buffer.		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	0 .. 2031		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>		<b>COM391, COM501 :</b>	
<b>Name</b>	ComSignalDataInvalidValue		
<b>Description</b>	COM391: On receiver side: When this value is received it is recognized as the invalid value and the appropriate invalid action (as specified by ComDataInvalidAction) is performed. COM501: On sender side: This configures the data invalid value that is used by a call to Com_InvalidateSignal.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>		<b>COM157 :</b>
<b>Name</b>	ComSignalEndianness	
<b>Description</b>	Defines the endianness of the signal's network representation.	
<b>Multiplicity</b>	1	

<b>Type</b>	EnumerationParamDef		
<b>Range</b>	BIG_ENDIAN		
	LITTLE_ENDIAN		
	OPAQUE		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM170, COM483 :</b>		
<b>Name</b>	ComSignalInitValue		
<b>Description</b>	COM170: Initial value for this signal. The default value is 0. The lower n-bits of the configured Integer shall be used as init-value for an n-bit sized signal type. COM483: If the signal is of type UINT[n], the Integer's least significant byte shall be assigned to the byte array's last byte. The second-least significant byte shall be assigned to the byte array's last but one byte, and so on.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	..		
<b>Default value</b>	0		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local dependency: IpduM		

<b>SWS Item</b>	<b>COM232 :</b>		
<b>Name</b>	ComTransferProperty		
<b>Description</b>	Defines if a write access to this signal can trigger the transmission of the corresponding I-PDU. If the I-PDU is triggered, depends also on the transmission mode of the corresponding I-PDU. TRIGGERED: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU. PENDING: A write access to this signal never triggers the transmission of the corresponding I-PDU. TRIGGERED_ON_CHANGE: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU, but only in case the written value is different to the locally stored (last written or init) value. TRIGGERED_WITHOUT_REPETITION: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU just once without a repetition. TRIGGERED_ON_CHANGE_WITHOUT_REPETITION: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU just once without a repetition, but only in case the written value is different to the locally stored (last written or init) value.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	PENDING		
	TRIGGERED		
	TRIGGERED_ON_CHANGE		
	TRIGGERED_ON_CHANGE_WITHOUT_REPETITION		
	TRIGGERED_WITHOUT_REPETITION		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependen-</b>	scope: Local		

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<b>SWS Item</b>	<b>COM257 :</b>		
<b>Name</b>	ComUpdateBitPosition		
<b>Description</b>	Bit position of update-bit inside I-PDU. If this attribute is omitted then there is no update-bit. This setting must be consistently on sender and on receiver side.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Range</b>	0 .. 2031		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Local		

<b>SWS Item</b>	<b>COM550 :</b>		
<b>Name</b>	ComGwIPduRef		
<b>Description</b>	Symbolic reference to an I-PDU of a Signal Gateway source or destination description.		
<b>Multiplicity</b>	1		
<b>Type</b>	Reference to [ ComIPdu ]		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>			

**No Included Containers**

### 10.2.22 ComGwSignal

<b>SWS Item</b>	<b>COM551 :</b>		
<b>Container Name</b>	ComGwSignal		
<b>Description</b>	This container allows specifying a gateway source or destination respectively with a reference to a ComSignal, a ComGroupSignal or a ComSignalGroup.		
<b>Configuration Parameters</b>			

<b>SWS Item</b>	<b>COM547 :</b>		
<b>Name</b>	ComGwSignalRef		
<b>Description</b>	Reference to an object of a gateway relation. Either to a ComSignal, ComGroupSignal or to a SignalGroup.		
<b>Multiplicity</b>	1		
<b>Type</b>	Choice reference to [ ComGroupSignal , ComSignal , ComSignalGroup ]		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>			

**No Included Containers**



## 10.3 Published Information

Published information contains data defined by the implementer of the SW module that does not change when the module is adapted (i.e. configured) to the actual HW/SW environment. It thus contains version and manufacturer information.

**COM026:** The following table specifies parameters that shall be published in the module's header file and also in the module's description file.

The standard common published information like

- vendorId (<Module>\_VENDOR\_ID),
- moduleId (<Module>\_MODULE\_ID),
- arMajorVersion (<Module>\_AR\_MAJOR\_VERSION),
- arMinorVersion (<Module>\_AR\_MINOR\_VERSION),
- arPatchVersion (<Module>\_AR\_PATCH\_VERSION),
- swMajorVersion (<Module>\_SW\_MAJOR\_VERSION),
- swMinorVersion (<Module>\_SW\_MINOR\_VERSION),
- swPatchVersion (<Module>\_SW\_PATCH\_VERSION),
- vendorApiInfix (<Module>\_VENDOR\_API\_INFIX)

is provided in the BSW Module Description Template (see 0 Figure 4.1 and Figure 7.1).

Additional published parameters are listed below if applicable for this module.

## 10.4 Defines

Besides the configuration the following defines shall be implemented:

**COM028:** If COM\_DEV\_ERROR\_DETECT is set to ON, the detection and reporting of development errors is enabled for the AUTOSAR COM module. For configuration of this parameter see COM141.

**Note:** This parameter shall be an output of the configuration tool. (Input for the source code)

## 10.5 Configuration rules

### 10.5.1 General rules

**COM401:** It is illegal for any two of the following parameters to have the same value:

- shortName of a ComSignal
- shortName of a ComSignalGroup
- shortName of a ComGroupSignal
- shortName of a ComIPdu
- shortName of a ComIPduGroup

**COM732:** It is illegal for any of the following five parameters:

- ComNotification
- ComErrorNotification
- ComTimeoutNotification
- ComInvalidNotification
- ComIPduCallout

to have the same value as any of the following four parameters

- Com\_<shortName of a ComSignal>
- Com\_<shortName of a ComSignalGroup>
- Com\_<shortName of a ComGroupSignal>
- Com\_<shortName of a ComIPdu>
- Com\_<shortName of a ComIPduGroup>

**COM402** It is illegal for any of the following parameters not to be formulated according to C's identifier rules:

- shortName of a ComSignal
- shortName of a ComSignalGroup
- shortName of a ComGroupSignal
- shortName of a ComIPdu
- shortName of a ComIPduGroup
- ComNotification
- ComErrorNotification
- ComTimeoutNotification
- ComInvalidNotification
- ComIPduCallout

### 10.5.2 Signal configuration

**COM489:** It shall be ensured, that the data invalid value configured for the sender side is the same as configured for all receiver sides (see also COM097).

**Note:** The data invalid value shall not be within the valid range of the signal. This cannot be enforced by COM since knowledge about the application is needed.

More than one signal can be packed into an I-PDU as long as the following packing rules are fulfilled:

**COM101:** No (group) signal shall span more than one I-PDU.

**COM102:** (Group) signals are not allowed to overlap each other.

**Note:** It is explicitly allowed that a (group) signal may have the size 0, see COM158.

**COM389:** The ComBitSize of a (group) signal shall not extend the size of its configured ComSignalType.

For example, the ComBitSize of a signal with ComSignalType UINT8 shall not exceed 8 bits.

**COM443:** A (group) signal of type uint8[n] shall always be mapped to an n-bytes sized (group) signal.

**COM553:** A (group) signal of type uint8[n] shall be configured to have OPAQUE endianness.

**COM105:** ComSignal/ ComGroupSignal of ComSignalType UINT8\_N shall be byte aligned (ComBitPosition is a multiple of 8).

**COM474:** The initial value of a (group) signal shall always be within the possible range of the (group) signal (including the data invalid value).

**Example:** If a signal is of data-type uint8 has a bit-size of 6-bit the possible range is 0..63. In this case it shall not be allowed to configure an init value of 64 or greater.

### 10.5.3 Signal group configuration

**COM365:** It shall not be allowed to configure signal groups for routing with data type differences between receive and transmit signal group. A sub-setting of signal groups (as defined in COM735) shall be supported.

**COM464:** All non-opaque group signals within a signal group shall have the same endianness.

How the signals of signal groups are placed within an I-PDU is not restricted. It is allowed to define interlaced signal groups, or to place other signals within the wholes of a signal group.

### 10.5.4 Transmission Mode configuration

**COM319:** It shall not be allowed to configure filter or TMS-conditions that uses floats. Floats are not allowed to be used in filter conditions. See [17] and COM132. Therefore floats are not allowed for conditions of TMS.

**COM465:** Every COM\_TRANSMISSION\_MODE\_TRUE or COM\_TRANSMISSION\_MODE\_FALSE that is a potential result of the configured/ calculated TMS must be configured. Within the COM\_IPDU at least one of the containers COM\_TRANSMISSION\_MODE\_FALSE or COM\_TRANSMISSION\_MODE\_TRUE has to be included.

### 10.5.5 Signal Gateway configuration

**COM384:** The bit size of a received and to be routed signal shall not differ.

In case of a ComSignal to be routed by the Signal Gateway has been configured for deadline monitoring at the receiving node, depending on the use case, it is possible to configure update-bits, via ComUpdateBitPosition, for the transmit signal thus that it

can be detected at the receiving node if the signal has really been update by the sender and is not just repeated not updated by the Signal Gateway.

### 10.5.6 Filter Configuration

**COM535:** For the filter *ONE EVERY N*, the ComFilterOffset shall be configured to a value lesser than ComFilterPeriodFactor.

**COM827:** The length of a ComFilter's ComFilterMask in bits shall not exceed the ComBitSize of the associated ComSignal.

### 10.5.7 Post Build Configuration

**COM373:** The post-build time configuration part (post-compile and post-link time) can only be updated when it is not in use.

**COM487:** The whole post-build time configurable configuration shall be identifiable by a unique identifier.

## 11 Appendix A

In the following use cases with different transmission modes and the necessary configuration for these are shown. For the legend of the pictures see Chapter 7.4.3.8.

Use Case A1 shows an I-PDU which is sent out cyclically with a cycle time  $t_c$ . This I-PDU consists of signals which all have the Pending transfer property. It is configured that the send out takes place when the TMS evaluates to true.

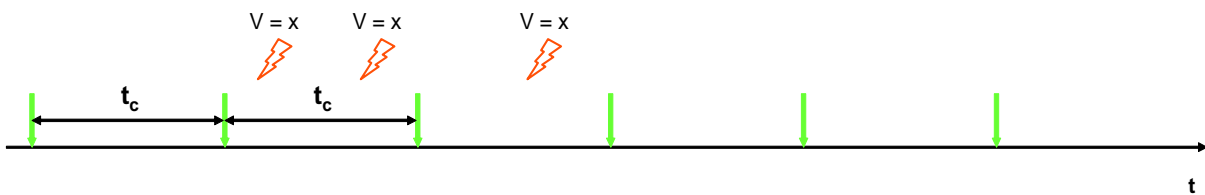


Figure 20: Use Case A1, TM periodic (without TMS switch (see Chapter 7.4.3.5))

<b>Relevant configuration items for the I-PDU transmission</b>		
Object SIGNAL		
TRANSFERPROPERTY		Pending or Triggered (Triggered has no influence)
Object COM_FILTER		
FILTERALGORITHM		ALWAYS
Object I-PDU		
PROPERTY		Sent
Object TRANSMISSION MODE on filter true		
TIMEPERIOD		$t_c$
MODE		periodic
NUMBER_OF_REPETITIONS		N/a
REPETITION_PERIOD		N/a
Object TRANSMISSION MODE on filter FALSE		
		N/a

Because of the configuration of the parameter FILTERALGORITHM (ALWAYS) of the COM\_FILTER, there is no need to configure a transmission mode for the case that the TMS evaluates to false.

It does not make any difference in the behavior whether the FILTERALGORITHM parameter of the COM\_FILTER is defined in the configuration for all the signals within the I-PDU with ALWAYS or if the COM\_FILTER is not defined (shall not contribute to the evaluation of the TMS), see COM255.

Use Case A2 shows an I-PDU which is sent out three times whenever a value is given by the upper (Com\_SendSignal or Com\_SendSignalGroup). The time between two send outs is  $t_d$ . This I-PDU consists of signals which all have the Triggered transfer property. It is configured that the send out takes place when the TMS evaluates to true.

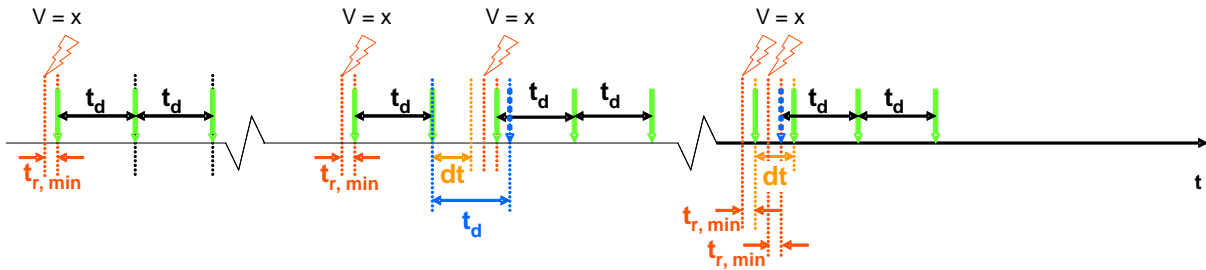


Figure 21: Use Case A2, TM Direct/N-Times, here n = 3 (without TMS switch)

<b>Relevant configuration items for the I-PDU transmission</b>	
Object SIGNAL	
TRANSFERPROPERTY	Triggered
Object COM_FILTER	
FILTERALGORITHM	ALWAYS
Object I-PDU	
PROPERTY	Sent
Object TRANSMISSION MODE on filter true	
TIMEPERIOD	N/a
MODE	Direct/N-Times
NUMBER_OF_REPETITIONS	3
REPETITION_PERIOD	$t_d$
Object TRANSMISSION MODE on filter false	
	N/a

If there is a new send request by the upper layer before the last three sent outs have taken place, the new sent out is started and the rest of the last one is discarded.

Use case A3 shows an I-PDU which is send out cyclically with a cycle time  $t_{c1}$  if value  $v = a$  (TMS evaluates to true) and with a cycle time  $t_{c2}$  if value  $v = b$  (TMS evaluates to false). The I-PDU consists of signals which all have the Pending transfer property.

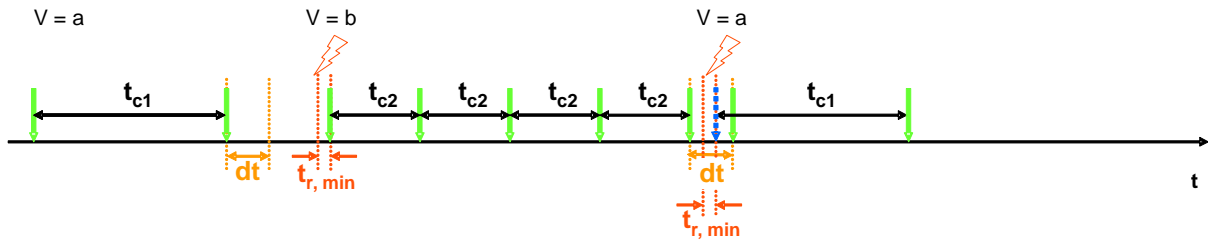


Figure 22: Use case A3, TM periodic + periodic (with TMS switch)

Relevant configuration items for the I-PDU transmission	
Object SIGNAL	
TRANSFERPROPERTY	Pending or Triggered (Triggered has no influence)
Object COM_FILTER	
FILTERALGORITHM	all except ALWAYS and NEVER
Object I-PDU	
PROPERTY	Sent
Object TRANSMISSION MODE on filter true	
TIMEPERIOD	$t_{c1}$
MODE	periodic
NUMBER_OF_REPETITIONS	N/a
REPETITION_PERIOD	N/a
Object TRANSMISSION MODE on filter false	
TIMEPERIOD	$t_{c2}$
MODE	periodic
NUMBER_OF_REPETITIONS	N/a
REPETITION_PERIOD	N/a

Because of the TMS switch caused by the new value  $v = b$ , the new cycle is started immediately and the new value is sent out. But nevertheless the minimum delay time  $dt$  has to be taken into account.

For the parameter FILTERALGORITHM of the configuration object COM\_FILTER every in OSEK COM defined item can be used except ALWAYS and NEVER. These are:

- ALWAYS
- NEVER
- MASKED\_NEW\_EQUALS\_X
- MASKED\_NEW\_DIFFERS\_X
- MASKED\_NEW\_DIFFERS\_MASKED\_OLD
- NEW\_IS\_WITHIN
- NEW\_IS\_OUTSIDE
- ONE\_EVERY\_N

If the FILTERALGORITHM *ONE\_EVERY\_N* is used not the value of the signal itself has an influence to the TMS but the number of send requests by the upper layer.

Use Case A4 shows an I-PDU which is send out cyclically with a cycle time  $t_c$  if value  $v = a$  (TMS evaluates to true) and if value  $v = b$  (TMS evaluates to false) it is sent out three times whenever the value is given by the upper layer. The time between two send outs is  $t_d$ . The I-PDU consists of signals which all have the Triggered transfer property.

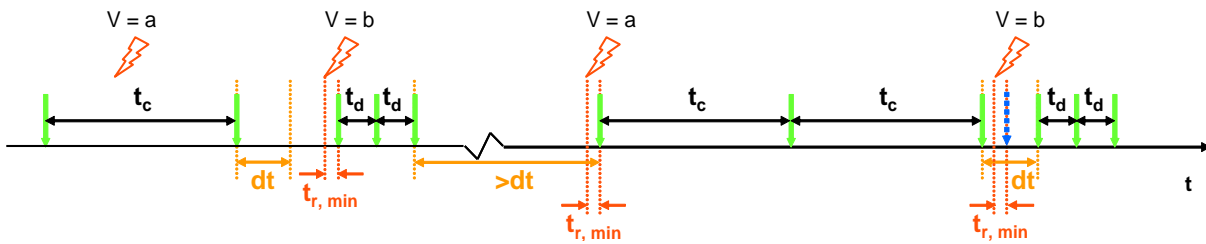


Figure 23: Use Case 4, TM periodic + Direct/N-Times, here  $n = 3$  (with TMS switch)

Relevant configuration items for the I-PDU transmission	
Object SIGNAL	
TRANSFERPROPERTY	Triggered
Object COM_FILTER	
FILTERALGORITHM	all except ALWAYS and NEVER
Object I-PDU	
PROPERTY	Sent
Object TRANSMISSION MODE on filter true	
TIMEPERIOD	$t_c$
MODE	periodic
NUMBER_OF_REPETITIONS	N/a
REPETITION_PERIOD	N/a
Object TRANSMISSION MODE on filter false	
TIMEPERIOD	N/a
MODE	Direct/N-Times
NUMBER_OF_REPETITIONS	3
REPETITION_PERIOD	$t_d$

After the switch from Direct/N-Times to periodic the cycle is started immediately and the new value  $a$  is sent out (with respect of the minimum delay time  $dt$ ).



Use case A5 shows an I-PDU which is send out cyclically with a cycle time  $t_c$  and if the value (the same or a new one) is given by the upper layer it is also sent out directly three times. The time between two of these three send outs is always  $t_d$ . The I-PDU consists of signals which all have the Triggered transfer property.

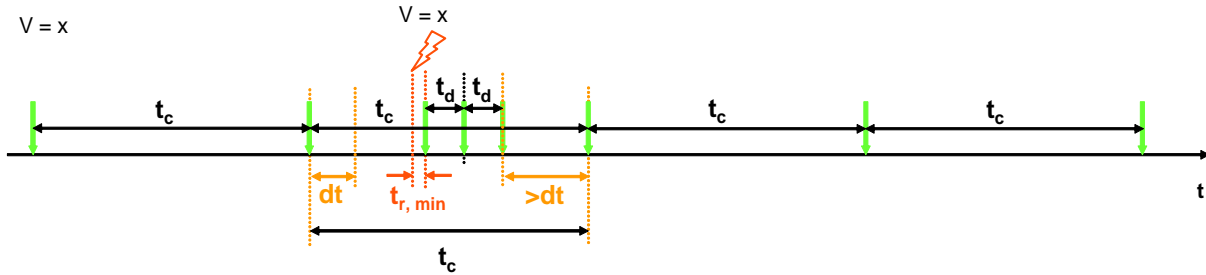


Figure 24: Use Case 5a, TM Mixed, here  $n = 3$  (without TMS switch)

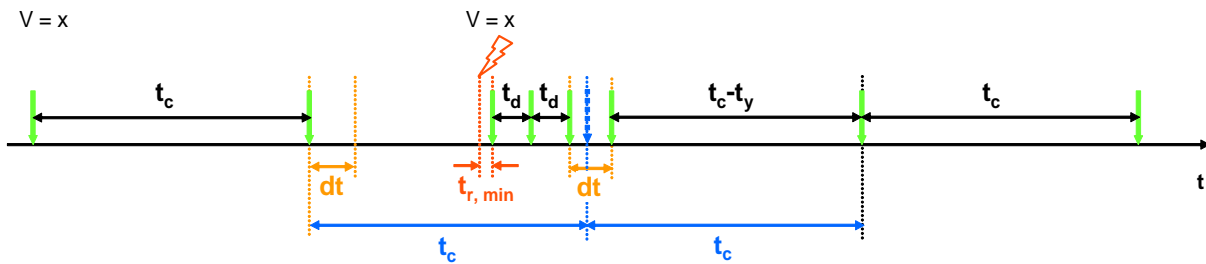


Figure 25: Use Case 5b, TM Mixed, here  $n = 3$  (without TMS switch), no phase shift

Relevant configuration items for the I-PDU transmission		
Object SIGNAL		
TRANSFERPROPERTY		Triggered
Object COM_FILTER		
FILTERALGORITHM		ALWAYS
Object I-PDU		
PROPERTY		Sent
Object TRANSMISSION MODE on filter true		
TIMEPERIOD		$t_c$
MODE		Mixed
NUMBER_OF_REPETITIONS		3
REPETITION_PERIOD		$t_d$
Object TRANSMISSION MODE on filter false		
		N/a

If the next sent out caused by the periodic part of the Mixed transmission mode should take place within the timeout  $dt$  (minimum delay time) after a sent out of the Direct/N-Times part, this sent out is delayed until the minimum delay time is elapsed. But after that the next time period of the periodic part is shortened so that there is only an intermediate phase shift of the periodic part but no continuous one.

Use case A6 shows an I-PDU which is send out cyclically with a cycle time  $t_{c2}$  if value  $v = b$  (TMS evaluates to false). If value  $v = a$  (TMS evaluates to true) it is sent out cyclically with a cycle time  $t_{c1}$  and whenever the value  $v = a$  is given by the upper layer it is also sent out directly three times. The time between two of these three send outs is always  $t_d$ . The I-PDU consists of signals which all have the Triggered transfer property.

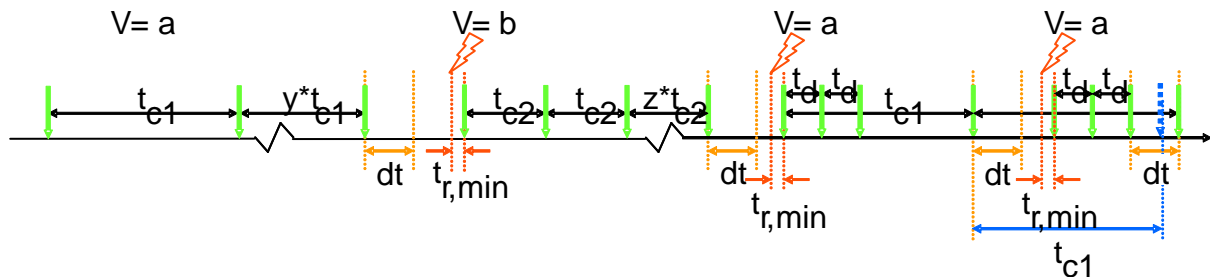


Figure 26: Use Case 6, TM Mixed, here  $n = 3 + \text{periodic}$  (with TMS switch)

Relevant configuration items for the I-PDU transmission	
Object SIGNAL	
TRANSFERPROPERTY	Triggered
Object COM_FILTER	
FILTERALGORITHM	all except ALWAYS and NEVER
Object I-PDU	
PROPERTY	Sent
Object TRANSMISSION MODE on filter true	
TIMEPERIOD	$t_{c1}$
MODE	Mixed
NUMBER_OF_REPETITIONS	3
REPETITION_PERIOD	$t_d$
Object TRANSMISSION MODE on filter false	
TIMEPERIOD	$t_{c2}$
MODE	periodic
NUMBER_OF_REPETITIONS	N/a
REPETITION_PERIOD	N/a

A usage of this in practice is for example the signal of the button that controls the window-lift motor. If the button is not pressed there is a long cycle time  $t_{c1}$  with this information. If it is pressed this information is distributed with a short cycle time  $t_{c2}$ . If the button is released again, this information is immediately distributed three times with  $t_d$  and after that again the long cycle time is used.