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1 Introduction and functional overview

This specification is the AUTOSAR COM Software Specification. It is based on the AUTOSAR COM SRS [7]. It specifies how the requirements of the AUTOSAR COM SRS shall be realized. That means that the functionality and the API of the AUTOSAR COM module are described in this document.

Within the AUTOSAR Layered Architecture the COM module is placed between RTE and the PDU Router, see [1].

AUTOSAR COM is derived from [17]. For details see Chapter 7.2.1.

AUTOSAR COM provides signal gateway functionality. For details see Chapter 7.2.4.

Main Features:

- Provision of signal oriented data interface for the RTE
- Packing of AUTOSAR signals to I-PDUs to be transmitted
- Unpacking of received I-PDUs and provision of received signals to RTE
- Routing of signals from received I-PDUs into I-PDUs to become transmitted
- Routing of signal groups from received I-PDUs into I-PDUs to become transmitted
- Communication transmission control (start/ stop of I-PDU groups)
- Replications of send requests
- Guarantee of minimum distances between transmit I-PDUs
- Monitoring of receive signals (signals timeout)
- Filter mechanisms for incoming signals
- Different notification mechanisms
- Provision of init values and update indications
- Byte order conversion
- Sign extension
- Support of two different transmission modes per I-PDU
- Signal based gateway

2 Acronyms, abbreviations and definitions

2.1 Acronyms and abbreviations

Acronym:	Description:
AUTOSAR COM	AUTOSAR COM is derived from OSEK COM [17]. For details see Chapter 7.2.1.
DM	Deadline Monitoring. For details see Chapter 7.4.5.4.
IL	Interaction Layer. A detailed description can be found in [17].
I-PDU	Interaction Layer Protocol Data Unit An I-PDU carries signals and is defined in [17].
LOM	Listen only mode
L-PDU	Data Link Layer PDU. In AUTOSAR the Data Link Layer is equivalent to the Communication Hardware Abstraction and Microcontroller Abstraction Layer.
MDT	Minimum Delay Timer. A detailed description can be found in [17]. See also chapter 7.4.5.4.
OSEK COM	Open systems and the corresponding interfaces for automotive electronics – communication [17]
PCI	Protocol Control Information For a description see [1] page 04-51 ff.
PDU Router	Module that transfers I-PDUs from one module to another module. The PDU Router can be utilized for gateway operations and for internal routing purposes.
SDT	Specification of System Template [12]
SDU	Service Data Unit For a description see [1] Chapter 4.
TM	Transmission Mode
TMC	Transmission Mode Condition, see Chapter 7.4.3.3
TMS	Transmission Mode Selector, see Chapter 7.4.3.3

2.1.1 Definitions

Acronym:	Description:
Confirmation	Lower layer reports that a request by COM has been completed successfully. It's a reaction to a request of COM. E.g. when a PDU has been successfully transmitted.
Data Invalid Value	Value sent by the AUTOSAR COM to indicate that the sender side AUTOSAR Software Component is not able to provide a valid value.
Group signal	A group signal is a signal that is contained in a signal group.
Indication	Asynchronous information from lower layer to COM, e.g. when something has been received.
Init Value	I-PDUs and signals are set to the Init Value by AUTOSAR COM after start-up. This value is used until it is overwritten.
I-PDU group	An I-PDU group contains zero or more I-PDUs or I-PDU groups. For a detailed description see [7].
Inter-ECU communication	Communication between two or more ECU for example via a CAN network.
Intra-ECU communication	Communication between Software components that reside on the same ECU.
Message	OSEK-COM uses always the synonym <i>message</i> . In AUTOSAR, <i>message</i> is replaced by <i>signal</i> but with the same meaning.
Notification	Information by COM to upper layer, e.g. when new data is available, an error occurred.
Signal	A description can be found in [7].
Signal groups	<p>In AUTOSAR, so called <i>complex data types</i> are used. Inside a complex data type, there are one or more data elements (primitive data types), like in a C struct. To ensure data consistency a complex data type must be treated as an atomic unit.</p> <p>The RTE decomposes the complex data type in single signals and sends them to the AUTOSAR COM module. As these signals altogether still have to be treated as atomic, they are called <i>signal group</i>.</p> <p>See also [7].</p>
Update-bits	A mechanism supported by AUTOSAR COM with that the receiver of a signal/ signal group can identify whether the sender has updated the data in this signal/ signal group before sending. See Chapter 7.7.

3 Related documentation

3.1 Deliverables of AUTOSAR

- [1] Layered Software Architecture
AUTOSAR_LayeredSoftwareArchitecture.pdf
- [2] Specification of Communication Stack Types
AUTOSAR_SWS_ComStackTypes.pdf
- [3] General Requirements on Basic Software Modules
AUTOSAR_SRS_General.pdf
- [4] Basic Software UML Model
AUTOSAR_UML_Model.eap
- [5] Specification of Standard Types
AUTOSAR_SWS_StandardTypes.pdf
- [6] Specification of the Virtual Functional Bus
AUTOSAR_VirtualFunctionBus.pdf
- [7] Requirements on Communication
AUTOSAR_SRS_COM.pdf
- [8] Software Component Template
AUTOSAR_SoftwareComponentTemplate.pdf
- [9] Requirements on Gateway
AUTOSAR_SRS_Gateway.pdf
- [10] Specification of PDU Router
AUTOSAR_SWS_PDU_Router.pdf
- [11] Specification of Operating System
AUTOSAR_SWS_OS.pdf
- [12] Specification of System Template
AUTOSAR_SystemTemplate.pdf
- [13] Specification of RTE Software
AUTOSAR_SWS_RTE.pdf
- [14] Specification of ECU Configuration
AUTOSAR_ECU_Configuration.pdf

[15] Specification of Generic Network Management
AUTOSAR_SWS_Generic_NM.pdf

[16] Specification of Communication Manager
AUTOSAR_SWS_ComManager.pdf

AUTOSAR Basic Software Module Description Template,
AUTOSAR_BSW_Module_Description.pdf

3.2 Related standards and norms

[17] OSEK/ VDX Communication Version 3.0.3
<http://www.osek-vdx.org>
OSEKCOM303.pdf

[18] OSEK implementation language Version 2.5
<http://www.osek-vdx.org>
oil25.pdf

4 Constraints and assumptions

This document is applicable for AUTOSAR release 3.0. Features for later AUTOSAR releases are not yet included.

4.1 Limitations

AUTOSAR COM is based on [17]. Nevertheless not all features of [17] are included and some features are different. See COM013 for a list of not included features.

Within the AUTOSAR COM Stack the I-PDUs of COM are passed via the PDU Router directly to the communication interfaces. Therefore the maximum length of an I-PDU depends of the maximum length of the L-PDU of the underlying communication interface. For CAN and LIN the maximum L-PDU length is 8 bytes. For FlexRay the maximum L-PDU length is 254 bytes.

For AUTOSAR release 3.0 there is no special treatment in COM to handle *floating point* data types. However, they may be handled with existing COM functionality.

The number of IPDU-groups is limited to 64, see COM187.

4.2 Applicability to car domains

No restrictions.

5 Dependencies to other modules

This chapter lists all the features from other modules which are used by the AUTOSAR COM module and functionalities which are provided by AUTOSAR COM to other modules. For the placement of AUTOSAR COM in the communication stack see **Figure 1**.

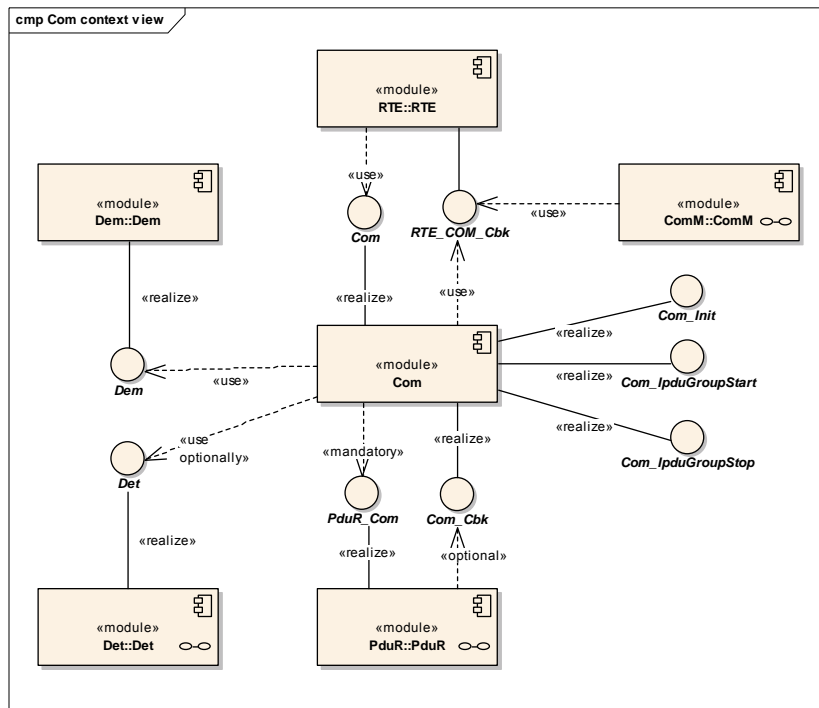


Figure 1: AUTOSAR COM context view

Note: RTE_COM_Cbk denotes the interface provided by the RTE that is used by COM to notify about transmission acknowledgements and errors. This must not necessarily result in an RTE_COM_Cbk.h file.

5.1 PDU router

The following summarizes the functionality AUTOSAR COM needs from the underlying layer PDU Router:

- Indication of incoming I-PDUs
- Sending interface for outgoing I-PDUs including the confirmation if an I-PDU has been send by the communication controller.
- Trigger interface to enable the PDU router to cause a transmission from AUTOSAR COM

A detailed description of the interface to the lower layer can be found in Chapter 7.6 and in Chapter 9.1. For further information see [10].

5.2 Runtime Environment (RTE)

RTE uses the capability to send and receive signals via AUTOSAR COM. In AUTOSAR the RTE is the higher layer above COM. For further information see [13].

5.3 COM Manager (ComM)

The COM Manager controls the start and stop of sending and receiving I-PDUs via AUTOSAR COM. For further information see [16].

5.4 File structure

5.4.1 Code file structure

The code file structure is not completely defined within this specification.

COM430: The code-file structure shall include the following files named:

- COM.c – module source file
- COM_Cfg.c – pre-compile-time configurable constant parameters
- COM_Lcfg.c – link-time configurable parameters
- COM_PBcfg.c – post-build time configurable parameters

5.4.2 Header file structure

COM005: AUTOSAR COM shall offer a header file Com.h which includes all user relevant information and another header file Com_Cbk.h which declares the callback functions and the I-PDU callout prototype.

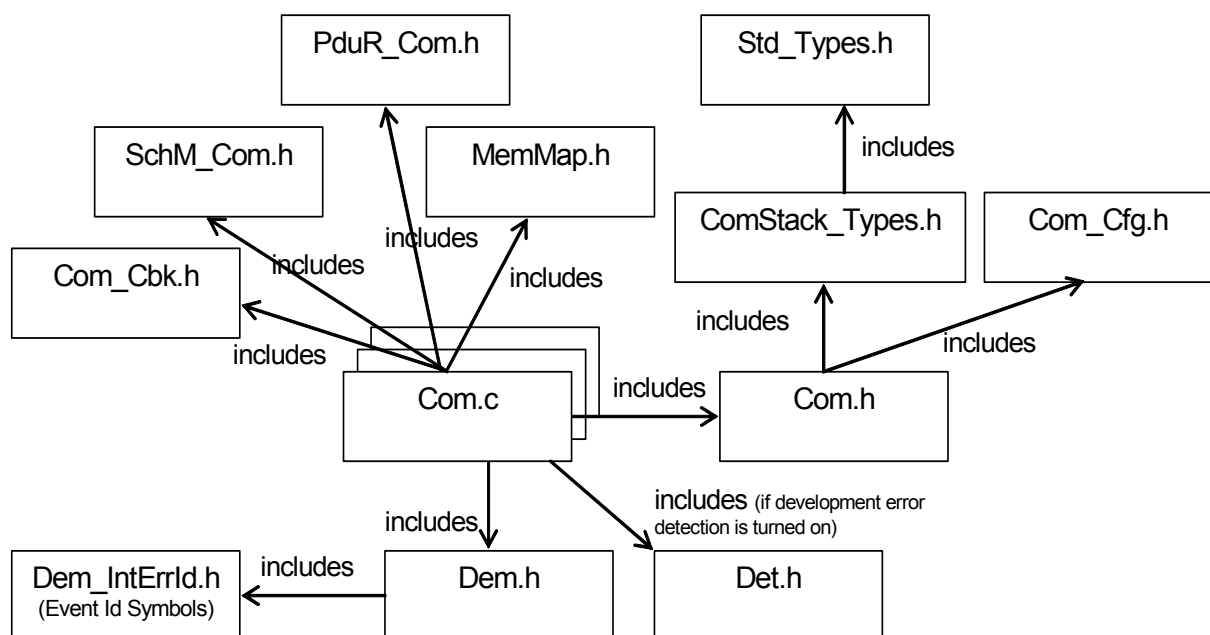


Figure 2: Include file structure

COM220: The include file structure regarding the specifics of the COM shall be constructed as shown in **Figure 2**.

COM431: The module shall include the Dem.h file. By this inclusion, the APIs to report errors as well as the required Event ID symbols are included. This specification defines the name of the Event ID symbols, which are provided by XML to the DEM configuration tool. The DEM configuration tool assigns ECU dependent values to the Event ID symbols and publishes the symbols in Dem_IntErrId.h.

6 Requirements traceability

Document: General Requirements on Basic Software Modules [3]

Requirement	Satisfied by
[BSW00344] Reference to link-time configuration	Chapter 10.2.1.2 COM432, COM430
[BSW00404] Reference to post build time configuration	Chapter 10.2, COM375, COM432
[BSW00405] Reference to multiple configuration sets	COM432
[BSW00345] Pre-compile-time configuration	Chapter 10.2.1.1 COM430
[BSW159] Tool-based configuration	not applicable (not in scope of this spec)
[BSW167] Static configuration checking	not applicable (not scope of this spec)
[BSW171] Configurability of optional functionality	not applicable (COM module has no features switches for optional functionality)
[BSW170] Data for reconfiguration of AUTOSAR SW-Components	not applicable (not in scope of this spec)
[BSW00380] Separate C-files for configuration parameters	COM430
[BSW00419] Separate C-files for pre-compile time □nstanceltion parameters	COM430
[BSW00381] Separate configuration header file for pre-compile time parameters	COM220
[BSW00412] Separate H-file for configuration parameters	COM220
[BSW00383] List dependencies of configuration files	not applicable (implementation specific)
[BSW00384] List dependencies to other modules	Chapter 5
[BSW00387] Specify the configuration class of callback function	Chapter 8.4
[BSW00388] Introduce containers	Chapter 10.2, COM541
[BSW00389] Containers shall have names	Chapter 10.2
[BSW00390] Parameter content shall be unique within the module	Chapter 10.2
[BSW00391] Parameter shall have unique names	Chapter 10.2
[BSW00392] Parameters shall have a type	Chapter 10.2
[BSW00393] Parameters shall have a range	Chapter 10.2
[BSW00394] Specify the scope of the parameters	Chapter 10.2
[BSW00395]	Chapter 10

Requirement	Satisfied by
List the required parameters (per parameter)	(scope and dependency fields)
[BSW00396] Configuration classes	Chapter 10.2
[BSW00397] Pre-compile-time parameters	Chapter 10.2
[BSW00398] Link-time parameters	Chapter 10.2
[BSW00399] Loadable post-build time parameters	Chapter 10.2
[BSW00400] Selectable post-build time parameters	Chapter 10.2
[BSW00402] Published information	Chapter 10.2.21
[BSW00375] Notification of wake-up reason	not applicable (not in scope of this spec)
[BSW101] Initialization interface	COM128, COM328, COM015, COM098, COM117, COM170, COM217, COM059, COM432
[BSW00416] Sequence of Initialization	not applicable (not in scope of this spec)
[BSW00406] Check module initialization	COM433
[BSW00437] Noninit-Area in RAM	not applicable (not in scope of this spec)
[BSW168] Diagnostic interface	not applicable (not in scope of this spec)
[BSW00407] Function to read out published parameters	COM426
[BSW00423] Usage of SW-C template to describe BSW modules with AUTOSAR Interfaces	not applicable (not valid for AUTOSAR COM module)
[BSW00424] BSW main processing function task allocation	not applicable (implementation specific)
[BSW00425] Trigger conditions for schedulable objects	COM398, COM399, COM400, COM359
[BSW00426] Exclusive areas in BSW modules	not applicable (implementation specific)
[BSW00427] ISR description for BSW modules	not applicable (not valid for AUTOSAR COM module)
[BSW00428] Execution order dependencies of main processing functions	not applicable (not valid for AUTOSAR COM module)
[BSW00429] Restricted BSW OS functionality access	not applicable (AUTOSAR COM has no interface to OS)
[BSW00431] The BSW Scheduler module implements task bodies	not applicable (not in scope of this spec)
[BSW00432] Modules should have separate main processing functions for read/receive and write/transmit data path	COM398, COM399, COM400, COM359, COM466
[BSW00433] Calling of main processing functions	not applicable (not in scope of this spec)
[BSW00434] The schedule module shall provide an API for exclusive areas	not applicable (not in scope of this spec)

Requirement	Satisfied by
[BSW00336] Shutdown interface	COM129, COM130
[BSW00337] Classification of errors	Chapter 7.10
[BSW00338] Detection and reporting of development errors	COM024, COM028, COM442 Configuration: COM141
[BSW00369] Do not return development error codes via API	COM442, COM459, Chapter 8
[BSW00339] Reporting of production relevant error status	COM459, COM428
[BSW00417] Reporting of error events by non-basic software	not applicable (not in scope of this spec)
[BSW00323] API parameter checking	COM024, COM028
[BSW004] Version check	COM026, COM337
[BSW00409] Header files for production code error IDs	COM431
[BSW00385] List possible error notifications	COM442, COM459
[BSW00386] Configuration for detecting an error	not applicable (not in scope of this spec)
[BSW161] Microcontroller abstraction	not applicable (not in scope of this spec)
[BSW162] ECU layout abstraction	not applicable (not in scope of this spec)
[BSW005] No hard coded horizontal interfaces within MCAL	not applicable
[BSW00415] User dependent include files	Chapter 5.4, COM005, COM220
[BSW164] Implementation of interrupt service routines	not applicable (not in scope of this spec)
[BSW00325] Runtime of interrupt service routines	not applicable (not in scope of this spec)
[BSW00326] Transition from ISRs to OS tasks	not applicable (not in scope of this spec)
[BSW00342] Usage of source code and object code	Chapter 10.2
[BSW00343] Specification and configuration of time	Chapter 10.2
[BSW160] Human-readable configuration data	Chapter 10.2
[BSW007] HIS MISRA C	API is MISRA conform other issues are implementation specific
[BSW00300] Module naming convention	COM005, COM220, COM540
[BSW00413] Accessing instances of BSW modules	not applicable (not in scope of this spec)
[BSW00347] Naming separation of different instances of BSW drivers	not applicable (not in scope of this spec)
[BSW00305] Self-defined data types naming convention	see Chapter 8.2
[BSW00307] Global variables naming convention	not applicable (implementation specific)

Requirement	Satisfied by
[BSW00310] API naming convention	Chapter 8.3 and 8.4
[BSW00373] Main processing function naming convention	Chapter 8.5
[BSW00327] Error values naming convention	COM442, COM459
[BSW00335] Status values naming convention	Chapter 8.2.1
[BSW00350] Development error detection keyword	COM028
[BSW00408] Configuration parameter naming convention	Chapter 10.2
[BSW00410] Compiler switches shall have defined values	not applicable (implementation specific)
[BSW00411] Get version info keyword	COM425
[BSW00346] Basic set of module files	COM005, COM220
[BSW158] Separation of configuration from implementation	COM005, COM220
[BSW00314] Separation of interrupt frames and service routines	not applicable (not in scope of this spec)
[BSW00370] Separation of callback interface from API	Chapter 8
[BSW00435] Module header file structure for the basic software scheduler	COM220
[BSW00436] Module header file Structure for the basic software memory mapping	COM220
[BSW00348] Standard type header	COM220
[BSW00353] Platform specific type header	not applicable (implementation specific)
[BSW00361] Compiler specific language extension header	not applicable (implementation specific)
[BSW00301] Limit imported information	not applicable (implementation specific)
[BSW00302] Limit exported information	not applicable (implementation specific)
[BSW00328] Avoid duplication of code	not applicable (implementation specific)
[BSW00312] Shared code shall be reentrant	COM320, COM321
[BSW006] Platform independency	not applicable (implementation specific)
[BSW00357] Standard API return type	Chapter 8
[BSW00377] Module specific API return types	Chapter 7.10, COM459
[BSW00304] AUTOSAR integer data types	COM220, (implementation specific)
[BSW00355] Do not redefine AUTOSAR integer data types	Chapter 7.10 and Chapter 8.2
[BSW00378] AUTOSAR boolean type	not applicable (implementation specific)
[BSW00306] AUTOSAR boolean type	not applicable

Requirement	Satisfied by
Avoid direct use of compiler and platform specific keywords	(implementation specific)
[BSW00308] Definition of global data	not applicable (implementation specific)
[BSW00309] Global data with read-only constraint	not applicable (implementation specific)
[BSW00371] Do not pass function pointers via API	Chapter 8
[BSW00358] Return type of init functions	COM432
[BSW00414] Parameter of init function	COM432
[BSW00376] Return type and parameters of main processing functions	Chapter 8.5
[BSW00359] Return type of callback functions	COM468, COM491, COM536, COM554, COM555, COM556
[BSW00360] Parameters of callback functions	COM468, COM491, COM536, COM554, COM555, COM556
[BSW00329] Avoidance of generic interfaces	Chapter 8
[BSW00330] Usage of macros / inline functions instead of functions	COM434
[BSW00331] Separation of error and status values	Chapter 8, COM194
[BSW009] Module user documentation	not applicable (implementation specific)
[BSW00401] Documentation of multiple instances of Configuration parameters	Chapter 10
[BSW172] Compatibility and documentation of scheduling strategy	see Chapter 8.5, COM298 further item are implementation specific
[BSW010] Memory resource documentation	not applicable (implementation specific)
[BSW00333] Documentation of callback function context	not applicable (not in scope of this spec)
[BSW00374] Module vendor identification	COM208
[BSW00379] Module identification	COM417
[BSW003] Version identification	COM426, COM425, COM424, COM026, COM337, COM141, COM208, COM417, COM418, COM419, COM420, COM421, COM422, COM423, COM438
[BSW00318] Format of module version numbers	COM026
[BSW00321] Enumeration of module version numbers	not applicable (not in scope of this spec)
[BSW00341] Microcontroller compatibility documentation	not applicable (not in scope of this spec)
[BSW00334] Provision of XML file	not applicable (not in scope of this spec)

Document: Requirements on Communication [7]

Requirement	Satisfied by
[BSW02037] AUTOSAR COM shall be based on the functionality and APIs of OSEK COM 3.0.3	COM010, COM011, COM012, COM013, COM396
[BSW02078] Support of endianness conversion	COM007, COM221, COM352, COM472, COM473
[BSW02086] Support of sign-extension for received signals	COM008, COM353, COM352
[BSW02042] Initialization of not used areas of an I-PDU	COM015
[BSW02040] AUTOSAR COM configuration language	COM006, Chapter 10
[BSW177] Configuration of communication parameters	Chapter 10.2
[BSW02067] Rules for checking the consistency of Configuration input	COM101, COM102, COM105, COM319, COM365, COM373, COM384, COM386, COM310, COM401, COM402, COM443, COM474, COM489, COM535, COM553
[BSW02046] Configuration of signal notification	COM298, COM300, COM301, COM393
[BSW02089] Timeout indication mechanism on receiver-side [approved]	[17] COM292, COM290, COM291, COM393 Configuration: COM186, COM263, COM264, COM333, COM552
[BSW02088] Value substitution in case of a signal timeout [approved]	COM393
[BSW02083] Transmission modes [approved]	COM329, COM330, COM135, COM276, COM305, COM392, COM277, COM278, COM307, COM308, COM467, COM478, COM494 Configuration: COM351, COM178, COM137, COM180, COM281, COM282
[BSW02082] Two different transmission modes	COM032, COM239, COM244, COM238, COM495 Configuration: COM454, COM455, COM465
[BSW02084] Transmission mode selection	COM274, COM283, COM241, COM245, COM284, COM255, COM032
[BSW02080] Re-triggering of repetitions of I-PDUs	COM279
[BSW02077] Signal invalidation mechanism on sender-side	COM097, COM099, COM286 API: COM203, COM288, COM557 Configuration: COM314, COM315, COM391, COM501
[BSW02079] Signal invalidation mechanism on receiver-side	COM100, COM287, COM323, COM536, COM558, COM559
[BSW02087] Substitution of invalid value by configurable data	COM100, COM412, COM470, COM500

Requirement	Satisfied by
value	
[BSW218] Separate start/stop AUTOSAR COM for separate groups of I-PDUs	COM085, COM114, COM222, COM223, COM228, COM229, COM334, COM090, COM115, COM311, COM187, COM444, COM476, COM479 API: COM190, COM191 Configuration: COM341, COM126, COM184, COM185
[BSW192] Disable reception deadline monitoring	COM092, COM225 API: COM192,
[BSW02081] Re-enable reception deadline monitoring	COM095, COM224, COM486, COM534 API: COM193
[BSW02041] Atomic transfer of complex data types	COM042, COM043, COM047, COM049, COM050, COM051, COM052, COM053, COM327, COM326, COM461, COM464 API: COM199, COM200, COM201, COM202 Configuration: COM345, COM044, COM513, COM520, COM521
[BSW02043] Indication service Com_RxIndication	COM574, COM575 API: COM123
[BSW02044] Confirmation service Com_TxConfirmation	COM260 API: COM124
[BSW02045] Function Com_TriggerTransmit	API: COM001, COM260, COM475
[BSW02030] Identify if a signal is updated by the sender	COM054, COM055, COM056, COM057, COM059, COM061, COM062, COM067, COM076, COM324, COM117, COM310 Configuration: COM257
[BSW02058] Deadline monitoring of receiving updated signals	COM292, COM290, COM291, COM117, COM393

Document: OSEK/ VDX Communication Version 3.0.3 [17]

Requirement	Satisfied by
Filtering (Section 2.2.2 in [17])	COM325, COM380, COM272, COM273, COM132, COM230, COM302, COM303, COM231, COM439, COM480 Configuration: COM339, COM235, COM312, COM313, COM146, COM147, COM317, COM318
Reception deadline monitoring (Section 2.5.1 in [17])	COM292, COM290, COM291
Transmission deadline monitoring (Section 2.5.2 in [17])	COM304, COM445, COM481
I-PDU callout (Section 2.9.3.2, Appendix C in [17])	COM381, COM346, COM347, COM395, COM388, COM492 API: COM348
OSEK APIs	COM197, COM198, COM469, COM562 Configuration: COM340, COM174, COM175, COM176, COM017, COM181, COM119, COM387, COM206, COM233, COM234, COM157, COM158, COM259, COM183, COM263, COM264, COM333, COM344, COM163, COM165, COM232, COM170, COM127, COM169, COM275, COM437, COM471, COM493, COM496, COM497, COM518, COM519
Notifications	API: COM123, COM124 Configuration: COM498, COM499

Document: Requirements on Gateway [9]

Requirement	Satisfied by
Interface between AUTOSAR COM and the lower layer (PDU-Router)	COM138
[BSW06002] Updateable Configuration	COM373, COM357, COM361, COM544, COM545, COM546, COM547, COM548, COM549, COM550, COM551
[BSW06097] Configuration identification	COM374, COM375, COM394, COM487
[BSW06003] Static Routing Rules	COM376 Configuration: COM355, COM358
[BSW06055] Signal Based Gateway	COM377, COM539
[BSW06056] Gateway of Signal Groups	COM361, COM383
[BSW06061] Routing operation on Signals	COM371, COM360, COM361, COM362
[BSW06098]	COM024, COM442, COM459

Requirement	Satisfied by
Signal Gateway Error Handling at signal routing	
[BSW06099] Signal Gateway Error Handling at signal routing	COM024, COM442, COM459
[BSW06077] Routing of multiple signals of the same PDU	COM371
[BSW06089] Timeout handling	COM381, COM377, COM568, COM569, COM570, COM571, COM572, COM573
[BSW06064] Signal gateway scalability	COM370

7 Functional specification

7.1 Introduction

7.1.1 Signal values

The signals sent by AUTOSAR COM respectively received by AUTOSAR COM could have the values defined in Table 1.

Signal value	Remark
init value	See Chapter 7.4.1.4 for details.
data invalid value	See Chapter 7.4.3.6 for details.
<value>	This is the normal case: A valid value after initialization phase which is sent by AUTOSAR COM respectively received by AUTOSAR COM.

Table 1: Possible signal values

7.2 General functionality

7.2.1 OSEK-COM

OSEK COM 3.0.3 is the functional basis of AUTOSAR COM.

COM010: AUTOSAR COM shall implement all the functionality and all the APIs of OSEK/ VDX Communication Version 3.0.3 [17] except the features and APIs mentioned in COM013.

COM011: If this specification defines functionality in a different way compared to definitions in [17], the definitions made in this AUTOSAR COM specification shall be used.

COM012: AUTOSAR COM shall in addition implement all those features, that are defined in this specification and that are not part of [17].

COM013: AUTOSAR COM needs *not* to implement the following features of [17]. If they are implemented in a specific AUTOSAR COM configuration the configuration shall by default disable them. This also applies for all other additional features a specific implementation may offer.

OSEK-COM feature	Rationale	related OSEK COM API
Mapping of a received network message (within an I-PDU) to more than one message data objects (1:n splitting mechanism)	not required, done by the RTE, see [13]	none
Mapping of an internal message to more than one message data objects (1:n splitting mechanism)	not required, done by the RTE, see [13]	none
Mapping an only locally send mes-	not required, done by the	none

OSEK-COM feature	Rationale	related OSEK COM API
sage to both an external send message object and an internal receive message object (1:n splitting mechanism)	RTE, see [13]	
M:1 sending; mapping of messages from multiple senders to one and the same message object	not required, ensured by RTE, see [13]	SendMessage
Queued messages	not required, done by the RTE, see [13]	GetMessageStatus
Zero size messages	it is possible to set up communication without them functionality is partly covered by Com_TriggerTransmit	SendZeroMessage
Dynamic size messages	were introduced for diagnostics, no use case in AUTOSAR	SendDynamicMessage, ReceiveDynamicMessage
Notification mechanisms TASK, FLAG and EVENT	not required, done by the RTE, see [13]	none
Overlapping messages in an I-PDU	no use case, dangerous concept	none
Usage of OIL	not the OSEK OIL shall be used to configure the AUTOSAR COM	none
Application modes	not needed	GetApplicationMode
Start-up behavior	replaced by <ul style="list-style-type: none"> • Com_Init • Com_DeInit • Com_IpduGroupStart • Com_IpduGroupStop 	StartCOM, StopCOM, StartCOMExtensions, InitMessage
Start and stop of periodic messages	no use case, is realized by I-PDU group mechanism	StartPeriodic, StopPeriodic
Reentrancy	Not all of the AUTOSAR API calls are reentrant. See Chapter 8.3.	See Chapter 8.3.
Interface to OSEK indirect NM	not needed	I_MessageTransfer, I_MessageTimeout
Sender side filtering	no use case, the filter conditions are still used in the selection of the transmission mode but there is no signal filtering	none
Network-order message callout CPU-order message callout	Only I-PDU callouts with a defined AUTOSAR interface are supported by AUTOSAR COM. This is to avoid proprietary solutions.	none
Error hook routine	AUTOSAR COM will use a direct interface to DEM/DET instead of using the OSEK COM error hook	COMErrorHook COMError_Name1_Name2 macros COMErrorGetServiceId

<i>OSEK-COM feature</i>	<i>Rationale</i>	<i>related OSEK COM API</i>
Interface for callback routines	The signatures for the used callback function in AUTOSAR COM will be explicitly defined within AUTOSAR COM.	COMCallback
Internal communication	not required, ensured by RTE, see [13]	SendMessage, ReceiveMessage

Table 2: Excluded OSEK COM features in AUTOSAR COM

7.2.2 Endianness conversion and sign extension

COM007: To support the required AUTOSAR data types (signed- and unsigned integer, ASCII, enum, opaque bitfield) the AUTOSAR COM layer shall provide support for endianness conversion of all integer types. Other data types (ASCII, enum, opaque¹) are either treated as signed or unsigned integer or nothing has to be done, i.e. their contents is not interpreted by the AUTOSAR COM layer.

The supported data types of AUTOSAR COM are:

- boolean
- uint8
- uint16
- uint32
- sint8
- sint16
- sint32

uint8[n]

COM472: Opaque data shall always be of uint8[n] and shall always be mapped to an n-bytes sized signal.

Note: For opaque data (see [13]) endianness conversion shall be configured to *Opaque* (see COM157).

COM473: If the endianness conversion is configured to *Opaque* (see COM157) the parameter ComSignalBitPosition (see COM259) shall define the bit0 of the first byte like in little endian byte order.

Remark: [17] Chapter 2.4 defines the endianness conversion for unsigned data types. This endianness conversion shall be extended to signed data types. The associated configurations can be found in the configuration chapter. See also COM127 and COM157.

¹ This Data type represents an array of exactly numberOfBits bits. It is called *opaque* because this array of bits should be transported "as is" by the AUTOSAR communication stack.

COM008: To map negative values of signed data correctly, the received data shall be extended to the size of the receiver (sign extension). The platform specific representation of signed data shall be taken into account.

Example: A 10-Bit signed signal is received and shall be copied by Com_Receive-Signal to a 16-Bit signed integer variable. If $(-3)_{\text{decimal}}$ is received the received 10-Bit signal has a value of 1111111101b. While copying it to the 16-Bit integer variable the value has to be extended to 1111111111111101b.

COM353: On sender side there shall be no sign extensions.

COM221: Endianness conversion shall take place before the I-PDU callout on the sender side. (For an overview see Chapter 7.12).

COM352: Sign extensions and endianness conversion shall take place before configuration filtering and notification detection on receiver side

7.2.3 Filtering

COM272: Each filtering condition shall either evaluate to true or false. Filtering out signals shall only take place at receiver side. On sender side the mechanisms are still used for Transmission Mode Conditions (TMC) but no signal filtering shall take place.

Note: For Transmission Mode Selection (TMS) see Chapters 7.4.3.4 and 7.4.3.3.

COM480: AUTOSAR COM shall only provide the following filter types which are defined in [17]

- F_Always
- F_Never
- F_MaskedNewEqualsX
- F_MaskedNewDiffersX
- F_MaskedNewDiffersMaskedOld
- F_NewIsWithin
- F_NewIsOutside
- F_OneEveryN

Note: Some filters defined in [17] are removed from AUTOSAR COM to reduce complexity. The removed filters were either obsolete or special cases of other filters. For example the filter F_NewIsDifferent is a special case of F_MaskedNewDiffersMaskedOld with a fully set mask.

COM325: All filter mechanisms defined in COM480 shall be supported for all data types listed in COM007; considering the exceptions defined in COM380 and COM439.

COM380: For the type uint8[n] only the filters F_Always and F_Never shall be supported.

COM439: For the type boolean only the following filters shall be supported:

- F_Always
- F_Never
- F_MaskedNewEqualsX
- F_MaskedNewDiffersX
- F_MaskedNewDiffersMaskedOld
- F_OneEveryN

COM273: If a signal is filtered out on receiver side (i.e. filter condition evaluates to FALSE), it shall be discarded and not be further processed. See also COM303.

COM327: Filtering out of signals as specified in COM273 shall not be applied to group signals.

Note: Conditions for TMS may be applied to group signals, see COM326.

COM132: The filtering mechanisms, defined in [17] and in Chapter 7.4.3.3 shall also be supported for signed data types.

In the case a filter is evaluated before a signal has been written to by a send-API, there needs to be a way to determine the filter state of this signal. Some of the filters require a *new_value* to evaluate the filter. However, this is only available after the signal has been updated using a send-API. So it is necessary to define the value used by the filter for *new_value* in the period before the first send takes place.

COM230: The *old_value* of the filtering mechanisms is set during start-up to the init-value, see [17]. Up to the point in time where the application has not updated the value, for the *new_value* also the init-value shall be used.

The next two requirements shall clarify the definitions of [17] according to the update of the *old_value* of filters.

COM302: If a filter is evaluated to true (value is not filtered out) then the value is placed into *old_value* (as defined in [17]).

COM303: When a value is being filtered, if the filter does not allow the passage of the value (i.e. the filter evaluates to false) then the value is not placed into *old_value* (as defined in [17]).

COM231: In the case of the filter F_OneEveryN,

- OCCURRENCE shall be set to zero by Com_IpduGroupStart
- FILTER shall be set true when OCCURRENCE == OFFSET
- OCCURRENCE shall be incremented after filter processing
- When OCCURRENCE == PERIOD, OCCURRENCE shall be set to zero.

For definition of OCCURRENCE, FILTER, OFFSET and PERIOD see [17].

This definition of the filter `F_OneEveryN` has the effect that the signal is passed by the filter (i.e. the filter returns true) once every `PERIOD` call of the filter. If the `OFFSET` parameter is zero then the first time the filter is used the signal is allowed to pass (i.e. filter returns true). If the `OFFSET` is greater than zero then more than one message must pass through the filter before it returns true.

This definition exists to clarify the description of the `F_OneEveryN` filter in [17].

The associated configuration items can be found in the configuration chapter, see COM339.

7.2.4 Signal Gateway

AUTOSAR COM provides a signal gateway for forwarding signals and signal groups in a 1:n manner.

Signals and signal groups to be routed by the signal gateway are identified and configured by unique static names. The signal gateway determines the destination of a signal or of a signal group by using its name and a configuration table.

COM370: Furthermore the signal gateway should scale down to no size if no signal routing functionality is needed.

COM371: The signal gateway is placed as shown in Figure 3, Figure 13, Figure 14 and Figure 15.

7.3 Configuration

See Chapter 10.

7.4 Normal operation

7.4.1 Start-up behavior

This chapter describes the actions which shall be performed during `Com_Init`.

COM217: The I-PDU init value (Chapter 7.4.1.3) and the signal / update-bit init value (Chapter 7.4.1.4) together result in one init value for each I-PDU. During `Com_Init` this init value shall be used to initialize the I-PDU.

7.4.1.1 Preconditions

Note: The C initialization code (also known as *start-up code*) which initializes global and static variables with the initial values shall be executed before any call of an AUTOSAR COM service.

7.4.1.2 Initialization

COM128: All internal data that is not yet initialized by the *start-up code* e.g. C-structs shall be initialized by `Com_Init` (see COM432).

COM328: The AUTOSAR COM initialization routine shall not enable Inter-ECU communication. Inter-ECU communication requires a separate start (see Chapter 7.4.5 for details).

The API function is defined by COM432.

Note: This initialization chapter is not complete. Details about initialization of some COM features are described within the different feature chapters.

7.4.1.3 Initialization of not used areas of an I-PDU

COM015: AUTOSAR COM shall fill not used areas within an I-PDU with a value configurable at configuration-time, e.g. 0xFF.

See also COM017 for the associated configuration element.

7.4.1.4 Initialization of signals and Update-bits

COM098: AUTOSAR COM shall initialize all signals on sender and receiver side with the configured init values which shall be the same value as used for the initialization of the signal in the related I-PDU (see COM217). For configuration see COM170 in the configuration chapter.

The signal init values may be identical to the AUTOSAR COM data invalid values. These may be different for each signal. For the related configuration items see COM391 and COM501.

COM117: AUTOSAR COM shall clear all update-bits during initialization. See also COM059.

7.4.1.5 Initialization of I-PDU groups

COM444: By default all I-PDU groups shall be in the state 'stopped' and they shall not be started automatically while AUTOSAR COM initialization.

7.4.2 Shutdown behavior

7.4.2.1 De-initialization

COM129: AUTOSAR COM shall provide a functionality to de-initialize the layer. This means that after de-initialization of the layer no communication via AUTOSAR COM is possible and all started I-PDU groups are stopped.

The API function is defined by COM130.

7.4.3 Communication modes

This chapter defines the signal flow in AUTOSAR COM and how the different transmission modes in AUTOSAR COM are defined. Chapter 7.4.3.6 shows exemplary communication use cases that can be solved with AUTOSAR COM. Chapter 7.4.3.3 defines a mechanism to switch between two transmission modes for one I-PDU. The replication of signals is defined in Chapter 7.4.3.5.

7.4.3.1 Transfer Properties and I-PDU Transmission Modes

7.4.3.1.1 Signals

[17] distinguishes between:

- Transfer properties (applies for signals)
- Transmission modes (applies for I-PDUs).

The following two tables are derived from [17]. *The AUTOSAR extensions are marked with bold and configuration letters.*

<i>TRANSFER PROPERTY</i>	<i>Description</i>
<i>(per signal)</i>	
TRIGGERED	COM329: The triggered transfer property causes immediate transmission of the I-PDU, except if transmission mode <i>PERIODIC</i> or transmission mode NONE is defined for the I-PDU (see Table 4).
PENDING	The <i>PENDING</i> transfer property does not cause transmission of an I-PDU.
TRIGGERED_ON_CHANGE	COM563: <i>At a send request of a signal with ComTransferProperty TRIGGERED_ON_CHANGE assigned to an I-PDU with ComTxModeMode DIRECT or MIXED, the AUTOSAR COM module shall immediately initiate ComTxModeNumberOfRepetitions transmissions of the assigned I-PDU if the new value of the sent signal differs to the locally stored (last sent or init) value.</i>

Table 3: Transfer Properties defined for signals

Note: A pending signal associated with an I-PDU is transmitted if either a signal with *TRIGGERED* transfer property within the same I-PDU is sent or the I-PDU is sent because of a timer (Periodic / Mixed transmission mode).

<i>Transmission mode</i> <i>(per I-PDU)</i>	<i>Description</i>
DIRECT (N-Times)	COM330: Transmission of an I-PDU with Direct transmission mode is caused by the transfer of any signal assigned to the I-PDU with the <i>TRIGGERED</i> or <i>TRIGGERED_ON_CHANGE</i> transfer property. The transfer of the signal to AUTOSAR COM is immediately followed by <i>n</i> transmissions ($n = 1 \dots m, m \leq 255$) on the underlying layer (associated requirements see 7.4.3.5).
<i>PERIODIC</i>	In Periodic transmission mode, AUTOSAR COM issues periodic transmission requests for an I-PDU to the underlying layer.
<i>MIXED</i>	Mixed transmission mode is a combination of the “Direct/N-Times” and the Periodic transmission modes.
NONE	COM135: <i>In transmission mode “None” no transmission is initiated by AUTOSAR COM. It shall only be possibly to request I-PDUs with Com_TriggerTransmit (see COM001). The configuration is defined by COM137.</i>

Table 4: Transmission modes defined for I-PDUs

On the one hand the timing of bus messages can be controlled by send requests of the upper layer in combination with the transmission mode and the transfer property as described above. On the other hand it can be controlled by the lower layer (esp. for FlexRay and LIN) with the service Com_TriggerTransmit. In this case the lower layer requests I-PDUs that have to be provided by COM.

COM260: It shall be possible to use Com_TriggerTransmit to request the transmission of any I-PDU with any transmission mode.

Note: This allows LIN and FlexRay to use all the available transmission modes, particularly for sporadic communication. This mechanism is also used by the NM to send user data.

7.4.3.1.2 Signal Groups

In AUTOSAR COM also signal groups and group signals may have a transfer property, defining in combination with the transmission mode, if the I-PDU is sent out in case of an update of a signal group or group signal, respectively.

<i>TRANSFER PROPERTY</i> <i>(per signal group)</i>	<i>Description</i>
TRIGGERED	COM564 : The triggered transfer property causes immediate transmission of the I-PDU, except if transmission mode <i>PERIODIC</i> or transmission mode <i>NONE</i> is defined for the I-PDU (see Table 4).
PENDING	COM565 : The “Pending” transfer property does not cause transmission of an I-PDU.
TRIGGERED_ON_CHANGE	At a send request of a signal group with ComTransferProperty <i>TRIGGERED_ON_CHANGE</i> assigned to an I-PDU with ComTxModeMode <i>DIRECT</i> or <i>MIXED</i> two cases shall be distinguished:

	<p>COM566: If none of the signal group's group signals has a ComTransferProperty specified, the AUTOSAR COM module shall immediately initiate ComTxModeNumberOfRepetitions transmissions of the assigned I-PDU, if at least one new value of the signal group's group signals differs to the locally stored (last sent or init) value.</p> <p>COM567: If at least one group signal of a signal group has the ComTransferProperty configured, all other group signals of that signal group shall have configured ComTransferProperty as well. If the ComTransferProperty is set to <i>PENDING</i>: a change of the value of this group signal shall trigger the transmission of the assigned I-PDU. If the "ComTransferProperty" is set to <i>TRIGGERED_ON_CHANGE</i>, a change of the value of this group signal shall trigger the transmission of the assigned I-PDU.</p>
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7.4.3.2 Link to the VFB specification

Note: This chapter is just an illustration how the transfer mode relates to the VFB specification and links to a non normative part of the VFB specification.

Because, from the point of view of the AUTOSAR SW Component, it is not known at implementation time, which communication media is used, all bus specific replications of send requests by a SW component to underlying layers as well as all bus specific timing behavior must be done either by AUTOSAR COM or by the appropriate bus interfaces and drivers.

AUTOSAR COM implements the replication of transmission requests and the bus specific timing behavior by a combination of transfer properties and transmission modes, which is shown in the table below. The entries in the table correspond to the VFB's send modes:

<i>Transfer property (horizontal) Transmission mode (vertical)</i>	<i>TRIGGERED/ TRIGGERED_ON_CHANGE</i>	<i>PENDING</i>
Direct/N-Times	N-Times	--
Periodic	--	Cyclic
Mixed	N-Times	Cyclic
None	--	--

Table 5: Mapping of transfer property and transmission Mode (I-PDU) to send modes defined in the AUTOSAR Specification of the Virtual Functional Bus [6]

7.4.3.3 Selection of the Transmission Mode for one specific I-PDU

Signals are carried by I-PDUs. Because an I-PDU can contain more than one signal, in the following, a method is defined to derive the I-PDU's transmission mode from the state of the signals that are contained in one specific I-PDU.

AUTOSAR COM allows configuring statically two different transmission modes for each I-PDU (see COM032). The transmission mode of an I-PDU that is valid at a specific point in time is selected using only the values of the signals that are mapped to this I-PDU.

The signals of one I-PDU that contribute to the selection of one of the two transmission modes as well as the conditions used for the selection of the transmission mode are configured statically.

COM326: For the selection of the transmission mode the group signals shall be treated like normal signals. Therefore each group signal shall contribute, depending on its configuration, to the evaluation of the transmission mode.

The following definitions give an overview about terms used in the following specification articles.

Definitions	
s_i	Signal in AUTOSAR COM
$IPDU_k$	I-PDU in AUTOSAR COM
$C(s_i, IPDU_k)$	Transmission Mode Condition (TMC), condition attached to a signal (s_i) within an I-PDU ($IPDU_k$)
S_k	The set of all signals (s_i) within one I-PDU ($IPDU_k$)
M_k	The set of all signals (s_i) within one I-PDU ($IPDU_k$) which contribute according to their configuration to the selection of the transmission mode. M_k has to be a subset of S_k .
TMS_k	The Transmission Mode Selector (TMS) is calculated from the evaluation of all $C(s_i, IPDU_k)$ for all s_i in M_k

Table 6: Definitions for transmission mode selection

COM274: To each signal (s_i) mapped to a specific I-PDU ($IPDU_k$) a condition $C(s_i, IPDU_k)$ shall be associated (see COM275).

COM283: The conditions $C(s_i, IPDU_k)$ available shall be the same as provided for the filter mechanism (see COM272 and COM480). The definitions made in COM230 and COM231 shall also be applied for the evaluation of the TMS.

Definition: (see also [17])

For each I-PDU ($IPDU_k$) a Transmission Mode Selector (TMS_k) is defined. TMS_k is calculated by evaluating the conditions $C(s_i, IPDU_k)$ for a configurable subset of signals M_k (see COM275) of the set of all signals S_k mapped to the $IPDU_k$.

TMS_k is defined to be true, if at least one $C(s_i, IPDU_k)$ in M_k evaluates to true and is defined to be false, if all $C(s_i, IPDU_k)$ in M_k evaluate to false.

$$TMS_k = \begin{cases} \text{true, if at least one } C(s_i, IPDU_k) \equiv \text{true for all } s_i \in M_k \\ \text{false, if } C(s_i, IPDU_k) \equiv \text{false for all } s_i \in M_k \end{cases}$$

Table 7: Calculation of transmission mode selector

COM241: AUTOSAR COM shall be able to define and calculate a TMS for each I-PDU as defined in the definition given above.

COM245: The TMS of each I-PDU containing a specific signal shall be re-calculated within a call of Com_SendSignal respective Com_SendSignalGroup by the upper layers for that specific signal.

COM284: AUTOSAR COM must provide the mechanisms to specify which signals shall contribute to the evaluation of TMS, i.e. to define the set of signals M_k that contribute to the evaluation of the TMS_k .

For the configuration see COM275.

COM255: If no signal within an I-PDU is configured to contribute to the calculation of the TMS, the TMS shall be set to true.

Comment: Note that a signal with $C(s_i, IPDU_k)$ F_ALWAYS – if it contributes to the selection of the transmission mode – will always set the TMS of the respective I-PDU to true. Therefore, care must be taken when defining the signals that contribute to the TMS.

COM032: On sender-side two independent transmission modes shall be configured for each I-PDU. One of those transmission modes shall be valid if the TMS evaluates to true, the other transmission mode shall be valid, if the TMS evaluates to false.

The transmission modes, which can be configured separately for each evaluation result, are defined in the configuration chapter, see COM233 and COM234.

COM238: In each of the two TMS states, the rules for combination of transfer properties of signals and transmission modes of I-PDUs shall apply as defined in [17], Section 2.3.

COM239: When the TMS state changes, the now valid transmission mode shall immediately be used. That means, first the mode change shall be done and after that the appropriate requests to the underlying layers, resulting from the request causing the mode change shall be executed.

COM244: If a change of the TMS causes a change of the transmission mode for one I-PDU, the timer for the cycle time of the Periodic and the Mixed transmission mode shall be restarted.

COM495: By a TMS-switch to the Cyclic or Mixed transmission mode the new cycle shall start with an immediate transmission request to the underlying layers respecting the MDT. See also Figure 6.

Remark: In case the TMS evaluates to false, it shall be possible to configure the transmission mode in that way that no transmission takes place (transmission mode

None). This prevents the I-PDU to be transmitted and shall be the default. For the configuration see COM234.

COM478: An I-PDU shall be sent out at most once while one call to Com_MainFunctionTx.

7.4.3.4 Signal flow and Transmission Mode Selection

After a send request from an upper layer for a specific signal the signal is written to the appropriate I-PDU buffer as defined by configuration and the selection of the transmission mode of the I-PDUs is done according to Chapter 7.4.3.3.

Figure 3 shows the signal flow:

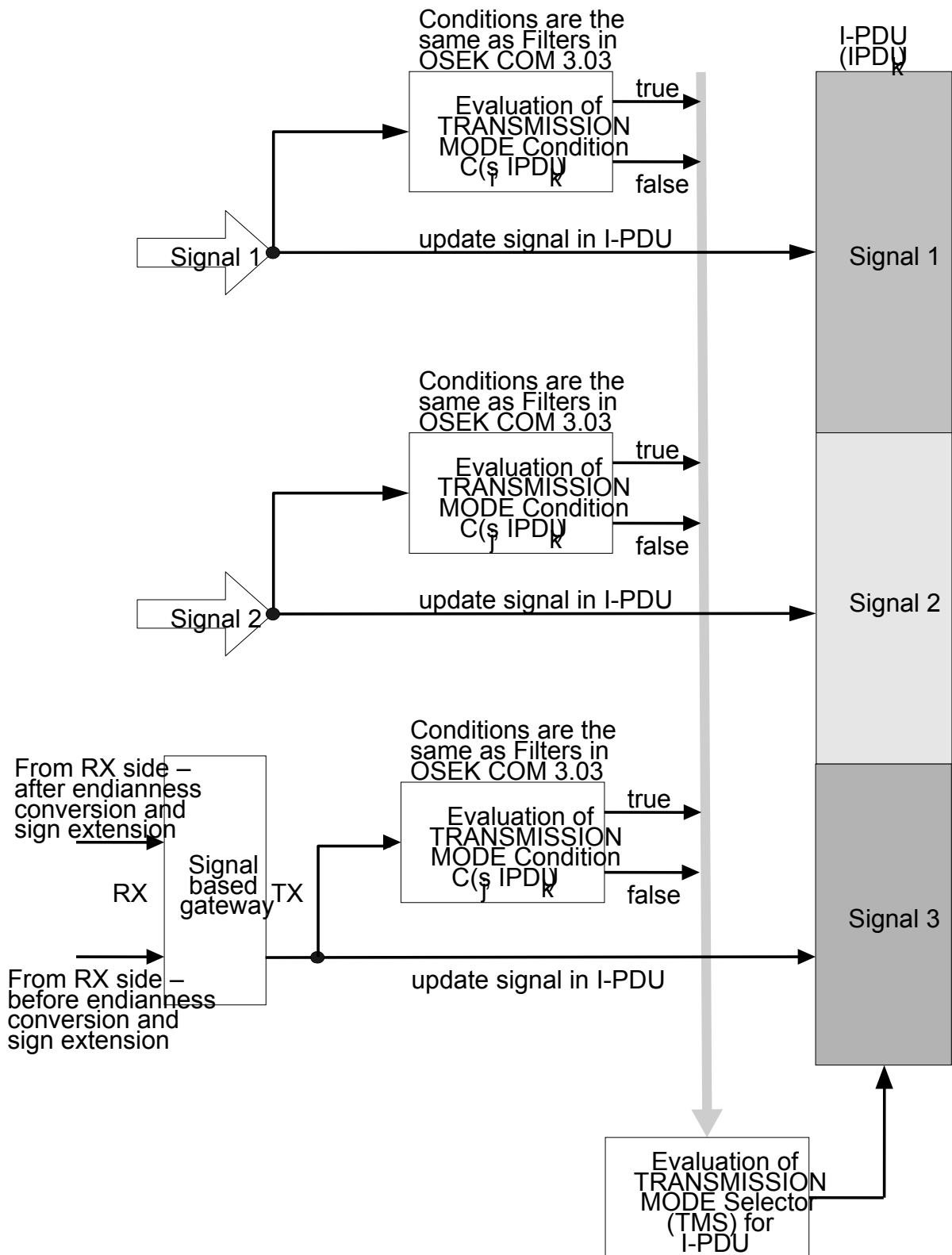


Figure 3: Logical signal flow in AUTOSAR COM shown for two signals (Signal1 and Signal2) that are mapped to one I-PDU (IPDU_k)

7.4.3.5 Replication of Signal Transmission Requests

COM276: In the Direct/N-Times and Mixed transmission modes AUTOSAR COM shall be able to send n transmission requests ($n = 0, 1 \dots m, m \leq 255$) to the lower layer for each send request by an upper layer. See also the matching configuration requirement COM281.

COM467: If Direct/N-Times or Mixed transmission mode with $n == 0$ is used this shall result in only one send request without waiting for any confirmation (original OSEK behavior for Direct transmission mode).

COM279: If a new send request is received from an upper layer while sending n transmissions belonging together (e.g. after the 3rd of 5 repetitions, see COM276) AUTOSAR COM shall cancel the outstanding transmission repetitions and start processing the new request immediately, see Figure 4.

COM305: The confirmation behavior to the upper layer in the Direct/N-Times transmission mode with $n > 0$ shall be according to the following definition:

- 1) When an I-PDU is sent by the application with Direct/N-Times transmission mode, n is put into a counter in COM.
- 2) COM sends to the underlying layer an N-Times I-PDU periodically as long as the counter is non-zero.
- 3) Whenever a TX confirmation is received and the counter is greater than 0, the counter is decremented. When the counter is 0, transmission confirmations for that I PDU are ignored.
- 4) When the counter reaches 0 the transmission confirmation is send to the upper layer and transmission deadline monitoring is cancelled (if configured). See COM392 and Chapter 7.4.6.2.

Note: The definition in COM305 shall not define a concrete implementation. But every implementation shall implement the confirmation behavior according to the above definition.

Note: This solution allows the violation of the period in certain extreme circumstances when the confirmations arrive late in the period.

This solution requires that CAN does not have a queue for these L-PDUs.

There is a race condition in the interaction between the CAN driver, interface and hardware that may cause an extra transmission to occur in certain unlikely circumstances.

Note: If the underlying layer returns E_NOT_OK while an N-Times transmission is in progress this error notification shall be ignored (as defined in COM428). As COM305 specifies only confirmed transmissions are counted for the N-Times transmission, erroneous send request can safely be ignored.

Note: If the N-Times transmission is requested in Mixed transmission mode after a Cyclic transmission of the Mixed transmission mode with a pending confirmation, the confirmation of the cyclic transmission will be assigned to the N-Times transmission. In this case only $n-1$ transmissions of the new value of the N-Times request are

made, if no confirmation gets lost. The transmission deadline monitoring timer will then be reset earliest after the N-Times request is completed. This must be respected when configuring the transmission deadline monitoring timer in conjunction with the Mixed transmission mode and N-Times transmission.

COM494: If within the Mixed transmission mode an N-Times transmission request overlaps with the cyclic part of the Mixed transmission the Cyclic transmission shall be counted as the corresponding transmission of the N-Times transmission request.

COM392: If a transmission deadline monitoring timeout occurs before the N-Times transmission is complete, the N-Times transmission shall be abandoned.

Note: The minimum delay time shall always be taken into account as defined in [17].

Note: To avoid bursts in start-up a time offset can be configured per I-PDU. For details see COM180.

COM277: The number of repetitions (n) shall be configurable (see COM281).

COM278: The time between two repetitions shall be configurable (see COM282).

Note: If the transmission mode change leads to the start of the Mixed transmission mode by sending a triggered signal and ComTxModeNumberOfRepetitions is configured > 1 then there will be at least n transmission requests to the lower layer at the beginning of the Mixed transmission mode. See also COM276.

COM310: It shall not be possible to use/configure update-bits for signals that are transmitted within I-PDUs having the Direct/N-Times transmission mode with $n \geq 1$. (I.e. only $n=0$ is allowed).

Note: There is no common understanding how update-bits and N-Times transmission can be combined. It is unclear when update-bits shall be set and cleared respecting the replication. Therefore this is currently forbidden.

7.4.3.6 Use Cases for communication modes

This chapter shows use cases which have to be realizable by the transmission modes and transfer properties specified in AUTOSAR COM.

Note: For a more detailed discussion of the following use cases see Appendix A.




Use case diagram legend	
t_c, t_{c1}, t_{c2}	Cycle times
t_d	Cycle time of N-Times send signals
$t_{r, min}$	Minimum SW reaction time of COM-Layer, e.g. due to internal cycle time
V	Value: x stands for an arbitrary value / value range, a...w for specific values / value ranges, defined by the user, with $a <> b$, range a is disjoint from range b.
	Request from upper layers (RTE) to the COM-Layer
	Request from COM-Layer to lower layers (PDU-Router)
	Potential but skipped request from COM-Layer to lower layers (e.g. because of a new send request by upper layers or delayed due to minimum delay time)
dt	Minimum distance between two requests to lower layers (minimum delay time), dt can be set per I-PDU.
w/o TMS switch	Without switching of the TMS (see 7.4.3.3) from true to false or vice versa.
w TMS switch	With switching of the TMS (see 7.4.3.3) from true to false or vice versa (from TM 1 to TM 2) One TM is named before the "+" and one behind in the description.

Table 8: Legend for use case diagrams.

Use case diagrams:

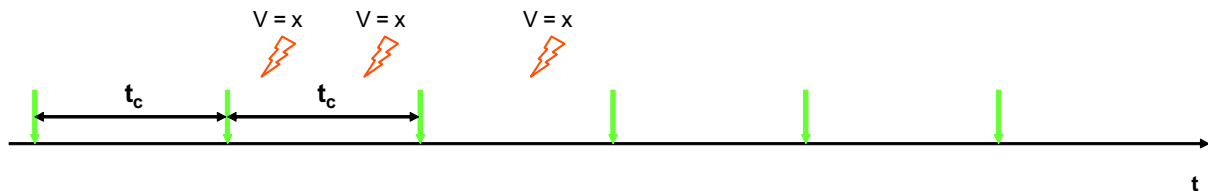


Figure 4: Use case 1, TM Periodic (without TMS switch)

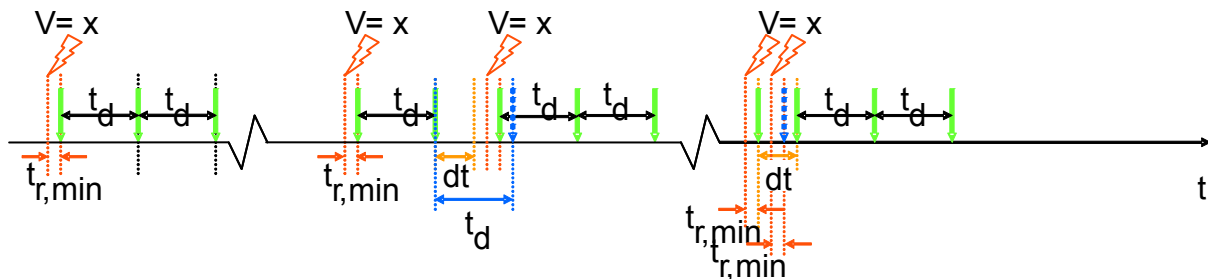


Figure 5: Use case 2, TM Direct/N-Times, here n = 3 (without TMS switch)

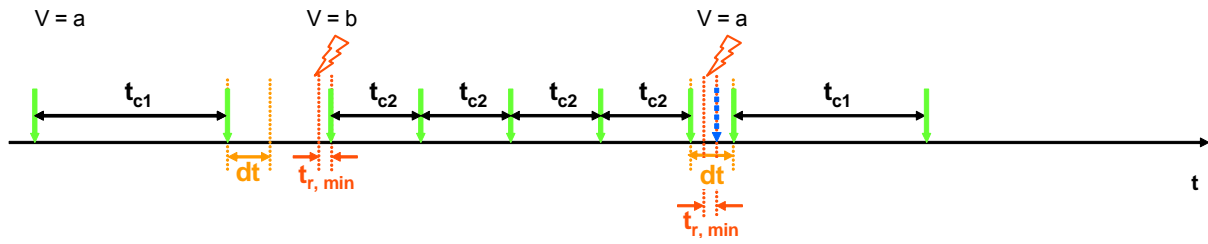


Figure 6: Use case 3, TM Periodic + Periodic (with TMS switch)

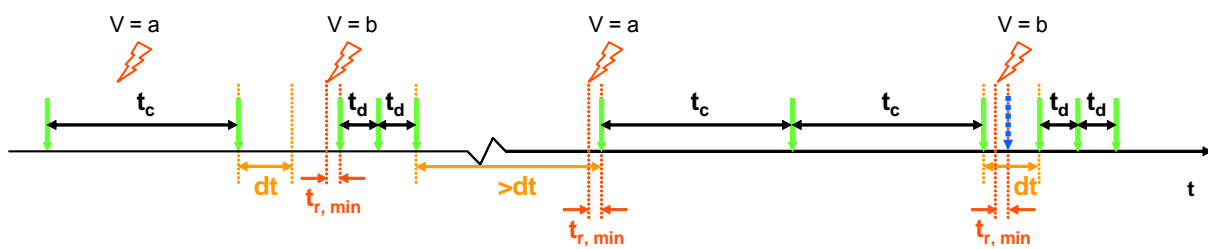


Figure 7: Use case 4a, TM Periodic + Direct/N-Times, here n = 3 (with TMS switch)

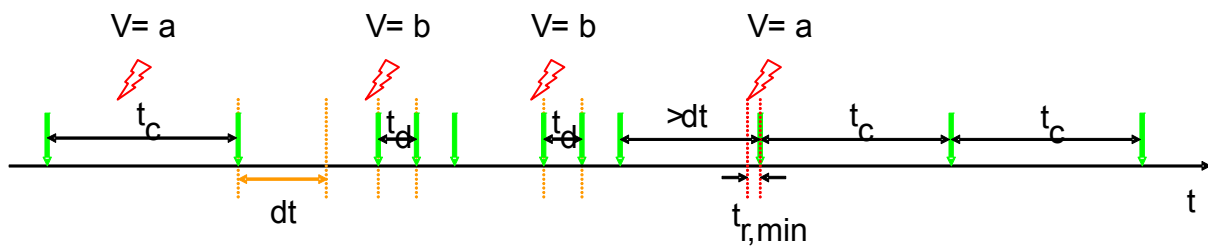


Figure 8: Use case 4b, TM Periodic + Direct/N-Times, here n = 3 (with TMS switch)

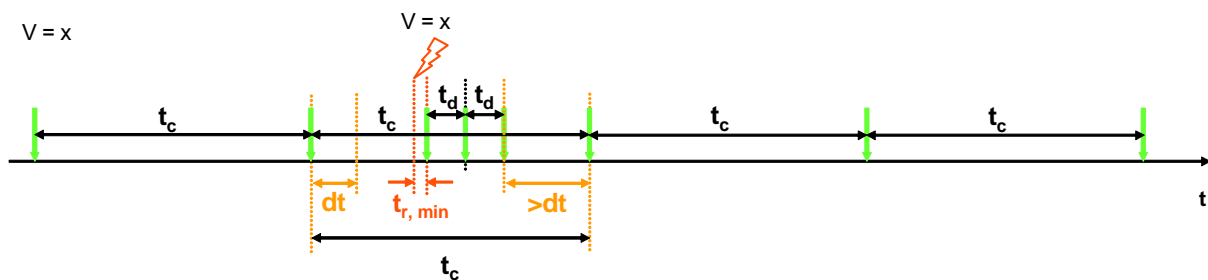


Figure 9: Use case 5a, TM Mixed, here n = 3 (without TMS switch)

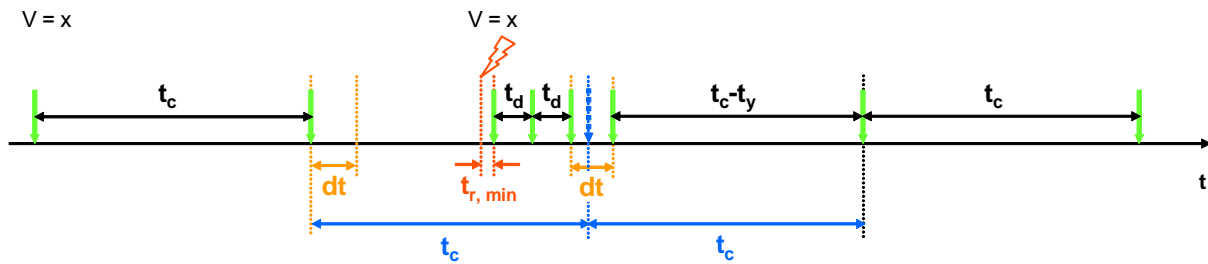


Figure 10: Use case 5b, TM Mixed, here $n = 3$ (without TMS switch)

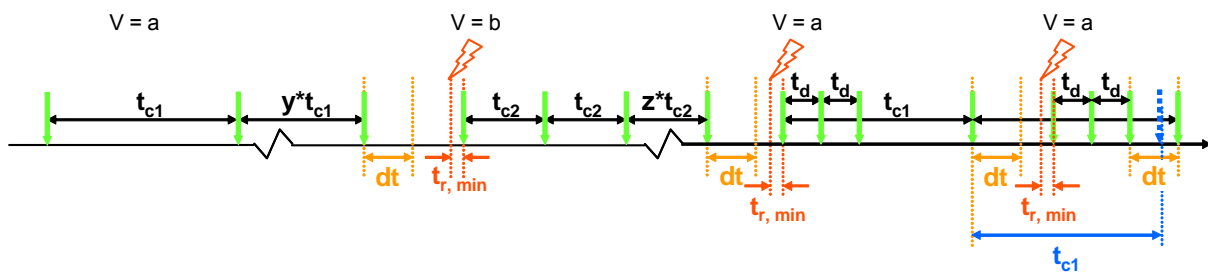


Figure 11: Use case 6, TM Mixed, here $n = 3 + \text{Periodic}$ (with TMS switch)

7.4.4 Signal invalidation mechanism

COM097: It shall be possible for the sender side to indicate AUTOSAR COM that it is not able to provide a valid value for a corresponding signal (e.g. sensor is faulty). It shall be possible during configuration to define a *data invalid value* (for configuration see COM501).

7.4.4.1 Transmission of an invalidated signal

COM099: AUTOSAR COM shall replace the current value of a signal by the data invalid value if the AUTOSAR software component indicates that it is not able to provide a valid value, see also Com_InvalidateSignal. AUTOSAR COM shall internally perform a Com_SendSignal with the configured data invalid value. For the associated configuration elements see COM501. Therefore the transmission of the data invalid value on the bus is determined by the transfer property and the transmission mode.

Note: The internally performed Com_SendSignal with the data invalid value leads to data invalid value to be used as current value for filters and TMS.

COM286: By a call of Com_InvalidateShadowSignal AUTOSAR COM shall replace the current value of the signal with the given SignalId within the associated signal

group by the configured data invalid value. By this call no send request shall be initiated.

Note: Compared to Com_InvalidateSignal, there is no send request associated with Com_InvalidateShadowSignal.

Note: The RTE has to call Com_InvalidateShadowSignal for each signal inside a signal group.

Example with 2 signals signal_a and signal_b which belong to group_x:

```
/* invalidate signal a in shadow buffer with configured data invalid value */  
Com_InvalidateShadowSignal (signal_a);  
  
/* invalidate signal b in shadow buffer with configured data invalid value */  
Com_InvalidateShadowSignal (signal_b);  
  
/* copy shadow buffer to I-PDU */  
Com_SendSignalGroup (group_x);
```

The data invalid values are configured per group signal see COM391.

Note: The invalidation of the whole signal group results in a consistent state of the signal group during transmission.

Note: The VFB defines only one attribute for a complex data type. Therefore the best mapping of an invalidated complex data type to an invalidated signal group is to invalidate all group signals of a signal group.

7.4.4.2 Reception of an invalidated signal

COM100: Receiver side AUTOSAR COM module shall provide the following configuration options:

- **InvalidNotification**
The reception of an invalidated signal shall be notified by the function configured by COM315. The normal signal indication shall not take place.
- **ReplaceValue**
When an invalidated signal is received, this signal value shall be replaced by the init value. Only the normal signal reception indication shall take place (if configured).
- **no invalidation handling**
In case no ComDataInvalidAction is configured for a (group) signal, the AUTOSAR COM module, shall handle a reception of this signal always like a reception of valid value.

The last option is useful if a system signal has a globally defined invalid value, but shall be handled specially on certain ECUs.

COM287: The mechanisms as described in COM100 shall also be applicable for signal groups:

- **InvalidNotification**
If at least one of the signals inside a signal group is identified as invalid, an invalid notification for the whole signal group shall take place. In this case, the normal signal group indication shall not take place
- **ReplaceValue**
If at least one of the signals inside a signal group is identified as invalid, all associated signals shall be replaced by their init value. In this case, only the normal signal group reception indication for this signal group shall take place.
- **no invalidation handling**
In case no ComDataInvalidAction is configured for a signal group, the AUTOSAR COM module, shall handle a reception of this signal group always like a reception of valid signal group.

The last option is useful for example, in case one ECU needs to receive partial values of a signal group, even in case some of the signals are invalidated. In this case the concrete invalidation handling is done in the SWC.

COM323: For signals groups it shall be possible to configure an invalid notification for the whole signal group and additionally for each group signal.

The corresponding configuration parameters are ComDataInvalidAction, ComInvalidNotification and ComSignalDataInvalidValue.

COM558: If the configured ComSignalDataInvalidValue is received for a signal and its ComDataInvalidAction is configured to NOTIFY, the AUTOSAR COM module shall not store the received ComSignalDataInvalidValue into the signal object.

The next call to Com_ReceiveSignal will return the last valid reserved signal or the ComSignalInitValue in case no signal was received yet respectively.

COM559: If the configured ComSignalDataInvalidValue is received for at least one group signal of a signal group and its ComDataInvalidAction is configured to NOTIFY, the AUTOSAR COM module shall not store any of the received group signals into the signal objects.

The next call to Com_ReceiveSignalGroup will copy the last valid reserved group signals or the ComSignalInitValues in case the signal group was not received yet respectively into the shadow buffer.

7.4.5 Handling of I-PDUs

7.4.5.1 Definitions

For the definition of an I-PDU group see [7] and Figure 12. For the configuration of I-PDU groups see COM206 and COM126.

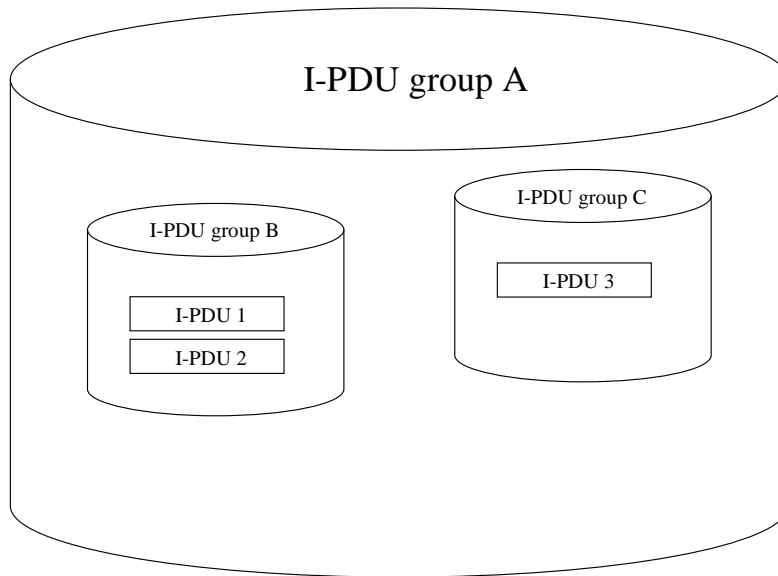


Figure 12: Grouping of I-PDUs and I-PDU groups

COM187: The number of supported I-PDU groups per ECU shall be limited to a maximum of 64.

7.4.5.2 Separate Start/Stop AUTOSAR COM for separate groups of I-PDUs

7.4.5.2.1 Starting of I-PDU groups

By default all I-PDU groups are stopped, see COM444.

COM085: AUTOSAR COM shall provide a routine which starts communication per I-PDU group. The name of the routine shall be `Com_IpduGroupStart`, see COM191. A reference to the I-PDU group shall be transferred in the call to `Com_IpduGroupStart`.

COM114: Starting an I-PDU group shall permit to transmit/receive I-PDUs which belong to the I-PDU group, see also Table 10.

COM222: If an I-PDU group is started by `Com_IpduGroupStart` with parameter `Initialize` set to true the following attributes (see also Chapter 9.2) for each I-PDU belonging to the group shall be initialized:

- time period and offset attributes of I-PDUs in Periodic or Mixed transmission mode
- the minimum delay time attribute of I-PDUs in Direct/N-Times or Mixed transmission mode
- timeout attributes of I-PDUs for deadline monitoring aspect. All timeout timers (`ComSignalFirstTimeoutFactor`, `ComSignalTimeoutFactor`, `ComSignalGroupFirstTimeoutFactor`, `ComSignalGroupTimeoutFactor`) shall restart

- all included update-bits shall be cleared

COM223: If an I-PDU group is started, the transmission mode of all associated I-PDUs is determined by the current data content of the I-PDU. E.g. transmission of periodic I-PDUs is started according to their TMS-switch.

Note: In order to disable transmission of a group of I-PDUs, the I-PDUs are put into an I-PDU group which is then stopped. This mechanism allows implementing listen-only-mode. Receiving of I-PDUs may be stopped also. Note that an I-PDU group cannot contain a mixture of send I-PDUs and receive I-PDUs.

COM228: When an I-PDU group containing an I-PDU is started but one or more signals in that I-PDU have not yet been written to via one of the send-APIs, the initial value is used to determine the transmission mode.

COM229: When an I-PDU group containing an I-PDU is started but one or more signals in that I-PDU has been written to via one of the send APIs by the higher layer, the most recently sent values are used to determine the TMS of this I-PDU.

COM476: If by starting an I-PDU group (or a contained I-PDU group) an already started I-PDU is started again the further starts shall be ignored.

COM561: If an I-PDU is started by a call to `Com_IpduGroupStart` and the I-PDU contains signals that have deadline monitoring configured (COM183, COM263), the AUTOSAR COM module shall start the deadline monitoring for these signals independently of the value of the initialize parameter.

7.4.5.2.2 Stopping of I-PDU groups

COM090: AUTOSAR COM shall provide a routine which supports the possibility of stopping communication per I-PDU group. The name of the routine shall be `Com_IpduGroupStop`, see COM190. A reference to the I-PDU group shall be transferred in the call to `Com_IpduGroupStop`.

COM334: If an I-PDU-group is stopped, a call of the functions: `Com_SendSignal`, `Com_UpdateShadowSignal`, `Com_SendSignalGroup`, `Com_InvalidateSignal` and `Com_InvalidateShadowSignal` shall still update the values in the COM internal buffers, see Table 9.

Note: If a signal is written to an I-PDU that belongs to a stopped I-PDU group and this write would trigger the transmission of the I-PDU if it was not stopped then this trigger shall not be stored. After re-starting the corresponding I-PDU group such an old trigger shall not lead to an immediate transmission of the I-PDU.

COM115: Stopping I-PDU groups shall disable transmission of I-PDUs which belong to the I-PDU group. Only the `Com_TriggerTransmit` function is processed because this can not be prohibited by AUTOSAR COM. Deadline monitoring for pending confirmations shall be cancelled. Transmit confirmations shall be ignored. Stopping I-PDU groups shall disable processing of received I-PDUs which belong to the I-PDU group. Reception deadline monitoring shall be cancelled.

COM479: If an I-PDU group is stopped all outstanding not confirmed transmitted signals/ signal groups shall immediately receive an error notification if configured, see COM499 and COM511.

COM461: A call to Com_ReceiveSignalGroup shall always copy the last known data (or the init value) of the I PDU to the shadow buffer even if the I-PDU is stopped and COM_SERVICE_NOT_AVAILABLE is returned.

Note: If by stopping an I-PDU group (or a contained I-PDU group) an already stopped I-PDU is stopped again this has no effect.

Table 9 gives an overview of the behavior of stopped I-PDU groups:

Behavior on a stopped I PDU group	
Receiver side (RX)	Transmitter side (TX)
<ul style="list-style-type: none"> • disable RX deadline monitoring • no action on a Com_RxIndication to RTE, no storing of the I PDU • return code COM_SERVICE_NOT_AVAILABLE on Com_ReceiveSignal and Com_ReceiveSignalGroup and the last known value (or init value) is given back as data • normal reaction on Com_ReceiveShadowSignal() 	<ul style="list-style-type: none"> • disable sending • disable TX deadline monitoring • Com_TxConfirmation: <ul style="list-style-type: none"> if it is for timeout ignore it if it is used by the RTE ignore it. • on a call of Com_SendSignal, Com_UpdateShadowSignal, Com_SendSignalGroup, Com_InvalidateSignal and Com_InvalidateShadowSignal the values in the COM internal buffers are still up-dated but the return code COM_SERVICE_NOT_AVAILABLE is returned • outstanding transmission request (e.g. N-Times) shall be cancelled • normal reaction on Com_TriggerTransmit
	For periodic (TX)
	do not send any more

Table 9: Behavior of stopped I-PDU-groups

Table 10 gives an overview of the behavior of started I-PDU groups:

Behavior on a started I-PDU group	
Receiver side (RX)	Transmitter side (TX)
<ul style="list-style-type: none"> reinitialize timeouts if Initialize==true (ComSignalFirstTimeoutFactor, ComSignalTimeoutFactor, ComSignalGroupFirstTimeoutFactor, ComSignalGroupTimeoutFactor) normal reaction on Com_RxIndication normal reaction on Com_ReceiveSignal, Com_ReceiveShadowSignal and Com_ReceiveSignalGroup deadline monitoring is enabled 	<ul style="list-style-type: none"> normal reaction on Com_InvalidateSignal, Com_InvalidateShadowSignal, Com_SendSignal, Com_SendSignalGroup, Com_UpdateShadowSignal and Com_SendSignalGroup no transmission timeout notification until next send normal reaction on Com_TxConfirmation normal reaction on Com_TriggerTransmit deadline monitoring is enabled
	For periodic (TX)
	Start at 0

Table 10 Behavior of started I-PDU-groups

COM311: When an I-PDU group containing one or more other I-PDU groups is started the contained I-PDU groups shall also be started. When an I-PDU group containing one or more other I-PDU groups is stopped the contained I-PDU groups shall also be stopped.

Note: According to [7] there is only a two level hierarchy of I-PDU groups. That is an I-PDU-group contained in another I-PDU group is not allowed to have any further subgroups. As example see also Figure 12.

With respect to Figure 12 the following examples are given:

- If A is stopped then all I-PDUs are stopped
- If A is started then all I-PDUs are started.
- If A is stopped and then B is started only I-PDU 1 and I-PDU 2 are active.
- If A is started and then B is stopped only I-PDU 3 is active.

7.4.5.3 Signal indication (Unpacking of I-PDUs)

COM298: In order to support both interrupt-driven and polled system, it shall be configurable when the signal indication takes place. There shall be two configurable signal indication modes:

Immediate:

The signal indications/ confirmations are performed in Com_RxIndication/ Com_TxConfirmation

Deferred:

Signal indication/ confirmations are deferred for example to a cyclic task

COM300: In Immediate mode the signal notification shall be done in Com_RxIndication.

COM301: In Deferred mode: First in Com_RxIndication the I-PDU's data shall be copied from the underlying layer into COM. Then Com_RxIndication shall return. Then the signal notification shall be processed asynchronously, for example during the next call to Com_MainFunctionRx.

Note: If in Deferred mode a call to Com_ReceiveSignal is made before the deferred unpacking takes place the previous (not updated) values are returned.

A sequence chart with both indication options can be found in Chapter 9.3. The configuration of these modes is defined in COM119.

COM574: Within the function Com_RxIndication, the AUTOSAR COM module shall check the received data length (PduInfoPtr->SduLength) and unpack and notify only completely received signals via ComNotification.

Note: If the received I-PDU length is smaller than the configured/ expected I-PDU length, it shall be prevented that signals are updated partially. On the other hand all completely received signals shall be received and notified to the upper layer.

COM575: Within the function Com_RxIndication, the AUTOSAR COM module shall check the received data length (PduInfoPtr->SduLength) and in case a signal group is received only partially, such a signal group and all included group signals shall not be unpacked or notified via ComNotification.

Note: The above requirement prevents inconsistently received signal groups and therefore inconsistently received complex data types.

7.4.5.4 Minimum Delay Timer (MDT)

The minimum delay timer shall be defined as in [17].

Note: When an I PDU group is started the MDT eventually is re-initialized, depending on the 'Initialize' parameter of Com_IpduGroupStart, see COM222. Therefore the MDT can be violated by stopping and starting I-PDU groups rapidly.

Note: As defined in [17] the MDT is started when the confirmation of the sent I-PDU is received. Therefore exists a time-slot between the send-call and the confirmation where an (erroneous) application could create a burst of I-PDUs by sending rapidly.

Note: The behavior of the transmission deadline monitoring timer shall not be affected by any transmission delay caused by the minimum delay time supervision.

7.4.6 Deadline Monitoring

Deadline monitoring for signals is defined in [17].

In the context of deadline monitoring a signal group shall be handled like a signal. The deadline monitoring parameters can be configured via ComFirstTimeoutFactor and ComTimeoutFactor in configuration container ComSignal or ComSignalGroup respectively.

The corresponding error notification callback functions can be configured via configuration parameter ComErrorNotification in configuration container ComSignal or ComSignalGroup respectively.

COM562: If ComTxIPduMinimumDelayTimeFactor (COM181) of an I PDU is configured greater than 0, the AUTOSAR COM module shall load and start the minimum delay time counter upon transmission of that I PDU to the PDU Router via PduR_ComTransmit.

COM469: If ComTxIPduMinimumDelayTimeFactor of an I-PDU is configured greater than 0, the AUTOSAR COM module shall (re-)load the already running minimum delay time counter with ComTxIPduMinimumDelayTimeFactor for that I-PDU when Com_TxConfirmation is invoked and the minimum delay time counter of that I-PDU, started at PduR_ComTransmit, is not already elapsed.

The running minimum delay timer is reloaded upon the reception of the TX-confirmation of that I-PDU, unless the transmission was already delayed longer than ComTxIPduMinimumDelayTime at the reception of the confirmation. In normal case, there will be no further transmission of that I-PDU by the AUTOSAR COM module unless the loaded and started minimum delay has expired. See also Figures 2-4, 2-5 and 2-7 in [17]. However, some exception exists: According to COM475 Com_TriggerTransmit does not interfere with the minimum delay timer. Further, the minimum delay timer is reset if the transmission deadline monitoring timer expires; see Chapter 2.3.4 in [17]. In addition, starting an I-PDU group resets the minimum delay time timer of the included I-PDUs.

7.4.6.1 Reception Deadline Monitoring

COM292: In the case where reception deadline monitoring is used on signals with update-bits, there shall be a separate reception deadline monitoring for each signal/signal group with an update-bit. For configuration see COM263 and COM264.

COM290: There shall be an I-PDU based reception deadline monitoring for signals without an update-bit.

COM291: For all signals/ signal groups without update-bits within the same I-PDU, the smallest configured timeout parameter (ComSignalFirstTimeoutFactor, ComSignalGroupFirstTimeoutFactor / ComSignalTimeoutFactor, ComSignalGroupTimeoutFactor) of the associated signals is chosen as timeout parameter for the reception deadline monitoring of the I-PDU.

Note: If all signals within an I-PDU have an update-bit configured, no reception deadline monitoring on I-PDU base needs to be performed.

COM393: In case of an Rx-timeout it shall be configurable whether COM replaces the signal/ signal group value with the initial value or keeps it as it is. In case of replacement the *old_value* of the corresponding filter-object (if configured) shall not be replaced.

Note: Rx-timeout-indication can be combined and configured separately from COM393.

7.4.6.1.1 En-/Disable Reception Deadline Monitoring

COM092: AUTOSAR COM shall provide a routine which supports the possibility to disable reception deadline monitoring for an I-PDU group. The name of the routine shall be `Com_DisableReceptionDM`. A reference to the I-PDU group shall be transferred in the call to `Com_DisableReceptionDM`.

Disabling reception deadline monitoring implies that no error indication of reception deadline monitoring expiry is notified to the upper layer for an I-PDU in reception belonging to the concerned I-PDU group.

Disabling reception deadline monitoring shall not stop communication activity for the concerned I-PDU group.

COM095: AUTOSAR COM shall provide a routine which supports the possibility to re-enable reception deadline monitoring for an I-PDU group where reception deadline monitoring has been previously disabled. The name of the routine shall be `Com_EnableReceptionDM`. A reference to the I-PDU group shall be transferred in the call to `Com_EnableReceptionDM`.

COM224: A call to `Com_EnableReceptionDM` shall reset the reception deadline monitoring timer to `ComSignalFirstTimeoutFactor` and `ComSignalGroupFirstTimeoutFactor` if and only if reception deadline monitoring was disabled for the corresponding I-PDU group.

COM486: Enabling an already enabled reception deadline monitoring shall have no effect.

Enabling reception deadline monitoring implies that error indications of deadline monitoring expiry are notified to the upper layer for an I-PDU in reception belonging to the concerned I-PDU group.

COM534: If `Com_EnableReceptionDM` is invoked on an I-PDU group containing only/ also Tx-I-PDUs, then the Tx-I-PDUs shall be silently ignored.

COM225: Disabling an already disabled reception deadline monitoring shall have no effect.

7.4.6.2 Transmission Deadline Monitoring

For transmission deadline monitoring there is no difference between signals with update-bits and signals without update-bits. Therefore transmission deadline monitoring can be performed on I-PDU base. Nevertheless notification about detected transmission deadline violations on sender side is done per signal. See [17] for further details.

COM481: Transmission deadline monitoring shall not distinguish between signals with Pending or Triggered transfer property. It shall be performed for all signals and all transmission modes as defined for signals with Triggered transfer property in [17] if it is configured.

COM445: If different ComTimeoutFactor parameters of the associated signals/ signal groups of an I-PDU are configured the smallest value shall be used as timeout parameter for the transmission deadline monitoring of the I-PDU.

Note: Transmission deadline monitoring should only be configured in COM if the lower layer supports the generation of transmit confirmations. Otherwise the transmission deadline monitoring would always notify a transmission error.

Note: Transmission deadline monitoring is not supported for transmission mode None.

Note: The PDUR does not support transmit confirmations for PDUs that are configured to be fanned out by the PDUR to multiple receivers.

Note: In case of a signal group it is only possible to configure transmission deadline monitoring for the whole signal group and not for group signals, see COM345 and COM520.

7.4.6.2.1 Clarification of the OSEK COM specification

The following requirement COM304 states the behavior of the transmission deadline monitoring in the Mixed transmission mode defined in [17] more precisely.

COM304: If the transmission does not occur, i.e. if there is no confirmation of the I-PDU's transmission by the underlying layer, the time-out occurs and the application shall be notified using the appropriate notification mechanism.

Note: If the transmission deadline monitoring timer runs out there shall be an error notification regardless of the reason. Even if it was postponed because of the MDT or it was filtered out via an I-PDU callout.

Note: In the case that there are any contradictions between text and diagrams in [17] the text is the normative part.

Note: In [17] is defined that in Direct transmission mode (here Direct/N-times with $n \neq 0$): "The monitoring timer is started upon completion of the call to the SendMessage, SendDynamicMessage or SendZeroMessage API service."

Clarification: The transmission deadline monitoring timer shall only be reset if the corresponding signal has transmission deadline monitoring timeouts configured. Signals that have not configured transmission deadline monitoring shall not interfere in the I-PDU based monitoring process.

7.4.6.2.2 Transmission Deadline Monitoring with N-Times Transmission Mode

Note: As defined in [17] the monitoring timer shall be started upon completion of a call to Com_SendSignal or Com_SendSignalGroup respectively if transmission deadline monitoring is configured for the corresponding signal or signal group nstantively.

COM307: In Direct/N-Times transmission mode it must be ensured that all n requests can be made within the configured time period, see Chapter 7.4.3.5.

As defined in [17], if the monitoring timer expires the upper layer is notified with the configured notification mechanism about that failure.

COM308: In Direct/N-Times transmission mode with $n > 0$ the timer shall only be cancelled when n-confirmations are received or if another send request for this I-PDU is initiated.

Note: If the timer is cancelled after the n-th confirmation the transmission was successful and then the transmission confirmation is send to the upper layer. See also COM305.

7.5 Map Complex Data Types to I-PDUs – Signal Groups

COM042: To support the AUTOSAR concept of complex data types the AUTOSAR COM layer provides signal groups (see Chapter 2). A signal group shall be transmitted and received atomically; therefore it provides data consistency for complex data types.

COM043: Signal groups are configured statically. For each signal group a symbolic name shall be provided. See COM345 and COM044 for the configuration details.

COM047: The atomicity of a signal group shall be achieved by means of a shadow buffer mechanism, i.e. the upper layer uses the group signals in the shadow buffer. If the shadow buffer needs to be synchronized with the I-PDU this is triggered explicitly by the upper layer. Synchronization shall be performed atomically.

7.5.1 Initialization

COM484: The shadow buffer of a signal group on sender-side shall be initialized by a call to Com_Init.

Note: Since it is not suspected that a well-formed SWC tries to read a group signal before a call to Com_ReceiveSignalGroup COM484 applies to the sender side only.

7.5.2 Transmission

COM049: A group signal in the shadow buffer shall be updated by the call of the service Com_UpdateShadowSignal.

COM050: If Com_SendSignalGroup is called for the signal group the AUTOSAR COM layer shall copy the shadow buffer atomically to the I-PDU buffer.

Example with 2 group signals signal_a and signal_b which belong to group_x:

```
/* copy a to shadow buffer */  
Com_UpdateShadowSignal (signal_a, &a);  
  
/* copy b to shadow buffer */  
Com_UpdateShadowSignal (signal_b, &b);  
  
/* copy shadow buffer to I-PDU */  
Com_SendSignalGroup (group_x);
```

7.5.3 Reception

COM051: If Com_ReceiveSignalGroup is called for the signal group the AUTOSAR COM layer shall copy the data atomically from the I-PDU buffer to the shadow buffer.

COM052: A group signal shall be received from the shadow buffer by means of the service Com_ReceiveShadowSignal.

Example with 2 group signals signal_a and signal_b which belong to group_x:

```
/* copy I-PDU to shadow buffer */  
Com_ReceiveSignalGroup (group_x);  
  
/* copy a from shadow buffer */  
Com_ReceiveShadowSignal (signal_a, &a);  
  
/* copy b from shadow buffer */  
Com_ReceiveShadowSignal (signal_b, &b);
```

7.5.4 Notifications

It is only possible to configure the signal and error notifications (on sender and receiver side) for the whole signal group.

COM053: The notifications shall be sent to the RTE if a whole signal group has been sent to / received or detected to be invalid from the lower layer. See COM345 and COM520 for the configuration details.

7.5.5 Collection of the attributes of a signal group

Table 11 gives an overview of the attributes of a signal group:

Attribute	Per group signal	Per signal group
Update-bit	No	Yes, associated on the whole group (see 7.7)
Signal Notification (sender side)	No	Yes
Signal Notification (receiver side)	No	Yes
Error Notification (sender side)	No	Yes
Error Notification (receiver side)	No	Yes
Invalid Notification (receiver side)	Yes (see COM323)	Yes (see COM323)
Data access (receiver side)	Yes, with ReceiveSignal API (see 0)	Yes, via shadow buffer (see 8.3.2.5 and 8.3.2.6)
Data access (sender side)	No	Yes, via shadow buffer (see 0 and 8.3.2.4)
Data Filtering (receiver side)	No (see 7.2.3)	No
Data Filtering (sender side)	No	No
TMS on sender side	Each signal, according to TMS selection definition. (see 7.4.3.3)	No

Table 11: Attributes of signal groups

7.6 Interface between AUTOSAR COM and the lower layer (PDU-Router)

OSEK COM leaves the interface between OSEK COM and the lower layers undefined. In AUTOSAR the only lower layer that AUTOSAR COM interfaces to is the PDU Router.

The interaction diagram in Chapter 9.1 shows the interaction between the PDU Router and AUTOSAR COM.

A detailed description can be found in the API chapter see Com_RxIndication, Com_TxConfirmation and Com_TriggerTransmit.

COM138: When AUTOSAR COM wants to send out an I-PDU, AUTOSAR COM shall use the PduR_ComTransmit function.

7.7 Signal status information

7.7.1 Identify if a signal is updated by the sender

COM054: To enable the receiver of a signal/ signal group to identify whether the sender has updated the data in this signal/ signal group before sending, AUTOSAR COM shall support *update-bits*.

The update-bit shall indicate whether upper layers on sender-side have updated a signal value before lower layers have fetched the I-PDU containing that signal for transmission or before AUTOSAR COM has handed over the I-PDU to lower layers for transmission.

Note: Update-bits are not allowed if Direct/N-Times transmission mode with $n > 1$ is used (see COM310).

COM055: By configuration on sender- and on receiver-side, it shall be possible to add separately for each signal and/or separately for each signal group at most one additional bit (= update-bit). The update-bit is not part of the signal or signal group itself and shall only be used by AUTOSAR COM itself. The update-bit shall not be visible to or accessible by the AUTOSAR Software Component.

COM056: The position of the update-bit shall be configurable. For configuration parameter see COM257.

COM057: A signal/ signal group and the corresponding update-bit shall always be part of the same I-PDU.

COM059: The interpretation of the update-bit shall be as follows:

<i>Update-BIT</i>	
0	cleared
1	set

Table 12 update-bit interpretation

If the value of the update-bit is set, data has been updated; if the value of the update-bit is cleared it has not been updated.

7.7.1.1 Sender Side

The initialization of the update-bit is defined in the Chapter 7.4.1 by COM117.

COM061: If upper layers update the value of a signal by calling the AUTOSAR COM API `Com_SendSignal`, the update-bit for this signal shall be set. For signal groups,

the update-bit shall be set, if the upper layers call the AUTOSAR COM API `Com_SendSignalGroup`.

COM062: After an I-PDU is sent to lower layers and no synchronous error is returned by the lower layer the update-bits of all signals and signal groups belonging to the I-PDU sent shall be cleared.

7.7.1.2 Receiver Side

COM324: On receiver-side, if there is an update-bit attached to a signal/signal group, AUTOSAR COM shall only process this signal (i.e. filter, notification, signal based, byte swapping), if the signal has been updated. If the signal has not been updated AUTOSAR COM shall discard the signal.

Note: If the signals has not been updated the signal will not be routed via the signal gateway. It will only be discarded.

Remark: If the upper layer reads a signal with an associated cleared update-bit, the init value or the last received value is returned.

COM067: A signal/ signal group shall be interpreted as *updated* if the signal has an update-bit attached and the value of the update-bit is set.

For the behavior of deadline monitoring on signals with update-bits, see Chapter 7.4.5.4.

7.8 Callouts

As stated in COM013 *Network-order message callout* and *CPU-order message callout* are not supported in AUTOSAR COM. The only callout method in AUTOSAR COM therefore is the I-PDU callout. AUTOSAR COM supports I-PDU callouts on sender and on receiver side.

7.8.1 I-PDU Callout

COM381: In an I-PDU callout other COM APIs than `Com_TriggerIPDUSend` shall not be called.

COM346: The I-PDU-Callout API shall be defined as:

boolean `<IPDU_CalloutName>(PduldType ID, uint8* ipduD)`

where `<IPDU_CalloutName>` has to be substituted with the concrete I-PDU callout name.

Note: As specified in OSEK COM if the I-PDU callout returns false the I-PDU shall not be processed any further.

COM347: It shall be possible to configure separate I-PDU callout function for each I-PDU. Therefore the I-PDU callout function shall be configurable per I-PDU if used.

For configuration see COM387.

COM395: When Com_TriggerTransmit is called, COM shall ignore the return value from the I-PDU callout (if configured).

7.9 Signal Gateway

The signal gateway is an integrated part of COM. The signal gateway can't be accessed by any external modules, except the cyclic task call.

The signal gateway is working on (group) signals and signal groups.

COM376: The signal gateway only supports static routing: All routes shall be used independent of the content of the signals and signal groups to be routed. The destination of a signal or signal group shall only depend on the name of the received signal respectively signal group.

COM377: The signal gateway shall copy the value of signals respectively signal groups to be routed to the signals respectively signal groups for transmission according to configuration.

COM358: It shall be possible to route a signal/ signal group from one source signal/ signal group to zero (no signal gateway functionality) or more destinations (1:n).

7.9.1 Dealing with signals

COM357: COM shall forward signals to be routed from received I-PDUs to transmit I-PDUs. For configuration see configuration container ComGwMapping (COM544).

COM360: If the endianness of a received signal to be routed differs from the endianness of a related destination signal, its endianness shall be converted using the applicable COM mechanisms.

7.9.2 Dealing with signal groups

COM361: COM shall forward signal groups to be routed from received I-PDUs to transmit I-PDUs. For configuration see configuration container ComGwMapping (COM544).

COM383: Signal groups shall be routed in an atomic manner. I.e. it must be guaranteed that the data within the signal group is transferred as one consistent set of data during the whole routing operation.

COM362: It shall be possible to change the endianness of signals contained in signal groups to be routed by signal gateway. The signal gateway shall use the applicable COM mechanisms to do so.

COM464: All non-opaque group signals within a signal group shall have the same endianness.

7.9.3 Routing of out timed signals and signal groups

COM568: The AUTOSAR COM module's signal gateway shall route signal and signal groups even if any configured reception deadline monitoring timeout expired.

In case of a not in time received signal or signal group the AUTOSAR COM module's signal gateway will route these signal or signal group anyway.

7.9.3.1 Handling of update-bits

COM569: If both, the received signal/ signal group and the destination signal/ signal group have an update-bit (ComUpdateBitPosition) configured and the update-bit of the received signal/ signal group is set, the AUTOSAR COM module shall route the signal/ signal group with the set update-bit and clear the update-bit of the destination signal/ signal group after it was sent.

COM570: If the received signal/ signal group and the destination signal/ signal group have an update-bit (ComUpdateBitPosition) configured, and the update-bit of the received signal/ signal group is not set, the AUTOSAR COM module shall not route this signal/ signal group.

COM571: If the received signal/ signal group has an update-bit (ComUpdateBitPosition) configured, but the destination signal has no update-bit configured, and the update-bit is set, the AUTOSAR COM module shall route this signal/ signal group without the update-bit.

COM572: If the received signal/ signal group has an update-bit (ComUpdateBitPosition) configured, but the destination signal has no update-bit configured, and the update-bit is not set, the AUTOSAR COM module shall not route this signal/ signal group.

COM573: If the received signal/ signal group has no update-bit (ComUpdateBitPosition) configured and the destination signal/ signal group has an update-bit configured, the AUTOSAR COM module shall set the update-bit of the destination signal when a new signal/ signal group was received and clear it after sending of the destination signal/ signal group.

7.9.4 Decoupling signal gateway

To protect interrupt routines (used for I-PDU reception) from incalculable (and perhaps expensive) time usage, it is necessary to decouple the signal gateway from interrupt routines.

COM359: The functions of the signal gateway shall be executed during a separate function call only. During this function call the signal gateway checks received and to be routed signals and signal groups and forwards them from the related receive I-PDUs to the related transmit I-PDUs (see COM400).

COM466: Within `Com_MainFunctionRouteSignals` the evaluation of transfer properties and transmission mode must be performed in the following sequence (see also Figure 3):

Copy all gated signals from the source to the target I-PDUs
Evaluate the TMC of all gated signals
Evaluate the TMS for the target I-PDUs
For any target I-PDU containing gated signals with Triggered transfer property send it according to its transmission mode

COM539: An I-PDU shall be sent out at most once while one call to `Com_MainFunctionRouteSignals`.

7.10 Error classification

7.10.1 Development Errors

COM024: All input parameters shall be checked for validity during development. The parameter check shall be not contained in the production code. For the configuration of this feature see COM028.

COM442: When a development error is detected the function `Det_ReportError` of the development error tracer shall be called with:

the COM moduleID (see COM417)
the COM instanceID
the service ID of the COM API the error is detected (see `Com_ServiceIdType`)
the error ID as defined in Table 13

<i>Type of development error</i>	<i>Related error code</i>	<i>Value [hex]</i>
API service called with wrong parameter	COM_E_PARAM	0x01
Error code if any other API service is called before COM was initialized with <code>Com_Init</code> or after a call to <code>Com_Deinit</code>	COM_E_UNINIT	0x02

Table 13: Mapping of COM development error IDs

7.10.2 Production Errors

Actually no production errors are defined in AUTOSAR COM. If production errors will be defined in later versions AUTOSAR COM shall report them directly to the DEM.

7.10.3 Return Codes

AUTOSAR COM does not define a special COM return type. The API services return errors either by using the Std_ReturnType as defined in [5] or via a uint8 value mapped according to Table 14.

COM459: Return codes of AUTOSAR Com shall be defined according Table 14.

Name	Description	Type	Value	Defined in
E_OK	the service has been accepted	#define	0x00	Std_Types.h
COM_SERVICE_NOT_AVAILABLE	the service is currently not available e.g. the corresponding I-PDU group is stopped (or a development error has been detected)	#define	0x80	Com.h
COM_TIMEOUT	a timeout has occurred	#define	0x81	Com.h

Table 14: Mapping of AUTOSAR COM return codes

7.11 Error handling

COM428: If not stated otherwise AUTOSAR COM will ignore all errors from the underlying communication layer.

Note: AUTOSAR COM supervises the communication with deadline monitoring if configured. The specific error codes from the underlying layer therefore can be ignored. In case of update-bits this error codes are handled see COM062.

7.12 AUTOSAR COM interaction model

This chapter corresponds to the chapter *Functional Model of Interaction Layer* of [17]. The following figures illustrate the behavior of the Interaction layer for external reception and external transmission. The complete functionality is shown but it depends on the configuration what parts are present/ used in a concrete implementation.

COM396: A signal can be configured to have filtering, data invalidation and notification. The order of execution (if configured) is:

- 1) Data invalidation
- 2) Filtering
- 3) Notification

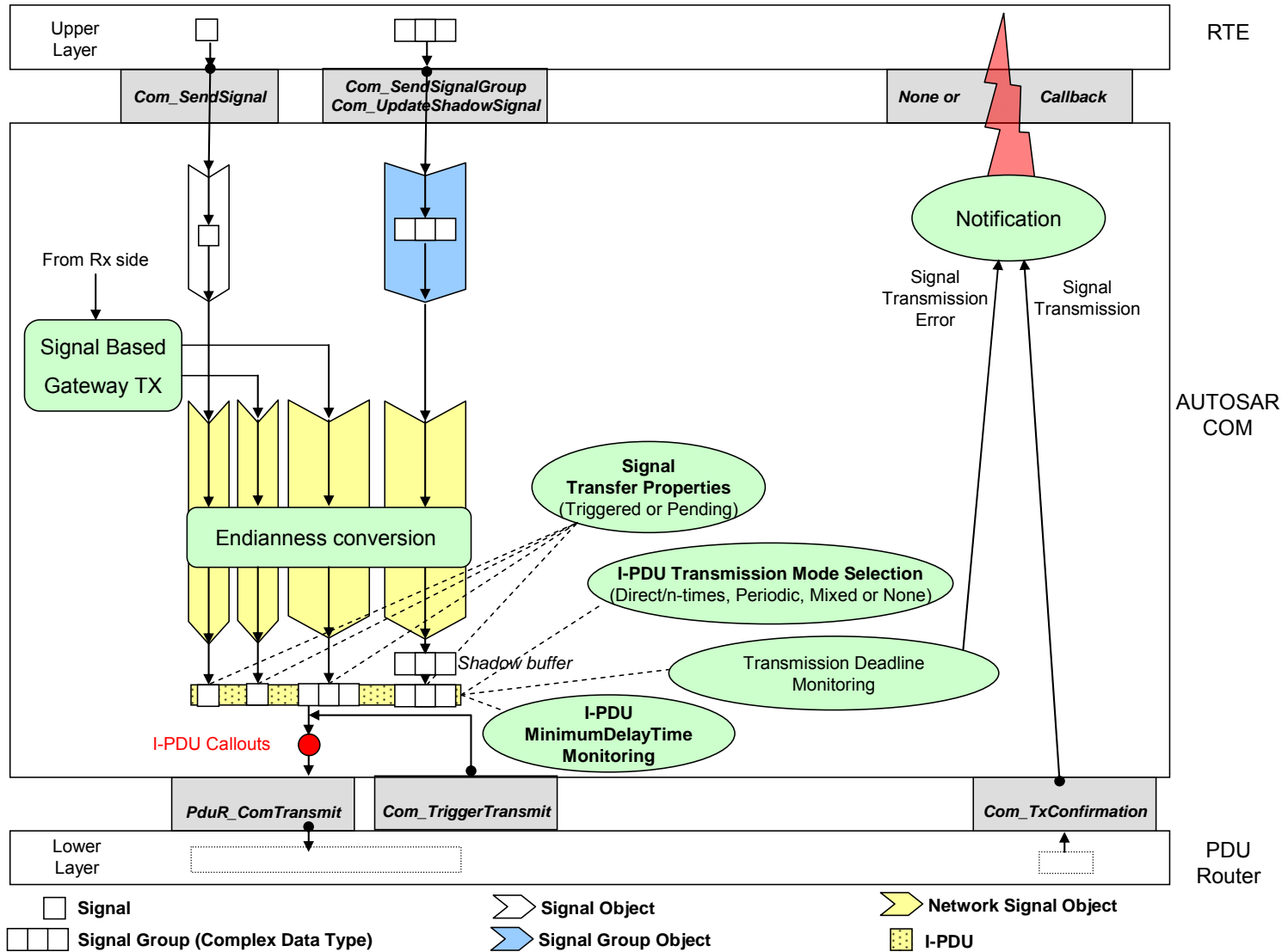


Figure 13 AUTOSAR COM interaction model for transmission

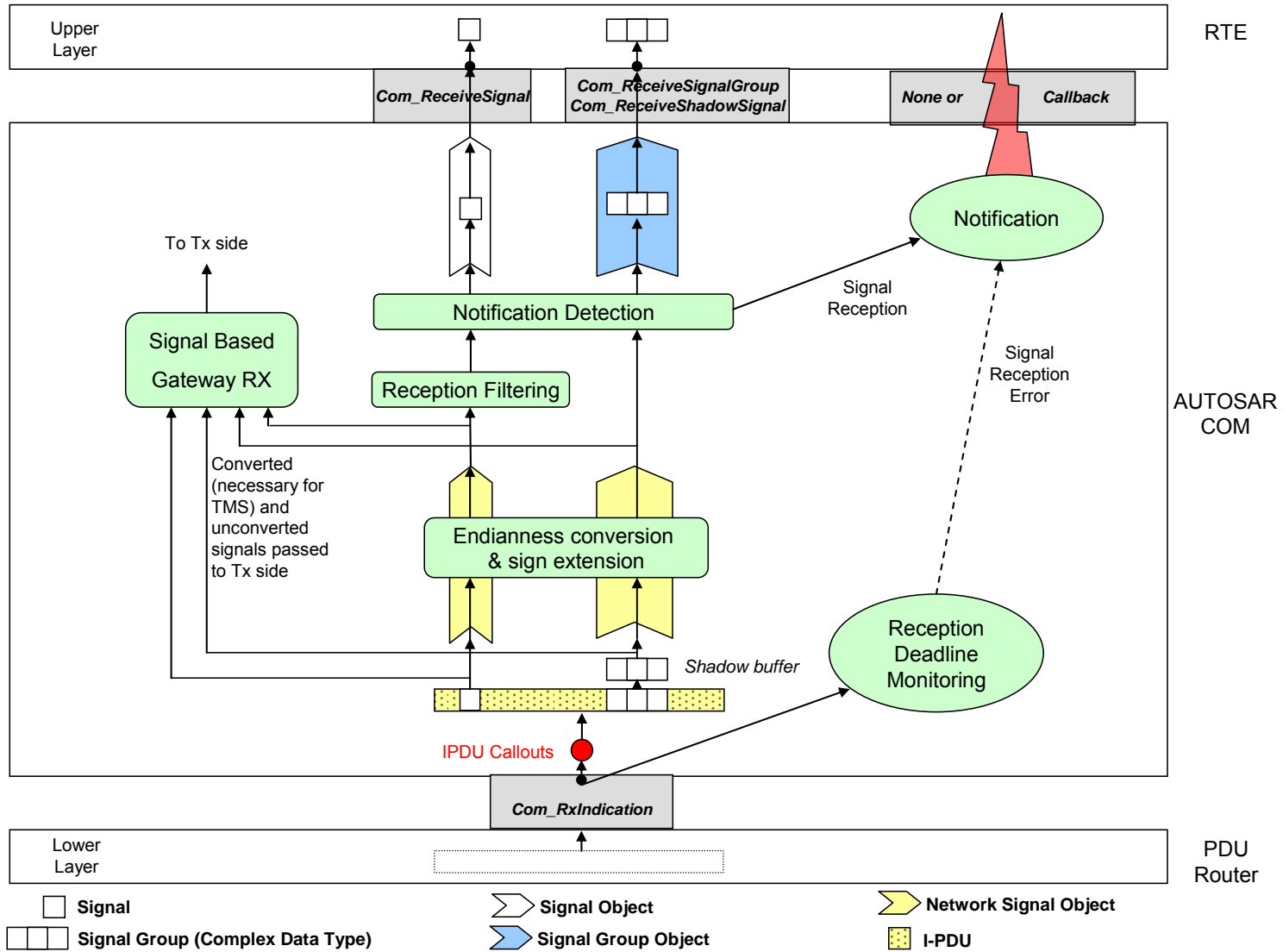


Figure 14 AUTOSAR COM interaction model for reception

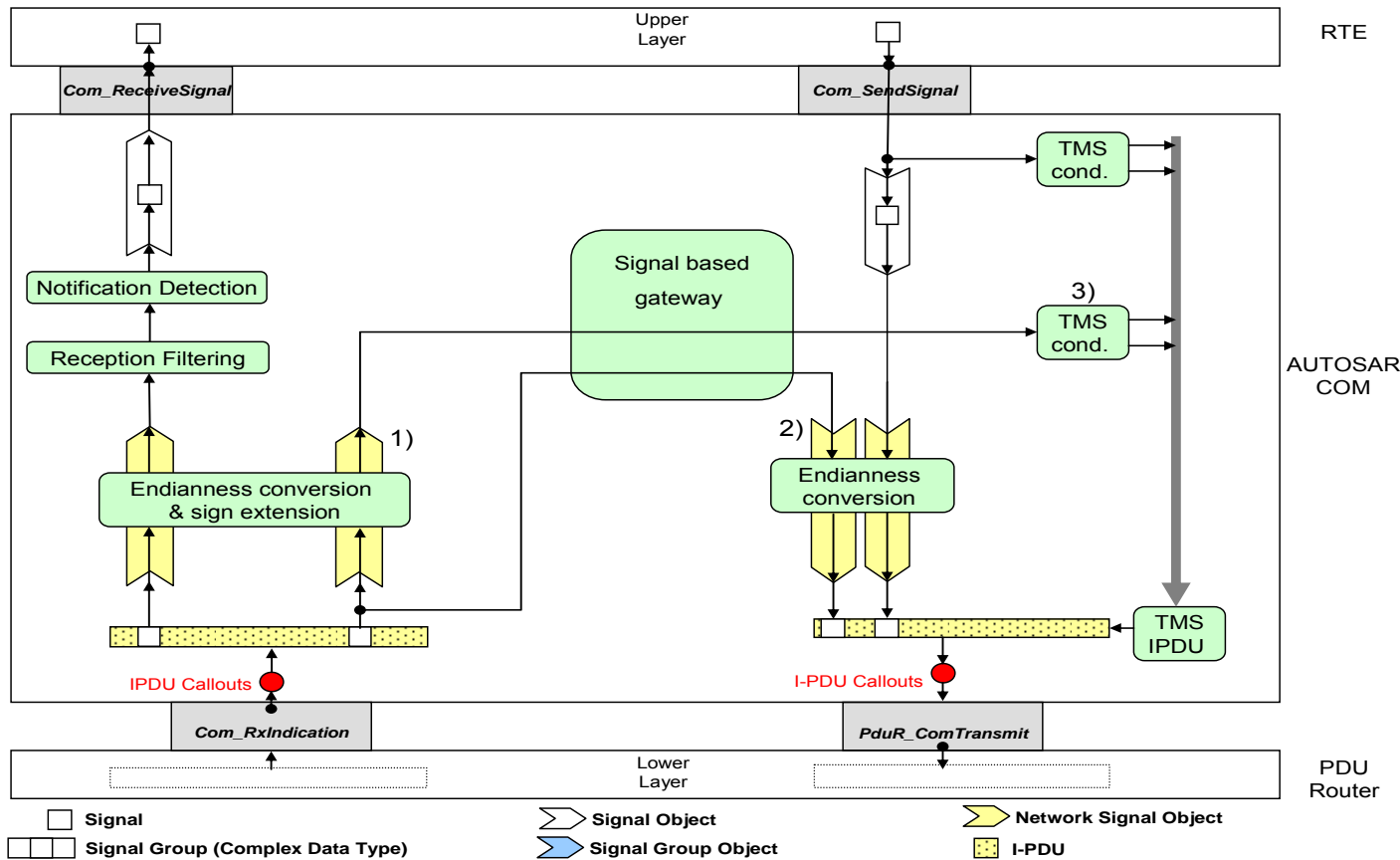


Figure 15: AUTOSAR COM-interaction model for integrated Signal Gateway

The endianness conversion and sign extension on receiver side is needed to feed the TMS with a correct data format. This endianness conversion is only necessary if the endianness of the Rx-bus differs from the endianness of the CPU. The endianness conversion on the sender side is only necessary if the endianness of the Rx-bus differs from the endianness of the Tx-bus. If a gated signal should not always trigger the associated IPDU to be sent out, one of the configured transmission modes must be None.

8 API specification

8.1 Imported types

8.1.1 PduldType

The definition of the PduldType can be found in [2].

8.1.2 Std_ReturnType

The definition of the Std_ReturnType can be found in [5].

8.1.3 Std_VersionInfoType

The definition of the Std_VersionInfoType can be found in [5].

8.2 Type definitions

8.2.1 Com_StatusType

Name:	Com_StatusType	
Type:	Enumeration	
Range:	COM_UNINIT	The AUTOSAR COM module is not initialized or not usable. This shall be the default value after reset. This status shall have the value 0.
	COM_INIT	The AUTOSAR COM Module is initialized and usable.
Description:	This is a status value returned by the API service Com_GetStatus().	

8.2.2 Com_SignalIdType

Name:	Com_SignalIdType	
Type:	uint16	
Range:	0..<SignalIdmax>	Zero-based integer number
Description:	AUTOSAR COM signal object identifier.	

8.2.3 Com_SignalGroupIdType

Name:	Com_SignalGroupIdType	
Type:	uint16	
Range:	0..<SignalGroupIdmax>	Zero-based integer number
Description:	AUTOSAR COM signal group object identifier.	

8.2.4 Com_PduGroupIdType

Name:	Com_PduGroupIdType	
Type:	uint8	
Range:	0..<PduGroupId-max>	Zero-based integer number
Description:	AUTOSAR COM PDU group object identifier.	

8.2.5 Com_ServiceIdType

Name:	Com_ServiceIdType		
Type:	uint8		
Range:	COMServiceId_MainFunctionRouteSignals	0x1A	--
	COMServiceId_MainFunctionTx	0x19	--
	COMServiceId_MainFunctionRx	0x18	--
	COMServiceId_TriggerIPDUSend	0x17	--
	COMServiceId_InvalidateShadowSignal	0x16	--
	COMServiceId_TxConfirmation	0x15	--
	COMServiceId_RxIndication	0x14	--
	COMServiceId_TriggerTransmit	0x13	--
	COMServiceId_Error <Name1> <Name2>Macros	0x12	--
	COMServiceId_ErrorGetServiceId	0x11	--
	COMServiceId_InvalidateSignal	0x10	--
	COMServiceId_ReceiveShadowSignal	0x0F	--
	COMServiceId_ReceiveSignalGroup	0x0E	--
	COMServiceId_SendSignalGroup	0x0D	--
	COMServiceId_UpdateShadowSignal	0x0C	--
	COMServiceId_ReceiveSignal	0x0B	--
	COMServiceId_SendSignal	0x0A	--
	COMServiceId_GetVersionInfo	0x09	--
	COMServiceId_GetConfigurationId	0x08	--
	COMServiceId_GetStatus	0x07	--
	COMServiceId_DisableReceptionDM	0x05	--
	COMServiceId_EnableReceptionDM	0x06	--
	COMServiceId_IpduGroupStop	0x04	--
	COMServiceId_InvalidateSignalGroup	0x1B	--
	COMServiceId_IpduGroupStart	0x03	--
	COMServiceId_DeInit	0x02	--
	COMServiceId_Init	0x01	--
Description:	Unique identifier of an AUTOSAR COM service. Example: COMServiceId_SendSignal 0x0A.		

8.2.6 Com_ConfigType

Name:	Com_ConfigType	
Type:	Structure	
Range:	implementation specific	The content of the initialization data structure is implementation specific
Description:	This is the type of the data structure containing the initialization data for COM.	

8.3 Function definitions

COM320: If a function is marked as non-reentrant the caller of that function shall ensure that this function must not be called while it is running.

COM321: Non-reentrant functions do not have to check if they are called reentrant.

COM434: It is allowed to use macros instead of functions where source code is used and runtime is critical.

8.3.1 Start up and control services

8.3.1.1 Com_Init

COM432:

Service name:	Com_Init
Syntax:	void Com_Init(const Com_ConfigType* config)
Service ID[hex]:	0x01
Sync/Async:	Synchronous
Reentrancy:	Non Reentrant
Parameters (in):	config Pointer to the COM configuration data.
Parameters (in-out):	None
Parameters (out):	None
Return value:	None
Description:	This service initializes internal and external interfaces and variables of the AUTOSAR COM layer for the further processing. After calling this function the inter-ECU communication is still disabled.

COM433: If the config parameter does not correspond to a valid configuration then the development error COM_E_PARAM is generated. The behavior of AUTOSAR COM is unspecified until a correct call to Com_Init is made.

Caveats: Com_Init shall not pre-empt any COM function. The rest of the system must guarantee that Com_Init is not called in such a way.

8.3.1.2 Com_Delnit

COM130:

Service name:	Com_Delnit
Syntax:	void Com_Delnit()
Service ID[hex]:	0x02
Sync/Async:	Synchronous
Reentrancy:	Non Reentrant
Parameters (in):	None
Parameters (in-out):	None
Parameters (out):	None

Return value:	None
Description:	This service stops the inter-ECU communication. All started I-PDU groups are stopped and have to be started again, if needed, after Com_Init is called. By a call to ComDelnit COM is put into an not initialized state.

Caveats: Com_Delnit shall not pre-empt any COM function. The rest of the system must guarantee that Com_Delnit is not called in such a way.

8.3.1.3 Com_IpduGroupStart

COM191:

Service name:	Com_IpduGroupStart	
Syntax:	void Com_IpduGroupStart(Com_PduGroupIdType IpduGroupId, boolean Initialize)	
Service ID[hex]:	0x03	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant for different I-PDU groups. Non reentrant for the same I-PDU group.	
Parameters (in):	IpduGroupId	Id of I-PDU group to be started
	Initialize	flag to request initialization of the data in the I-PDUs of this I-PDU group
Parameters (in-out):	None	
Parameters (out):	None	
Return value:	None	
Description:	Starts a preconfigured I-PDU group. For example, cyclic I-PDUs will be sent out cyclically after the call of Com_IpduGroupStart(). See Chapter 7.4.5 for details. If Initialize is true all I-PDUs of the I-PDU group shall be (re-)initialized before the I-PDU group is started. That is they shall behave like after a start-up of COM, for example the old_value of the filter objects and shadow buffers of signal groups have to be (re-)initialized.	

Caveats: A call to Com_IpduGroupStart shall not be interrupted by another call to Com_IpduGroupStart or a call to Com_IpduGroupStop. Note that this function is not only called by the COMM but also from other modules e.g. diagnosis.

Configuration: An I PDU group must be configured before this call. See COM206 and COM341 for details.

8.3.1.4 Com_IpduGroupStop

COM190:

Service name:	Com_IpduGroupStop	
Syntax:	void Com_IpduGroupStop(Com_PduGroupIdType IpduGroupId)	
Service ID[hex]:	0x04	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant for different I-PDU groups. Non reentrant for the same I-PDU group.	
Parameters (in):	IpduGroupId	Id of I-PDU group to be stopped
Parameters (in-out):	None	

out):	
Parameters (out):	None
Return value:	None
Description:	Stops a preconfigured I-PDU group. For example, cyclic I-PDUs will be stopped after the call of Com_IpduGroupStop(). See Chapter 7.4.5 for details.

Caveats: A call to Com_IpduGroupStop shall not be interrupted by another call to Com_IpduGroupStop or a call to Com_IpduGroupStart. Note that this function is not only called by the COMM but also from other modules e.g. diagnosis.

Configuration: An I PDU group must be configured before this call. See COM206 and COM341 for details.

8.3.1.5 Com_DisableReceptionDM

COM192:

Service name:	Com_DisableReceptionDM
Syntax:	void Com_DisableReceptionDM(Com_PduGroupIdType IpduGroupId)
Service ID[hex]:	0x05
Sync/Async:	Synchronous
Reentrancy:	Reentrant for different I-PDU groups. Non reentrant for the same I-PDU group.
Parameters (in):	IpduGroupId Id of I-PDU group where reception DM shall be disabled.
Parameters (in-out):	None
Parameters (out):	None
Return value:	None
Description:	Disables the reception deadline monitoring for the I-PDUs within the given I-PDU group.

Configuration: An I PDU group must be configured before this call. See COM206 and COM341 for details.

8.3.1.6 Com_EnableReceptionDM

COM193:

Service name:	Com_EnableReceptionDM
Syntax:	void Com_EnableReceptionDM(Com_PduGroupIdType IpduGroupId)
Service ID[hex]:	0x06
Sync/Async:	Synchronous
Reentrancy:	Reentrant for different I-PDU groups. Non reentrant for the same I-PDU group.
Parameters (in):	IpduGroupId Id of I-PDU group where reception DM shall be enabled.
Parameters (in-out):	None
Parameters (out):	None
Return value:	None
Description:	Enables the reception deadline monitoring for the I-PDUs within the given I-PDU group.

Configuration: An I-PDU group must be configured before this call. See COM206 and COM341 for details.

8.3.1.7 Com_GetStatus

COM194:

Service name:	Com_GetStatus	
Syntax:	Com_StatusType Com_GetStatus()	
Service ID[hex]:	0x07	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant	
Parameters (in):	None	
Parameters (in-out):	None	
Parameters (out):	None	
Return value:	Com_StatusType	COM_UNINIT: AUTOSAR COM is not initialized and not usable COM_INIT: AUTOSAR COM is initialized and usable
Description:	Returns the status of the AUTOSAR COM module.	

8.3.1.8 Com_GetConfigurationId

COM375:

Service name:	Com_GetConfigurationId	
Syntax:	uint32 Com_GetConfigurationId()	
Service ID[hex]:	0x08	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant	
Parameters (in):	None	
Parameters (in-out):	None	
Parameters (out):	None	
Return value:	uint32	configured ConfigurationID, see COM394
Description:	Provides the unique identifier of the configuration.	

Configuration: The provided Identification shall be set during configuration process and can't be changed by COM.

8.3.1.9 Com_GetVersionInfo

COM426:

Service name:	Com_GetVersionInfo	
Syntax:	void Com_GetVersionInfo(Std_VersionInfoType* versioninfo)	
Service ID[hex]:	0x09	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant	

Parameters (in):	None
Parameters (in-out):	None
Parameters (out):	versioninfo Pointer to where to store the version information of this module.
Return value:	None
Description:	Returns the version information of this module.

COM424: This service returns the version information of this module. The version information includes:

- 1) Module ID
- 2) Vendor ID
- 3) Vendor specific version numbers (BSW00407).

COM425: This function shall be pre compile time configurable On/Off by the configuration parameter: COM_VERSION_INFO_API

Note: If source code for caller and called of this function is available, this function should be realized as a macro. The macro should be defined in the modules header file.

Configuration: see COM026

8.3.2 Communication services

8.3.2.1 Com_SendSignal

COM197:

Service name:	Com_SendSignal	
Syntax:	uint8 Com_SendSignal(Com_SignalIdType SignalId, const void* SignalDataPtr)	
Service ID[hex]:	0x0a	
Sync/Async:	Asynchronous	
Reentrancy:	Non Reentrant for the same signal. Reentrant for different signals.	
Parameters (in):	SignalId	Id of signal to be sent.
	SignalDataPtr	Reference to the signal data to be transmitted.
Parameters (in-out):	None	
Parameters (out):	None	
Return value:	uint8	E_OK: service has been accepted COM_SERVICE_NOT_AVAILABLE: corresponding I-PDU group was stopped (or service failed due to development error)
Description:	The service Com_SendSignal updates the signal object identified by SignalId with the signal referenced by the SignalDataPtr parameter. If the signal has the Triggered transfer property, the update is followed by immediate transmission of the I-PDU associated with the signal except when the signal is packed into an I-PDU with Periodic transmission mode; in this case, no transmission is initiated by the call to this service. If the signal has the Pending transfer property, no transmission is caused by the update.	

8.3.2.2 Com_ReceiveSignal

COM198:

Service name:	Com_ReceiveSignal	
Syntax:	uint8 Com_ReceiveSignal(Com_SignalIdType SignalId, void* SignalDataPtr)	
Service ID[hex]:	0x0b	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant for the same signal. Reentrant for different signals.	
Parameters (in):	SignalId	Id of signal to be received.
Parameters (in-out):	None	
Parameters (out):	SignalDataPtr	Reference to the signal data in which to store the re-ceived data.
Return value:	uint8	E_OK: service has been accepted COM_SERVICE_NOT_AVAILABLE: corresponding I-PDU group was stopped (or service failed due to development error)
Description:	The service Com_ReceiveSignal updates the signal referenced by SignalDataPtr with the data in the signal object identified by SignalId.	

8.3.2.3 Com_UpdateShadowSignal

COM199:

Service name:	Com_UpdateShadowSignal	
Syntax:	void Com_UpdateShadowSignal(Com_SignalIdType SignalId, const void* SignalDataPtr)	
Service ID[hex]:	0x0c	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant for the same group signal. Reentrant for different group signals.	
Parameters (in):	SignalId	Id of group signal to be updated.
	SignalDataPtr	Reference to the group signal data to be updated.
Parameters (in-out):	None	
Parameters (out):	None	
Return value:	None	
Description:	The service Com_UpdateShadowSignal updates a group signal with the data, referenced by SignalDataPtr. The update of the group signal data is done in the shadow buffer, not in the I-PDU. To send out the shadow buffer, Com_SendSignalGroup has to be called. Sign extension and byte swapping are performed as the group signal is inserted into the shadow buffer.	

Configuration: A signal group must be configured before this call. See COM345 for details.

8.3.2.4 Com_SendSignalGroup

COM200:

Service name:	Com_SendSignalGroup
Syntax:	uint8 Com_SendSignalGroup()

	Com_SignalGroupIdType SignalGroupId)	
Service ID[hex]:	0x0d	
Sync/Async:	Asynchronous	
Reentrancy:	Non Reentrant for the same group signal. Reentrant for different group signals.	
Parameters (in):	SignalGroupId	Id of signal group to be send.
Parameters (in-out):	None	
Parameters (out):	None	
Return value:	uint8	E_OK: service has been accepted COM_SERVICE_NOT_AVAILABLE: corresponding I-PDU group was stopped (or service failed due to development error)
Description:	The service Com_SendSignalGroup copies the content of the associated shadow buffer to the associated I-PDU. Prior to this call, all group signals should be updated in the shadow buffer by the call of Com_UpdateShadowSignal.	

Configuration: A signal group must be configured before this call. See COM345 for details.

8.3.2.5 Com_ReceiveSignalGroup

COM201:

Service name:	Com_ReceiveSignalGroup	
Syntax:	uint8 Com_ReceiveSignalGroup(Com_SignalGroupIdType SignalGroupId)	
Service ID[hex]:	0x0e	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant for the same group signal. Reentrant for different group signals.	
Parameters (in):	SignalGroupId	Id of signal group to be received.
Parameters (in-out):	None	
Parameters (out):	None	
Return value:	uint8	E_OK: service has been accepted COM_SERVICE_NOT_AVAILABLE: corresponding I-PDU group was stopped (or service failed due to development error)
Description:	The service Com_ReceiveSignalGroup copies the received signal group from the I-PDU to the shadow buffer. After this call, the group signals could be copied from the shadow buffer to the upper layer by a call of Com_ReceiveShadowSignal.	

Configuration: A signal group must be configured before this call. See COM345 for details.

8.3.2.6 Com_ReceiveShadowSignal

COM202:

Service name:	Com_ReceiveShadowSignal	
Syntax:	void Com_ReceiveShadowSignal(Com_SignalIdType SignalId, void* SignalDataPtr)	
Service ID[hex]:	0x0f	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant for the same group signal. Reentrant for different group signals.	

Parameters (in):	SignalId	Id of group signal to be received.
Parameters (in-out):	None	
Parameters (out):	SignalDataPtr	Reference to the group signal data in which to store the received data.
Return value:	None	
Description:	The service Com_ReceiveShadowSignal updates the group signal which is referenced by SignalDataPtr with the data in the shadow buffer. The data in the shadow buffer should be updated before the call of Com_ReceiveShadowSignal by a call of the service Com_ReceiveSignalGroup.	

8.3.2.7 Com_InvalidSignal

COM203:

Service name:	Com_InvalidSignal	
Syntax:	uint8 Com_InvalidSignal(Com_SignalIdType SignalId)	
Service ID[hex]:	0x10	
Sync/Async:	Asynchronous	
Reentrancy:	Non Reentrant for the same signal. Reentrant for different signals.	
Parameters (in):	SignalId	Id of signal to be invalidated.
Parameters (in-out):	None	
Parameters (out):	None	
Return value:	uint8	E_OK: service has been accepted COM_SERVICE_NOT_AVAILABLE: corresponding I-PDU group was stopped (or service failed due to development error)
Description:	Sender side AUTOSAR Software Component indicates via the RTE to AUTOSAR COM that it is not able to provide a valid value for the corresponding signal (e.g. sensor is faulty). After invaliding the actual signal data a Com_SendSignal is performed internally, for details see COM097 and COM099.	

Configuration: For processing, a Data Invalid Value must have been configured, see COM501.

8.3.2.8 Com_InvalidShadowSignal

COM288:

Service name:	Com_InvalidShadowSignal	
Syntax:	void Com_InvalidShadowSignal(Com_SignalIdType SignalId)	
Service ID[hex]:	0x16	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant for the same signal. Reentrant for different signals.	
Parameters (in):	SignalId	Id of signal to be sent.
Parameters (in-out):	None	
Parameters (out):	None	
Return value:	None	
Description:	Sender side AUTOSAR Software Component indicates via the RTE to AUTOSAR COM that it is not able to provide a valid value for the corresponding group signal,	

	e.g. sensor is faulty. See also COM047. The RTE has to call this function for each group signal of a signal group. To send out the invalidated signal group Com_SendSignalGroup must be called separately.
--	--

Configuration: For processing, a ComSignalDataInvalidValue must have been configured.

8.3.2.9 Com_InvalidateSignalGroup

COM557:

Service name:	Com_InvalidateSignalGroup	
Syntax:	uint8 Com_InvalidateSignalGroup(Com_SignalGroupIdType SignalGroupId)	
Service ID[hex]:	0x1b	
Sync/Async:	Asynchronous	
Reentrancy:	Non Reentrant for the same signal group. Reentrant for different signal groups.	
Parameters (in):	SignalGroupId	Id of signal group to be invalidated.
Parameters (in-out):	None	
Parameters (out):	None	
Return value:	uint8	E_OK: service has been accepted COM_SERVICE_NOT_AVAILABLE: corresponding I-PDU group was stopped (or service failed due to development error)
Description:	Sender side AUTOSAR Software Component indicates via the RTE to AUTOSAR COM that it is not able to provide a valid value for the corresponding signal group. After invalidating the actual signal group data a Com_SendSignalGroup is performed internally,	

8.3.2.10 Com_TriggerIPDUSend

COM348:

Service name:	Com_TriggerIPDUSend	
Syntax:	void Com_TriggerIPDUSend(PduldType ComTxPduld)	
Service ID[hex]:	0x17	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant	
Parameters (in):	ComTxPduld	The I-PDU-ID if the I-PDU that shall be triggered for sending
Parameters (in-out):	None	
Parameters (out):	None	
Return value:	None	
Description:	By a call to Com_TriggerIPDUSend the I-PDU with the given ID is triggered for transmission.	

COM388: When an I-PDU is sent out because of this API only the minimum delay time has to be taken into account. That is postpone transmissions if necessary and

reset the minimum delay timer in case of transmissions. All other transmission mode related parameters like N-Times shall not be taken into account.

COM492: If an I-PDU triggered by Com_TriggerIPDU_Send has a configured I-PDU-callout this I-PDU-Callout shall also be called.

Caveats: Shall only be used from within an I PDU callout.

8.4 Callback notifications

8.4.1 Com_TriggerTransmit

COM001:

Service name:	Com_TriggerTransmit	
Syntax:	Std_ReturnType Com_TriggerTransmit(PduldType ComTxPduld, PduldInfoType* PduldInfoPtr)	
Service ID[hex]:	0x13	
Sync/Async:	Synchronous	
Reentrancy:	Non reentrant for the same PDU-ID. Reentrant for different PDU-ID.	
Parameters (in):	ComTxPduld	ID of AUTOSAR COM I-PDU that is requested to be transmitted by AUTOSAR COM.
Parameters (in-out):	PduldInfoPtr	Contains a pointer to a buffer (SduDataPtr) to where the SDU shall be copied to. On return, the service will indicate the length of the copied SDU data in SduLength.
Parameters (out):	None	
Return value:	Std_ReturnType	E_OK: SDU has been copied and SduLength indicates the number of copied bytes. E_NOT_OK: No SDU has been copied. SduLength has not been set.
Description:	This function is called by the lower layer when an AUTOSAR COM I-PDU shall be transmitted. Within this function, AUTOSAR COM shall copy the contents of its I-PDU transmit buffer to the L-PDU buffer given by SduDataPtr.	

COM475: Com_TriggerTransmit is not interfered by the I-PDU minimum delay time and shall not reset the minimum delay timer, see COM181.

Use case: This function is used e.g. by the LIN Master for sending out a LIN frame. In this case, the trigger transmit can be initiated by the Master schedule table itself or a received LIN header.

This function is also used by the FlexRay Interface for requesting PDUs to be sent in static part (synchronous to the FlexRay global time).

Once the I PDU has been successfully sent by the lower layer (PDU Router), the lower layer must call Com_TxConfirmation.

Caveats: This function might be called in interrupt context.

8.4.2 Com_RxIndication

COM123:

Service name:	Com_RxIndication
----------------------	------------------

Syntax:	void Com_RxIndication(PduIdType ComRxPduId, const PduInfoType* PduInfoPtr)	
Service ID[hex]:	0x14	
Sync/Async:	Synchronous	
Reentrancy:	Non reentrant for the same PDU-ID. Reentrant for different PDU-ID.	
Parameters (in):	ComRxPduId	ID of AUTOSAR COM I-PDU that has been received. Identifies the data that has been received. Range: 0..(maximum number of I-PDU IDs received by AUTOSAR COM) - 1
	PduInfoPtr	Contains the length (SduLength) of the received I-PDU and a pointer to a buffer (SduDataPtr) containing the I-PDU.
Parameters (in-out):	None	
Parameters (out):	None	
Return value:	None	
Description:	This function is called by the lower layer after an I-PDU has been received.	

Caveats: This function might be called in interrupt context. Therefore, data consistency must be ensured.

8.4.3 Com_TxConfirmation

COM124:

Service name:	Com_TxConfirmation	
Syntax:	void Com_TxConfirmation(PduIdType ComTxPduId)	
Service ID[hex]:	0x15	
Sync/Async:	Synchronous	
Reentrancy:	Non reentrant for the same PDU-ID. Reentrant for different PDU-ID.	
Parameters (in):	ComTxPduId	ID of AUTOSAR COM I-PDU that has been transmitted. Range: 0..(maximum number of I-PDU IDs transmitted by AUTOSAR COM) - 1
Parameters (in-out):	None	
Parameters (out):	None	
Return value:	None	
Description:	This function is called by the lower layer after the PDU has been transmitted on the network. A confirmation that is received for an I-PDU that does not require a confirmation is silently discarded.	

Caveats: This function might be called in interrupt context (e.g. from transmit interrupt).

8.5 Scheduled Functions

8.5.1 Com_MainFunctionRx

COM398:

Service name:	Com_MainFunctionRx
Syntax:	void Com_MainFunctionRx()
Service ID[hex]:	0x18
Timing:	FIXED_CYCLIC
Description:	This function shall perform the processing of the AUTOSAR COM receive processing that are not directly initiated by the calls from the RTE and PDU-R. A call to Com_MainFunctionRx shall simply return if COM was not previously initialized with a call to Com_Init.

Configuration: see COM186.

8.5.2 Com_MainFunctionTx

COM399:

Service name:	Com_MainFunctionTx
Syntax:	void Com_MainFunctionTx()
Service ID[hex]:	0x19
Timing:	FIXED_CYCLIC
Description:	This function shall perform the processing of the AUTOSAR COM transmission activities that are not directly initiated by the calls from the RTE and PDU-R. A call to Com_MainFunctionTx shall simply return if COM was not previously initialized with a call to Com_Init.

Configuration: see COM186.

8.5.3 Com_MainFunctionRouteSignals

COM400:

Service name:	Com_MainFunctionRouteSignals
Syntax:	void Com_MainFunctionRouteSignals()
Service ID[hex]:	0x1a
Timing:	FIXED_CYCLIC
Description:	Calls the signal gateway part of COM to forward received signals to be routed. The insertion of this call is necessary for decoupling receive interrupts and signal gateway tasks. A call to Com_MainFunctionRouteSignals shall simply return if COM was not previously initialized with a call to Com_Init.

Caveat: The time between to consecutive calls (perhaps the related task/thread cycle) affects directly the signal gateway latency.

Configuration: A cyclic task/thread to call this function cyclical shall be configured. The cycle of this task/thread directly affects the latency of the signal gateway, see COM186.

8.6 Expected Interfaces

8.6.1 Mandatory Interfaces

This chapter defines all interfaces which are required to fulfill the core functionality of the module.

<i>API function</i>	<i>Module</i>	<i>Description</i>
PduR_ComTransmit	PDU-R	Request the transmission of I-PDU.
Dem_ReportErrorStatus	DEM	Routine to report production relevant error events by event ID.

8.6.2 Optional Interfaces

This chapter defines all interfaces that are required to fulfill an optional functionality of the module.

<i>API function</i>	<i>Module</i>	<i>Description</i>	<i>Configuration parameter (description see Chapter 10)</i>
Det_ReportError	DET	Development error notification	COM_CONFIGURATION_USE_DET

8.6.3 Configurable interfaces

Caveats: A callback routine runs either on interrupt level or on task level. Thus, the OS restrictions of usage of system functions for interrupt service routines as well as for tasks apply.

COM468:

Service name:	Com_CbkTxAck
Syntax:	void Com_CbkTxAck()
Sync/Async:	Synchronous
Reentrancy:	don't care
Parameters (in):	None
Parameters (in-out):	None
Parameters (out):	None
Return value:	None
Description:	This callback represents notification class 2 of [17]. It is called immediately after successful transmission of the I-PDU containing the message. Com_CbkTxAck is called on sender side only. It can be configured for signals and

	<p>signal groups. Com_CbkTxAck corresponds to Rte_COMCbktAck_<sn> or Rte_COMCbktAck_<sg> respectively.</p> <p>For configuration of the callback function names, see COM498.</p>
--	---

COM491:

Service name:	Com_CbkTxErr
Syntax:	void Com_CbkTxErr()
Sync/Async:	Synchronous
Reentrancy:	don't care
Parameters (in):	None
Parameters (in-out):	None
Parameters (out):	None
Return value:	None
Description:	<p>This callback corresponds to notification class 4 of [17]. It is called in case the transmission is not possible because the corresponding I-PDU group is stopped.</p> <p>Com_CbkTxErr is called on sender side only. This callback function corresponds to Rte_COMCbktErr_<sn> or Rte_COMCbktErr_<sg> respectively.</p> <p>For configuration of the callback function name, see COM499.</p>

COM554:

Service name:	Com_CbkTxTOut
Syntax:	void Com_CbkTxTOut()
Sync/Async:	Synchronous
Reentrancy:	don't care
Parameters (in):	None
Parameters (in-out):	None
Parameters (out):	None
Return value:	None
Description:	<p>This callback corresponds to notification class 4 of [17]. It is called immediately after a message transmission error has been detected by the deadline monitoring mechanism.</p> <p>Com_CbkTxTOut is called on sender side only. It can be configured for signals and signal groups. This callback function corresponds to Rte_COMCbktOut_<sn> or Rte_COMCbktOut_<sg> respectively.</p> <p>For configuration of the callback function names, see COM552.</p>

COM555:

Service name:	Com_CbkRxAck
Syntax:	void Com_CbkRxAck()

)
Sync/Async:	Synchronous
Reentrancy:	don't care
Parameters (in):	None
Parameters (in-out):	None
Parameters (out):	None
Return value:	None
Description:	<p>This callback represents notification class 1 of [17]. It is called immediately after the message has been stored in the receiving message object.</p> <p>Com_CbkRxAck is called on receiver side only . It can be configured for signals and signal groups. Com_CbkRxAck corresponds to Rte_COMCbk_<sn> or Rte_COMCbk_<sg> respectively.</p> <p>For configuration of the callback function names, see COM498.</p>

COM556:

Service name:	Com_CbkRxTOut
Syntax:	void Com_CbkRxTOut()
Sync/Async:	Synchronous
Reentrancy:	don't care
Parameters (in):	None
Parameters (in-out):	None
Parameters (out):	None
Return value:	None
Description:	<p>This callback corresponds to notification class 3 of [17]. It is called immediately after a message reception error has been detected by the deadline monitoring mechanism.</p> <p>Com_CbkRxTOut is called on receiver side only. It can be configured for signals and signal groups. This callback function corresponds to Rte_COMCbkTOut_<sn> or Rte_COMCbkTOut_<sg> respectively.</p> <p>For configuration of the callback function names, see COM552.</p>

COM536:

Service name:	Com_CbkInv
Syntax:	void Com_CbkInv()
Sync/Async:	Synchronous
Reentrancy:	don't care
Parameters (in):	None
Parameters (in-out):	None
Parameters (out):	None
Return value:	None
Description:	<p>This callback function corresponds to COM100. It is called after reception of an invalid signal or signal group respectively.</p>

	<p>Com_CbkInv is called on receiver side only . It can be configured for signals, group signals and signal groups.</p> <p>This callback function corresponds to Rte_COMCbklv_<sn> (for signals and group signals) and Rte_COMCbklv_<sg> respectively.</p> <p>For configuration of the callback function names, see COM315.</p>
--	--

Note: The naming conventions for the RTE callback routines are defined in [13] in Chapter “Naming convention of callbackRoutineName”.

Note: AUTOSAR COM uses no direct interface of RTE beside the callback functions.

9 Sequence diagrams

A sequence diagram of the underlying OSEK COM communication stack can be found in [17].

9.1 Interface between AUTOSAR COM and the lower layer (PDU Router)

The following chart shows the communication between AUTOSAR COM and the PDU Router.

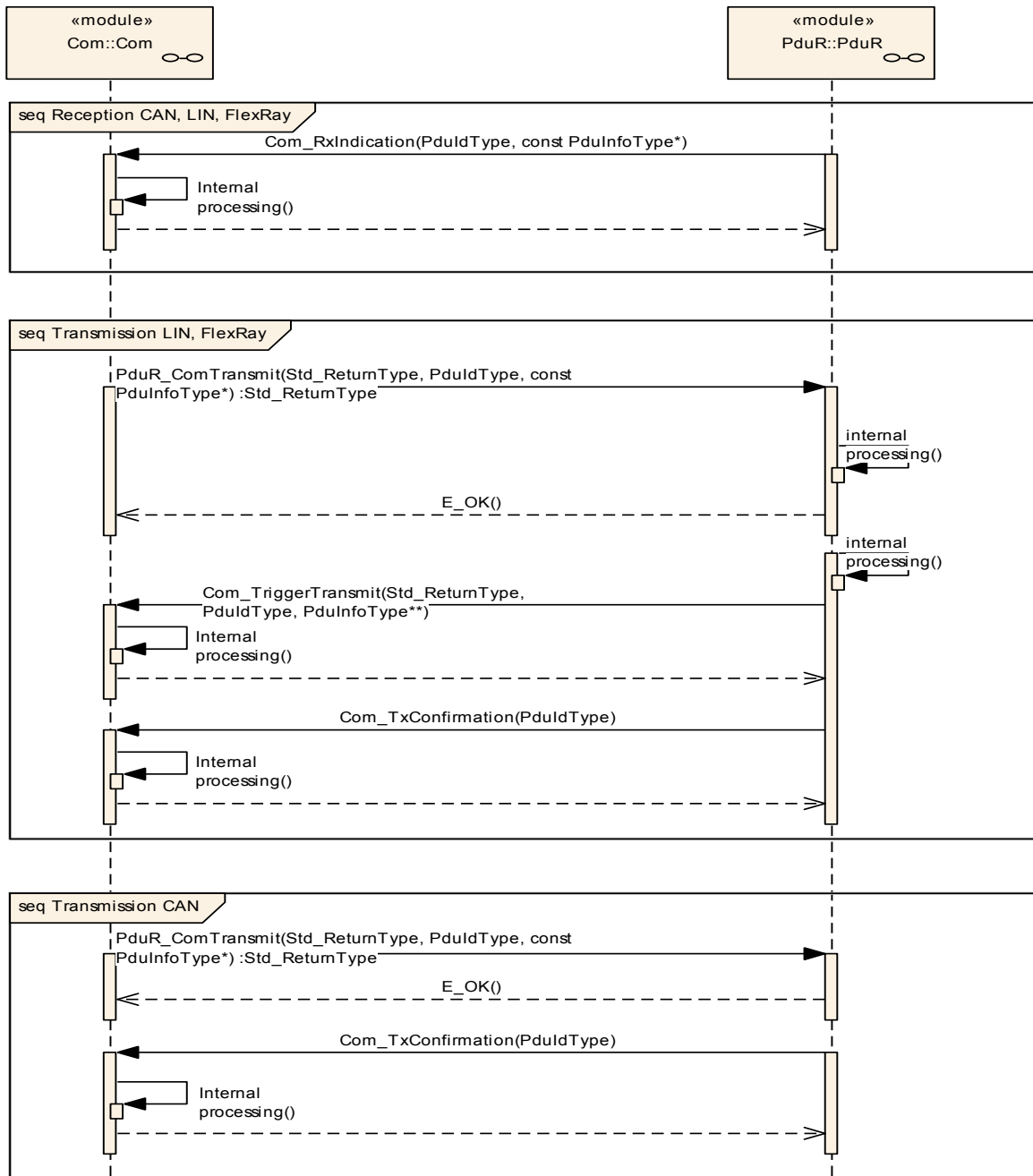


Figure 16: Interactions between AUTOSAR COM and the PDU router

9.2 Confirmation handling between PDUR, COM and RTE

The following chart shows the confirmation handling with respect to the two different IPDU-processing modes. (See also Chapter 7.4.5.3.)

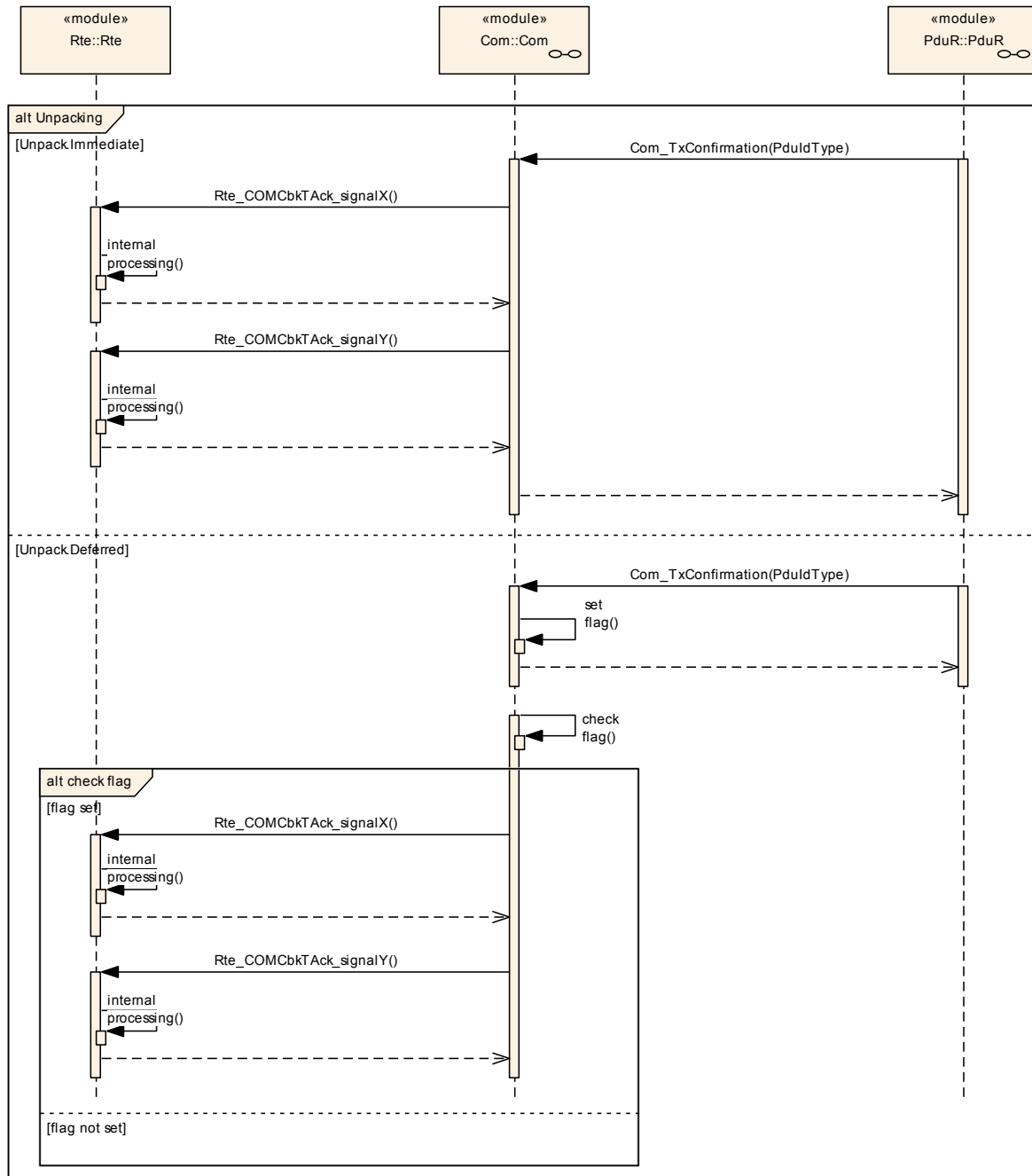


Figure 17: Confirmation handling between PDUR, COM and RTE

9.3 Indication handling between PDUR, COM and RTE

The following chart shows the indication handling with respect to the two different unpacking modes. (See also Chapter 7.4.5.3.)

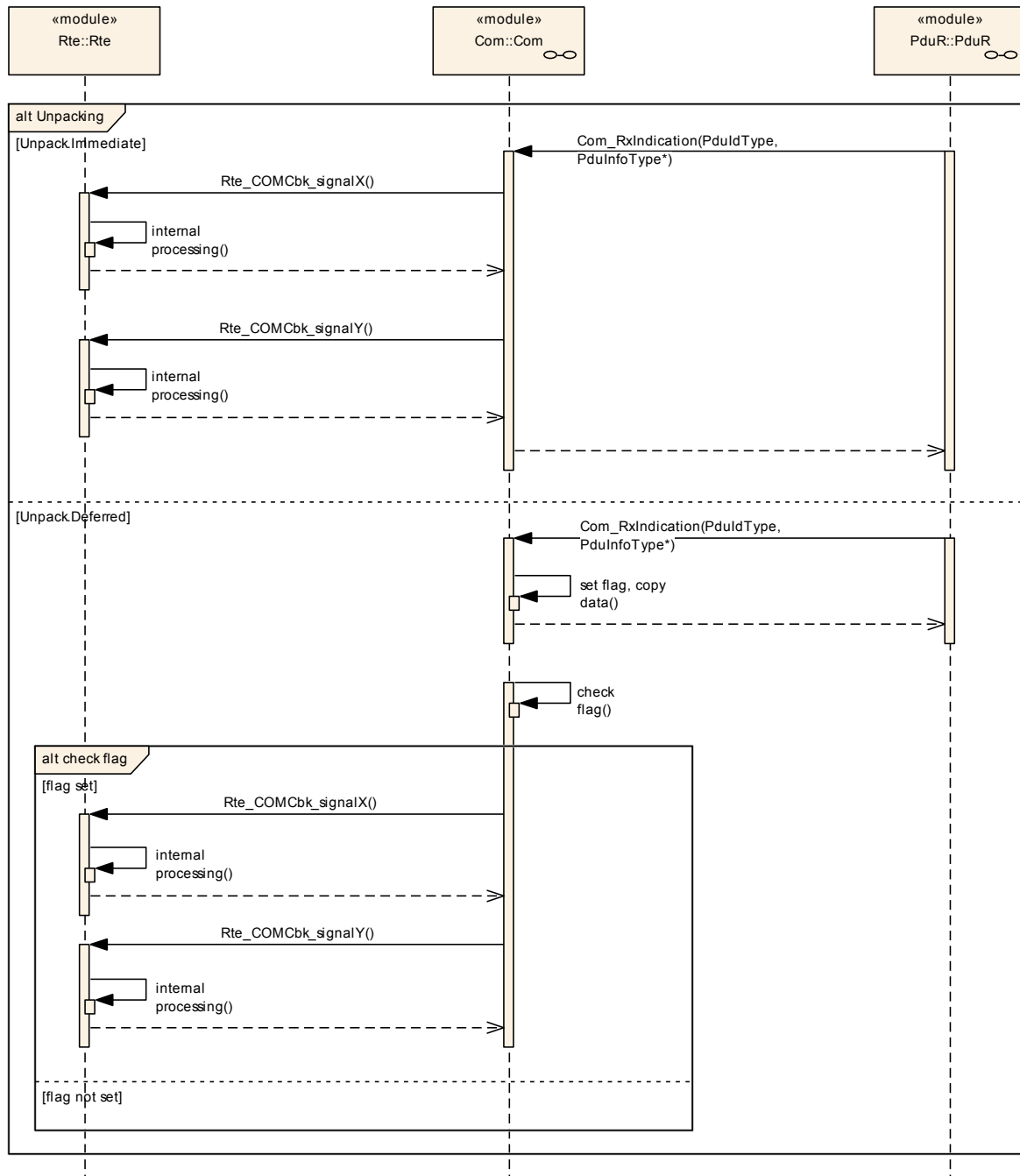


Figure 18: Indication handling between PDUR, COM and RTE

10 Configuration specification

10.1 How to read this chapter

In addition to this section, it is highly recommended to read the documents:

- AUTOSAR Layered Software Architecture [1]
- AUTOSAR ECU Configuration Specification [14]
This document describes the AUTOSAR configuration methodology and the AUTOSAR configuration meta model in detail.

The following is only a short survey of the topic and it will not replace the ECU Configuration Specification document.

10.1.1 Configuration and configuration parameters

Configuration parameters define the variability of the generic part(s) of an configuration of a module. This means that only generic or configurable module implementation can be adapted to the environment (software/ hardware) in use during system and/ or ECU configuration.

The configuration of parameters can be achieved at different times during the software process: before compile time, before link time or after build time. In the following, the term **configuration class** (of a parameter) shall be used in order to refer to a specific configuration point in time.

COM006: The configuration parameters are based on [18]. All parameters have to be stored in an XML format.

10.1.2 Containers

Containers structure the set of configuration parameters. This means: *all* configuration parameters are kept in containers. (sub-) containers can reference (sub-) containers. It is possible to assign a multiplicity to these references. The multiplicity then defines the possible number of instances of the contained parameters.

10.2 Containers and configuration parameters

The following chapters summarize all configuration parameters. The detailed meanings of the parameters describe Chapter 7 and Chapter 8.

10.2.1 Variants

Currently three configuration variants for AUTOSAR COM are defined.

COM374: All configuration sets shall be identifiable by a unique identifier, see COM394.

10.2.1.1 VARIANT-PRE-COMPILE

VARIANT-PRE-COMPILE only supports pre-compile configurable parameters. Parameters below that are marked as Pre-compile configurable shall be configurable in a pre-compile manner, for example as #defines. A VARIANT-PRE-COMPILE module is most likely delivered as source code.

Remark: Even though the module is delivered as source code the implementation might use techniques similar to link time, i.e. table driven configuration.

10.2.1.2 VARIANT-LINK-TIME

VARIANT-LINK-TIME includes mainly link-time and some pre-compile configurable parameters. All parameters defined below as link-time configurable shall be configurable at link time for example by linking a special configured parameter object file.

A VARIANT-LINK-TIME module is most likely delivered as object code.

10.2.1.3 VARIANT-POST-BUILD

VARIANT-POST-BUILD includes post-build-time, link-time and some pre-compile configurable parameters. All parameters defined below as post build configurable shall be configurable post build for example by flashing configuration data.

A VARIANT-POST-BUILD configurable module is most likely delivered as object code.

10.2.2 Configuration of the AUTOSAR COM Layer

For an overview of the COM Configuration see Figure 19:

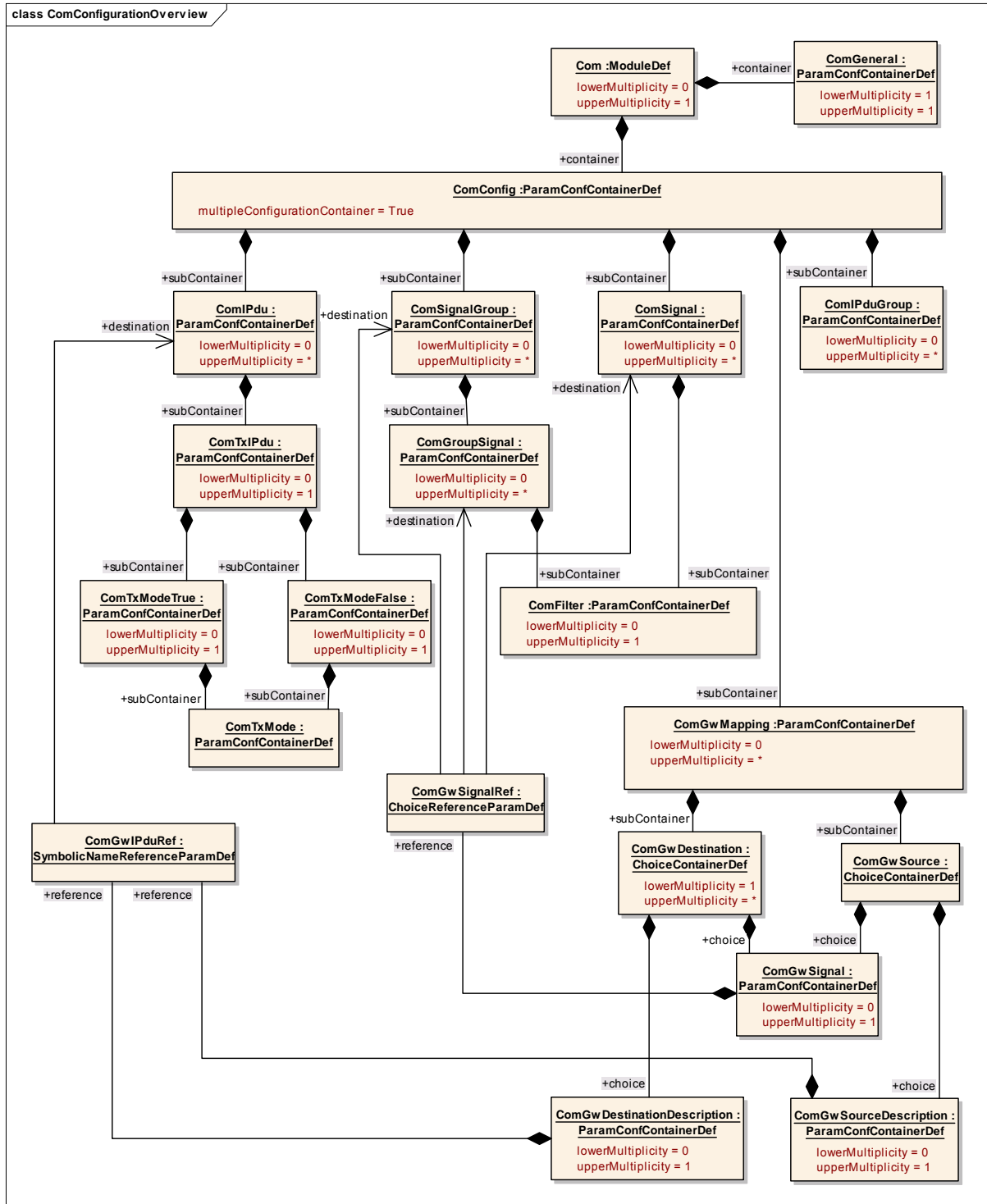


Figure 19: Com Configuration Overview

10.2.3 Com

Module Name	Com
Module Description	COM540: Configuration of the Com module.

Included Containers		
Container Name	Multiplicity	Scope / Dependency
ComConfig	1	This container contains the configuration parameters and sub containers of the COM module. This container is a Multiple-ConfigurationContainer, i.e. this container and its sub-containers exist once per configuration set.
ComGeneral	1	Contains the general configuration parameters of the Com module.

10.2.4 ComConfig

SWS Item	COM337 :
Container Name	ComConfig [Multi Config Container]
Description	This container contains the configuration parameters and sub containers of the COM module. This container is a MultipleConfigurationContainer, i.e. this container and its sub-containers exist once per configuration set.
Configuration Parameters	

SWS Item	COM394 :		
Name	ComConfigurationId		
Description	This ID is returned by a call to Com_GetConfigurationId.		
Multiplicity	1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

Included Containers		
Container Name	Multiplicity	Scope / Dependency
ComGwMapping	0..*	Each instance of this container defines one mapping of the integrated Signal Gateway.
ComIPdu	0..*	COM404: See COM340. If there is no such container included no I-PDU is defined. In this case only internal communication is possible.
ComIPduGroup	0..*	COM405: See COM341 If there is no such container included then no I-PDU group is defined. In this case only internal communication is possible.
ComSignal	0..*	COM407: At least one signal container shall be present, see COM344.
ComSignalGroup	0..*	COM408: If there is no such container included no signal groups are defined.

COM404: See COM340, if there is no ComIpdu container included no I-PDUs are defined. In this case no communication via COM is possible.

COM405: See COM341, if there is no ComIPduGroup container included then no I-PDU group is defined. In this case no communication via COM is possible.

COM407: See COM344, if there is no ComSignal container included no single signals are defined.

COM408: See COM345, if there is no ComSignalGroup container included no signal groups are defined.

10.2.5 ComGeneral

SWS Item	COM541 :		
Container Name	ComGeneral		
Description	Contains the general configuration parameters of the Com module.		
Configuration Parameters			

SWS Item	COM186 :		
Name	ComConfigurationTimeBase		
Description	The period between successive calls to the Main Functions (Rx, Tx, Routing) of AUTOSAR COM in seconds.		
Multiplicity	1		
Type	FloatParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM141 :		
Name	ComConfigurationUseDet		
Description	The error hook shall contain code to call the Det. If this parameter is configured COM_DEV_ERROR_DETECT shall be set to ON as output of the configuration tool. (as input for the source code), see COM028.		
Multiplicity	0..1		
Type	BooleanParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM438 :		
Name	ComVersionInfoApi		
Description	Activate/Deactivate the version information API (Com_GetVersionInfo).		

	True: version information API activated False: version information API deactivated		
Multiplicity	1		
Type	BooleanParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: Local		

No Included Containers

10.2.6 ComFilter

SWS Item	COM339 :
Container Name	ComFilter
Description	This container contains the configuration parameters of COM Filters. Note: On sender side the container is used to specify the transmission mode conditions.
Configuration Parameters	

SWS Item	COM146 :		
Name	ComFilterAlgorithm		
Description	The range of values is specified in the [17] specification, chapter 2.2.2, Reception Filtering.		
Multiplicity	1		
Type	EnumerationParamDef		
Range	ALWAYS		
	MASKED_NEW_DIFFERS_MASKED_OLD		
	MASKED_NEW_DIFFERS_X		
	MASKED_NEW_EQUALS_X		
	NEVER		
	NEW_IS_OUTSIDE		
	NEW_IS_WITHIN		
	ONE_EVERY_N		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM235 :		
Name	ComFilterMask		
Description	The name of this attribute corresponds to the parameter name in the [17] specification of Reception Filtering. Only the least significant 32 bits are significant.		
Multiplicity	0..1		

Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM317 :		
Name	ComFilterMax		
Description	The name of this attribute corresponds to the parameter name in the [17] specification of Reception Filtering. Only the least significant 32 bits are significant.		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM318 :		
Name	ComFilterMin		
Description	The name of this attribute corresponds to the parameter name in the [17] specification of Reception Filtering. Only the least significant 32 bits are significant.		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM313 :		
Name	ComFilterOffset		
Description	The name of this attribute corresponds to the parameter name in the [17] specification of Reception Filtering. Only the least significant 32 bits are significant. Range = 0..(ComFilterPeriodFactor-1)		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local dependency: COM312		

SWS Item	COM312 :		
Name	ComFilterPeriodFactor		
Description	The name of this attribute corresponds to the parameter name in the [17] specification of Reception Filtering. Only the least significant 32 are significant.		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM147 :		
Name	ComFilterX		
Description	The name of this attribute corresponds to the parameter name in the [17] specification of Reception Filtering. Only the least significant 32 bits are significant.		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

No Included Containers

10.2.7 ComIPdu

SWS Item	COM340, COM174 :		
Container Name	ComIPdu		
Description	Contains the configuration parameters of Com I-Pdus. COM174: The shortName is used as the symbolic name (ComIpduName) of this I-Pdu when communicating with the PduR. Is optional because the Com module might be used for internal communication only. This parameter is only stored in the XML file, and must not be used within the implementation.		
Configuration Parameters			

SWS Item	COM387 :		
Name	ComIPduCallout		
Description	If there is a callout defined for this I-PDU this parameter contains the name of the callout function..		
Multiplicity	0..1		
Type	FunctionNameDef		
Default value	--		

ConfigurationClass	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM175 :		
Name	ComIPduRxHandleId		
Description	The numerical value used as the ID of this I-PDU. The Com_IPduRxHandleId is required by the API calls to receive I-PDUs from the PduR. It is only present for I-PDU is received from the PduR, because Com is the starting module for Tx I-PDUs and there is no need to define IDs for Tx I-PDUs in the Com module.		
Multiplicity	0..1		
Type	IntegerParamDef (Symbolic Name generated for this parameter)		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: external, depends on configuration process		

SWS Item	COM119 :		
Name	ComIPduSignalProcessing		
Description	For the definition of the two modes Immediate and Deferred, see COM298.		
Multiplicity	0..1		
Type	EnumerationParamDef		
Range	DEFERED		
	IMMEDIATE		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM176 :		
Name	ComIPduSize		
Description	The size of the I-PDU in bytes. The maximum size is limited by the underlying communication interface. 0-8 for CAN and LIN 0-254 for FlexRay		
Multiplicity	1		
Type	IntegerParamDef		
Range	0 .. 254		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM493 :		
Name	ComIpduDirection		
Description	The direction defines if this I-PDU, and therefore the contributing signals and		

	signal groups, shall be send or received.		
Multiplicity	1		
Type	EnumerationParamDef		
Range	RECEIVE		
	SEND		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local dependency: If configured to Send also a ComTxIpdu container shall be included, see COM496		

SWS Item	COM206 :		
Name	ComIPduGroupRef		
Description	Reference to the I-PDU group this I-PDU belongs to.		
Multiplicity	1		
Type	Reference to ComIPduGroup		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM519 :		
Name	ComIPduSignalGroupRef		
Description	References to all signal groups contained in this I-Pdu		
Multiplicity	0..*		
Type	Reference to ComSignalGroup		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	COM518 :		
Name	ComIPduSignalRef		
Description	References to all signals contained in this I-PDU.		
Multiplicity	0..*		
Type	Reference to ComSignal		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	--		
Name	PduIdRef		
Description	Reference to the "global" Pdu structure to allow harmonization of handle IDs in the COM-Stack.		
Multiplicity	1		
Type	Reference to Pdu		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-POST-BUILD
	Post-build time	--	

Scope / Dependency		
Included Containers		
Container Name	Multiplicity	Scope / Dependency
ComTxIPdu	0..1	COM496: This container must be included if COM_IPDU_DIRECTION is configured to SEND.

COM497: A ComTxIPdu container must be included if ComIpdudirection is configured to Send.

10.2.8 ComTxIPdu

SWS Item	COM496 :
Container Name	ComTxIPdu
Description	This container contains additional transmission related configuration parameters of COM I-PDUs
Configuration Parameters	

SWS Item	COM181, COM471 :		
Name	ComTxIPduMinimumDelayTimeFactor		
Description	COM181: Minimum delay between successive transmissions of this I-PDU, independent of the transmission mode. There is only one minimum delay time parameter for the I-PDU. This minimum delay time does not change with mode changes. Neither is the timer reset. This means that mode changes are not allowed to violate the minimum delay time. It is not possible to monitor the minimum delay time for I-PDUs that are requested using the Com_TriggerTransmit API. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter. COM471: No minimum delay time monitoring shall take place, if ComTxIPduMinimumDelayTimeFactor is omitted or configured to 0.		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	COM017 :		
Name	ComTxIPduUnusedAreasDefault		
Description	AUTOSAR COM fills not used areas of an I-PDU with this bit-pattern. This attribute is mandatory to avoid undefined behaviour. This byte-pattern will be repeated throughout the I-PDU.		
Multiplicity	1		
Type	IntegerParamDef		
Range	0 .. 255		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-

			BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

Included Containers		
Container Name	Multiplicity	Scope / Dependency
ComTxModeFalse	0..1	COM234: The referenced transmission mode object that is used when the filtering state for this I-PDU evaluates to false The default is transmission mode None.
ComTxModeTrue	0..1	COM233: The referenced transmission mode object that is used when the filtering state for this I-PDU evaluates to true.

ComTxModeTrue: COM233: The referenced transmission mode object (see section 10.2.2.8) that is used when the filtering state for this I PDU evaluates to true.

ComTxModeFalse: COM234: The referenced transmission mode object (see section 10.2.2.8) that is used when the filtering state for this I PDU evaluates to false

The default is transmission mode None.

10.2.9 ComIPduGroup

SWS Item	COM341, COM126 :		
Container Name	ComIPduGroup		
Description	Contains the configuration parameters of Com I-Pdu groups. COM126: The shortName is used as the symbolic name of the I-Pdu group (ComIpdgroupName). This parameter is only stored in the XML file, and must not be used within the implementation.		
Configuration Parameters			

SWS Item	COM184 :		
Name	ComIPduGroupHandleId		
Description	The numerical value used as the ID of this I-PDU Group . The ComIPduGroupHandleId is required by the API calls to start and stop I-PDU Groups. For the rational for the range see COM187.		
Multiplicity	1		
Type	IntegerParamDef (Symbolic Name generated for this parameter)		
Range	0 .. 63		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: external, depends on configuration process		

SWS Item	COM185 :		
Name	ComIPduGroupGroupRef		
Description	If the I-PDU Group belongs to an I-PDU group, this is the name of the I-		

	PDU group it belongs to. This I-PDU Group does not belong to another I-PDU group, if this reference is omitted.		
Multiplicity	0..1		
Type	Reference to ComIPduGroup		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

No Included Containers

10.2.10 ComSignal

SWS Item	COM344, COM163 :		
Container Name	ComSignal		
Description	Contains the configuration parameters of Com signals. COM163: The shortName is used as the symbolic name of the signal (ComSignalName). This name is also used as the handle name for the signal. This parameter is only stored in the XML file, and must not be used within the implementation.		
Configuration Parameters			

SWS Item	COM259 :		
Name	ComBitPosition		
Description	Starting position within the I-PDU. This parameter refers to the position in the I-PDU and not in the shadow buffer.		
Multiplicity	1		
Type	IntegerParamDef		
Range	0 .. 63		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM158 :		
Name	ComBitSize		
Description	Size in bits.		
Multiplicity	1		
Type	IntegerParamDef		
Range	0 .. 64		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM314 :		
Name	ComDataInvalidAction		
Description	This parameter defines the action performed upon reception of an invalid signal. Relating to signal groups the action in case if one of the included signals is an invalid signal. If Replace is used the ComSignalInitValue will be used for the replacement.		
Multiplicity	0..1		
Type	EnumerationParamDef		
Range	NOTIFY		
	REPLACE		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM499 :		
Name	ComErrorNotification		
Description	Only valid on sender side: Name of Com_CbkTxErr callback function to be called. If this parameter is omitted no error notification shall take place.		
Multiplicity	0..1		
Type	FunctionNameDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	COM183 :		
Name	ComFirstTimeoutFactor		
Description	Defines the first timeout period for the deadline monitoring. Details can be found in [17]. Note: See also COM263 for the configuration of the remaining timeout periods. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter.		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM165 :		
Name	ComHandleId		
Description	The numerical value used as the ID. For signals it is required by the API calls Com_UpdateShadowSignal, Com_ReceiveShadowSignal and Com_InvalidateShadowSignal. For signal groups it is required by the Com_SendSignalGroup and Com_ReceiveSignalGroup calls.		

Multiplicity	1		
Type	IntegerParamDef (Symbolic Name generated for this parameter)		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: external, depends on configuration process		

SWS Item	COM315 :		
Name	ComInvalidNotification		
Description	Only valid on receiver side: Name of Com_CbkRxInv callback function to be called. Name of the function which notifies the RTE about the reception of an invalidated signal/ signal group. Only applicable if ComSignalDataInvalidAction is configured to Notify.		
Multiplicity	0..1		
Type	FunctionNameDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM498 :		
Name	ComNotification		
Description	On sender side: Name of Com_CbkTxAck callback function to be called. On receiver side: Name of Com_CbkRxAck callback function to be called. If this parameter is omitted no notification shall take place.		
Multiplicity	0..1		
Type	FunctionNameDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM412, COM470, COM500, COM513 :		
Name	ComRxDataTimeoutAction		
Description	COM412: This parameter defines the action performed upon a reception timeout violation. COM500: If this parameter is omitted or configured to None no replacement shall take place. COM470: Relating to signals: When this parameter is set to Replace, the replacement value used shall be the ComInitValue. COM513: Relating to signal groups: When this parameter is set to Replace, all included signals shall be set to their ComInitValue.		
Multiplicity	0..1		
Type	EnumerationParamDef		
Range	NONE		

	REPLACE		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM391, COM501 :		
Name	ComSignalDataInvalidValue		
Description	COM391: On receiver side: When this value is received it is recognized as the invalid value and the appropriate invalid action (as specified by ComDataInvalidAction) is performed. COM501: On sender side: This configures the data invalid value that is used by a call to Com_InvalidateSignal.		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM157 :		
Name	ComSignalEndianness		
Description	Defines the endianness of the signal's network representation.		
Multiplicity	1		
Type	EnumerationParamDef		
Range	BIG_ENDIAN		
	LITTLE_ENDIAN		
	OPAQUE		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM170, COM483 :		
Name	ComSignalInitValue		
Description	COM170: Initial value for this signal. The default value is 0. The lower n-bits of the configured Integer shall be used as init-value for an n-bit sized signal type. COM483: If the signal is of type UINT[n], the Integer's least significant byte shall be assigned to the byte array's last byte. The second-least significant byte shall be assigned to the byte array's last but one byte, and so on.		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	0		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local dependency: IpduM		

SWS Item	COM437 :		
Name	ComSignalLength		
Description	The ComSignalLength specifies the n (in Bytes: 1..8) of the type UINT8[n]. For other types it will be ignored.		
Multiplicity	0..1		
Type	IntegerParamDef		
Range	1 .. 8		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM127 :		
Name	ComSignalType		
Description	The AUTOSAR type of the signal. Whether or not the signal is signed or unsigned can be found by examining the value of this attribute. This type could also be used to reserved appropriate storage in AUTOSAR COM.		
Multiplicity	1		
Type	EnumerationParamDef		
Range	BOOLEAN		
	SINT16		
	SINT32		
	SINT8		
	UINT16		
	UINT32		
	UINT8		
	UINT8_N		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM263, COM264, COM333 :		
Name	ComTimeoutFactor		
Description	<p>COM263: Defines the timeout period for the deadline monitoring. Details can be found in [17]. Note: The period for the ComFirstTimeoutFactor could differ from the ComTimeoutFactor. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter.</p> <p>COM264: If deadline monitoring is used on a signal with an update-bit this defines the timeout for deadline monitoring.</p> <p>COM333: If the timeout is omitted or configured to 0 than no timeout monitoring shall take place. In this case ComFirstTimeoutFactor shall be ignored.</p>		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE

	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM552 :		
Name	ComTimeoutNotification		
Description	On sender side: Name of Com_CbkTxTOut callback function to be called. On receiver side: Name of Com_CbkRxTOut callback function to be called.		
Multiplicity	0..1		
Type	FunctionNameDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM232 :		
Name	ComTransferProperty		
Description	Defines if a write access to this signal can trigger the transmission of the corresponding I-PDU. If the I-PDU is triggered, depends also on the transmission mode of the corresponding I-PDU. TRIGGERED: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU. PENDING: A write access to this signal never triggers the transmission of the corresponding I-PDU. TRIGGERED_ON_CHANGE: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU, but only in case the written value is different to the locally stored (last written or init) value.		
Multiplicity	0..1		
Type	EnumerationParamDef		
Range	PENDING		
	TRIGGERED		
	TRIGGERED_ON_CHANGE		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM257 :		
Name	ComUpdateBitPosition		
Description	Bit position of update-bit inside I-PDU. If this attribute is omitted then there is no update-bit. This setting must be consistently on sender and on receiver side.		
Multiplicity	0..1		
Type	IntegerParamDef		
Range	0 .. 63		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME

	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	--		
Name	SystemTemplateSystemSignalRef		
Description	Reference to the ISignalToIPduMapping that contains a reference to the ISignal (System Template) which this ComSignal (or ComGroupSignal) represents.		
Multiplicity	1		
Type	Foreign reference to ISignalToIPduMapping		
ConfigurationClass	Pre-compile time	--	
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: system configuration		

Included Containers		
Container Name	Multiplicity	Scope / Dependency
ComFilter	0..1	This container contains the configuration parameters of COM Filters. Note: On sender side the container is used to specify the transmission mode conditions.

ComFilter: COM169: On receiver side:

The name of the filter type as defined in the filter object in section 11.3.1.

ComFilter: COM275: On sender side:

Reference to a filter object which is used to determine the transmission mode selector of the I PDU the signal belongs to.

If this attribute is omitted, the signal does not contribute to the evaluation of the transmission mode of the I PDU the signal belongs to.

10.2.11 ComSignalGroup

SWS Item	COM345, COM044 :		
Container Name	ComSignalGroup		
Description	Contains the configuration parameters of Com signal groups. COM044: The shortName is used as the symbolic name of the signal group (ComSignalGroupName). This name is also used as the handle name for the signal group. This parameter is only stored in the XML file, and must not be used within the implementation.		
Configuration Parameters			

SWS Item	COM259 :		
Name	ComBitPosition		
Description	Starting position within the I-PDU. This parameter refers to the position in the I-PDU and not in the shadow buffer.		
Multiplicity	1		
Type	IntegerParamDef		
Range	0 .. 63		

Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM158 :		
Name	ComBitSize		
Description	Size in bits.		
Multiplicity	1		
Type	IntegerParamDef		
Range	0 .. 64		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM314 :		
Name	ComDataInvalidAction		
Description	This parameter defines the action performed upon reception of an invalid signal. Relating to signal groups the action in case if one of the included signals is an invalid signal. If Replace is used the ComSignalInitValue will be used for the replacement.		
Multiplicity	0..1		
Type	EnumerationParamDef		
Range	NOTIFY		
	REPLACE	Literal for DataInvalidAction	
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM499 :		
Name	ComErrorNotification		
Description	Only valid on sender side: Name of Com_CbkTxErr callback function to be called. If this parameter is omitted no error notification shall take place.		
Multiplicity	0..1		
Type	FunctionNameDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	COM183 :		
Name	ComFirstTimeoutFactor		
Description	Defines the first timeout period for the deadline monitoring. Details can be found in [17].		

	Note: See also COM263 for the configuration of the remaining timeout periods. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter.		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM165 :		
Name	ComHandleId		
Description	The numerical value used as the ID. For signals it is required by the API calls Com_UpdateShadowSignal, Com_ReceiveShadowSignal and Com_InvalidateShadowSignal. For signals groups it is required by the Com_SendSignalGroup and Com_ReceiveSignalGroup calls.		
Multiplicity	1		
Type	IntegerParamDef (Symbolic Name generated for this parameter)		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: external, depends on configuration process		

SWS Item	COM315 :		
Name	ComInvalidNotification		
Description	Only valid on receiver side: Name of Com_CbkRxInv callback function to be called. Name of the function which notifies the RTE about the reception of an invalidated signal/ signal group. Only applicable if ComSignalDataInvalidAction is configured to Notify.		
Multiplicity	0..1		
Type	FunctionNameDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM498 :		
Name	ComNotification		
Description	On sender side: Name of Com_CbkTxAck callback function to be called. On receiver side: Name of Com_CbkRxAck callback function to be called. If this parameter is omitted no notification shall take place.		
Multiplicity	0..1		
Type	FunctionNameDef		

Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM412, COM470, COM500, COM513 :		
Name	ComRxDataTimeoutAction		
Description	<p>COM412: This parameter defines the action performed upon a reception timeout violation.</p> <p>COM500: If this parameter is omitted or configured to None no replacement shall take place.</p> <p>COM470: Relating to signals: When this parameter is set to Replace, the replacement value used shall be the ComInitValue.</p> <p>COM513: Relating to signal groups: When this parameter is set to Replace, all included signals shall be set to their ComInitValue.</p>		
Multiplicity	0..1		
Type	EnumerationParamDef		
Range	NONE	Literal for DataTimeoutAction	
	REPLACE	Literal for DataTimeoutAction	
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM263, COM264, COM333 :		
Name	ComTimeoutFactor		
Description	<p>COM263: Defines the timeout period for the deadline monitoring. Details can be found in [17].</p> <p>Note: The period for the ComFirstTimeoutFactor could differ from the ComTimeoutFactor. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter.</p> <p>COM264: If deadline monitoring is used on a signal with an update-bit this defines the timeout for deadline monitoring.</p> <p>COM333: If the timeout is omitted or configured to 0 than no timeout monitoring shall take place. In this case ComFirstTimeoutFactor shall be ignored.</p>		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM552 :		
Name	ComTimeoutNotification		
Description	<p>On sender side: Name of Com_CbkTxTOut callback function to be called.</p> <p>On receiver side: Name of Com_CbkRxTOut callback function to be called.</p>		
Multiplicity	0..1		
Type	FunctionNameDef		

Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM232 :		
Name	ComTransferProperty		
Description	<p>Defines if a write access to this signal can trigger the transmission of the corresponding I-PDU. If the I-PDU is triggered, depends also on the transmission mode of the corresponding I-PDU.</p> <p>TRIGGERED: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU.</p> <p>PENDING: A write access to this signal never triggers the transmission of the corresponding I-PDU.</p> <p>TRIGGERED_ON_CHANGE: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU, but only in case the written value is different to the locally stored (last written or init) value.</p>		
Multiplicity	0..1		
Type	EnumerationParamDef		
Range	PENDING		
	TRIGGERED		
	TRIGGERED_ON_CHANGE		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM257 :		
Name	ComUpdateBitPosition		
Description	<p>Bit position of update-bit inside I-PDU.</p> <p>If this attribute is omitted then there is no update-bit. This setting must be consistently on sender and on receiver side.</p>		
Multiplicity	0..1		
Type	IntegerParamDef		
Range	0 .. 63		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	--		
Name	SystemTemplateSignalGroupRef		
Description	Reference to the ISignalToIPduMapping that contains a reference to the ISignal (SystemTemplate) which this ComSignalGroup represents.		
Multiplicity	1		
Type	Foreign reference to ISignalToIPduMapping		
ConfigurationClass	Pre-compile time	--	
	Link time	--	

	Post-build time	--	
Scope / Dependency	scope: system configuration		

Included Containers		
Container Name	Multiplicity	Scope / Dependency
ComGroupSignal	0..*	COM520: This container contains the configuration parameters of group signals. I.e. signals that are included within a signal group. COM521: The shortName is used as the symbolic name of the signal (ComSignalName). This name is also used as the handle name for the signal. This parameter is only stored in the XML file, and must not be used within the implementation.

10.2.12 ComGroupSignal

SWS Item	COM520, COM521 :
Container Name	ComGroupSignal
Description	COM520: This container contains the configuration parameters of group signals. I.e. signals that are included within a signal group. COM521: The shortName is used as the symbolic name of the signal (ComSignalName). This name is also used as the handle name for the signal. This parameter is only stored in the XML file, and must not be used within the implementation.
Configuration Parameters	

SWS Item	COM259 :		
Name	ComBitPosition		
Description	Starting position within the I-PDU. This parameter refers to the position in the I-PDU and not in the shadow buffer.		
Multiplicity	1		
Type	IntegerParamDef		
Range	0 .. 63		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM158 :		
Name	ComBitSize		
Description	Size in bits.		
Multiplicity	1		
Type	IntegerParamDef		
Range	0 .. 64		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	

Scope / Dependency	scope: Local
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SWS Item	COM165 :		
Name	ComHandleId		
Description	The numerical value used as the ID. For signals it is required by the API calls Com_UpdateShadowSignal, Com_ReceiveShadowSignal and Com_InvalidateShadowSignal. For signals groups it is required by the Com_SendSignalGroup and Com_ReceiveSignalGroup calls.		
Multiplicity	1		
Type	IntegerParamDef (Symbolic Name generated for this parameter)		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: external, depends on configuration process		

SWS Item	COM315 :		
Name	ComInvalidNotification		
Description	Only valid on receiver side: Name of Com_CbkRxInv callback function to be called. Name of the function which notifies the RTE about the reception of an invalidated signal/ signal group. Only applicable if ComSignalDataInvalidAction is configured to Notify.		
Multiplicity	0..1		
Type	FunctionNameDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM391, COM501 :		
Name	ComSignalDataInvalidValue		
Description	COM391: On receiver side: When this value is received it is recognized as the invalid value and the appropriate invalid action (as specified by ComDataInvalidAction) is performed. COM501: On sender side: This configures the data invalid value that is used by a call to Com_InvalidateSignal.		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM157 :		
Name	ComSignalEndianess		

Description	Defines the endianness of the signal's network representation.		
Multiplicity	1		
Type	EnumerationParamDef		
Range	BIG_ENDIAN		
	LITTLE_ENDIAN		
	OPAQUE		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM170, COM483 :		
Name	ComSignalInitValue		
Description	COM170: Initial value for this signal. The default value is 0. The lower n-bits of the configured Integer shall be used as init-value for an n-bit sized signal type. COM483: If the signal is of type UINT[n], the Integer's least significant byte shall be assigned to the byte array's last byte. The second-least significant byte shall be assigned to the byte array's last but one byte, and so on.		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	0		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local dependency: IpduM		

SWS Item	COM437 :		
Name	ComSignalLength		
Description	The ComSignalLength specifies the n (in Bytes: 1..8) of the type UINT8[n]. For other types it will be ignored.		
Multiplicity	0..1		
Type	IntegerParamDef		
Range	1 .. 8		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM127 :		
Name	ComSignalType		
Description	The AUTOSAR type of the signal. Whether or not the signal is signed or unsigned can be found by examining the value of this attribute. This type could also be used to reserved appropriate storage in AUTOSAR COM.		
Multiplicity	1		
Type	EnumerationParamDef		
Range	BOOLEAN		
	SINT16		

	SINT32		
	SINT8		
	UINT16		
	UINT32		
	UINT8		
	UINT8_N		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM560 :		
Name	ComTransferProperty		
Description	<p>Optionally defines whether this group signal shall contribute to the TRIGGERED_ON_CHANGE transfer property of the signal group. If at least one group signal of a signal group has the "ComTransferProperty" configured all other group signals of that signal group shall have the attribute configured as well.</p> <p>PENDING: a change of the value of this group signal shall not be considered in the evaluation of the signal groups ComTransferProperty.</p> <p>TRIGGERED_ON_CHANGE: a change of the value of this group signal shall be considered in the in the evaluation of the signal groups ComTransferProperty.</p>		
Multiplicity	0..1		
Type	EnumerationParamDef		
Range	PENDING		
	TRIGGERED_ON_CHANGE		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	--		
Name	SystemTemplateSystemSignalRef		
Description	Reference to the ISignalToIPduMapping that contains a reference to the ISignal (System Template) which this ComSignal (or ComGroupSignal) represents.		
Multiplicity	1		
Type	Foreign reference to ISignalToIPduMapping		
ConfigurationClass	Pre-compile time	--	
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: system configuration		

Included Containers		
Container Name	Multiplicity	Scope / Dependency
ComFilter	0..1	This container contains the configuration parameters of COM Filters. Note: On sender side the container is used to specify the transmission mode conditions.

10.2.13 ComTxMode

SWS Item	COM351 :
Container Name	ComTxMode
Description	This container contains the configuration parameters of COM transmission modes.
Configuration Parameters	

SWS Item	COM137 :		
Name	ComTxModeMode		
Description	The available transmission modes described in [18] shall be extended by the additional mode None. The transmission mode None shall not have any further sub-attributes in the ComTxMode object.		
Multiplicity	1		
Type	EnumerationParamDef		
Range	DIRECT		
	MIXED		
	NONE	Literal for TxMode	
	PERIODIC		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM281 :		
Name	ComTxModeNumberOfRepetitions		
Description	Defines the number of repetitions for the Direct/N-Times transmission mode and the event driven part of Mixed transmission mode.		
Multiplicity	0..1		
Type	IntegerParamDef		
Range	0 .. 255		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM282 :		
Name	ComTxModeRepetitionPeriodFactor		
Description	Period of the repetition of the n transmission for the Direct/NTimes transmission mode and the event driven part of the Mixed transmission mode. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter.		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE

	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM180 :		
Name	ComTxModeTimeOffsetFactor		
Description	Time until first transmission of this I-PDU. ComTxModeTimeOffsetFactor defines the time between Com_IpduGroupStart and the first transmission of the cyclic part of this transmission request for this I-PDU. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter.		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM178 :		
Name	ComTxModeTimePeriodFactor		
Description	Period of the repetition of cyclic transmissions. Depending on the implementation, this timeout may be implemented as a 32-bit or a 16-bit counter.		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

No Included Containers

10.2.14 ComTxModeTrue

SWS Item	COM455 :		
Container Name	ComTxModeTrue		
Description	This container contains the configuration parameters of COM transmission modes in the case the ComFilter evaluates to true.		
Configuration Parameters			

Included Containers		
Container Name	Multiplicity	Scope / Dependency
ComTxMode	1	This container contains the configuration parameters of COM transmission modes.

10.2.15 ComTxModeFalse

SWS Item	COM454 :
Container Name	ComTxModeFalse
Description	This container contains the configuration parameters of COM transmission modes in the case the ComFilter evaluates to false.
Configuration Parameters	

Included Containers		
Container Name	Multiplicity	Scope / Dependency
ComTxMode	1	This container contains the configuration parameters of COM transmission modes.

10.2.16 ComGwMapping

SWS Item	COM544 :
Container Name	ComGwMapping
Description	Each instance of this container defines one mapping of the integrated Signal Gateway.
Configuration Parameters	

Included Containers		
Container Name	Multiplicity	Scope / Dependency
ComGwDestination	1..*	Each instance of this choice container allows to define one routing destination either by reference to an already configured COM signal / signal group or by a destination description container.
ComGwSource	1	This choice container allows the definition of the gateway source signal either by reference to an already configured COM signal / signal group or by a source description container.

10.2.17 ComGwSource

SWS Item	COM545 :
Choice Container Name	ComGwSource
Description	This choice container allows the definition of the gateway source signal either by reference to an already configured COM signal / signal group or by a source description container.

Container Choices		
Container Name	Multiplicity	Scope / Dependency
ComGwSignal	0..1	This container allows specifying a gateway source or destination respectively with a reference to a ComSignal, a ComGroupSignal or a ComSignalGroup.
ComGwSourceDescription	0..1	Description of a gateway source. This container allows defining a gateway source without the configuration of a complete

		COM signal. This allows adding / changing gateway relations post build without the configuration of new signals.
--	--	--

10.2.18 ComGwSourceDescription

SWS Item	COM548 :		
Container Name	ComGwSourceDescription		
Description	Description of a gateway source. This container allows defining a gateway source without the configuration of a complete COM signal. This allows adding / changing gateway relations post build without the configuration of new signals.		
Configuration Parameters			

SWS Item	COM259 :		
Name	ComBitPosition		
Description	Starting position within the I-PDU. This parameter refers to the position in the I-PDU and not in the shadow buffer.		
Multiplicity	1		
Type	IntegerParamDef		
Range	0 .. 63		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM158 :		
Name	ComBitSize		
Description	Size in bits.		
Multiplicity	1		
Type	IntegerParamDef		
Range	0 .. 64		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM157 :		
Name	ComSignalEndianess		
Description	Defines the endianness of the signal's network representation.		
Multiplicity	1		
Type	EnumerationParamDef		
Range	BIG_ENDIAN		
	LITTLE_ENDIAN		
	OPAQUE		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD

Scope / Dependency	scope: Local		
SWS Item	COM127 :		
Name	ComSignalType		
Description	The AUTOSAR type of the signal. Whether or not the signal is signed or unsigned can be found by examining the value of this attribute. This type could also be used to reserved appropriate storage in AUTOSAR COM.		
Multiplicity	1		
Type	EnumerationParamDef		
Range	BOOLEAN		
	SINT16		
	SINT32		
	SINT8		
	UINT16		
	UINT32		
	UINT8		
	UINT8_N		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM257 :		
Name	ComUpdateBitPosition		
Description	Bit position of update-bit inside I-PDU. If this attribute is omitted then there is no update-bit. This setting must be consistently on sender and on receiver side.		
Multiplicity	0..1		
Type	IntegerParamDef		
Range	0 .. 63		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM550 :		
Name	ComGwlPduRef		
Description	Symbolic reference to an I-PDU of a Signal Gateway source or destination description.		
Multiplicity	1		
Type	Reference to ComIPdu		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency			

No Included Containers

10.2.19 ComGwDestination

SWS Item	COM546 :
Choice Container Name	ComGwDestination
Description	Each instance of this choice container allows to define one routing destination either by reference to an already configured COM signal / signal group or by a destination description container.

Container Choices		
Container Name	Multiplicity	Scope / Dependency
ComGwDestinationDescription	0..1	Description of a gateway destination. This container allows defining a gateway destination without the configuration of a complete COM signal. This allows adding / changing gateway relations post build without the configuration of new signals.
ComGwSignal	0..1	This container allows specifying a gateway source or destination respectively with a reference to a ComSignal, a ComGroupSignal or a ComSignalGroup.

10.2.20 ComGwDestinationDescription

SWS Item	COM549 :
Container Name	ComGwDestinationDescription
Description	Description of a gateway destination. This container allows defining a gateway destination without the configuration of a complete COM signal. This allows adding / changing gateway relations post build without the configuration of new signals.
Configuration Parameters	

SWS Item	COM259 :		
Name	ComBitPosition		
Description	Starting position within the I-PDU. This parameter refers to the position in the I-PDU and not in the shadow buffer.		
Multiplicity	1		
Type	IntegerParamDef		
Range	0 .. 63		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM391, COM501 :		
Name	ComSignalDataInvalidValue		
Description	COM391: On receiver side: When this value is received it is recognized as the invalid value and the appropriate invalid action (as specified by ComDataInvalidAction) is performed. COM501: On sender side: This configures the data invalid value that is used by a call to Com_InvalidateSignal.		
Multiplicity	0..1		
Type	IntegerParamDef		

Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	--	
Scope / Dependency	scope: Local		

SWS Item	COM157 :		
Name	ComSignalEndianess		
Description	Defines the endianness of the signal's network representation.		
Multiplicity	1		
Type	EnumerationParamDef		
Range	BIG_ENDIAN		
	LITTLE_ENDIAN		
	OPAQUE		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM170, COM483 :		
Name	ComSignalInitValue		
Description	COM170: Initial value for this signal. The default value is 0. The lower n-bits of the configured Integer shall be used as init-value for an n-bit sized signal type. COM483: If the signal is of type UINT[n], the Integer's least significant byte shall be assigned to the byte array's last byte. The second-least significant byte shall be assigned to the byte array's last but one byte, and so on.		
Multiplicity	0..1		
Type	IntegerParamDef		
Default value	0		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local dependency: IpduM		

SWS Item	COM232 :		
Name	ComTransferProperty		
Description	Defines if a write access to this signal can trigger the transmission of the corresponding I-PDU. If the I-PDU is triggered, depends also on the transmission mode of the corresponding I-PDU. TRIGGERED: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU. PENDING: A write access to this signal never triggers the transmission of the corresponding I-PDU. TRIGGERED_ON_CHANGE: Depending on the transmission mode, a write access to this signal can trigger the transmission of the corresponding I-PDU, but only in case the written value is different to the locally stored (last written or init) value.		
Multiplicity	0..1		
Type	EnumerationParamDef		

Range	PENDING		
	TRIGGERED		
	TRIGGERED_ON_CHANGE		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM257 :		
Name	ComUpdateBitPosition		
Description	Bit position of update-bit inside I-PDU. If this attribute is omitted then there is no update-bit. This setting must be consistently on sender and on receiver side.		
Multiplicity	0..1		
Type	IntegerParamDef		
Range	0 .. 63		
Default value	--		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: Local		

SWS Item	COM550 :		
Name	ComGwIPduRef		
Description	Symbolic reference to an I-PDU of a Signal Gateway source or destination description.		
Multiplicity	1		
Type	Reference to ComIPdu		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency			

No Included Containers

10.2.21 ComGwSignal

SWS Item	COM551 :		
Container Name	ComGwSignal		
Description	This container allows specifying a gateway source or destination respectively with a reference to a ComSignal, a ComGroupSignal or a ComSignalGroup.		
Configuration Parameters			

SWS Item	COM547 :		
Name	ComGwSignalRef		
Description	Reference to an object of a gateway relation. Either to a ComSignal, ComGroupSignal or to a SignalGroup.		
Multiplicity	1		

Type	Choice Reference to ComGroupSignal,ComSignal,ComSignalGroup		
ConfigurationClass	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency			

No Included Containers

10.3 Published Information

Published information contains data defined by the implementer of the SW module that does not change when the module is adapted (i.e. configured) to the actual HW/SW environment. It thus contains version and manufacturer information.

COM026: The following table specifies parameters that shall be published in the module's header file and also in the module's description file.

The standard common published information like

- vendorId (<Module>_VENDOR_ID),
- onfigur (<Module>_MODULE_ID),
- arMajorVersion (<Module>_AR_MAJOR_VERSION),
- arMinorVersion (<Module>_AR_MINOR_VERSION),
- arPatchVersion (<Module>_AR_PATCH_VERSION),
- swMajorVersion (<Module>_SW_MAJOR_VERSION),
- swMinorVersion (<Module>_SW_MINOR_VERSION),
- swPatchVersion (<Module>_SW_PATCH_VERSION),
- vendorApiInfix (<Module>_VENDOR_API_INFIX)

is provided in the BSW Module Description Template (see 0 Figure 4.1 and Figure 7.1).

Additional published parameters are listed below if applicable for this module.

10.4 Defines

Besides the configuration the following defines shall be implemented:

COM028: If COM_DEV_ERROR_DETECT is set to ON, the detection and reporting of development errors is enabled for the AUTOSAR COM module. For configuration of this parameter see COM141.

Note: This parameter shall be an output of the configuration tool. (Input for the source code)

10.5 Configuration rules

10.5.1 General rules

COM401: It is illegal for any two of the following parameters to have the same value:

- shortName of a ComSignal
- shortName of a ComSignalGroup
- shortName of a ComIPdu
- shortName of a ComIPduGroup

COM560: It is illegal for any of the following five parameters:

- ComNotification
- ComErrorNotification
- ComTimeoutNotification
- ComInvalidNotification
- ComIPduCallout

to have the same value as any of the following four parameters

- shortName of a ComSignal
- shortName of a ComSignalGroup
- shortName of a ComIPdu
- shortName of a ComIPduGroup

COM402 It is illegal for any of the following parameters not to be formulated according to C's identifier rules:

- shortName of a ComSignal
- shortName of a ComSignalGroup
- shortName of a ComIPdu
- shortName of a ComIPduGroup
- ComNotification
- ComErrorNotification
- ComTimeoutNotification
- ComInvalidNotification
- ComIPduCallout

10.5.2 Signal configuration

COM489: It shall be ensured, that the data invalid value configured for the sender side is the same as configured for all receiver sides (see also COM097).

Note: The data invalid value shall not be within the valid range of the signal. This can not be enforced by COM since knowledge about the application is needed.

More than one signal can be packed into an I-PDU as long as the following packing rules are fulfilled:

COM101: No (group) signal shall span more than one I-PDU.

COM102: (Group) signals are not allowed to overlap each other.

COM105: Signals (no group signals or signal groups) which are represented in I-PDUs as a multiple of 8-bits shall start at byte border only.

Note: It is explicitly allowed that a (group) signal may have the size 0, see COM158.

COM443: A (group) signal of type uint8[n] shall always be mapped to an n-bytes sized (group) signal.

COM553: A (group) signal of type uint8[n] shall be configured to have OPAQUE endianness.

COM474: The initial value of a (group) signal shall always be within the possible range of the (group) signal (including the data invalid value).

Example: If a signal is of data-type uint8 has a bit-size of 6-bit the possible range is 0..63. In this case it shall not be allowed to configure an init value of 64 or greater.

10.5.3 Signal group configuration

COM365: It shall not be allowed to configure signal groups for routing with data type differences between receive and transmit signal group.

10.5.4 Transmission Mode configuration

COM319: It shall not be allowed to configure filter or TMS-conditions that uses floats. Floats are not allowed to be used in filter conditions. See [17] and COM132. Therefore floats are not allowed for conditions of TMS.

COM465: Every COM_TRANSMISSION_MODE_TRUE or COM_TRANSMISSION_MODE_FALSE that is a potential result of the configured/ calculated TMS must be configured. Within the COM_IPDU at least one of the containers COM_TRANSMISSION_MODE_FALSE or COM_TRANSMISSION_MODE_TRUE has to be included.

10.5.5 Signal Gateway configuration

COM384: The bit size of a received and to be routed signal shall not differ.

COM386: Optimization issue: In case of an I-PDU containing signals to be routed completely via a transmit I-PDU by retention the signal order and the signals endianness (related use case: rate conversion), it can be configured to be handled en bloc.

In case of a ComSignal to be routed by the Signal Gateway has been configured for deadline monitoring at the receiving node, depending on the use case, it is possible to configure update-bits, via ComUpdateBitPosition, for the transmit signal thus that it can be detected at the receiving node if the signal has really been update by the sender and is not just repeated not updated by the Signal Gateway.

10.5.6 Filter Configuration

COM535: For the filter F_OneEveryN, the COM_FILTER_OFFSET shall be configured to a value lesser than COM_FILTER_PERIOD_FACTOR.

10.5.7 Post Build Configuration

COM373: The post-build time configuration part (post-compile and post-link time) can only be updated when it is not in use

COM487: The whole post-build time configurable configuration shall be identifiable by a unique identifier.

11 Changes to Release 2.1

This chapter lists all modified SWS items. Additionally referenced figures, tables, notes and so on were updated.

11.1 Deleted SWS Items

SWS Item	Rationale
COM045	removed due to revision of the COM configuration
COM076	interaction of update-bits and Com_IpduGroupStart is now completely defined in COM222
COM116	deleted due to removal of internal communication
COM149	removed due to revision of the COM configuration
COM152	removed due to revision of the COM configuration
COM156	removed due to revision of the COM configuration
COM161	removed due to revision of the COM configuration
COM166	due to the removal of the internal communication the direction is configured via COM_IPDU_DIRECTION see COM493
COM167	removed due to revision of the COM configuration
COM216	removed due to revision of the COM configuration
COM246	removed due to revision of the COM configuration
COM247	removed due to revision of the COM configuration
COM248	removed due to revision of the COM configuration
COM258	removed due to revision of the COM configuration
COM267	removed due to revision of the COM configuration
COM285	turned requirement into a note, since it was redundant to N-Times requirements COM276 and accessory
COM316	removed due to revision of the COM configuration
COM343	removed due to revision of the COM configuration
COM349	deleted due to removal of internal communication
COM350	removed COM_SIGNAL_GROUP_TRANSFER_PROPERTY – the transfer property of the signal group shall be configured within the corresponding COM_NETWORK_SIGNAL
COM356	removed due to revision of the COM configuration
COM338	removed due to revision of the COM configuration
COM342	removed due to revision of the COM configuration
COM382	removed due to revision of the COM configuration
COM385	removed, as considered a unnecessary restriction
COM389	removed due to revision of the COM configuration
COM406	COM_NETWORK_SIGNAL was removed by revising the COM configuration
COM410	removed due to revision of the COM configuration
COM411	removed due to revision of the COM configuration
COM415	removed due to revision of the COM configuration
COM416	COM_RX_DATA_TIMEOUT_SUBSTITUTION shall be configured via the associated COM_NETWORK_SIGNAL
COM429	removed due to revision of the COM configuration
COM440	deleted due to removal of internal communication
COM441	deleted due to removal of internal communication

COM446	removed due to revision of the COM configuration
COM447	removed due to revision of the COM configuration
COM448	removed due to revision of the COM configuration
COM449	removed due to revision of the COM configuration
COM450	removed due to revision of the COM configuration
COM451	removed due to revision of the COM configuration
COM452	removed due to revision of the COM configuration
COM453	COM_NOTIFICATION_ERROR shall be configured via the associated COM_NETWORK_SIGNAL
COM456	deleted due to removal of internal communication
COM457	deleted due to removal of internal communication
COM458	changed to note due to revision of the COM configuration
COM462	became obsolete because of deleting COM350
COM463	removed due to revision of the COM configuration
COM482	deleted due to removal of internal communication
COM485	deleted due to removal of internal communication
COM490	deleted due to removal of internal communication

11.2 Replaced SWS Items

<i>SWS Item</i>	<i>Rationale</i>

11.3 Changed SWS Items

<i>SWS Item</i>	<i>Rationale</i>
COM001	harmonized TriggerTransmit APIs within the communication stack
COM013	removed internal communication
COM017	updated due to revision of the COM configuration
COM044	updated due to revision of the COM configuration
COM053	updated due to revision of the COM configuration
COM119	updated due to revision of the COM configuration
COM126	updated due to revision of the COM configuration
COM127	updated due to revision of the COM configuration
COM130	changed due to removal of internal communication
COM137	updated due to revision of the COM configuration
COM141	updated due to revision of the COM configuration
COM157	updated due to revision of the COM configuration
COM158	updated due to revision of the COM configuration
COM163	updated due to revision of the COM configuration
COM165	updated due to revision of the COM configuration
COM170	updated due to revision of the COM configuration
COM175	updated due to revision of the COM configuration
COM176	the maximum size of an I-PDU is no longer restricted to 8 bytes for FlexRay
COM178	updated due to revision of the COM configuration
COM180	updated due to revision of the COM configuration
COM181	updated due to revision of the COM configuration
COM183	updated due to revision of the COM configuration

COM184	extended maximum number of I-PDU groups to 64
COM185	updated due to revision of the COM configuration
COM186	updated due to revision of the COM configuration
COM187	extended maximum number of I-PDU groups to 64
COM197	replaced Com_ApplicationDataRefType by void* respectively const void* to allow usage of compiler abstraction macros
COM198	replaced Com_ApplicationDataRefType by void* respectively const void* to allow usage of compiler abstraction macros
COM199	replaced Com_ApplicationDataRefType by void* respectively const void* to allow usage of compiler abstraction macros
COM202	replaced Com_ApplicationDataRefType by void* respectively const void* to allow usage of compiler abstraction macros
COM206	updated due to revision of the COM configuration
COM222	included initialization information of update-bits
COM232	added TRIGGERED_ON_CHANGE
COM257	updated due to revision of the COM configuration
COM259	updated due to revision of the COM configuration
COM263	updated due to revision of the COM configuration
COM281	updated due to revision of the COM configuration
COM282	updated due to revision of the COM configuration
COM287	clarified requirement
COM291	updated due to revision of the COM configuration
COM314	updated due to revision of the COM configuration
COM315	updated due to revision of the COM configuration
COM328	updated due to removal of internal communication
COM330	adapted to new transfer property TRIGGER_ON_CHANGE
COM339	updated due to revision of the COM configuration
COM355	updated due to revision of the COM configuration
COM380	clarification of filter-usage for uint[n]
COM384	clarification of Signal Gateway behavior
COM387	updated due to revision of the COM configuration
COM391	updated due to revision of the COM configuration
COM396	changed order of execution
COM401	removed several items
COM404	updated due to removal of internal communication
COM407	updated due to revision of the COM configuration
COM412	updated due to revision of the COM configuration
COM430	renamed Com_PCcf.c to Com_Cfg.c according to the General SRS
COM432	updated due to removal of internal communication
COM437	updated due to revision of the COM configuration
COM438	updated due to revision of the COM configuration
COM442	added instancelid
COM459	development COM_SERVICE_NOT_AVAILABLE also might indicate development error removed E_NOT_OK since it is no longer used
COM468	harmonization of COM-RTE callback interface: Com_CbkTxAck
COM469	clarified minimum delay time handling
COM470	updated due to revision of the COM configuration
COM471	updated due to revision of the COM configuration
COM491	harmonization of COM-RTE callback interface: Com_CbkTxAck
COM493	updated due to revision of the COM configuration

11.4 Added SWS Items

SWS Item	Rationale
COM492	clarification if an I-PDU-Callout has to be called in conjunction with COM_TriggerIPDU_Send
COM493	due to the removal of the internal communication the direction is configured within the I-PDU via COM_IPDU_DIRECTION.
COM494	clarification of N-Times request within Mixed transmission mode
COM495	clarification of TMS-switch to Cyclic transmission mode
COM496	added due to revision of the COM configuration
COM497	added due to revision of the COM configuration
COM498	added due to revision of the COM configuration
COM499	added due to revision of the COM configuration
COM500	added due to revision of the COM configuration
COM501	added due to revision of the COM configuration
COM513	added due to revision of the COM configuration
COM518	added due to revision of the COM configuration
COM519	added due to revision of the COM configuration
COM520	added due to revision of the COM configuration
COM521	added due to revision of the COM configuration
COM534	clarification of reception deadline monitoring mechanism
COM535	added configuration rule for F_OneEveryN filter
COM536	harmonization of COM-RTE callback interface: Com_CbkInV
COM539	restrict send out of I-PDUs while one call to Com_MainFunctionRouteSignals
COM540	ComModuleDef
COM541	configuration container ComGeneral added according to actual Meta-Model
COM544	configuration container ComGwMapping added according to actual MetaModel
COM545	configuration container ComGwSource added according to actual Meta-Model
COM546	configuration container ComGwDestination added according to actual MetaModel
COM547	configuration container ComGwSignalRef added according to actual MetaModel
COM548	configuration container ComGwSourceDescription added according to actual MetaModel
COM549	configuration container ComGwDestinationDescription added according to actual MetaModel
COM550	configuration container ComGwIPduRef added according to actual MetaModel
COM551	configuration container ComGwRef added according to actual MetaModel
COM552	configuration container ComTimeoutNotification added according to actual MetaModel
COM553	restricted configuration of uint8[n] signal types
COM554	harmonization of COM-RTE callback interface: Com_CbkTxTOut
COM555	harmonization of COM-RTE callback interface: Com_CbkRxAck
COM556	harmonization of COM-RTE callback interface: Com_CbkRxTOut
COM557	added API Com_InvalidateSignalGroup
COM558	clarified the reception of an invalidated signal
COM559	clarified the reception of an invalidated signal
COM560	removed unnecessary configuration restrictions by splitting COM401

<i>SWS Item</i>	<i>Rationale</i>
COM561	clarified starting of deadline monitoring
COM562	clarified minimum delay time handling
COM563	added new transfer property TRIGGERED_ON_CHANGE
COM564	transfer properties of signal groups clarified
COM565	transfer properties of signal groups clarified
COM566	transfer properties of signal groups clarified
COM567	transfer properties of signal groups clarified
COM568	handling of update-bits in signal gateway specified
COM569	handling of update-bits in signal gateway specified
COM570	handling of update-bits in signal gateway specified
COM571	handling of update-bits in signal gateway specified
COM572	handling of update-bits in signal gateway specified
COM573	handling of update-bits in signal gateway specified
COM574	defined handling of I-PDUs having a size smaller than expected
COM575	defined handling of I-PDUs having a size smaller than expected

12 Appendix A

In the following use cases with different transmission modes and the necessary configuration for these are shown. For the legend of the pictures see Chapter 7.4.3.6.

Use Case A1 shows an I-PDU which is sent out cyclically with a cycle time t_c . This I-PDU consists of signals which all have the Pending transfer property. It is configured that the send out takes place when the TMS evaluates to true.

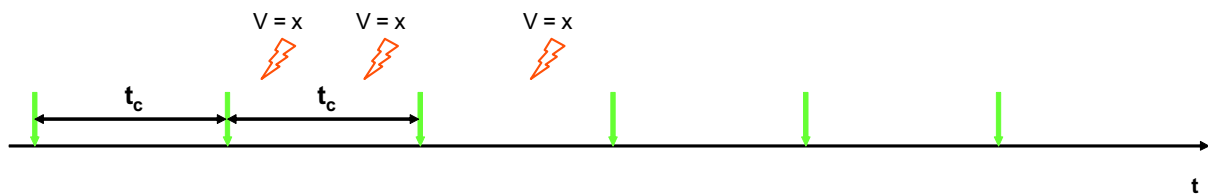


Figure 20: Use Case A1, TM periodic (without TMS switch (see Chapter 7.4.3.3))

Relevant configuration items for the I-PDU transmission		
Object SIGNAL		
TRANSFERPROPERTY		Pending or Triggered (Triggered has no influence)
Object COM_FILTER		
FILTERALGORITHM		F_ALWAYS
Object I-PDU		
PROPERTY		Sent
Object TRANSMISSION MODE on filter true		
TIMEPERIOD		t_c
MODE		periodic
NUMBER_OF_REPETITIONS		N/a
REPETITION_PERIOD		N/a
Object TRANSMISSION MODE on filter FALSE		
		N/a

Because of the configuration of the parameter FILTERALGORITHM (F_ALWAYS) of the COM_FILTER, there is no need to configure a transmission mode for the case that the TMS evaluates to false.

It does not make any difference in the behavior whether the FILTERALGORITHM parameter of the COM_FILTER is defined in the configuration for all the signals within the I-PDU with F_ALWAYS or if the COM_FILTER is not defined (shall not contribute to the evaluation of the TMS), see COM255.

Use Case A2 shows an I-PDU which is sent out three times whenever a value is given by the upper (Com_SendSignal or Com_SendSignalGroup). The time between two send outs is t_d . This I-PDU consists of signals which all have the Triggered transfer property. It is configured that the send out takes place when the TMS evaluates to true.

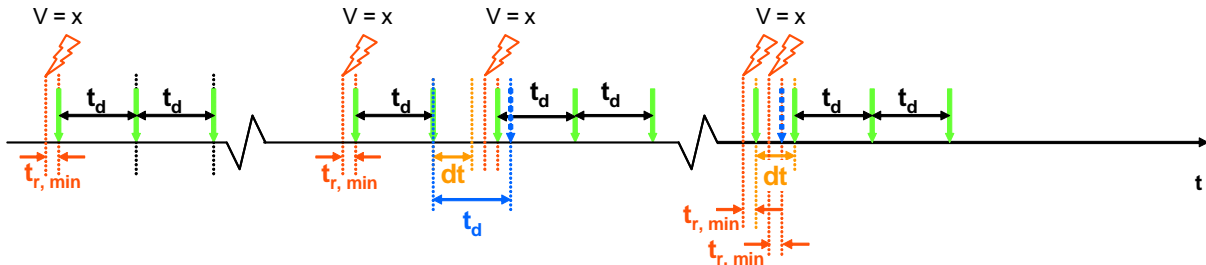


Figure 21: Use Case A2, TM Direct/N-Times, here $n = 3$ (without TMS switch)

Relevant configuration items for the I-PDU transmission	
Object SIGNAL	
TRANSFERPROPERTY	Triggered
Object COM_FILTER	
FILTERALGORITHM	F_ALWAYS
Object I-PDU	
PROPERTY	Sent
Object TRANSMISSION MODE on filter true	
TIMEPERIOD	N/a
MODE	Direct/N-Times
NUMBER_OF_REPETITIONS	3
REPETITION_PERIOD	t_d
Object TRANSMISSION MODE on filter false	
	N/a

If there is a new send request by the upper layer before the last three sent outs have taken place, the new sent out is started and the rest of the last one is discarded.

Use case A3 shows an I-PDU which is send out cyclically with a cycle time t_{c1} if value $v = a$ (TMS evaluates to true) and with a cycle time t_{c2} if value $v = b$ (TMS evaluates to false). The I-PDU consists of signals which all have the Pending transfer property.

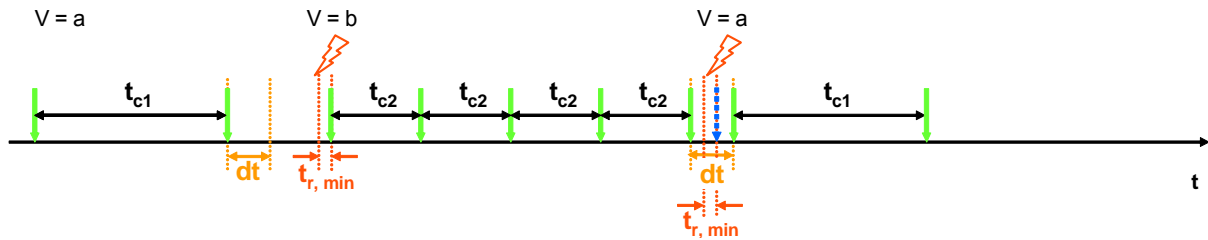


Figure 22: Use case A3, TM periodic + periodic (with TMS switch)

Relevant configuration items for the I-PDU transmission		
Object SIGNAL		
TRANSFERPROPERTY		Pending or Triggered (Triggered has no influence)
Object COM_FILTER		
FILTERALGORITHM		all except F_ALWAYS and F_Never
Object I-PDU		
PROPERTY		Sent
Object TRANSMISSION MODE on filter true		
TIMEPERIOD		t_{c1}
MODE		periodic
NUMBER_OF_REPETITIONS		N/a
REPETITION_PERIOD		N/a
Object TRANSMISSION MODE on filter false		
TIMEPERIOD		t_{c2}
MODE		periodic
NUMBER_OF_REPETITIONS		N/a
REPETITION_PERIOD		N/a

Because of the TMS switch caused by the new value $v = b$, the new cycle is started immediately and the new value is sent out. But nevertheless the minimum delay time dt has to be taken into account.

For the parameter FILTERALGORITHM of the configuration object COM_FILTER every in OSEK COM defined item can be used except F_ALWAYS and F_NEVER. These are:

- F_Always
- F_Never
- F_MaskedNewEqualsX
- F_MaskedNewDiffersX
- F_MaskedNewDiffersMaskedOld

- F_NewIsWithin
- F_NewIsOutside
- F_OneEveryN

If the FILTERALGORITHM F_OneEveryN is used not the value of the signal itself has an influence to the TMS but the number of send requests by the upper layer.

Use Case A4 shows an I-PDU which is send out cyclically with a cycle time t_c if value $v = a$ (TMS evaluates to true) and if value $v = b$ (TMS evaluates to false) it is sent out three times whenever the value is given by the upper layer. The time between two send outs is t_d . The I-PDU consists of signals which all have the Triggered transfer property.

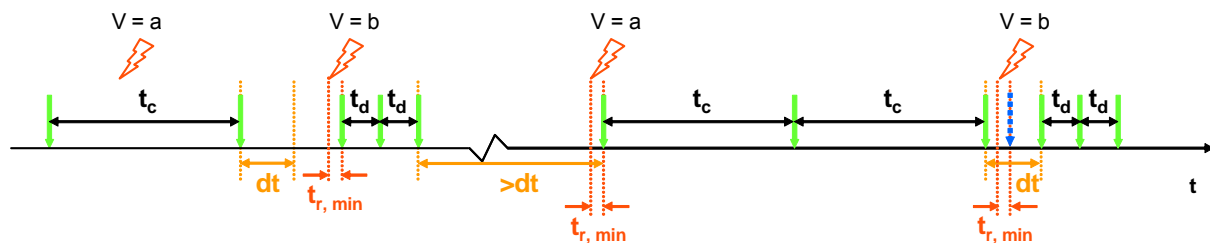


Figure 23: Use Case 4, TM periodic + Direct/N-Times, here n = 3 (with TMS switch)

Relevant configuration items for the I-PDU transmission		
Object SIGNAL		
TRANSFERPROPERTY		Triggered
Object COM_FILTER		
FILTERALGORITHM		all except F_ALWAYS and F_Never
Object I-PDU		
PROPERTY		Sent
Object TRANSMISSION MODE on filter true		
TIMEPERIOD		t_c
MODE		periodic
NUMBER_OF_REPETITIONS		N/a
REPETITION_PERIOD		N/a
Object TRANSMISSION MODE on filter false		
TIMEPERIOD		N/a
MODE		Direct/N-Times
NUMBER_OF_REPETITIONS		3
REPETITION_PERIOD		t_d

After the switch from Direct/N-Times to periodic the cycle is started immediately and the new value a is sent out (with respect of the minimum delay time dt).

Use case A5 shows an I-PDU which is send out cyclically with a cycle time t_c and if the value (the same or a new one) is given by the upper layer it is also sent out directly three times. The time between two of these three send outs is always t_d . The I-PDU consists of signals which all have the Triggered transfer property.

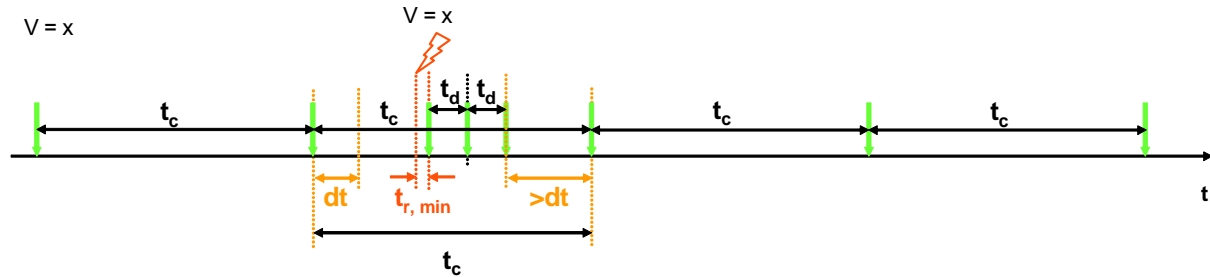


Figure 24: Use Case 5a, TM Mixed, here $n = 3$ (without TMS switch)

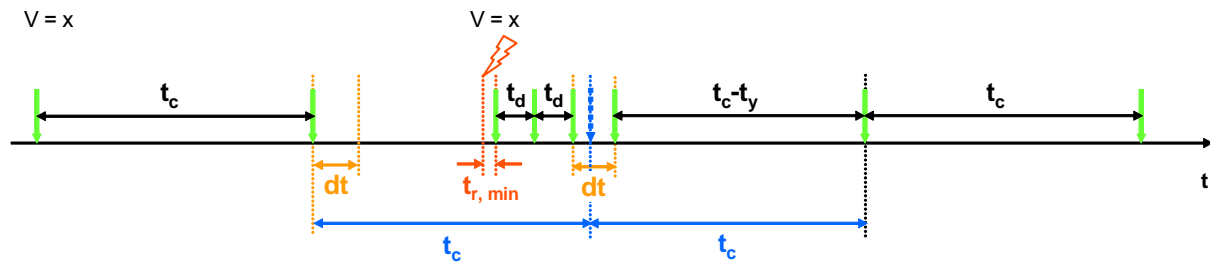


Figure 25: Use Case 5b, TM Mixed, here $n = 3$ (without TMS switch), no phase shift

Relevant configuration items for the I-PDU transmission		
Object SIGNAL		
TRANSFERPROPERTY		Triggered
Object COM_FILTER		
FILTERALGORITHM		F_ALWAYS
Object I-PDU		
PROPERTY		Sent
Object TRANSMISSION MODE on filter true		
TIMEPERIOD		t_c
MODE		Mixed
NUMBER_OF_REPETITIONS		3
REPETITION_PERIOD		t_d
Object TRANSMISSION MODE on filter false		
		N/a

If the next sent out caused by the periodic part of the Mixed transmission mode should take place within the timeout dt (minimum delay time) after a sent out of the

Direct/N-Times part, this sent out is delayed until the minimum delay time is elapsed. But after that the next time period of the periodic part is shortened so that there is only an intermediate phase shift of the periodic part but no continuous one.

Use case A6 shows an I-PDU which is send out cyclically with a cycle time t_{c2} if value $v = b$ (TMS evaluates to false). If value $v = a$ (TMS evaluates to true) it is sent out cyclically with a cycle time t_{c1} and whenever the value $v = a$ is given by the upper layer it is also sent out directly three times. The time between two of these three send outs is always t_d . The I-PDU consists of signals which all have the Triggered transfer property.

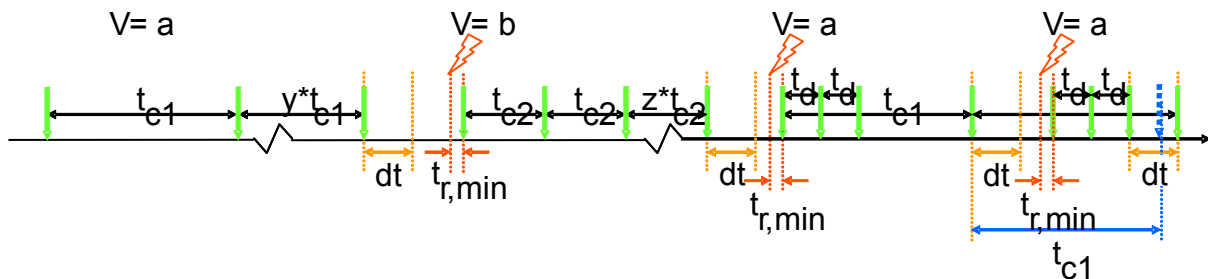


Figure 26: Use Case 6, TM Mixed, here $n = 3 +$ periodic (with TMS switch)

Relevant configuration items for the I-PDU transmission		
Object SIGNAL		
TRANSFERPROPERTY		Triggered
Object COM_FILTER		
FILTERALGORITHM		all except F_ALWAYS and F_Never
Object I-PDU		
PROPERTY		Sent
Object TRANSMISSION MODE on filter true		
TIMEPERIOD		t_{c1}
MODE		Mixed
NUMBER_OF_REPETITIONS		3
REPETITION_PERIOD		t_d
Object TRANSMISSION MODE on filter false		
TIMEPERIOD		t_{c2}
MODE		periodic
NUMBER_OF_REPETITIONS		N/a
REPETITION_PERIOD		N/a

A usage of this in practice is for example the signal of the button that controls the window-lift motor. If the button is not pressed there is a long cycle time t_{c1} with this information. If it is pressed this information is distributed with a short cycle time t_{c2} . If

the button is released again, this information is immediately distributed three times with t_d and after that again the long cycle time is used.