

<b>Document Title</b>	Specification of MCU Driver
<b>Document Owner</b>	AUTOSAR
<b>Document Responsibility</b>	AUTOSAR
<b>Document Identification No</b>	031
<b>Document Classification</b>	Standard

<b>Document Version</b>	2.3.0
<b>Document Status</b>	Final
<b>Part of Release</b>	3.1
<b>Revision</b>	0004

<b>Document Change History</b>			
<b>Date</b>	<b>Version</b>	<b>Changed by</b>	<b>Change Description</b>
28.01.2010	2.3.0	AUTOSAR Administration	<ul style="list-style-type: none"> <li>• Allow multiplicity of sub-container Mcu Clock Setting</li> <li>• Legal disclaimer revised</li> </ul>
23.08.2008	2.2.2	AUTOSAR Administration	Legal disclaimer revised
23.01.2008	2.2.1	AUTOSAR Administration	Table formatting corrected
11.12.2007	2.2.0	AUTOSAR Administration	<ul style="list-style-type: none"> <li>• Wakeup concept clarified (resulted in removal of wakeup functionality and sequence diagrams in the MCU SWS). As per the concept agreed within the Startup / Wakeup Taskforce.</li> <li>• Obsolete function Dem_ReportErrorEvent() removed.</li> <li>• Technical Office Improvements: wording improvements.</li> <li>• Re-wording of requirements for clarification</li> <li>• Document meta information extended</li> <li>• Small layout adaptations made</li> </ul>

31.01.2007	2.1.0	AUTOSAR Administration	<ul style="list-style-type: none"> <li>• Update to section 5.2.2: Inclusion of new file structure</li> <li>• Sections 8.3.2, 8.3.3, 8.3.9 : Removal of 'const' from API type definition.</li> <li>• Section 8.2.4, 8.2.5, 10.2.5: Description detail amended</li> <li>• Section 8.2.4: Default value (0x0) for MCU_POWER_ON_RESET removed.</li> <li>• Section 8.3.8 : Description updated to include reference to new pre-processor switch McuPerformResetApi.</li> <li>• Section 10.2.2: Introduction of pre-processor switch McuPerformResetApi</li> <li>• Section 10.2.3: Multiplicity of sub-container Mcu Clock Setting Configuration changed to 1.</li>   <li>• Legal disclaimer revised</li> <li>• Release Notes added</li> <li>• “Advice for users” revised</li> <li>• “Revision Information” added</li> </ul>
26.01.2006	2.0.0	AUTOSAR Administration	Document structure adapted to common Release 2.0 SWS Template. <ul style="list-style-type: none"> <li>• Major changes in chapter 10</li> <li>• Structure of document changed partly</li> <li>• Other changes see chapter 11</li> </ul>
23.06.2005	1.0.0	AUTOSAR Administration	Initial Release

**Disclaimer**

This specification and the material contained in it, as released by AUTOSAR, is for the purpose of information only. AUTOSAR and the companies that have contributed to it shall not be liable for any use of the specification.

The material contained in this specification is protected by copyright and other types of Intellectual Property Rights. The commercial exploitation of the material contained in this specification requires a license to such Intellectual Property Rights.

This specification may be utilized or reproduced without any modification, in any form or by any means, for informational purposes only.

For any other purpose, no part of the specification may be utilized or reproduced, in any form or by any means, without permission in writing from the publisher.

The AUTOSAR specifications have been developed for automotive applications only. They have neither been developed, nor tested for non-automotive applications.

The word AUTOSAR and the AUTOSAR logo are registered trademarks.

**Advice for users**

AUTOSAR specifications may contain exemplary items (exemplary reference models, "use cases", and/or references to exemplary technical solutions, devices, processes or software).

Any such exemplary items are contained in the specifications for illustration purposes only, and they themselves are not part of the AUTOSAR Standard. Neither their presence in such specifications, nor any later documentation of AUTOSAR conformance of products actually implementing such exemplary items, imply that intellectual property rights covering such exemplary items are licensed under the same rules as applicable to the AUTOSAR Standard.

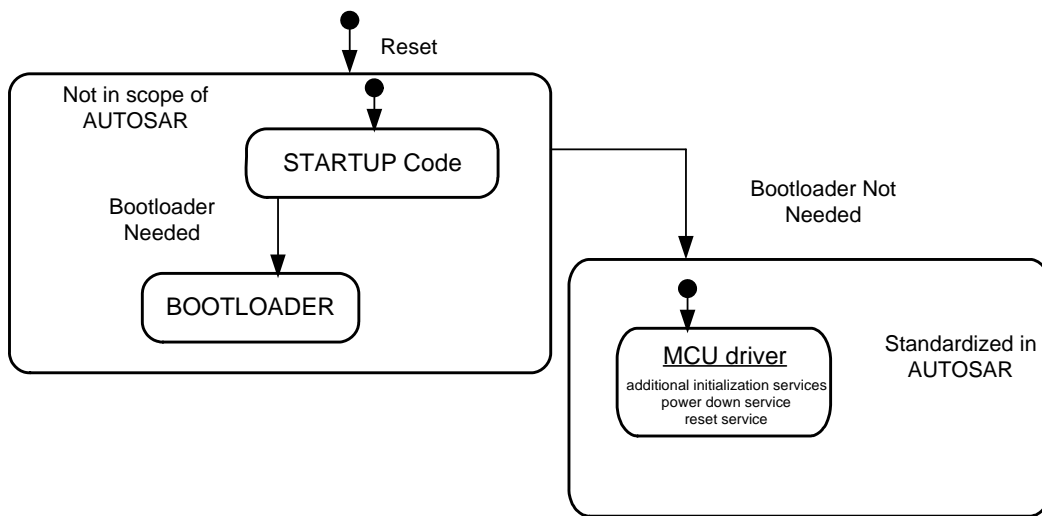
## Table of Contents

1	Introduction and functional overview .....	6
2	Acronyms and abbreviations .....	7
3	Related documentation.....	8
3.1	Input documents.....	8
4	Constraints and assumptions .....	9
4.1	Limitations .....	9
4.2	Applicability to car domains.....	9
5	Dependencies to other modules.....	10
5.1	Start-up code.....	10
5.2	File structure .....	11
5.2.1	Code file structure .....	11
5.2.2	Header file structure.....	11
6	Requirements traceability .....	14
7	Functional specification .....	21
7.1	General Behavior .....	21
7.1.1	Background and Rationale.....	21
7.1.2	Requirements.....	21
7.1.3	Version Check.....	22
7.2	Error classification.....	22
7.2.1	Background and Rationale.....	22
7.2.2	Requirements.....	22
7.3	Error detection.....	23
7.4	Error notification .....	23
8	API specification.....	25
8.1	Imported types.....	25
8.2	Type definitions .....	25
8.2.1	Mcu_ConfigType .....	25
8.2.2	Mcu_PllStatusType .....	26
8.2.3	Mcu_ClockType .....	26
8.2.4	Mcu_ResetType .....	26
8.2.5	Mcu_RawResetType.....	27
8.2.6	Mcu_ModeType .....	27
8.2.7	Mcu_RamSectionType.....	27
8.3	Function definitions .....	28
8.3.1	Mcu_Init .....	28
8.3.2	Mcu_InitRamSection .....	29
8.3.3	Mcu_InitClock.....	29
8.3.4	Mcu_DistributePllClock .....	30
8.3.5	Mcu_GetPllStatus .....	30
8.3.6	Mcu_GetResetReason.....	31
8.3.7	Mcu_GetResetRawValue.....	32
8.3.8	Mcu_PerformReset .....	32

8.3.9	Mcu_SetMode .....	33
8.3.10	Mcu_GetVersionInfo .....	33
8.4	Call-back Notifications.....	35
8.5	Scheduled Functions.....	35
8.6	Expected Interfaces.....	35
8.6.1	Mandatory Interfaces .....	35
8.6.2	Optional Interfaces .....	35
8.7	API parameter checking .....	35
9	Sequence diagrams .....	37
9.1	Example Sequence for MCU initialization services .....	37
9.2	Mcu_GetResetReason .....	38
9.3	Mcu_GetResetRawValue .....	38
9.4	Mcu_PerformReset .....	39
10	Configuration specification .....	40
10.1	How to read this chapter .....	40
10.1.1	Configuration and configuration parameters .....	40
10.1.2	Containers.....	40
10.2	Containers and configuration parameters .....	41
10.2.1	Variants.....	41
10.2.2	Mcu .....	41
10.2.3	McuGeneralConfiguration .....	41
10.2.4	McuModuleConfiguration .....	42
10.2.5	McuClockSettingConfig.....	43
10.2.6	McuModeSettingConf.....	44
10.2.7	McuRamSectorSettingConf.....	44
10.2.8	McuClockReferencePoint.....	45
10.3	Published Information.....	46
11	Changes to Release 1 .....	47
11.1	Deleted SWS Items .....	47
11.2	Replaced SWS Items .....	47
11.3	Changed SWS Items.....	47
11.4	Added SWS Items .....	47
12	Changes to Release 2.1 .....	48
12.1	Deleted SWS Items .....	48
12.2	Replaced SWS Items .....	48
12.3	Changed SWS Items.....	48
12.4	Added SWS Items .....	48
13	Changes during SWS Improvements by Technical Office .....	49
13.1	Deleted SWS Items .....	49
13.2	Replaced SWS Items .....	49
13.3	Changed SWS Items.....	49
13.4	Added SWS Items .....	49

# 1 Introduction and functional overview

This specification describes the functionality and API for a MCU [Microcontroller Unit] driver. The MCU driver provides services for basic microcontroller initialization, power down functionality, reset and microcontroller specific functions required from other MCAL software modules. The initialization services allow a flexible and application related MCU initialization in addition to the start-up code (see figure below). The start-up code is very MCU specific. The provided start-up code description in this document is for guidance and implies functionality which **has** to be taken into account before standardized MCU initialization is able to start.



**Figure 1: Scope of the MCU Driver Specification**

The MCU driver accesses the microcontroller hardware directly and is located in the Microcontroller Abstraction Layer (MCAL).

**MCU driver Features:**

- Initialization of MCU clock, PLL, clock prescalers and MCU clock distribution
- Initialization of RAM sections
- Activation of µC reduced power modes
- Activation of a µC reset

Provides a service to get the reset reason from hardware

## 2 Acronyms and abbreviations

<b>Abbreviation / Acronym:</b>	<b>Description:</b>
uC	Microcontroller
MCU	Micro Controller Unit
SFR	Special Function Register (MCU register)
DEM	Diagnostic Event Manager
DET	Development Error Tracer

**Table 1: Acronyms and Abbreviations**

## 3 Related documentation

### 3.1 Input documents

- [1] List of Basic Software Modules,  
AUTOSAR\_BasicSoftwareModules.pdf
- [2] Layered Software Architecture,  
AUTOSAR\_LayeredSoftwareArchitecture.pdf
- [3] General Requirements on Basic Software Modules,  
AUTOSAR\_SRS\_General.pdf
- [4] Specification of Development Error Tracer,  
AUTOSAR\_SWS\_Development\_Error\_Tracer.pdf
- [5] Specification of ECU Configuration,  
AUTOSAR\_ECU\_Configuration.pdf
- [6] Specification of Diagnostic Event Manager,  
AUTOSAR\_SWS\_DEM.pdf
- [7] Specification of ECU State Manager,  
AUTOSAR\_SWS\_ECUStateManager.pdf
- [8] General Requirements on SPAL,  
AUTOSAR\_SRS\_General.pdf
- [9] Requirements on MCU driver,  
AUTOSAR\_SRS\_MCU\_Driver.pdf
- [10] Specification of Standard Types,  
AUTOSAR\_SWS\_StandardTypes.pdf
- [11] AUTOSAR Basic Software Module Description Template,  
AUTOSAR\_BSW\_Module\_Description.pdf



## **4 Constraints and assumptions**

### **4.1 Limitations**

In general the activation and configuration of MCU reduced power mode is not mandatory within AUTOSAR standardization.

Enabling/disabling of the ECU or uC power supply is not the task of the MCU driver. This is to be handled by the upper layer.

### **4.2 Applicability to car domains**

No restrictions

## 5 Dependencies to other modules

### 5.1 Start-up code

Before the MCU driver can be initialized, a basic initialization of the MCU has to be executed. This MCU specific initialization is typically executed in a start-up code.

The start-up code of the MCU shall be executed after power up and any kind of microcontroller reset. It shall perform very basic and microcontroller specific start-up initialization and shall be kept short because the MCU clock and PLL are not yet initialized. The start-up code shall cover MCU specific initialization which is not part of other MCU services or other MCAL drivers. The following description summarizes the basic functionality to be included in the start-up code. It is listed for guidance because some functionality might not be supported in all MCU's.

The start-up code shall initialize the base addresses for interrupt and trap vector tables. These base addresses are provided as configuration parameters or linker/locator setting.

The start-up code shall initialize the interrupt stack pointer if an interrupt stack is supported by the MCU. The interrupt stack pointer base address and the stack size are provided as configuration parameter or linker/locator setting

The start-up code shall initialize the user stack pointer. The user stack pointer base address and the stack size are provided as configuration parameter or linker/locator setting.

If the MCU supports context save operation, the start-up code shall initialize the memory which is used for context save operation. The maximum amount of consecutive context save operations is provided as configuration parameter or linker/locator setting.

The start-up code shall ensure that the MCU internal watchdog shall not be serviced until the watchdog is initialized from the MCAL watchdog driver. This can be done for example by increasing the watchdog service time.

If the MCU supports cache memory for data and/or code, it shall be initialized and enabled in the start-up code.

The start-up code shall initialize MCU specific features with respect to internal memory as, for example, memory protection.

If external memory is used, the memory shall be initialized in the start-up code. The start-up code shall be prepared to support different memory configurations depending on code location. Different configuration options shall be taken into account for code execution from external/internal memory.

The settings of the different memories shall be provided to the start-up code as configuration parameters.

In the start-up code a default initialization of the MCU clock system shall be performed including global clock prescalers.

The start-up code shall enable protection mechanisms for special function registers (SFR's) if supported by the MCU.

The start-up code shall initialize all necessary write once registers or registers common to several drivers where one write, rather than repeated writes, to the register is required or highly desirable.

The start-up code shall initialize a minimum amount of RAM in order to allow proper execution of the MCU driver services and the caller of these services.

Note: The start-up code is ECU and MCU dependant. Details of the specification shall be described in the design specification of the MCAL.

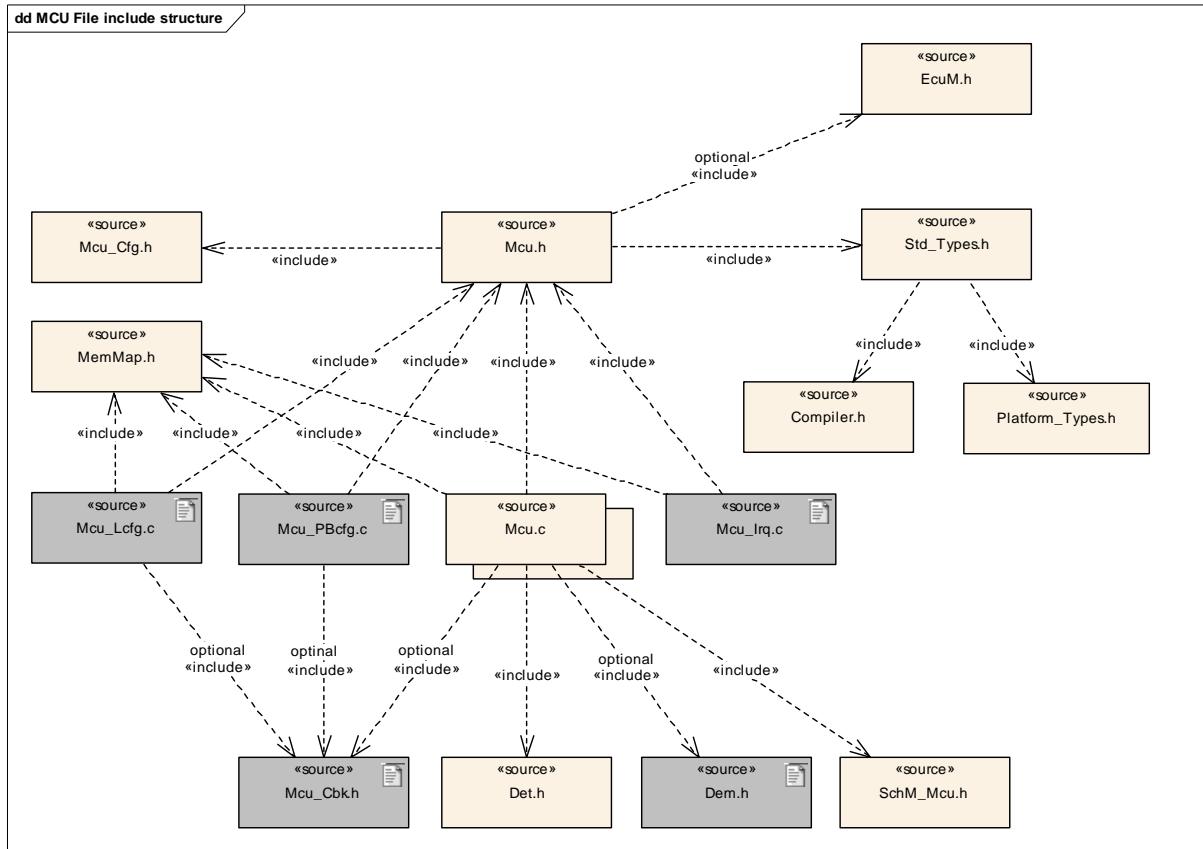
## **5.2 File structure**

### **5.2.1 Code file structure**

**MCU105:** The code file structure shall not be defined within this specification.

### **5.2.2 Header file structure**

**MCU108:** The include file structure shall be as follows:



**Figure 2: Header File Structure**

- `Mcu.c` shall include `Mcu.h`
- `Mcu.h` shall include `Mcu_Cfg.h` for the API pre-compiler switches.

`Mcu.c` has access to the `Mcu_Cfg.h` via the implicitly included `Mcu.h` file.

`Mcu_Irq.c` shall include `Mcu.h` for the function which shall be called in the interrupt function.

The Type definitions for `Mcu_Lcfg.c` and `Mcu_PBcfg.c` are located in the file `Mcu_Cfg.h`. or `Mcu.h`.

Rather the implicit include of `Mcu_Cfg.h` via `Mcu.h` in the files `Mcu_Lcfg.c` and `Mcu_PBcfg.c` is necessary to solve the following construct:

```

Mcu.h
-----
#ifdef xxx_VERSION_INFO_API
xxx_GetVersionInfo(...)
#endif

Mcu_Cfg.h
-----
#include "Mcu.h"
#define xxx_VERSION_INFO_API
    
```

`Mcu_Lcfcg.c` shall include `Mcu_Cbk.h` for a link time configuration if the call back function is linked to the module via the ROM structure.

`Mcu_PBcfg.c` shall include `Mcu_Cbk.h` for post build time configuration if the call back function is linked to the module via the ROM structure.

`Mcu.c` shall include `Mcu_Cbk.h` for pre-compile time configuration.

**MCU109:** The MCU module shall include the `Dem.h` file. By this inclusion, the APIs to report errors as well as the required Event Id symbols are included. This specification defines the name of the Event Id symbols which are provided by XML to the DEM configuration tool. The DEM configuration tool assigns ECU dependent values to the Event Id symbols and publishes the symbols in `Dem_IntErrId.h`.

## 6 Requirements traceability

Document: AUTOSAR requirements on Basic Software, general

<b>Requirement</b>	<b>Satisfied by</b>
[BSW003] Version identification	<a href="#">MCU121</a> , <a href="#">MCU037</a>
[BSW004] Version check	<a href="#">MCU110</a>
[BSW005] No hard coded horizontal interfaces within MCAL	Not applicable (Because the architectural AUTOSAR concept is the basis for this concept).
[BSW006] Platform independency	Not applicable (Because the MCU module is not above the MCAL).
[BSW007] HIS MISRA C	Not applicable (Because this is a requirement for implementation).
[BSW009] Module User Documentation	See <a href="#">Section 3.1</a>
[BSW010] Memory resource documentation	Not applicable (Because this is a requirement for implementation).
[BSW101] Initialization interface	<a href="#">MCU026</a>
[BSW158] Separation of configuration from implementation	See <a href="#">Section 5.2</a>
[BSW159] Tool-based configuration	See <a href="#">Section 5.2</a>
[BSW160] Human-readable configuration data	Not applicable (Because this requirements only applies to the configuration. Requirement on implementation).
[BSW161] Microcontroller abstraction	Not applicable (Because the architectural AUTOSAR concept is the basis for this concept).
[BSW162] ECU layout abstraction	Not applicable (Because the architectural AUTOSAR concept is the basis for this concept).
[BSW164] Implementation of interrupt service routines	Not applicable (Because the MCU does not provide interrupt functionality).
[BSW167] Static configuration checking	Not Applicable (Because this is a requirement for the configuration tool).
[BSW168] Diagnostic Interface of SW components	Not applicable (Because this is a requirement on SW components).
[BSW170] Data for reconfiguration of AUTOSAR SW-Components	Not applicable (Because this is a requirement on SW components).
[BSW171] Configurability of optional functionality	MCU119, <a href="#">MCU120</a>
[BSW172] Compatibility and documentation of scheduling strategy	Not applicable (Because the MCU does not have any special scheduling requirements).
[BSW00300] Module naming convention	See <a href="#">Section 5.2</a>
[BSW00301] Limit imported information	See <a href="#">Section 5.2</a>

[BSW00302] Limit exported information	See <a href="#">Section 5.2</a>
[BSW00304] AUTOSAR integer data types	See <a href="#">Section 8.2</a>
[BSW00305] Self-defined data types naming convention	See <a href="#">Section 8.2</a>
[BSW00306] Avoid direct use of compiler and platform specific keywords	See <a href="#">Figure 5.2</a>
[BSW00307] Global variables naming convention	Not applicable (Because this is a requirement on implementation).
[BSW00308] Definition of global data	Not applicable (Because this is a requirement for the implementer).
[BSW00309] Global data with read-only constraint	See <a href="#">Section 8.3.1</a>
[BSW00310] API naming convention	See <a href="#">Section 8.3</a>
[BSW00312] Shared code shall be reentrant	See <a href="#">Section 8.3</a>
[BSW00314] Separation of interrupt frames and service routines	See <a href="#">Section 5.2</a>
[BSW00318] Format of module version numbers	<a href="#">MCU121</a> , <a href="#">MCU037</a>
[BSW00321] Enumeration of module version numbers	Not Applicable (Because this is a requirement for the implementer).
[BSW00323] API parameter checking	<a href="#">MCU017</a>
[BSW00325] Runtime of interrupt service routines	Not applicable (Because this is not a requirement of the MCU driver. Requirement for the implementer).
[BSW00326] Transition from ISRs to OS tasks	Not applicable (Because this is a requirement for the implementer).
[BSW00327] Error values naming convention	<a href="#">MCU012</a>
[BSW00328] Avoid duplication of code	Not applicable (Because this is a requirement for the implementer).
[BSW00329] Avoidance of generic interfaces	Not applicable (Because there are no generic interfaces specified within this SWS).
[BSW00330] Usage of macros / inline functions instead of functions	Not applicable (Because this is a requirement for the implementer).
[BSW00331] Separation of error and status values	Not applicable (Because there are no status values specified within this SWS).
[BSW00333] Documentation of callback function context	Not applicable (Because there is no callback functionality in the MCU driver).
[BSW00334] Provision of XML file	Not applicable (Because this requirement is specified by another document).
[BSW00335] Status values naming convention	Not applicable (Because there are no status values specified within the SWS).

[BSW00336] Shutdown interface	Not applicable (Because for the MCU driver there is no need for this requirement).
[BSW00337] Classification of errors	<a href="#">MCU012</a> , <a href="#">MCU015</a>
[BSW00338] Detection and Reporting of development errors	<a href="#">MCU013</a>
[BSW00339] Reporting of production relevant error status	<a href="#">MCU014</a>
[BSW00341] Microcontroller compatibility documentation	Not applicable (Because this is a requirement for the implementer).
[BSW00342] Usage of source code and object code	Not applicable (Because this is a requirement for the implementer).
[BSW00343] Specification and configuration of time	Not applicable (Because time configuration is not a requirement of the MCU driver).
[BSW00344] Reference to Link-time configuration	MCU119
[BSW00345] Pre-compile-time configuration	See <a href="#">Section 5.2.2</a> , MCU119
[BSW00346] Basic set of module files	See <a href="#">Section 5.2.2</a>
[BSW00347] Naming separation of different instances of BSW drivers	Not applicable (Because this is a requirement on implementation).
[BSW00348] Standard type header	See <a href="#">Section 5.2.2</a>
[BSW00350] Development error detection keyword	MCU118
[BSW00353] Platform specific type header	See <a href="#">Section 5.2.2</a>
[BSW00355] Do not redefine AUTOSAR integer data types	Not applicable (Because there is no integer data types redefined in this specification).
[BSW00357] Standard API return type	Not applicable (Because this type is not used within the SWS).
[BSW00358] Return type of init() functions	<a href="#">See Section 8.3.1</a>
[BSW00359] Return type of callback functions	Not applicable (Because the MCU driver does not provide a callback mechanism).
[BSW00360] Parameters of callback functions	Not applicable (Because the MCU driver does not provide a callback mechanism).
[BSW00361] Compiler specific language extension header	See <a href="#">Section 5.2.2</a>
[BSW00369] Do not return development error codes via API	<a href="#">MCU013</a> , <a href="#">MCU015</a>
[BSW00370] Separation of callback interface from API	Not applicable (Because the MCU driver does not provide a callback mechanism).
[BSW00371] Do not pass function pointers via API	Not applicable (Because no function pointers are passed via API in this SWS).
[BSW00373] Main processing function naming convention	Not applicable (Because there is no main processing function is specified).
[BSW00374] Module vendor identification	<a href="#">MCU121</a> , <a href="#">MCU037</a>



[BSW00375] Notification of wake-up reason	Not Applicable (Because the MCU driver does not provide notification of wake-up).
BSW00376] Return type and parameters of main processing functions	Not applicable (Because there is no main processing function specified).
[BSW00377] Module specific API return types	Not applicable (Because this type is not used within the SWS).
[BSW00378] AUTOSAR boolean type	See Section 10.2.2
[BSW00379] Module identification	<a href="#">MCU121</a>
[BSW00380] Separate C-File for configuration parameters	See <a href="#">Section 5.2.2</a>
[BSW00381] Separate configuration header file for pre-compile time parameters	See <a href="#">Section 5.2.2</a>
[BSW00382] Not-used configuration elements need to be listed	Not applicable (Because this is an implementation requirement).
[BSW00383] List dependencies of configuration files	See <a href="#">Section 5.2.2</a>
[BSW00384] List dependencies to other modules	See <a href="#">Section 5.2.2</a>
[BSW00385] List possible error notifications	See <a href="#">Section 7.4</a>
[BSW00386] Configuration for detecting an error	See <a href="#">Section 7.2.2</a>
[BSW00387] Specify the configuration class of callback function	Not applicable (Because the MCU driver does not have any callback capability).
[BSW00388] Introduce containers	See Section 10.2.2
[BSW00389] Containers shall have names	See Section 10.2.2
[BSW00390] Parameter content shall be unique within the module	See <a href="#">Chapter 8.3</a>
[BSW00391] Parameter shall have unique names	See <a href="#">Chapter 8.3</a>
[BSW00392] Parameters shall have a type	See <a href="#">Chapter 8.3</a>
[BSW00393] Parameters shall have a range	See <a href="#">Chapter 8.3</a>
[BSW00394] Specify the scope of the parameters	See <a href="#">Chapter 8.3</a>
[BSW00395] List the required parameters (per parameter)	Not applicable (Because none of the parameters of the MCU driver are dependent on other modules).
[BSW00396] Configuration classes	See Chapter 10.2.2
[BSW00397] Pre-compile-time parameters	See Chapter 10.2.2
[BSW00398] Link-time parameters	See Chapter 10.2.2
[BSW00399] Loadable Post-build time parameters	See Chapter 10.2.2
[BSW00400] Selectable Post-build time parameters	See Chapter 10.2.2
[BSW00401] Documentation of multiple instances of configuration parameters	See Chapter 10.2.2
[BSW00402] Published information	<a href="#">See Chapter 10.3</a>
[BSW00404] Reference to post build time configuration	See Chapter 10.2.2
[BSW00405] Reference to multiple configuration sets	See Chapter 10.2.2
[BSW00406] Check module initialization	<a href="#">MCU026</a>
[BSW00407] Function to read out published parameters	<a href="#">MCU103</a>
[BSW00408] Configuration parameter naming convention	See Chapter 10.2.2
[BSW00409] Header files for production code error IDs	See <a href="#">Section 5.2.2</a>
[BSW00410] Compiler switches shall have defined values	See Chapter 10.2.2
[BSW00411] Get version info keyword	<a href="#">MCU103</a> , <a href="#">MCU104</a>
[BSW00412] Separate H-File for configuration parameters	See <a href="#">Section 5.2.2</a>
[BSW00413] Accessing instances of BSW modules	Not applicable (Because this is a requirement on implementation).
[BSW00414] Parameter of init function	<a href="#">MCU126</a>

[BSW00415] User dependent include files	See <a href="#">Section 5.2.2</a>
[BSW00416] Sequence of Initialization	Not applicable (Because this requirement describes the initialization of the whole SPAL layer).
[BSW00417] Reporting of Error Events by Non-Basic Software	Not applicable (Because this driver is part of the basic software layer, applies only for non-BSW modules).
[BSW00419] Separate C-Files for pre-compile time configuration parameters	See <a href="#">Section 5.2.2</a>
[BSW00420] Production relevant error event rate detection	Not applicable (Because this requirement applies only to DEM).
[BSW00421] Reporting of production relevant error events	<a href="#">MCU014</a>
[BSW00422] Debouncing of production relevant error status	<a href="#">MCU014</a>
[BSW00423] Usage of SW-C template to describe BSW modules with AUTOSAR Interfaces	Not applicable (Because it is a non functional requirement. The MCU driver has no AUTOSAR interface).
[BSW00424] BSW main processing function task allocation	Not applicable (Because the MCU driver does not contain any main processing functions).
[BSW00425] Trigger conditions for schedulable objects	Not applicable (Because the MCU driver does not contain any schedulable objects/services. This is a requirement for the implementer).
[BSW00426] Exclusive areas in BSW modules	Not applicable (Because this requirement applies only for the module descriptions template).
[BSW00427] ISR description for BSW modules	Not applicable (Because this is a requirement for the implementer).
[BSW00428] Execution order dependencies of main processing functions	Not applicable (Because the MCU driver does not contain any main processing functions).
[BSW00429] Restricted BSW OS functionality access	Not applicable (Because the MCU driver is not dependent on the OS driver).
[BSW00431] The BSW Scheduler module implements task bodies	Not applicable (Because this requirement is for an upper layer. There is no scheduling functionality in the MCU driver).
[BSW00432] Modules should have separate main processing functions for read/receive and write/transmit data path	Not applicable (Because the MCU driver does not contain any main processing functions).
[BSW00433] Calling of main processing functions	Not applicable (Because the MCU driver does not contain any main processing functions).
[BSW00434] The Schedule Module shall provide an API for exclusive areas	Not applicable (Because it is a non-functional requirement. There is no scheduling functionality in the MCU driver)
[BSW00435] Header file Structure for the Basic Software Scheduler	See <a href="#">Figure 2</a>
[BSW00436] Module Header File Structure for the Basic Software Memory Mapping	See <a href="#">Figure 2</a>

## Document: AUTOSAR requirements on Basic Software, cluster SPAL

<b>Requirement</b>	<b>Satisfied by</b>
[BSW12263] Object code compatible configuration concept	SeeSection 10.2.2
[BSW12056] Configuration of notification mechanisms	SeeSection 10.2.2
[BSW12267] Configuration of wake-up sources.	Not Applicable <ul style="list-style-type: none"> <li>(Because the MCU driver does not provide configuration information for wake-up sources).</li> </ul>
[BSW12057] Driver module initialization	<a href="#">MCU026</a>
[BSW12125] Initialization of hardware resources	<a href="#">MCU116</a>
[BSW12163] Driver module deinitialization	Not applicable (Because the MCU driver cannot be de-initialized).
BSW12068] MCAL initialization sequence	Not applicable (Because this is a general software integration requirement).
[BSW12069] Wake-up notification of ECU State Manager	Not Applicable (Because the MCU driver does not provide notification of wake-up).
[BSW157] Notification mechanisms of drivers and handlers	<a href="#">MCU008</a> , <a href="#">MCU005</a> , <a href="#">MCU006</a> , <a href="#">MCU012</a>
[BSW12155] Prototypes of callback functions	Not applicable (Because there is no callback functionality in the MCU driver).
[BSW12169] Control of operation mode	Not applicable (Because there are no special operation modes defined for the MCU driver. The specified MCU mode interface (see <a href="#">MCU164</a> , <a href="#">MCU165</a> ) is able to change operation modes of the whole MCU, which is not meant with this requirement).
[BSW12063] Raw value mode	<a href="#">MCU006</a>
[BSW12075] Use of application buffers	Not applicable (Because there is no random streaming capability).
[BSW12129] Resetting of interrupt flags	Not applicable (Because the interrupt functionality not part of the MCU driver)
[BSW12064] Change of operation mode during running operation	Not applicable (Because this is a non-functional requirement concerning system design).
[BSW12067] Setting of wake-up conditions	Not Applicable (Because the MCU driver does not provide notification of wake-up).
[BSW12448] Behaviour after development error detection	<a href="#">MCU013</a>
[BSW12077] Non-blocking implementation	Not Applicable (Because this is a requirement for the implementer).
[BSW12078] Runtime and memory efficiency	Not Applicable (Because this is a requirement for the implementer).
[BSW12092] Access to drivers	Not Applicable (Because this is a requirement concerning system design).
[BSW12265] Configuration data shall be kept constant	Not Applicable (Because this is a requirement for the imple-

	menter).
[BSW12264] Specification of configuration items	See Section 10.2.2
[BSW12350] Configuration of RAM segments	<a href="#">MCU030</a>
[BSW12331] RAM Initialization	<a href="#">MCU011</a>
[BSW12392] Provide lock status of PLL	<a href="#">MCU008</a>
[BSW12336] Activate PLL Clock distribution	<a href="#">MCU140</a> , <a href="#">MCU141</a> , <a href="#">MCU056</a>
[BSW12207] Configuration of clock safety features	<a href="#">MCU031</a> , <a href="#">MCU054</a>
[BSW12208] Initialization of MCU Clock	<a href="#">MCU137</a> , <a href="#">MCU138</a>
[BSW12394] Fault condition handling of clock safety features	<a href="#">MCU012</a> , <a href="#">MCU053</a> ;
[BSW12000] Provide standardized reset reason	<a href="#">MCU005</a> , <a href="#">MCU052</a>
[BSW12215] Provide raw reset status	<a href="#">MCU006</a>
[BSW12277] Reset trigger function	<a href="#">MCU143</a> , <a href="#">MCU144</a> , <a href="#">MCU055</a>
[BSW12268] MCU Power Management Control	<a href="#">MCU164</a> , <a href="#">MCU165</a>
[BSW12421] Low Power Mode Configuration	<a href="#">MCU035</a>
[BSW12461] Responsibility for register initialisation	<a href="#">MCU116</a>
[BSW12462] Provide settings for register initialisation.	See <a href="#">Section 10.3</a>
[BSW12463] Combine and forward settings for register initialisation.	Not applicable (Because this is a requirement for a configuration tool).

## 7 Functional specification

### 7.1 General Behavior

#### 7.1.1 Background and Rationale

The MCU driver provides MCU services for Clock and RAM initialization. In the MCU configuration set, the MCU specific settings for the Clock (i.e. PLL setting) and RAM (i.e. section base address and size) shall be configured.

#### 7.1.2 Requirements

##### 7.1.2.1 Reset

**MCU055:** The MCU module shall provide a service to provide software triggering of a hardware reset. Only an authorized user shall be able to call this reset service function.

**MCU052:** The MCU module shall provide services to get the reset reason of the last reset if the hardware supports such a feature.

Note: In an ECU, there are several sources which can cause a reset. Depending on the reset reason, several application scenarios might be necessary after re-initialization of the MCU.

##### 7.1.2.2 MCU Mode service

**MCU164:** The MCU module shall provide a service to activate MCU reduced power modes. This service shall allow access to power modes implemented in the uC hardware.

**MCU165:** The number of modes and the configuration is MCU dependent and shall be configured in the configuration set of the MCU module.

Note: The activation of MCU reduced power modes might influence the PLL, the internal oscillator, the CPU clock, uC peripheral clock and the power supply for core and peripherals.

In typical operation, MCU reduced power mode will be entered and exited frequently during ECU runtime. In this case, wake-up is performed when it is activated in one of the MCAL modules.

The upper layer is responsible for activating MCU normal operation (condition before execution of MCU power mode) or to switch off uC power supply.

For some MCU mode configuration, the MCU is able to wake up only via hardware reset.

### 7.1.3 Version Check

#### 7.1.3.1 Background and Rationale

The integration of incompatible files shall be avoided. Minimum implementation is the version check of the header file inside the C file (version numbers of C and H files shall be identical).

#### 7.1.3.2 Requirements

**MCU110:** The MCU module's implementer shall avoid the integration of incompatible files. Minimum implementation is the version check of the header file.

For included header files:

- `MCU_AR_MAJOR_VERSION`
- `MCU_AR_MINOR_VERSION`

shall be identical. For the module internal c and h files:

- `MCU_SW_MAJOR_VERSION`
- `MCU_SW_MINOR_VERSION`
- `MCU_AR_MAJOR_VERSION`
- `MCU_AR_MINOR_VERSION`
- `MCU_AR_PATCH_VERSION`

shall be identical.

## 7.2 Error classification

### 7.2.1 Background and Rationale

The error classification depends on the time of error occurrence according to the product life cycle:

- **Development Errors:**  
These errors shall be detected and fixed during the development phase. In most cases, these errors are software errors. The detection of errors that shall only occur during development can be switched off for production code (by static configuration, i.e. pre-processor switches).
- **Production:**  
These errors are hardware errors and software exceptions that cannot be avoided and are also expected to occur in production code.

### 7.2.2 Requirements

**MCU111:** Values for production code Event Ids are assigned externally by the configuration of the DEM. They are published in the file `Dem_IntErrId.h` and included via `Dem.h`.

**MCU112:** Development error values are of type uint8.

**MCU012:** The following errors and exceptions shall be detectable by the MCU module depending on its build version (development/production mode):

Type or error	Relevance	Related error code	Value
API service called with wrong parameter	Development	MCU_E_PARAM_CONFIG	0x0A
		MCU_E_PARAM_CLOCK	0x0B
		MCU_E_PARAM_MODE	0x0C
		MCU_E_PARAM_RAMSECTION	0x0D
		MCU_E_PLL_NOT_LOCKED	0x0E
		MCU_E_UNINIT	0x0F
Clock source failure	Production	MCU_E_CLOCK_FAILURE	Assigned by DEM

**Table 2: Error Classification**

**MCU053:** If clock failure notification is enabled in the configuration set and a clock source failure error occurs, the error code `MCU_E_CLOCK_FAILURE` is activated shall be reported. (See also [MCU051](#)).

### 7.3 Error detection

**MCU100:** The detection of development errors is configurable (*ON / OFF*) at pre-compile time. The switch `McuDevErrorDetect` (see chapter 10) shall activate or deactivate the detection of all development errors.

**MCU101:** If the `McuDevErrorDetect` switch is enabled, API parameter checking is enabled. The detailed description of the detected errors can be found in chapter 7.2 and chapter 8.

**MCU102:** The detection of production code errors cannot be switched off.

### 7.4 Error notification

**MCU016:** The MCU driver follows the standardized AUTOSAR concept to report development errors. The provided routines are specified in the Development Error Tracer (DET) specification.

**MCU013:** Detected development errors shall be reported to the `Det_ReportError` service of the Development Error Tracer (DET) if the pre-processor switch `McuDevErrorDetect` is set (see chapter 10).

**MCU051:** The MCU driver follows the standardized AUTOSAR concept to report production errors. The provided callback routines are specified in the Diagnostic Event Manager (DEM) specification (see 6).

**MCU0149:** Production errors shall be reported to the Diagnostic Event Manager (DEM). They shall not be used as the return value of the called function.

**MCU015:** Additional errors that are detected because of specific implementation and/or specific hardware properties shall be added to the MCU implementation specification. The classification and enumeration shall be compatible to the errors listed above (see **MCU012**).



## 8 API specification

### 8.1 Imported types

In this chapter all types included from the following files are listed:

MCU152:

Header file	Imported Type
Dem_Types.h	Dem_EventIdType
Std_Types.h	Std_VersionInfoType
	Std_ReturnType

### 8.2 Type definitions

#### 8.2.1 Mcu\_ConfigType

<b>Name:</b>	Mcu_ConfigType	
<b>Type:</b>	Structure	
<b>Range:</b>	Hardware dependent structure	A structure to hold the MCU driver configuration.
<b>Description:</b>	A pointer to such a structure is provided to the MCU initialization routines for configuration.	

**MCU131:** The structure `Mcu_ConfigType` is an external data structure (i.e. implementation specific) and shall contain the initialization data for the MCU module. It shall contain:

- MCU dependent properties
- Reset Configuration
- Definition of MCU modes
- Definition of Clock settings
- Definition of RAM sections

**MCU054:** The structure `Mcu_ConfigType` shall provide a configurable (enable/disable) clock failure notification if the MCU provides an interrupt for such detection. Error reporting shall follow the DEM procedures (see also MCU051). In case of other HW detection mechanisms e.g., the generation of a trap, this notification shall be disabled and the failure reporting shall be done outside the MCU driver.

**MCU035:** The definitions for each MCU mode within the structure `Mcu_ConfigType` shall contain: (depending on MCU)

- MCU specific properties
- Change of CPU clock
- Change of Peripheral clock
- Change of PLL settings
- Change of MCU power supply

**MCU031:** The definitions for each Clock setting within the structure

`Mcu_ConfigType` shall contain:

- MCU specific properties as, e.g., clock safety features and special clock distribution settings
- PLL settings /start lock options
- Internal oscillator setting

**MCU030:** The definitions for each RAM section within the structure

`Mcu_ConfigType` shall contain:

- RAM section base address
- Section size
- Data pre-setting to be initialized

Usage of linker symbols instead of scalar values is allowed.

### 8.2.2 Mcu\_PllStatusType

<b>Name:</b>	Mcu_PllStatusType	
<b>Type:</b>	Enumeration	
<b>Range:</b>	MCU_PLL_LOCKED	PLL is locked
	MCU_PLL_UNLOCKED	PLL is unlocked
	MCU_PLL_STATUS_UNDEFINED	PLL Status is unknown
<b>Description:</b>	This is a status value returned by the function <code>Mcu_GetPllStatus</code> of the MCU module.	

### 8.2.3 Mcu\_ClockType

<b>Name:</b>	Mcu_ClockType	
<b>Type:</b>	uint8, uint16, uint32	
<b>Range:</b>	0..<number of clock settings>- 1	The range is dependent on the number of different clock settings provided in the configuration structure. The type shall be chosen depending on MCU platform for best performance.
<b>Description:</b>	Specifies the identification (ID) for a clock setting, which is configured in the configuration structure	

### 8.2.4 Mcu\_ResetType

<b>Name:</b>	Mcu_ResetType	
<b>Type:</b>	Enumeration	
<b>Range:</b>	MCU_POWER_ON_RESET	Power On Reset (default)
	MCU_WATCHDOG_RESET	Internal Watchdog Timer Reset
	MCU_SW_RESET	Software Reset
	MCU_RESET_UNDEFINED	Reset is undefined
<b>Description:</b>	This is the type of the reset enumerator containing the subset of reset types. It is not required that all reset types are supported by hardware.	

**MCU134:** The MCU module shall provide at least the values `MCU_POWER_ON_RESET` and `UNDEFINED_RESET` for the enumeration `Mcu_ResetType`.

Note: Additional reset types of `Mcu_ResetType` may be added depending on MCU.

### 8.2.5 Mcu\_RawResetType

<b>Name:</b>	Mcu_RawResetType	
<b>Type:</b>	uint8, uint16, uint32	
<b>Range:</b>	MCU dependent register value	The type shall be chosen depending on MCU platform for best performance.
<b>Description:</b>	This type specifies the reset reason in raw register format read from a reset status register.	

### 8.2.6 Mcu\_ModeType

<b>Name:</b>	Mcu_ModeType	
<b>Type:</b>	uint8, uint16, uint32	
<b>Range:</b>	0..<number of MCU modes>-1	The range is dependent on the number of MCU modes provided in the configuration structure. The type shall be chosen depending on MCU platform for best performance.
<b>Description:</b>	This type specifies the identification (ID) for a MCU mode, which is configured in the configuration structure.	

### 8.2.7 Mcu\_RamSectionType

<b>Name:</b>	Mcu_RamSectionType	
<b>Type:</b>	uint8, uint16, uint32	
<b>Range:</b>	0..< number of RAM sections>-1	The range is dependent on the number of RAM sections provided in the configuration structure. The type shall be chosen depending on MCU platform for best performance.
<b>Description:</b>	This type specifies the identification (ID) for a RAM section, which is configured in the configuration structure.	

## 8.3 Function definitions

This is a list of functions provided for upper layer modules.

### 8.3.1 Mcu\_Init

#### MCU153:

<b>Service name:</b>	Mcu_Init
<b>Syntax:</b>	void Mcu_Init( const Mcu_ConfigType* ConfigPtr )
<b>Service ID[hex]:</b>	0x00
<b>Sync/Async:</b>	Synchronous
<b>Reentrancy:</b>	Non Reentrant
<b>Parameters (in):</b>	ConfigPtr   Pointer to MCU driver configuration set.
<b>Parameters (in-out):</b>	None
<b>Parameters (out):</b>	None
<b>Return value:</b>	None
<b>Description:</b>	This service initializes the MCU driver.

**MCU026:** The function `Mcu_Init` shall initialize the MCU module, i.e. make the configuration settings for power down, clock and RAM sections visible within the MCU module.

Note: After the execution of the function `Mcu_Init`, the configuration data are accessible and can be used by the MCU module functions as, e.g., `Mcu_InitRamSection`.

**MCU116:** The MCU module's implementer shall apply the following rules regarding initialization of controller registers within the function `Mcu_Init`:

1. If the hardware allows for only one usage of the register, the driver module implementing that functionality is responsible for initializing the register.
2. If the register can affect several hardware modules and if it is an I/O register, it shall be initialised by the PORT driver.
3. If the register can affect several hardware modules and if it is not an I/O register, it shall be initialised by this MCU driver.
4. One-time writable registers that require initialisation directly after reset shall be initialised by the startup code.
5. All other registers shall be initialised by the start-up code.

**MCU127:** If not applicable, the MCU module's environment shall pass a NULL pointer to the function `Mcu_Init`. In this case the check for this NULL pointer has to be omitted.

Note: The term 'Hardware Module' refers to internal modules of the MCU and not to a BSW module.

### 8.3.2 Mcu\_InitRamSection

#### MCU154:

<b>Service name:</b>	Mcu_InitRamSection	
<b>Syntax:</b>	Std_ReturnType Mcu_InitRamSection( Mcu_RamSectionType RamSection )	
<b>Service ID[hex]:</b>	0x01	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Non Reentrant	
<b>Parameters (in):</b>	RamSection	Selects RAM memory section provided in configuration set
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	Std_ReturnType	E_OK: command has been accepted E_NOT_OK: command has not been accepted e.g. due to parameter error
<b>Description:</b>	This service initializes the RAM section wise.	

**MCU011:** The function `Mcu_InitRamSection` shall initialize the RAM section wise. The definition of the section and the initialization value is provided by the configuration structure (see [MCU030](#)).

**MCU136:** The MCU module's environment shall call the function `Mcu_InitRamSection` only after the MCU module has been initialized using the function `Mcu_Init`.

### 8.3.3 Mcu\_InitClock

#### MCU155:

<b>Service name:</b>	Mcu_InitClock	
<b>Syntax:</b>	Std_ReturnType Mcu_InitClock( Mcu_ClockType ClockSetting )	
<b>Service ID[hex]:</b>	0x02	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Non Reentrant	
<b>Parameters (in):</b>	ClockSetting	Clock setting
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	Std_ReturnType	E_OK: Command has been accepted E_NOT_OK: Command has not been accepted
<b>Description:</b>	This service initializes the PLL and other MCU specific clock options.	

**MCU137:** The function `Mcu_InitClock` shall initialize the PLL and other MCU specific clock options. The clock configuration parameters are provided via the configuration structure.

**MCU138:** The function `Mcu_InitClock` shall start the PLL lock procedure (if PLL shall be initialized) and shall return without waiting until the PLL is locked.

**MCU139:** The MCU module's environment shall only call the function `Mcu_InitClock` after the MCU module has been initialized using the function `Mcu_Init`.

### 8.3.4 Mcu\_DistributePllClock

**MCU156:**

<b>Service name:</b>	<code>Mcu_DistributePllClock</code>
<b>Syntax:</b>	<code>void Mcu_DistributePllClock( )</code>
<b>Service ID[hex]:</b>	0x03
<b>Sync/Async:</b>	Synchronous
<b>Reentrancy:</b>	Non Reentrant
<b>Parameters (in):</b>	None
<b>Parameters (in-out):</b>	None
<b>Parameters (out):</b>	None
<b>Return value:</b>	None
<b>Description:</b>	This service activates the PLL clock to the MCU clock distribution.

**MCU140:** The function `Mcu_DistributePllClock` shall activate the PLL clock to the MCU clock distribution.

**MCU141:** The MCU module's environment shall execute the function `Mcu_DistributePllClock` if the MCU module needs a separate request to activate the PLL clock after the PLL is locked. In this case, the function shall remove the current clock source (for example internal oscillator clock) from MCU clock distribution.

**MCU056:** The function `Mcu_DistributePllClock` shall return without affecting the MCU hardware if the PLL clock has been automatically activated by the MCU hardware.

**MCU142:** The MCU module's environment shall only call the function `Mcu_DistributePllClock` after the status of the PLL has been detected as locked by the function `Mcu_GetPllStatus`.

### 8.3.5 Mcu\_GetPllStatus

**MCU157:**

<b>Service name:</b>	Mcu_GetPllStatus	
<b>Syntax:</b>	Mcu_PllStatusType Mcu_GetPllStatus( )	
<b>Service ID[hex]:</b>	0x04	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Reentrant	
<b>Parameters (in):</b>	None	
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	Mcu_PllStatusType	PLL Status
<b>Description:</b>	This service provides the lock status of the PLL.	

**MCU008:** The function `Mcu_GetPllStatus` shall return the lock status of the PLL.

**MCU132:** The function `Mcu_GetPllStatus` shall return `MCU_PLL_STATUS_UNDEFINED` if this function is called prior to calling of the function `Mcu_Init`.

### 8.3.6 Mcu\_GetResetReason

**MCU158:**

<b>Service name:</b>	Mcu_GetResetReason	
<b>Syntax:</b>	Mcu_ResetType Mcu_GetResetReason( )	
<b>Service ID[hex]:</b>	0x05	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Reentrant	
<b>Parameters (in):</b>	None	
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	Mcu_ResetType	--
<b>Description:</b>	The service reads the reset type from the hardware, if supported.	

**MCU005:** The function `Mcu_GetResetReason` shall read the reset reason from the hardware and return this reason if supported by the hardware. If the hardware does not support the hardware detection of the reset reason, the return value from the function `Mcu_GetResetReason` shall always be `MCU_POWER_ON_RESET`.

**MCU133:** The function `Mcu_GetResetReason` shall return `MCU_RESET_UNDEFINED` if this function is called prior to calling of the function `Mcu_Init`, and if supported by the hardware.

The User should ensure that the reset reason is cleared once it has been read out to avoid multiple reset reasons.

### 8.3.7 Mcu\_GetResetRawValue

#### MCU159:

<b>Service name:</b>	Mcu_GetResetRawValue	
<b>Syntax:</b>	Mcu_RawResetType Mcu_GetResetRawValue( )	
<b>Service ID[hex]:</b>	0x06	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Reentrant	
<b>Parameters (in):</b>	None	
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	Mcu_RawResetType	Reset raw value
<b>Description:</b>	The service reads the reset type from the hardware register, if supported.	

**MCU135:** The function `Mcu_GetResetRawValue` shall return an implementation specific value which does not correspond to a valid value of the reset status register and is not equal to 0 if this function is called prior to calling of the function `Mcu_Init`, and if supported by the hardware.

**MCU006:** The function `Mcu_GetResetRawValue` shall read the reset raw value from the hardware register if the hardware supports this. If the hardware does not have a reset status register, the return value shall be 0x0.

The User should ensure that the reset reason is cleared once it has been read out to avoid multiple reset reasons.

### 8.3.8 Mcu\_PerformReset

#### MCU160:

<b>Service name:</b>	Mcu_PerformReset	
<b>Syntax:</b>	void Mcu_PerformReset( )	
<b>Service ID[hex]:</b>	0x07	
<b>Sync/Async:</b>	Synchronous	
<b>Reentrancy:</b>	Non Reentrant	
<b>Parameters (in):</b>	None	
<b>Parameters (in-out):</b>	None	
<b>Parameters (out):</b>	None	
<b>Return value:</b>	None	
<b>Description:</b>	The service performs a microcontroller reset.	



**MCU143:** The function `Mcu_PerformReset` shall perform a microcontroller reset by using the hardware feature of the microcontroller.

**MCU144:** The function `Mcu_PerformReset` shall perform the reset type which is configured in the configuration set.

**MCU145:** The MCU module's environment shall only call the function `Mcu_PerformReset` after the MCU module has been initialized by the function `Mcu_Init`.

**MCU146:** The function `Mcu_PerformReset` is only available if the runtime parameter `McuPerformResetApi` is set to `TRUE`. If set to `FALSE`, the function `Mcu_PerformReset` is not applicable. (see Section 10.2.2).

### 8.3.9 Mcu\_SetMode

#### MCU161:

Service name:	<code>Mcu_SetMode</code>
<b>Syntax:</b>	<code>void Mcu_SetMode(     Mcu_ModeType McuMode )</code>
<b>Service ID[hex]:</b>	<code>0x08</code>
<b>Sync/Async:</b>	Synchronous
<b>Reentrancy:</b>	Non Reentrant
<b>Parameters (in):</b>	<code>McuMode</code>   Set different MCU power modes configured in the configuration set
<b>Parameters (in-out):</b>	None
<b>Parameters (out):</b>	None
<b>Return value:</b>	None
<b>Description:</b>	This service activates the MCU power modes.

**MCU147:** The function `Mcu_SetMode` shall set the MCU power mode. In case of the CPU switched off, the function `Mcu_SetMode` returns after it has performed a wake-up.

**MCU148:** The MCU module's environment shall only call the function `Mcu_SetMode` after the MCU module has been initialized by the function `Mcu_Init`.

Note: The environment of the function `Mcu_SetMode` has to ensure that the ECU is ready for reduced power mode activation.

### 8.3.10 Mcu\_GetVersionInfo

#### MCU162:

<b>Service name:</b>	Mcu_GetVersionInfo
<b>Syntax:</b>	void Mcu_GetVersionInfo( Std_VersionInfoType* versioninfo )
<b>Service ID[hex]:</b>	0x09
<b>Sync/Async:</b>	Synchronous
<b>Reentrancy:</b>	Non Reentrant
<b>Parameters (in):</b>	None
<b>Parameters (in-out):</b>	None
<b>Parameters (out):</b>	versioninfo   Pointer to where to store the version information of this module.
<b>Return value:</b>	None
<b>Description:</b>	This service returns the version information of this module.

**MCU103:** The function `Mcu_GetVersionInfo` shall return the version information of the MCU module. The version information includes:

- Module Id
- Vendor Id
- Vendor specific version numbers (BSW00407)

**MCU104:** The function `Mcu_GetVersionInfo` shall be pre-compile time configurable On/Off by the configuration parameter `McuVersionInfoApi`.

**MCU149:** If source code for caller and callee of the function `Mcu_GetVersionInfo` is available, the MCU module should realize this function as a macro. The MCU module should define this macro in the module's header file.

## 8.4 Call-back Notifications

There are no callback notifications for the MCU driver. The callback notifications are implemented in another module (ICU driver and/or complex drivers).

## 8.5 Scheduled Functions

There are no scheduled functions within the MCU driver.

## 8.6 Expected Interfaces

In this chapter all interfaces required from other modules are listed.

### 8.6.1 Mandatory Interfaces

#### MCU166:

<i>API function</i>	<i>Description</i>
Dem_ReportErrorStatus	Reports errors to the DEM.

### 8.6.2 Optional Interfaces

This chapter defines all interfaces, which are required to fulfil an optional functionality of the module.

#### MCU163:

<i>API function</i>	<i>Description</i>
Det_ReportError	Service to report development errors.

## 8.7 API parameter checking

**MCU017:** If the development error detection is enabled for the MCU module, the MCU functions shall check the following API parameters, report detected errors to the Development Error Tracer and reject with return value `E_NOT_OK` in case the function has a standard return type.

**MCU018:** If development error detection is enabled, the parameter `ConfigPtr` shall be checked for being `NULL`. Related error value: `MCU_E_PARAM_CONFIG`.

**MCU019:** `ClockSetting` shall be within the settings defined in the configuration data structure. Related error value: `MCU_E_PARAM_CLOCK`

**MCU020:** `McuMode` shall be within the modes defined in the configuration data structure. Related error value: `MCU_E_PARAM_MODE`

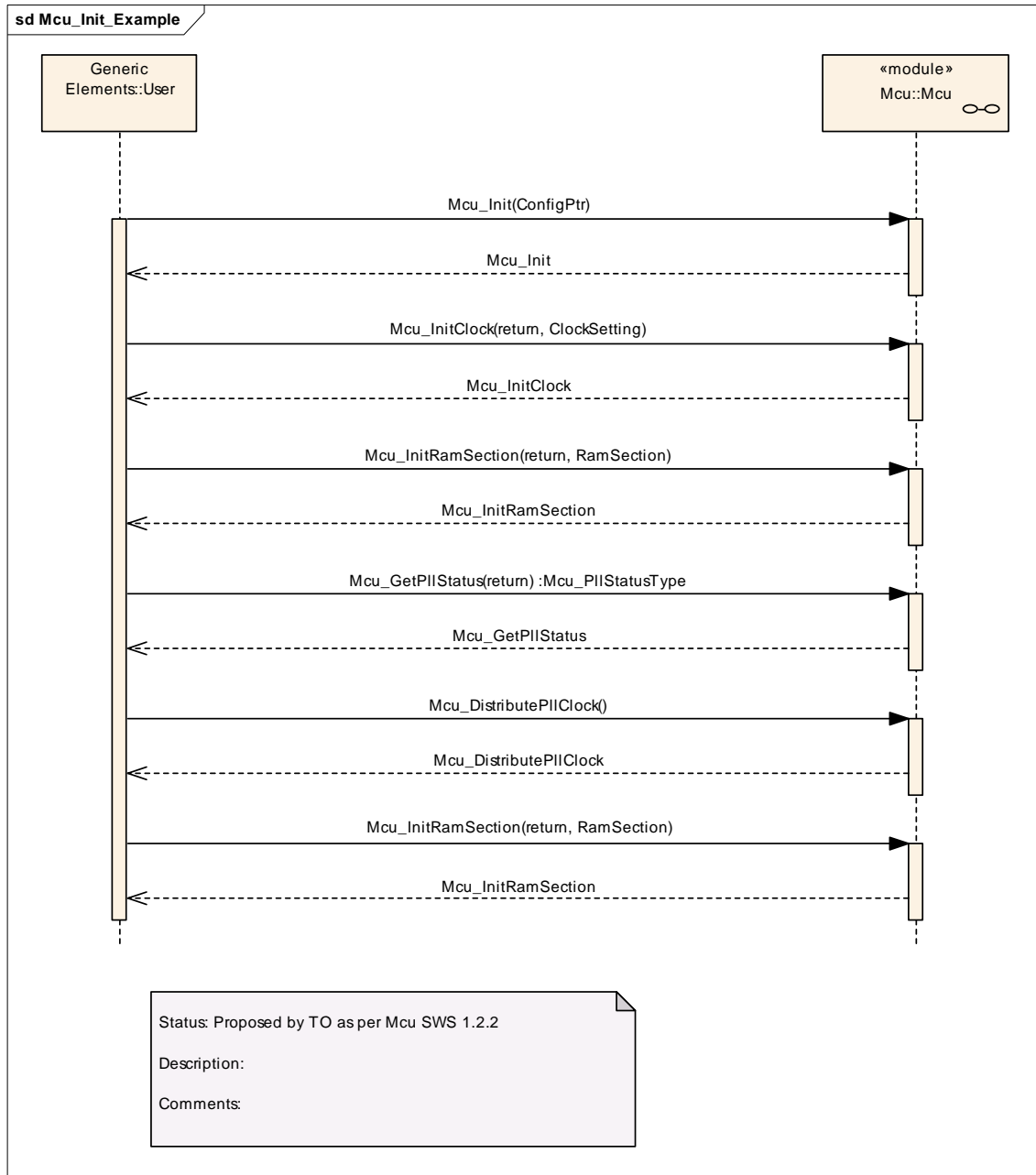
**MCU021:** `RamSection` shall be within the sections defined in the configuration data structure. Related error value: `MCU_E_PARAM_RAMSECTION`

**MCU122:** A error shall be reported if the status of the PLL is detected as not locked with the function `Mcu_DistributePIIClock()`. The DET error reporting shall be used. Related error value: `MCU_E_PLL_NOT_LOCKED`.

**MCU125:** The function `Mcu_Init` shall be called first before calling any other MCU function. If development error detection is enabled and if this sequence is not followed, the error code `MCU_E_UNINIT` shall be reported to the DET.

## 9 Sequence diagrams

### 9.1 Example Sequence for MCU initialization services



**Figure 3: Sequence Diagram – MCU Initialisation**

The order of services is just an example and might differ depending on the user. `Mcu_Init` shall be executed first after power-up. The user takes care that the PLL is locked by executing `Mcu_GetPllStatus`.

### 9.2 Mcu\_GetResetReason

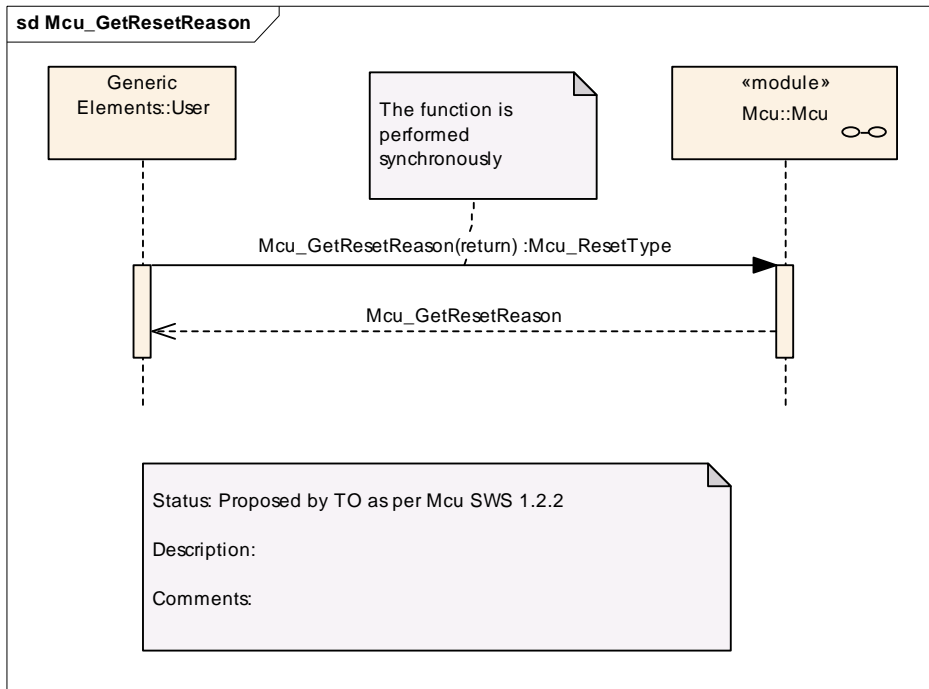


Figure 7: Sequence Diagram – MCU\_GetResetReason

### 9.3 Mcu\_GetResetRawValue

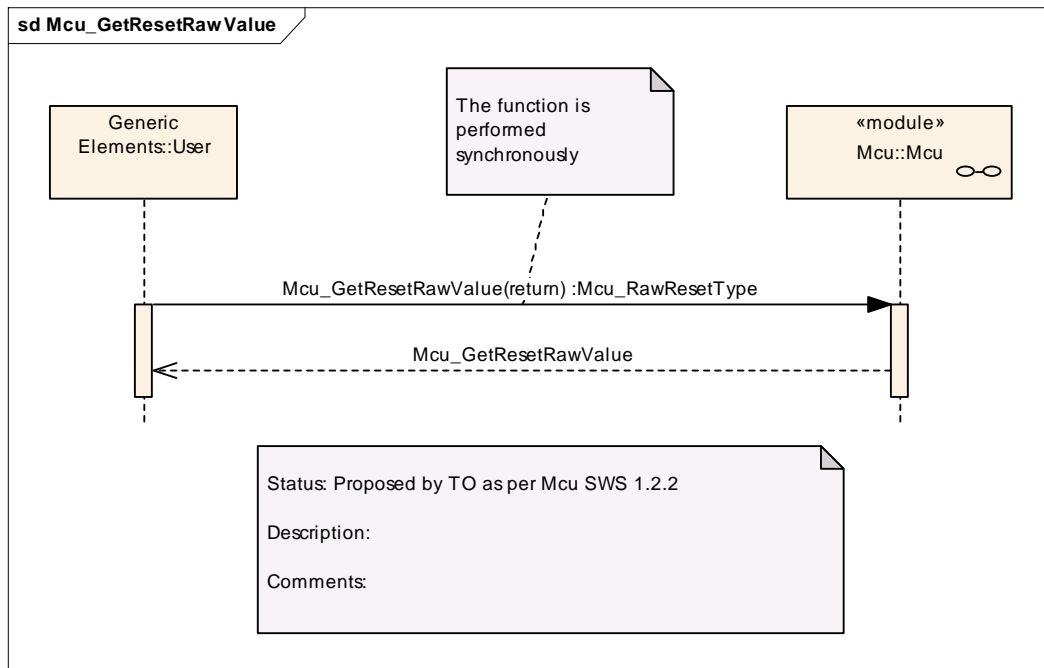
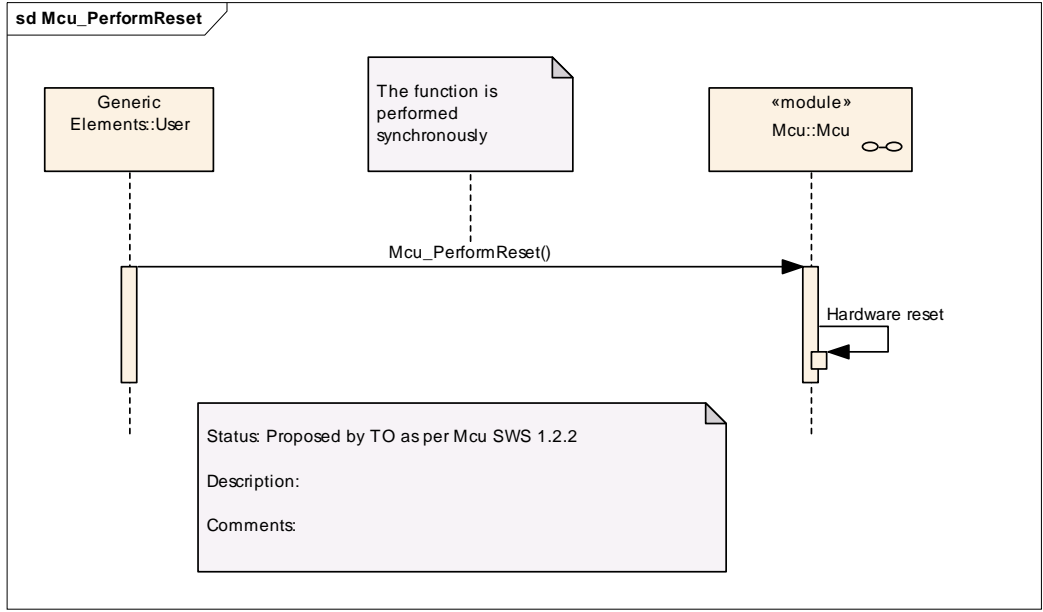


Figure 8: Sequence Diagram – Mcu\_GetResetRawValue

### 9.4 Mcu\_PerformReset



**Figure 9: Sequence Diagram – Mcu\_PerformReset**

## 10 Configuration specification

In general, this chapter defines configuration parameters and their clustering into containers. In order to support the specification Chapter 10.1 describes fundamentals. It also specifies a template (table) you shall use for the parameter specification. We intend to leave Chapter 10.1 in the specification to guarantee comprehension.

Chapter 10.2 specifies the structure (containers) and the parameters of the module MCU.

Chapter 10.3 specifies published information of the module MCU.

### 10.1 How to read this chapter

In addition to this section, it is highly recommended to read the documents:

- AUTOSAR Layered Software Architecture [2].
- AUTOSAR ECU Configuration Specification [5].  
This document describes the AUTOSAR configuration methodology and the AUTOSAR configuration metamodel in detail.

The following is only a short survey of the topic and it will not replace the ECU Configuration Specification document.

#### 10.1.1 Configuration and configuration parameters

Configuration parameters define the variability of the generic part(s) of an implementation of a module. This means that only generic or configurable module implementation can be adapted to the environment (software/hardware) in use during system and/or ECU configuration.

The configuration of parameters can be achieved at different times during the software process: before compile time, before link time or after build time. In the following, the term “configuration class” (of a parameter) shall be used in order to refer to a specific configuration point in time.

#### 10.1.2 Containers

Containers structure the set of configuration parameters. This means:

- *all* configuration parameters are kept in containers.

(sub-) containers can reference (sub-) containers. It is possible to assign a multiplicity to these references. The multiplicity then defines the possible number of instances of the contained parameters.



## 10.2 Containers and configuration parameters

The following chapters summarize all configuration parameters. The detailed meanings of the parameters describe Chapters 7 and Chapter 8.

### 10.2.1 Variants

**MCU129:** VariantPC: This variant is limited to pre-compile-configuration parameters only. The intention of this variant is to optimize the parameters configuration for a source code delivery.

**MCU130:** VariantPB: This variant allows a mix of pre-compile time-, post build-time configuration parameters. The intention of this variant is to optimize the parameters configuration for a re-loadable binary.

**MCU126:** The initialization function of this module shall always have a pointer as a parameter, even though for VariantPC no configuration set shall be given. Instead a NULL pointer shall be passed to the initialization function.

### 10.2.2 Mcu

<b>Module Name</b>	Mcu
<b>Module Description</b>	Configuration of the Mcu (Microcontroler Unit) module.

Included Containers		
Container Name	Multiplicity	Scope / Dependency
McuGeneralConfiguration	1	This container contains the configuration (parameters) of the MCU driver.
McuModuleConfiguration	1	This container contains the configuration (parameters) of the MCU driver

### 10.2.3 McuGeneralConfiguration

<b>SWS Item</b>	<b>MCU118 :</b>		
<b>Container Name</b>	McuGeneralConfiguration{MCU General Configuration}		
<b>Description</b>	This container contains the configuration (parameters) of the MCU driver.		
<b>Configuration Parameters</b>			

<b>SWS Item</b>	<b>MCU166 :</b>		
<b>Name</b>	McuDevErrorDetect {MCU_DEV_ERROR_DETECT}		
<b>Description</b>	Pre-processor switch for enabling the development error detection and reporting.		
<b>Multiplicity</b>	1		
<b>Type</b>	BooleanParamDef		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Module		

<b>SWS Item</b>	<b>MCU167 :</b>		
<b>Name</b>	McuPerformResetApi {MCU_PERFORM_RESET_API}		

<b>Description</b>	Pre-processor switch to enable / disable the use of the function Mcu_PerformReset()		
<b>Multiplicity</b>	1		
<b>Type</b>	BooleanParamDef		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>			

<b>SWS Item</b>	<b>MCU168 :</b>		
<b>Name</b>	McuVersionInfoApi {MCU_VERSION_INFO_API}		
<b>Description</b>	Pre-processor switch to enable / disable the API to read out the modules version information.		
<b>Multiplicity</b>	1		
<b>Type</b>	BooleanParamDef		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Module		

No Included Containers

#### 10.2.4 McuModuleConfiguration

<b>SWS Item</b>	<b>MCU119 :</b>		
<b>Container Name</b>	McuModuleConfiguration{MCU Module Configuration} [Multi Config Container]		
<b>Description</b>	This container contains the configuration (parameters) of the MCU driver		
<b>Configuration Parameters</b>			

<b>SWS Item</b>	<b>MCU170 :</b>		
<b>Name</b>	McuClockSrcFailureNotification {MCU_CLOCK_SOURCE_FAILURE_NOTIFICATION}		
<b>Description</b>	Enables/Disables clock failure notification. In case this feature is not supported by HW the setting should be disabled.		
<b>Multiplicity</b>	1		
<b>Type</b>	EnumerationParamDef		
<b>Range</b>	DISABLED		
	ENABLED		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	--	
	<b>Post-build time</b>	M	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Module		

<b>SWS Item</b>	<b>MCU171 :</b>		
<b>Name</b>	McuNumberOfMcuModes {Mcu_Number_Of_Modes}		
<b>Description</b>	This parameter shall represent the number of Modes available for the MCU. calculationFormula = Number of configured McuModeSettingConf		
<b>Multiplicity</b>	1		
<b>Type</b>	DerivedIntegerParamDef		

<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	--	
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Module		

<b>SWS Item</b>	<b>MCU172 :</b>		
<b>Name</b>	McuRamSectors {MCU_RAM_SECTORS}		
<b>Description</b>	This parameter shall represent the number of RAM sectors available for the MCU. calculationFormula = Number of configured McuRamSectorSettingConf		
<b>Multiplicity</b>	1		
<b>Type</b>	DerivedIntegerParamDef		
<b>Default value</b>	--		
<b>calculationFormula</b>	number of configured mcuramsectorsettingconf		
<b>calculationLanguage</b>	informal		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	--	
	<b>Post-build time</b>	M	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Module		

<b>SWS Item</b>	<b>MCU173 :</b>		
<b>Name</b>	McuResetSetting {MCU_RESET_SETTING}		
<b>Description</b>	This parameter relates to the MCU specific reset configuration. This applies to the function Mcu_PerformReset, which performs a microcontroller reset using the hardware feature of the microcontroller.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	IntegerParamDef		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	--	
	<b>Post-build time</b>	--	
<b>Scope / Dependency</b>	scope: Module		

<b>Included Containers</b>		
<b>Container Name</b>	<b>Multiplicity</b>	<b>Scope / Dependency</b>
McuClockSettingConfig	1..*	This container contains the configuration (parameters) for the Clock settings of the MCU. Please see MCU031 for more information on the MCU clock settings.
McuModeSettingConf	1..*	This container contains the configuration (parameters) for the Mode setting of the MCU. Please see MCU035 for more information on the MCU mode settings.
McuRamSectorSettingConf	0..*	This container contains the configuration (parameters) for the RAM Sector setting. Please see MCU030 for more information on RAM sector settings.

### 10.2.5 McuClockSettingConfig

<b>SWS Item</b>	<b>MCU124 :</b>
<b>Container Name</b>	McuClockSettingConfig{MCU Clock Setting Configuration}
<b>Description</b>	This container contains the configuration (parameters) for the Clock settings of the MCU. Please see MCU031 for more information on the MCU clock settings.

<b>Configuration Parameters</b>
---------------------------------

<b>Included Containers</b>
----------------------------

Container Name	Multiplicity	Scope / Dependency
McuClockReferencePoint	1..*	This container defines a reference point in the Mcu Clock tree. It defines the frequency which then can be used by other modules as an input value. Lower multiplicity is 1, as even in the simplest case (only one frequency is used), there is one frequency to be defined.

### 10.2.6 McuModeSettingConf

<b>SWS Item</b>	<b>MCU123 :</b>
<b>Container Name</b>	McuModeSettingConf{MCU Mode Setting Configuration}
<b>Description</b>	This container contains the configuration (parameters) for the Mode setting of the MCU. Please see MCU035 for more information on the MCU mode settings.
<b>Configuration Parameters</b>	

<b>SWS Item</b>	<b>MCU176 :</b>		
<b>Name</b>	McuMode {MCU_MODE_NORMAL}		
<b>Description</b>	The parameter represents the MCU Mode settings.		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef (Symbolic Name generated for this parameter)		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	--	
	<b>Post-build time</b>	M	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Module		

<b>No Included Containers</b>
-------------------------------

### 10.2.7 McuRamSectorSettingConf

<b>SWS Item</b>	<b>MCU120 :</b>
<b>Container Name</b>	McuRamSectorSettingConf{MCU RAM Sector Setting Configuration}
<b>Description</b>	This container contains the configuration (parameters) for the RAM Sector setting. Please see MCU030 for more information on RAM sector settings.
<b>Configuration Parameters</b>	

<b>SWS Item</b>	<b>MCU177 :</b>		
<b>Name</b>	McuRamDefaultValue {MCU_RAM_DEFAULT_VALUE}		
<b>Description</b>	This parameter shall represent the Data pre-setting to be initialized		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	--	
	<b>Post-build time</b>	M	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Module		

<b>SWS Item</b>	<b>MCU178 :</b>
<b>Name</b>	McuRamSectionBaseAddress {MCU_RAM_SECTION_BASE_ADDRESS}
<b>Description</b>	This parameter shall represent the MCU RAM section base address
<b>Multiplicity</b>	1
<b>Type</b>	IntegerParamDef

<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	--	
	<b>Post-build time</b>	M	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Module		

<b>SWS Item</b>	<b>MCU179 :</b>		
<b>Name</b>	McuRamSectionSize {MCU_RAM_SECTION_SIZE}		
<b>Description</b>	This parameter shall represent the MCU RAM Section size		
<b>Multiplicity</b>	1		
<b>Type</b>	IntegerParamDef		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	--	
	<b>Post-build time</b>	M	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Module		

**No Included Containers**

### 10.2.8 McuClockReferencePoint

<b>SWS Item</b>	<b>MCU174 :</b>		
<b>Container Name</b>	McuClockReferencePoint		
<b>Description</b>	This container defines a reference point in the Mcu Clock tree. It defines the frequency which then can be used by other modules as an input value. Lower multiplicity is 1, as even in the simplest case (only one frequency is used), there is one frequency to be defined.		
<b>Configuration Parameters</b>			

<b>SWS Item</b>	<b>MCU175 :</b>		
<b>Name</b>	McuClockReferencePointFrequency		
<b>Description</b>	This is the frequency for the specific instance of the McuClockReferencePoint container. It shall be given in Hz.		
<b>Multiplicity</b>	1		
<b>Type</b>	FloatParamDef		
<b>Default value</b>	--		
<b>ConfigurationClass</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	--	
	<b>Post-build time</b>	M	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: Module		

**No Included Containers**

### 10.3 Published Information

Published information contains data defined by the implementer of the SW module that does not change when the module is adapted (i.e. configured) to the actual HW/SW environment. It thus contains version and manufacturer information.

**MCU037:** The following table specifies parameters that shall be published in the modules header file Mcu.h and also in the modules description file.

The standard common published information like

vendorId (<Module>\_VENDOR\_ID),  
moduleId (<Module>\_MODULE\_ID),  
arMajorVersion (<Module>\_AR\_MAJOR\_VERSION),  
arMinorVersion (<Module>\_AR\_MINOR\_VERSION),  
arPatchVersion (<Module>\_AR\_PATCH\_VERSION),  
swMajorVersion (<Module>\_SW\_MAJOR\_VERSION),  
swMinorVersion (<Module>\_SW\_MINOR\_VERSION),  
swPatchVersion (<Module>\_SW\_PATCH\_VERSION),  
vendorApiInfix (<Module>\_VENDOR\_API\_INFIX)

is provided in the BSW Module Description Template (see [11] Figure 4.1 and Figure 7.1).

Additional published parameters are listed below if applicable for this module.

## 11 Changes to Release 1

### 11.1 Deleted SWS Items

<i>SWS Item</i>	<i>Rationale</i>
MCU022	Removed due to template change in Section 10.
MCU023	Removed due to template change in Section 10.
MCU061	Removed due to template change in Section 10.

### 11.2 Replaced SWS Items

<i>SWS Item of Release 1</i>	<i>replaced by SWS Item</i>	<i>Rationale</i>
MCU036 (SWS2098)	MCU110	New template structure.

### 11.3 Changed SWS Items

No changed SWS Items to Release 1.

### 11.4 Added SWS Items

<i>SWS Item</i>	<i>Rationale</i>
MCU100	Inclusion of switch for detection of development errors.
MCU101	Inclusion of McuDevErrorDetect switch
MCU102	Detection of production errors.
MCU103	New API service for Mcu_GetVersionInfo()
MCU104	New API service.
MCU105	New section – code file structure
MCU108	New section - code file structure
MCU109	New section – code file structure
MCU110	New requirement of this template
MCU111	New requirement of this template
MCU112	New requirement of this template
MCU113	New requirement [BSW12461] introduced in SPAL_General.SRS [3]
MCU114	New requirement [BSW12461] introduced in SPAL_General.SRS [3]
MCU115	New requirement [BSW12461] introduced in SPAL_General.SRS [3]
MCU116	New requirement [BSW12461] introduced in SPAL_General.SRS [3]
MCU117	New requirement of this template
MCU118	New requirement of this template
MCU119	New requirement of this template
MCU120	New requirement of this template
MCU121	New requirement of this template
MCU122	New DET error MCU_E_PLL_NOT_LOCKED.
MCU123	New requirement of this template
MCU124	New requirement of this template
MCU125	MCU_E_UNINIT added to API Parameter checking (section 8.8)
MCU126	Additional requirement introduced in line with BSW00414 (SPAL decision, 42 <sup>nd</sup> meeting, minutes day2, issue 5)

## 12 Changes to Release 2.1

### 12.1 Deleted SWS Items

<i>SWS Item</i>	<i>Rationale</i>
MCU057	This requirement was describing the obsolete wakeup concept as depicted in deleted sequence charts (Figure 4, Figure 5, and Figure 6). Since this concept is invalid, the corresponding SWS Items can be removed as well.
MCU058	This requirement was describing the obsolete wakeup concept as depicted in deleted sequence charts (Figure 4, Figure 5, and Figure 6). Since this concept is invalid, the corresponding SWS Items can be removed as well.
MCU059	This requirement was describing the obsolete wakeup concept as depicted in deleted sequence charts (Figure 4, Figure 5, and Figure 6). Since this concept is invalid, the corresponding SWS Items can be removed as well.
MCU060	This requirement was describing the configuration of possible wake-up reasons. Since the MCU driver is not responsible for wake-up configurations, the corresponding SWS Item can be removed as well.

### 12.2 Replaced SWS Items

<i>SWS Item of Release 1</i>	<i>replaced by SWS Item</i>	<i>Rationale</i>

### 12.3 Changed SWS Items

<i>SWS Item</i>	<i>Rationale</i>
MCU118	MCU General Configuration Container: Removal of configuration parameter MCU_REPORT_WAKE_UP_REASON. Since the MCU driver is not responsible for wake-up configurations, the corresponding SWS Item can be removed as well
MCU119	McuModuleConfiguration Container: Removal of configuration parameter MCU_WAKE_UP_REASON. Since the MCU driver is not responsible for wake-up configurations, the corresponding SWS Item can be removed as well.

### 12.4 Added SWS Items

<i>SWS Item</i>	<i>Rationale</i>



## 13 Changes during SWS Improvements by Technical Office

### 13.1 Deleted SWS Items

<i>SWS Item</i>	<i>Rationale</i>
MCU117	No requirement

### 13.2 Replaced SWS Items

<i>SWS Item of Release 1</i>	<i>replaced by SWS Item</i>	<i>Rationale</i>
MCU001	<u>MCU164</u> , <u>MCU165</u>	Made requirement atomic.
MCU009	<u>MCU137</u> , <u>MCU138</u>	Made requirement atomic.
MCU028	<u>MCU140</u> , <u>MCU141</u>	Made requirement atomic.
MCU007	<u>MCU143</u> , <u>MCU144</u>	Made requirement atomic.

### 13.3 Changed SWS Items

Many requirements have been changed to improve understandability without changing the technical contents.

### 13.4 Added SWS Items

<i>SWS Item</i>	<i>Rationale</i>
<u>MCU129</u>	Each variant gets an individual requirement ID.
<u>MCU130</u>	Each variant gets an individual requirement ID.
<u>MCU131</u>	Requirement for Mcu_ConfigType
<u>MCU132</u>	Requirement for Mcu_GetPllStatus() from Mcu_PllStatusType
<u>MCU133</u>	Requirement for Mcu_GetResetReason from Mcu_ResetType
<u>MCU134</u>	Mcu_ResetType: No description, requirement
<u>MCU135</u>	Requirement for Mcu_GetResetRawValue from Mcu_RawResetType
<u>MCU136</u>	Caveat Mcu_InitRamSection
<u>MCU139</u>	Caveat Mcu_InitClock
<u>MCU142</u>	Caveat Mcu_DistributePllClock
<u>MCU145</u>	Caveat Mcu_PerformReset
<u>MCU146</u>	Configuration Mcu_PerformReset
<u>MCU147</u>	Description from Mcu_SetMode
<u>MCU148</u>	Caveat Mcu_SetMode
<u>MCU149</u>	Hint from Mcu_GetVersionInfo
<u>MCU152</u>	UML Model linking of imported types
<u>MCU153</u>	UML Model linking of Mcu_Init
<u>MCU154</u>	UML Model linking of Mcu_InitRamSection
<u>MCU155</u>	UML Model linking of Mcu_InitClock
<u>MCU156</u>	UML Model linking of Mcu_DistributePllClock
<u>MCU157</u>	UML Model linking of Mcu_GetPllStatus
<u>MCU158</u>	UML Model linking of Mcu_GetResetReason
<u>MCU159</u>	UML Model linking of Mcu_GetResetRawValue
<u>MCU160</u>	UML Model linking of Mcu_PerformReset
<u>MCU161</u>	UML Model linking of Mcu_SetMode

<u>MCU162</u>	UML Model linking of Mcu_GetVersionInfo
<u>MCU163</u>	UML Model linking of optional interfaces
<u>MCU166</u>	UML Model linking of mandatory interfaces