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1 Introduction

1.1 Objective and Scope

AUTOSAR requires a common technical approach for at least the major development steps, called the AUTOSAR methodology.

The methodology for the AUTOSAR Classic Platform is given by [1], whereas this document defines the methodology for the AUTOSAR Adaptive Platform.

The corresponding requirements are defined in [2].

The present expansion was necessary, because the AUTOSAR Adaptive Platform has introduced new concepts.

In contrast to the AUTOSAR Classic Platform, instances of Adaptive Software, are executed within the context of processes (which are entities managed by the operating system). If permitted by the configuration of the operating system, processes may be started, executed or stopped, at any time during the life cycle of a Machine. As a consequence, the way of configuration (by the means of Manifests) or when and how software packages are deployed (e.g., by software updates over-the-air) clearly differ from the concepts of the AUTOSAR Classic Platform.

Moreover, the term Machine has been newly introduced with the AUTOSAR Adaptive Platform. A Machine is quasi a virtualized ECU, an entity where software can be deployed to. In this spirit, one real ECU could run several Machines, even though the methodology will not detail this. In the simplest case the term Machine may only be a synonym for ECU.

Although the list is not complete, aforementioned aspects may serve as sufficient motivation to provide a separate methodology for the AUTOSAR Adaptive Platform.

Despite all the differences, there are also many commonalities, such as the description of the system features, like topologies or hardware capabilities. This document, however, will rather focus on the specifics of the AUTOSAR Adaptive platform, in order to avoid duplications. The specification of the common aspects of both platforms may be the subject of a separate document (foundation document) later.

[TR_AMETH_00100] Scope of the Methodology for the AUTOSAR Adaptive Platform [The methodology for the AUTOSAR Adaptive Platform describes main aspects (use-cases, tasks, work products, ...) necessary to build an Adaptive AUTOSAR system and how they relate to each other. However, the methodology does neither provide a complete process description, nor does it stipulate a precise order of activities. Iterations of activities are possible, but it is not described how and when iterations shall be carried out.] (RS_METH_00006, RS_METH_00020, RS_METH_00056)



1.2 Document Outline

This document will follow the policies of the AUTOSAR Classic Platform, i.e., the way how to model use-cases, how to structure the document and the way to specify.

Thus, the outline of this document follows roughly its counterpart of the AUTOSAR Classic Platform:

The rest of this section documents the policies utilized and the requirements traceability map.

Section 2 describes the major use cases for the development of a system implementing an AUTOSAR Adaptive Platform. Note that the description of the life cycle of a Software Package is not included in the AUTOSAR methodology.

Section 3 lists and describes all tasks and work products, which are used in the descriptions of the use cases in section 2.

1.3 Document Conventions

This document follows a list of document conventions, which are described in the following.

Technical terms of AUTOSAR are typeset in mono spaced font, e.g. ECU. As a general rule, plural forms of technical terms are created by adding "s" to the singular form, e.g. ECUs.

This document contains specification items in textual form that are distinguished from the rest of the text by a unique numerical ID, a headline, and the actual text starting after the \[\] character and terminated by the \[\] character. The conventions for requirements traceability follow [TPS STDT 00080], see Standardization Template ([3]).

1.4 Abbreviations

The following table contains a list of abbreviations used in the scope of this document along with the spelled-out meaning of each of the abbreviations.

Abbreviation	Meaning
ABI	Application Binary Interface
AP	AUTOSAR Adaptive Platform
API	Application Programming Interface





 \triangle

Abbreviation	Meaning				
ARXML	AUTOSAR XML				
CP	AUTOSAR Classic Platform				
DoIP	Diagnostics over IP				
DM	Diagnostic Manager				
DTC	Diagnostic Trouble Code				
ECU	Electronic Control Unit, for CP also used in the sense of ECU-Instance				
E/E system	Electric and Electronic system				
HW	Hardware				
ID	Identifier				
IP	Internet Protocol				
JSON	JavaScript Object Notation				
(Adaptive) Ma- chine	Machine that represents an Adaptive AUTOSAR Software Stack.				
Manifest	A description to specify the behavior of an AUTOSAR platform module or service.				
NM	Network Management				
NV	Non-Volatile				
OEM	Original Equipment Manufacturer				
OS	Operating System				
PHM	Platform Health Management				
PortInterface	An AUTOSAR interface that is used an AUTOSAR Software Component.				
POSIX	Portable Operating System Interface				
SD	Service Discovery				
SOME/IP	Scalable service-Oriented MiddlewarE over IP				
SWC	Software Component				
TCP	Transport Control Protocol				
TLV	Tag Length Value				
UCM	Update and Configuration Management				
UDS	Unified Diagnostic Services				
UDP	User datagram Protocol				
UML	Unified Modeling Language				
UUID	Universally Unique Identifier				
VFB	Virtual Functional Bus				





Δ

Abbreviation	Meaning
XML	Extensible Markup Language
XSD	XML Schema Definition

Table 1.1: Abbreviations used in the scope of this Document

1.5 Methodology Concepts

The concepts of the methodology for the Adaptive Platform are identical with the concepts of the methodology for the Classic Platform. Hence, we will only mention the main principles here. Please refer to section 1.5 in [1] for further details.

[TR_AMETH_00101] Definition of tasks, work products and use cases [The methodology describes typical use cases by means of activitys, entities to aggregate tasks and their corresponding work products. Tasks are defined as reusable elements: input information (e.g., stored within particular work products) is processed in order to generate new work products. [(RS_METH_00018)]

[TR_AMETH_00102] Types and kinds of work products [Work products are either artifacts or deliverables and can be of the kind AUTOSAR XML, source code, object code, executable, text or custom. | (RS METH 00018)

[TR_AMETH_00226] Documentation of work products [In order to document design decisions or restrictions during the development process, each work product may aggregate a corresponding documentation. | (RS_METH_00069)

The definitions and the figures are made according to the Software Process Engineering Meta-Model Specification (SPEM) [4]. The symbols are those used by the Enterprise Architect modeling tool.

1.6 Requirements Traceability

The following table references the requirements specified in the corresponding requirements document [2].

Requirement	Description	Satisfied by
[RS_METH_00006]	The methodology shall explain	[TR_AMETH_00016]
	how to build an AUTOSAR	[TR_AMETH_00100]
	system	
[RS_METH_00015]	The methodology shall be independent of programming	[TR_AMETH_00013]
	languages	

¹This document describes use cases in Section 2, tasks and work products in Section 3.



IDC METH 000161	The weetherdeless, shall accomment	ITD AMETIL 000101
[RS_METH_00016]	The methodology shall support	[TR_AMETH_00212]
	building a system of both AUTOSAR and Non-AUTOSAR	[TR_AMETH_00213]
	ECUs	
IDC METH 000401		ITD AMETIL 004041
[RS_METH_00018]	The methodology shall be	[TR_AMETH_00101]
	modular	[TR_AMETH_00102]
IDO METIL 000001	The results adalasm about a marant	[TR_AMETH_00200]
[RS_METH_00020]	The methodology shall support	[TR_AMETH_00100]
IDO METIL OCCOOL	round-trip engineering	ITD AMETIL 000041
[RS_METH_00032]	The methodology shall support	[TR_AMETH_00001]
	different levels of abstractions	[TR_AMETH_00002]
		[TR_AMETH_00200]
		[TR_AMETH_00201]
		[TR_AMETH_00202]
IDC METH 000411	The methodology shall support	[TR_AMETH_00205]
[RS_METH_00041]	The methodology shall support	[TR_AMETH_00019]
	top-down and bottom-up	[TR_AMETH_00020]
	approaches	[TR_AMETH_00034]
		[TR_AMETH_00035]
IDC METH 000401	The methodology shall	[TR_AMETH_00204]
[RS_METH_00042]	The methodology shall incorporate the usage of	[TR_AMETH_00013]
	, ,	[TR_AMETH_00018]
[RS_METH_00056]	industry standard tools The AUTOSAR methodology	[TR AMETH 00100]
[H3_ME1H_00030]	shall not be bound to a particular	[TH_AMETH_00100]
	life-cycle model	
[RS_METH_00066]	The methodology shall allow	[TR AMETH 00012]
[H3_WETT_00000]	activities that reference tools	[TR AMETH 00013]
	activities that reference tools	[TR_AMETH_00016]
		[TR_AMETH_00018]
[RS_METH_00069]	It shall be possible to add	[TR AMETH 00226]
[precise and human readable	[TT_TIMETTI_OOLEO]
	documentation to each work	
	product	
[RS_METH_00077]	The methodology shall support	[TR AMETH 00014]
	different views on the SW-C	[TR AMETH 00015]
	structure by OEMs and suppliers	[TR_AMETH_00016]
	, , , , , , , , , , , , , , , , , , , ,	TR_AMETH_00024]
[RS_METH_00078]	The methodology shall explain	[TR_AMETH_00029]
-	the typical usage of different	[TR_AMETH_00033]
	views on the system of the OEM	[TR_AMETH_00203]
[RS_METH_00079]	The methodology shall explain	[TR_AMETH_00203]
	the typical usage of different	
	views on the system of the	
	supplier	
[RS_METH_00200]	The methodology shall support	[TR_AMETH_00208]
	building a system consisting of	[TR_AMETH_00209]
	several AUTOSAR platforms	[TR_AMETH_00210]
[RS_METH_00201]	The methodology shall explain	[TR_AMETH_00001]
	how to design the services of a	[TR_AMETH_00007]
	system	[TR_AMETH_00008]
		[TR_AMETH_00009]
		[TR_AMETH_00212]
		[TR_AMETH_00213]



IDO METU 000001	The area the entertonic algorithms and a significant	ITD AMETIL 000001
[RS_METH_00202]	The methodology shall explain	[TR_AMETH_00002]
	how to develop an Adaptive	[TR_AMETH_00010]
	Application	[TR_AMETH_00011]
		[TR_AMETH_00012]
		[TR_AMETH_00013]
		[TR_AMETH_00014]
		[TR_AMETH_00015]
		[TR_AMETH_00018]
		[TR_AMETH_00205]
		TR AMETH 00207
		[TR_AMETH_00208]
		[TR_AMETH_00209]
		[TR_AMETH_00210]
[RS_METH_00203]	The methodology shall explain	[TR_AMETH_00003]
[H3_ME111_00203]	the high-level usage of the	[TR_AMETH_00004]
	Manifest Specification	[TR_AMETH_00005]
		[TR_AMETH_00021]
		[TR_AMETH_00022]
		[TR_AMETH_00023]
		[TR_AMETH_00024]
		[TR_AMETH_00025]
		[TR_AMETH_00026]
		[TR_AMETH_00027]
		[TR_AMETH_00028]
		[TR_AMETH_00029]
		[TR_AMETH_00033]
		[TR_AMETH_00214]
		[TR_AMETH_00215]
		[TR_AMETH_00216]
		[TR_AMETH_00217]
[RS_METH_00204]	The methodology shall describe	[TR_AMETH_00003]
	how to configure a machine for	[TR_AMETH_00021]
	the Adaptive Platform	TR AMETH 00022
	постопринения	[TR_AMETH_00023]
		[TR_AMETH_00031]
		[TR_AMETH_00214]
		[TR_AMETH_00215]
		[TR_AMETH_00216]
		[TR_AMETH_00217]
[RS_METH_00205]	The methodology shall describe	[TR_AMETH_00006]
[113_WE111_00205]		[TR_AMETH_00006]
	how to deploy software on the	
IDC METH 00000	Adaptive Platform	[TR_AMETH_00206]
[RS_METH_00206]	The methodology shall explain	[TR_AMETH_00005]
	how to configure the instances	[TR_AMETH_00027]
	of services of a system	[TR_AMETH_00028]
		[TR_AMETH_00029]
		[TR_AMETH_00033]
[RS_METH_00207]	The methodology shall explain	[TR_AMETH_00017]
	how to develop Platform	[TR_AMETH_00019]
	Software for the Adaptive	[TR_AMETH_00020]
	Platform	[TR_AMETH_00034]
		[TR_AMETH_00035]
		[TR_AMETH_00212]
		[TR_AMETH_00213]
	1	-



1.7 Known Limitations

The sections related to the deployment of Software Packages, i.e., Section 2.4.5 (Set up an initial Machine), Section 2.4.6 (Create Software Packages) and Section 2.4.7 (Management and provision of Software Packages), are still under discussion.



2 Use Cases for the Adaptive Platform

This section describes the main use cases for building a system based on the AUTOSAR Adaptive Platform.

Each section consists of subsections for the overall purpose of the use case, the description in terms of specifications, and the modeled workflow according to [4].

Please be aware that the roles shown in the diagrams may only be regarded as a good approximation.

2.1 Overall View

2.1.1 Purpose

This section provides an overview of the design and development steps to build a system based on the AUTOSAR Adaptive Platform. The main activities of the overall development are depicted in Figure 2.6. An overview of the workflow including relevant work products is given in Figure 2.7. A brief description of these main steps is given below in Section 2.1.2. For a detailed description please refer to the relevant sections.

2.1.2 Description

2.1.2.1 Domains of Development

It is good practice to decompose the development of complex systems into different work phases, for example analysis, design, implementation and the like. Each work phase will thereby be linked to a different level of abstraction. Moreover, each stakeholder of this development will need a distinct view on the system in order to emphasize on its particular aspects.

Thus, all this needs to somehow be represented by the methodology, too. In this respect, the methodology of the AUTOSAR Classic Platform is structured into so-called domains of development [1], which is in some way a mix of the concepts *separation of concerns* and *abstraction*.

The methodology of the AUTOSAR Adaptive Platform will follow this approach.

[TR_AMETH_00200] Domains of development utilized for the methodology of the AUTOSAR Adaptive Platform | The methodology of the Adaptive Platform shall be structured by the following domains of development:

- Analysis
- Architecture and Design
- System



- Software Development
- Integration and Deployment

|(RS_METH_00018, RS_METH_00032)

2.1.2.2 Fundamental Activities

2.1.2.2.1 Analysis

Analysis tasks are often necessary for the purpose of preparing later decisions. One line of inquiry may be to identify and investigate timing critical event chains between sensors and actuators of a vehicle function in order to comply with the required timing behavior.

Although the present version does not, later versions of this document will specify corresponding use-cases/activities.

2.1.2.2.2 Architecture and Design

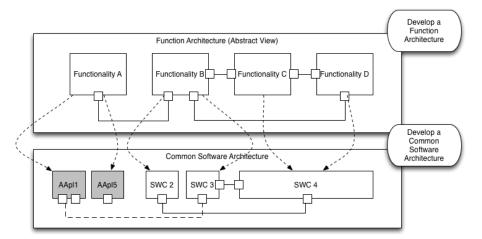


Figure 2.1: From the Function Architecture to a Common Software Architecture

[TR_AMETH_00201] Develop a Function Architecture [An engineer, e.g., an E/E system architect, may evaluate features and requirements necessary for a specific E/E vehicle project in order to form an appropriate Function Architecture during the activity Develop a Function Architecture.

The Function Architecture is composed of a number of function networks. A function network consists of a set of function blocks with their interfaces and corresponding interconnections. One functionality is encapsulated within one function block. Therefore, a particular function network represents all functionality that is needed to execute a particular feature (vehicle function). Note, that function blocks may be realized in software or hardware or as a mix of both.



The result of this activity, i.e., the Function Architecture can be specified by means of the Abstract System Description.

This activity is optional. (RS METH 00032)

[TR_AMETH_00202] Develop a Common Software Architecture [Another engineer, e.g., a software architect, could take the Function Architecture as one input to deduce a corresponding Common Software Architecture while executing an activity Develop a Common Software Architecture.

The Common Software Architecture provides a dedicated view of all software entities and their communication relation within the E/E vehicle system. In this light, the Common Software Architecture comprises both types, AUTOSAR software components of the Classic Platform as well as those entities that form later an Adaptive Software deployed to an Adaptive Platform-based machine. It is important to stress this, because not only software components of the same platform type communicate among each other. There is also a service oriented communication possible between software components or entities that belong to different platform types.

The communication entry and exit points of components are ports typed by a particular interface definition. In case of the Adaptive Platform, interfaces are expressed as ServiceInterfaces. In this respect, typed ports are means to instantiate specific interface definitions.

The term *component* may also include the term *compositions of components*. An Adaptive Software may also be subdivided into more fine-granular components.

The result of this activity, i.e., the Common Software Architecture can be specified by means of the System Description.

This activity is optional. | (RS METH 00032) 1

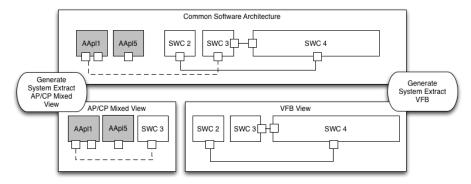


Figure 2.2: Views of subsystems enable to emphasize on relevant aspects

[TR_AMETH_00203] Provide views of subsystems \[A subsystem is a reduced part of the overall technical system and emphasizes on relevant aspects of it.

¹Figure 2.1 shows that a functionality may be implemented by one or more software components, by software components which are finally be mapped either to a machine running an AUTOSAR Adaptive Platform (gray boxes, named AApl for Adaptive Application) or to a Classic Platform ECU.



It is absolutely feasible, for example, to generate a pure VFB view or a view on a mixed Adaptive/Classic Platform subsystem. Latter could contain all those software entities which communicate at least to one other Adaptive Application Software. It may be usable to develop the interfaces for communication between software components/entities which belong to different platforms (namely AUTOSAR Adaptive Platform or AUTOSAR Classic Platform).

This activity is optional. | (RS METH 00078, RS METH 00079) 2

[TR_AMETH_00001] Identify Service Interfaces [During this activity, services for service-oriented communication are specified, i.e., particular events, methods and fields per interface. This may be done independently of any assignation to specific software components or any instantiation. In this respect it may be seen as a preparation step towards the development of Adaptive Software entities.] (RS_METH_00201, RS_METH_00032) 3

[TR_AMETH_00207] Design communication between Classic Platform ECUs and Adaptive Platform machines [Adaptive Software communicates in a service oriented manner. However, a typical vehicle will also be equipped with ECUs developed for the Classical Platform. Thus, it is very likely that ECUs of different types need to communicate.

In case that the Classic Platform ECU implements SOME/IP they can communicate in service oriented way. However, in order to describe this kind of communication a mapping between the elements of the ServiceInterface and the corresponding elements of the respective PortInterface of the Classic Platform needs to be specified.

If the counterpart on a Classic Platform ECU, however, communicates only in a signal-based way, a Signal-to-Service translation is needed. | (RS METH 00202) 4

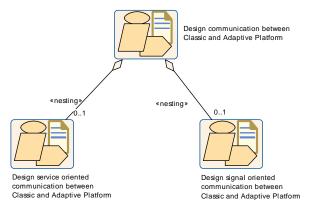


Figure 2.3: Design Communication between Classic Platform and Adaptive Platform

²Figure 2.2 shows two possible views on subsystems deduced from the Common Software Architecture.

³This use case is elaborated in section 2.2.1.

⁴The use case of SOME/IP communication is elaborated in section 2.2.2.1. The use case of Signal-to-Service translation is elaborated in section 2.2.2.2.



Activity	Design communication between Classic and Adaptive Platform		
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Architecture and Design::Communication		
Brief Description	Design communicati	on betw	een CP and AP
Description	Higher level activity that encloses all activities which are necessary to design communication between a Classic Platform (ECU) and a Adaptive Platform.		
Relation Type	Related Element Mul. Note		
Aggregates	Design service oriented communication between Classic and Adaptive Platform	01	
Aggregates	Design signal ori- ented communica- tion between Clas- sic and Adaptive Platform	01	

Table 2.1: Design communication between Classic and Adaptive Platform

2.1.2.2.3 System

Like for the CP methodology [1], this development domain will cover activities which refine the Common Software Architecture into a system defined by specific ECUs or Machines. In this respect, the main activities/issues specified there will be in principle also valid here (see Figure 2.4).

[TR_AMETH_00204] Develop the System [

The subsequent specifications of the Classic Platform methodology shall also be applicable for the Adaptive Platform (by following their general meanings):

- Development of the System (TR_METH_01046) and (Develop) the overall system (TR_METH_01048), which talk about the refinement of the VFB by the definition of a topology of ECUs and networks and the deployment of software components onto ECUs, with the extensions necessary for the Common Software Architecture and the additions to specify Machines and the corresponding mapping of Machines to ECUs.
- Two phase development approach (TR_METH_01047) and Interaction between organizations (TR_METH_01049), which structures the collaboration between different parties, like between OEMs and their suppliers.

(RS METH 00041)



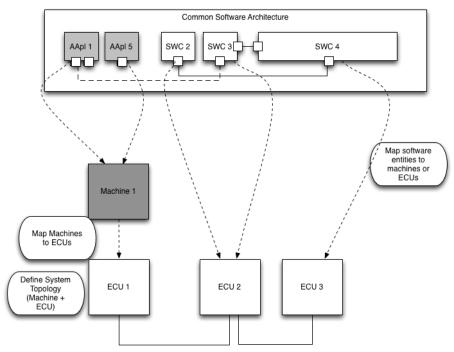


Figure 2.4: System development: ECUS, Machines, communication networks, mapping of software entities to ECUS or Machines

2.1.2.2.4 Software Development

[TR_AMETH_00002] Develop Adaptive Software [Once the service interfaces have been defined, Adaptive Software of category application-level and platform-level can be developed. The development may include several sub-activities like analysis, design, implementation or test. The most important artifacts of this activity are either source-code or object-code files, depending on whether or not the developer knows the Build Chain Configuration beforehand. The artifacts are handed over to an integrator.] (RS_METH_00202, RS_METH_00032) ⁵

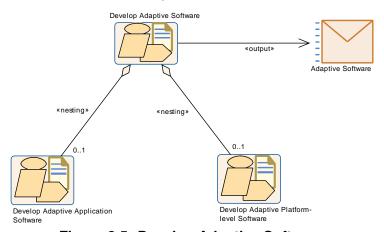


Figure 2.5: Develop Adaptive Software

⁵Sections 2.3.1 and 2.3.2 will refine the necessary activities associated with the development of application-level and platform-level software.



Activity	Develop Adaptive Software		
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Develop Adaptive Application		
Brief Description	Develop Adaptive So	oftware	
Description	This higher level activity encloses the development of Adaptive Applications with category application-level as well as platform-level.		
Relation Type	Related Element	Mul.	Note
Produces	Adaptive Software	1	
Aggregates	Develop Adaptive Application Software	01	
Aggregates	Develop Adaptive Platform-level Soft- ware	01	

Table 2.2: Develop Adaptive Software

2.1.2.2.5 Integration and Deployment

The term *Integration and deployment of software* (on the Adaptive Platform) refers to all activities that are necessary to make designated software run on a specific machine, determined by its hardware, connected networks, its operating system and (some) platform-level Adaptive Software, in order to satisfy all requirements.

[TR_AMETH_00205] Integrate Software An integrator will either take source-code or object-code files delivered by the software development and will bind them together in order to form an Executable for a specific machine and notably its application binary interface (ABI).

This activity does not include instantiation, i.e., the binding of an actual Executable to the context of an Process (exactly one Executable per Process). | (RS_METH_-00202, RS_METH_00032) |

[TR_AMETH_00003] Configuration of the machine [In AUTOSAR adaptive the meta model element Machine already represents a specific ECU implementation with dedicated configurations. In this respect, the Machine is more a model entity in the scope of an integrator of a Tier 1 company, than in the scope of on an communication designer of an OEM.

Therefore, the meta model element Machine Design has been introduced. It allows a communication designer of an OEM to define requirements on a machine in the context of a System during the system design stage. In this sense, Machine Design acts as a placeholder for a real adaptive ECU instance in early development phases.

In addition, the respective Machine Design will be uploaded onto the machines as part of Uploadable Design Artifacts. Since a particular Machine model will

⁶Section 2.4.1 will refine the necessary activities associated with the integration of software.



reference a particular Machine Design model, the configurations of Machine Design will also contribute to the Machine Manifest.

Thus, the configuration of the machine is subdivided into two process steps:

- 1. The first step is the configuration of the communication structure of a prospective machine and will be performed by a communication designer of an OEM as part of the (system) design phase. This step results in a Machine Design.
- 2. The second step covers activities and tasks for the configuration of a real adaptive ECU. It will be executed by an integrator of a Tier 1 company. The resulting configuration is then part of the Machine Manifest.

(RS METH 00204, RS METH 00203)7

[TR_AMETH_00004] Creation of the Execution Manifest [Executables of an Adaptive Software are instantiated by means of the Execution Manifest. Instantiation here means to bind the executables to the context of specific processes of the operating system. Each process may start with a different start-up configuration depending on a machine mode. Further on, the Execution Manifest may also define dependencies of processes. | (RS_METH_00203) 8

[TR_AMETH_00005] Configuration of the service instances [During this activity, the service instances are configured, notably the binding of the service interfaces to a chosen transport layer, whether a specific service instance is either provided or required and the mapping to a dedicated machine. The configurations of the service instance are manifested in the Service Instance Manifest.] (RS_METH_00206, RS_METH_00203) 9

[TR_AMETH_00006] Deployment of the application software [Software is deployed to a machine, i.e., a particular Adaptive AUTOSAR Platform instance, by means of Software Packages. This means that:

- 1. associated software artifacts need to be compiled into a dedicated Software Package.
- 2. Software Packages are provided by an OEM-specific Back-end server in order to be accessible by the machines in the field.

(RS METH 00205) 10

⁷See Section 2.2.3 for details regarding Machine Design. See Section 2.4.2 for details regarding Machine Manifest.

 $^{^8}$ The creation of the Execution Manifest is detailed in Section 2.4.3.

⁹See Section 2.4.4 for details.

¹⁰See section 2.4.6 regarding create Software Packages. See section) 2.4.7 regarding deploy Software Packages.



2.1.2.3 Workflow

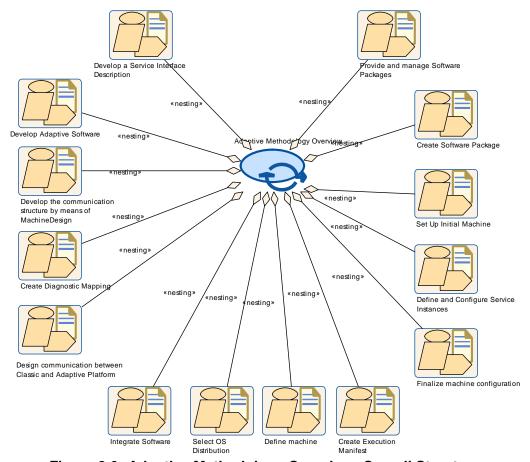


Figure 2.6: Adaptive Methodology Overview: Overall Structure

Process Pattern	Adaptive Methodology Overview		
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Adaptive Methodology Overview		
Brief Description	High-level view of the	e adapti	ve AUTOSAR methodology
Description	This process pattern covers the typical activities to develop an Adaptive AUTOSAR system.		
Relation Type	Related Element Mul. Note		
Aggregates	Create Diagnostic Mapping	1	
Aggregates	Create Execution Manifest	1	
Aggregates	Create Software Package	1	
Aggregates	Define and Configure Service Instances	1	
Aggregates	Define machine	1	



Relation Type	Related Element	Mul.	Note
Aggregates	Design commu- nication between Classic and Adap- tive Platform	1	
Aggregates	Develop Adaptive Platform-level Soft- ware	1	
Aggregates	Develop Adaptive Software	1	
Aggregates	Develop a Service Interface Descrip- tion	1	
Aggregates	Develop the communication structure by means of MachineDesign	1	
Aggregates	Finalize machine configuration	1	
Aggregates	Integrate Software	1	
Aggregates	Provide and manage Software Packages	1	
Aggregates	Select OS Distribution	1	
Aggregates	Set Up Initial Machine	1	

Table 2.3: Adaptive Methodology Overview



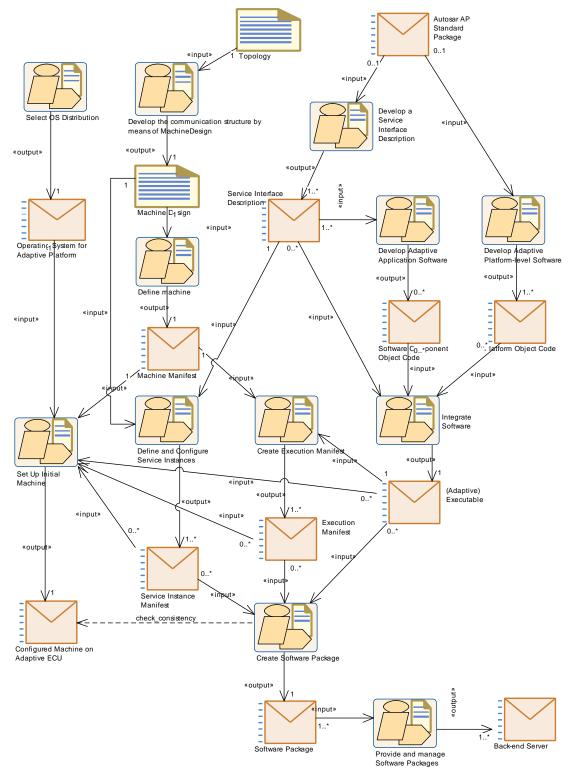


Figure 2.7: Adaptive Methodology Overview: Workflow



2.2 Architecture and Design

2.2.1 Develop a Service Interface Description

2.2.1.1 Purpose

This use case gives an outline of the definition of the services in a system, independent of any instantiation. All relevant tasks and deliverables for this use case are given in Figure 2.8. The workflow is depicted in Figure 2.9.

2.2.1.2 Description

[TR_AMETH_00007] Definition of data types for the Adaptive Platform [Data types for the Adaptive Platform can be defined based on standardized data types from AUTOSAR. As on the Classic Platform, data types are defined on different levels of abstractions: application data types, implementation data types and base types. Most concepts and data types can be taken over from the Classic Platform. However, in order to cope with the C++ programming language, for the Adaptive Platform also vectors, strings and maps can be defined. | (RS_METH_00201)

For more information on data types as specified for the Classic Platform and the extensions for the Adaptive Platform, see [5] and [6].

[TR_AMETH_00008] Develop Service Interfaces for Adaptive Software [All service interfaces, which are used in a system, need to be defined. Service interfaces aggregate elements as events, methods and fields. They are the basis for the header file generation. Therefore, it is also possible to define namespaces within a service interface, which has a direct influence on the generated code. | (RS_METH_00201)

[TR_AMETH_00009] Aggregating service interfaces for reducing the bus load [Optionally, service interfaces can be aggregated to more coarse-grained service interfaces by defining a service interface mapping or a service interface element mapping respectively. This results in an update of the Service Interface Description. The newly defined coarse-grained service interfaces are then used for the network-based communication. | (RS METH 00201)



2.2.1.3 Workflow

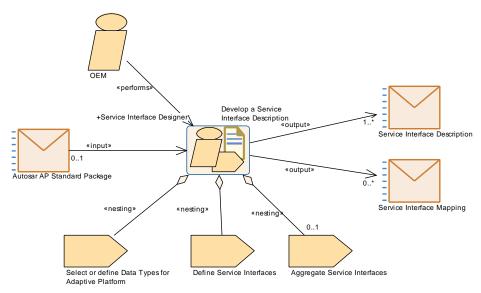


Figure 2.8: Develop a Service Interface Description

Activity	Develop a Service	nterfac	e Description	
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Architecture and Design::Service Interface Definition			
Brief Description	Define all service int	erfaces	used in the system	
Description	aggregating events, types. In addition, co	This activity describes the definition of the service interfaces, aggregating events, methods and fields, including the definition of data types. In addition, coarse-grained service interfaces can be defined for the network-based communication.		
Relation Type	Related Element	Mul.	Note	
Consumes	Autosar AP Stan- dard Package	01	Optional input for defining data types and service interfaces for the adaptive platform	
Produces	Service Interface Description	1*	All service interfaces, which are used for communication	
Produces	Service Interface Mapping	0*	Optionally, coarse-grained service interfaces are defined by a service interface mapping	
Aggregates	Aggregate Service Interfaces	01		
Aggregates	Define Service Interfaces	1		
Aggregates	Select or define Data Types for Adaptive Platform	1		
Performed by	OEM	1	Service Interface Designer: This activity will probably be performed by a Service Interface Designer	

Table 2.4: Develop a Service Interface Description



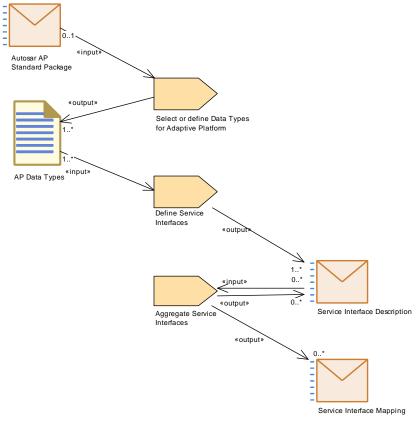


Figure 2.9: Workflow for defining Service Interfaces

2.2.2 Design communication between Classic Platform and Adaptive Platform

2.2.2.1 Design service oriented communication between Classic Platform and Adaptive Platform

2.2.2.1.1 Purpose

This use case covers the activities necessary to design service oriented communication between applications of a Classic Platform ECU and those of an Adaptive Platform Machine via SOME/IP.

The respective deliverables, activities and tasks are depicted in Figure 2.10.

2.2.2.1.2 Description

[TR_AMETH_00208] Design service oriented communication between Classic Platform and Adaptive Platform | The background of this activity is the request to enable service oriented communication between applications of a Classic Platform (CP) ECU and those of an Adaptive Platform (AP) machine via SOME/IP.



Unfortunately, the AUTOSAR Classic Platform does not support Service Interfaces. Thus, a SOME/IP service may be composed of different types of Classic Platform PortInterfaces like Sender Receiver Interfaces, Client Server Interfaces or Trigger Interfaces.

In order to describe the communication over SOME/IP between the CP ECU and an AP Machine, this activity describes the mapping of the elements of the PortInterfaces of the Classical Platform to the elements of a single Service Interface of the Apdaptive Platform.

Thus, the main objective of this activity is to map a single Service Interface to Port-Interface elements, in detail:

- to map method(s), i.e., to map a ClientServerOperation located in a Client Server Interface to a method located in a Service Interface.
- to map event(s), i.e., to map a VariableDataPrototype located in a Sender Receiver Interface to an event located in a Service Interface.
- to map field(s), i.e., to map operations located in ClientServerOperations to getter and setter methods of a Service Interface and to map a VariableDataPrototype of a Sender Receiver Interface to the field notifier of the Service Interface.
- to map "Fire and Forget", i.e., to map a "Fire and Forget" method located in a Service Interface to a VariableDataPrototype in a Sender Receiver Interface or to a trigger of a Trigger Interface.

The mapping description serves currently only for documentation.

|(RS_METH_00200, RS_METH_00202)



2.2.2.1.3 Workflow

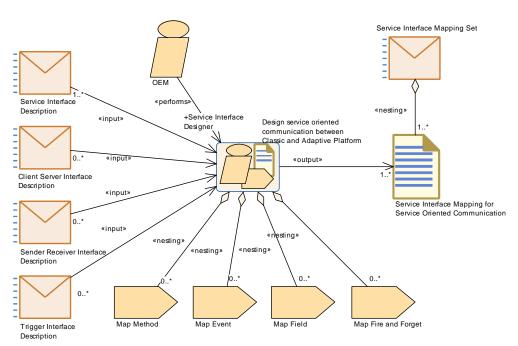


Figure 2.10: Design service oriented communication

Activity	Design service oriented communication between Classic and Adaptive Platform				
Package		AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Architecture and Design::Communication			
Brief Description	Design service orien	ted com	nmunication between CPand AP		
Description	communication betw	The background of this activity is the request to enable service oriented communication between applications of a Classic Platform (CP) ECU and those of an Adaptive Platform (AP) machine via SOME/IP.			
	Unfortunately, the AUTOSAR Classic Platform does not support ServiceInterfaces. Thus, a SOME/IP service may be composed of different types of Classic Platform PortInterfaces like SenderReceiverInterfaces, ClientServiceInterfaces or TriggerInterfaces.				
	In order to describe the communication over SOME/IP between the CP ECU and a AP machine, this activity describes the mapping of the elements of the PortInterfaces of the Classical Platform to the elements of a single ServiceInterface of the Apdaptive Platform. The mapping description serves currently only for documentation.				
Relation Type	Related Element	Mul.	Note		
Consumes	Client Server Interface Description	0*	The descriptions of Client Server Interfaces of CP are used to map a ClientServerOperation to a method in a ServiceInterface or to map a ClientServerOperation (representing getter or setter methods) to a field in a ServiceInterface		



Relation Type	Related Element	Mul.	Note
Consumes	Sender Receiver Interface Descrip- tion	0*	The descriptions of Sender Receiver Interfaces of CP are used to map a VariableDataPrototype to an Event in a ServiceInterface or to map a VariableDataPrototype to the notifier of a Field of a ServiceInterface or to map a Fire&Forget Method that is located in a ServiceInterface to a VariableDataPrototype in a SenderReceiverInterface
Consumes	Service Interface Description	1*	Description of the Service Interfaces which communicate to CP in a service-oriented manner
Consumes	Trigger Interface Description	0*	The descriptions of Trigger Interfaces are used to map a Fire&Forget Method that is located in ServiceInterface to a Trigger in a TriggerInterface
Produces	Service Inter- face Mapping for Service Oriented Communication	1*	An InterfaceMapping results from the design of service-oriented communication between CP and AP
Aggregates	Map Event	0*	
Aggregates	Map Field	0*	
Aggregates	Map Fire and Forget	0*	
Aggregates	Map Method	0*	
Performed by	OEM	1	Service Interface Designer: This activity will probably be performed by a Service Interface Designer of an OEM

Table 2.5: Design service oriented communication between Classic and Adaptive Platform

2.2.2.2 Design signal oriented communication between Classic Platform and Adaptive Platform

2.2.2.2.1 Purpose

This use case comprises activities to specify a signal oriented communication between Classic Platform and Adaptive Platform applications, if there is no service oriented communication possible.

The associated elements, i.e, deliverables, activities and tasks and their relations are depicted in Figure 2.11.



2.2.2.2. Description

[TR_AMETH_00209] Define a signal-based Service Interface [As a prerequisite for the mapping of Service Interface elements to ISignalTriggerings, the definition of a SignalBasedServiceInterfaceDeployment is needed. It specifies the configuration settings for a Service Interface from which the content will be transmitted in the signal-based way over a communication medium and therefore provides the ability to bind a Service Interface to a signal-based communication protocol like CAN or FlexRay.

Details are provided by the specifications TPS_MANI_03120, TPS_MANI_03121, TPS_MANI_03122 and TPS_MANI_03123 of the Manifest specification [6]. | (RS_-METH 00200, RS METH 00202)

[TR_AMETH_00210] Map signals to services [In a second step, the mapping of ServiceInstance elements of a specific AdaptivePlatformServiceInstance defined in the context of a process to ISignalTriggerings is described, in detail:

- to map SignalBasedMethodDeployment to ISignalTriggerings, according to TPS MANI 03125 of the Manifest specification [6]
- to map SignalBasedEventDeployment to ISignalTriggerings, according to TPS_MANI_03124 of the Manifest specification [6]
- to map SignalBasedFieldDeployment to ISignalTriggerings, according to TPS MANI 03126 of the Manifest specification [6]
- to map a ServiceInstance to a PortPrototype, according to TPS MANI 03000 of the Manifest specification [6]

](RS_METH_00200, RS_METH_00202)



2.2.2.2.3 Workflow

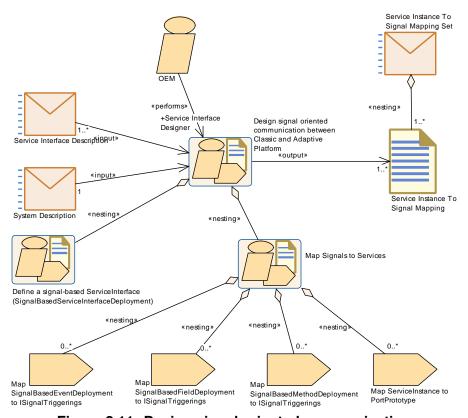


Figure 2.11: Design signal oriented communication

Activity	Design signal oriented communication between Classic and Adaptive Platform		
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Architecture and Design::Communication		
Brief Description	Design signal oriente	ed comn	nunication between CP and AP
Description	service oriented mar deployed to an Adap a service oriented water If the counterpart on only in a signal-base	nner. The tive Plate ay via Some a Classed way, a asses the transfer of the tr	sic Platform ECU, however, communicates a Signal-to-Service translation is needed. The description of the mapping of signals to viceInterface. It will be the base for the
Relation Type	Related Element	Mul.	Note
Consumes	Service Interface Description	1*	Description of the Service Interfaces which communicate to CP in a signal-oriented manner



Relation Type	Related Element	Mul.	Note
Consumes	System Description	1	The System Description based on the System Template on the AUTOSAR classic platform is used; it contains a communication matrix description with Pdus and ISignals
Produces	Service Instance To Signal Mapping	1*	A signal-to-service mapping results from the design of signal-oriented communication between CP and AP
Aggregates	Define a signal- based Service Interface (Signal BasedService InterfaceDeploy- ment)	1	
Aggregates	Map Signals to Services	1	
Performed by	OEM	1	Service Interface Designer: This activity will probably be performed by a Service Interface Designer of an OEM

Table 2.6: Design signal oriented communication between Classic and Adaptive Platform

Activity	Map Signals to Services		
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Architecture and Design::Communication		
Brief Description	Map Signals to Serv	ices	
Description	Describe the mapping of ServiceInstance elements of a specific AdaptivePlatformServiceInstance defined in the context of a process to ISignalTriggerings. The prerequisite is the definition of the SignalBasedServiceInterface.		
Relation Type	Related Element	Mul.	Note
Aggregates	Map ServiceInstance to Port Prototype	0*	
Aggregates	Map SignalBased EventDeploy- ment to ISignal Triggerings	0*	
Aggregates	Map SignalBased FieldDeployment to ISignalTrigger- ings	0*	
Aggregates	Map SignalBased MethodDeploy- ment to ISignal Triggerings	0*	

Table 2.7: Map Signals to Services



Activity	Define a signal-based ServiceInterface (SignalBasedServiceInterfaceDeployment)			
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Architecture and Design::Communication			
Brief Description	Define SignalBased	Servicel	nterface	
Description	Express that a ServiceInterface will be transmitted via a signal-based communication protocol like CAN or FlexRay.			
Relation Type	Related Element	Mul.	Note	
Consumes	Service Interface Description	1*	Description of the Service Interfaces	
Consumes	System Description	1	The System Description based on the System Template on the AUTOSAR classic platform	

Table 2.8: Define a signal-based ServiceInterface (SignalBasedServiceInterfaceDeployment)

2.2.3 Develop the communication structure by means of Machine Design

2.2.3.1 **Purpose**

By means of this activity, an OEM specifies the communication structure as well as corresponding configuration parameters of prospective machines, already during the (system) design phase.

2.2.3.2 Description

A primary task of an OEM is to specify entities which are associated with the topology, network and the system design, already in early development phases.

[TR_AMETH_00021] Define and configure the network communication for machine | This activity will cover the definition and configuration of the network communication for a prospective machine and consists of the following tasks:

- Define and configure the network connection of a prospective machine, i.e., define all network endpoint with corresponding IP address (IPv4 or IPv6)
- Configure the service discovery message exchange of a prospective machine,
 i.e., specify all designated multicast IP addresses and a UDP port

(RS METH 00204, RS METH 00203)

The Machine is a model entity which already represents a specific ECU implementation with dedicated configurations. Therefore, it should not be used during system design.

The meta model element Machine Design has been introduced in order to allow the communication designer to define a placeholder for an adaptive Machine in the scope



of the System. In this respect, the element Machine Design corresponds to the ECUInstance of AUTOSAR classic.

Hence, the design activities of this step will result in a deliverable Machine Design, which will contribute to the Machine Manifest, since a particular Machine model will reference a particular Machine Design model.

Since the configuration elements of Machine Design are needed during run-time, Machine Design needs to be uploaded to the target machine. Thus, Machine Design needs to be part of Uploadable Design Artifacts.

Figure 2.12 shows the involved entities – inputs, outputs, tasks – necessary to perform this activity.

2.2.3.3 Workflow

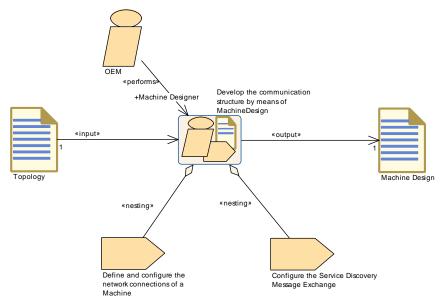


Figure 2.12: Develop the communication structure by means of Machine Design



Activity	Develop the communication structure by means of MachineDesign				
Package		AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Architecture and Design::Develop Machine Design			
Brief Description	placeholder during the Scope of an Sys		n phase for an adaptive ECU(Machine) in		
Description		dedicate	ty which already represents a specific ECU ed configurations. Therefore, it should not gn.		
	communication designation (Machine) in the sco	The element MachineDesign has been introduced in order to allow the communication designer to define a placeholder for an adaptive ECU (Machine) in the scope of the System. The element MachineDesign corresponds to the Eculnstance of AUTOSAR classic, in this respect.			
	This activity will agg	regate th	ne following tasks:		
	Define and comachine	onfigure	the network connection of a prospective		
	Configure the prospective m		discovery message exchange of a		
Relation Type	Related Element	Mul.	Note		
Consumes	Topology	1	Description of (inter)connections between Machines.		
Produces	Machine Design	1	Configuration settings of the network connections and service discovery network exchange of a Machine		
Aggregates	Configure the Service Discov- ery Message Exchange	1			
Aggregates	Define and configure the network connections of a Machine	1			
Performed by	OEM	1	Machine Designer: This activity will probably be performed by a dedicated designer of an OEM.		

Table 2.9: Develop the communication structure by means of MachineDesign

2.2.4 Create a Diagnostic Mapping

2.2.4.1 **Purpose**

This activity associates given diagnostic information (diagnostic data, diagnostic enable conditions, diagnostic events, diagnostic operation cycles) with the software structure (applications, instances, components, ports, events, data) of a particular machine.



2.2.4.2 Description

[TR_AMETH_00212] Design a diagnostic mapping This activity covers all necessary tasks to perform the diagnostic mapping, except the task which associates corresponding Process Design(s) and Diagnostic Mapping(s).

These tasks are in detail:

- Map Diagnostic Clear Condition to Port(s)
- Map Diagnostic Data
- Map Diagnostic Enable Condition to Port(s)
- Map Diagnostic Event to Port(s)
- Map Diagnostic Generic UDS Service Handler to Port(s)
- Map Diagnostic Indicator to Port(s)
- Map Diagnostic Memory Destination to Port(s)
- Map Diagnostic Operation Cycle to Port(s)
- Map Diagnostic Storage Condition to Port(s)
- Map Diagnostic Security Level to Port(s)
- Map Diagnostic Service Data Identifier to Port(s)
- Map Diagnostic Upload/Download to Port(s)

In order to perform the particular tasks, the following inputs are necessary:

- The Diagnostic Machine Extract that contains the diagnostic information
- Service Interface Description which collects the descriptions of the service interfaces with their events, methods and fields
- Software Component Description for Adaptive Platform which collects the description of software components and their ports

This step results in partly filled in artifact Diagnostic Mapping.

(RS METH 00207, RS METH 00201, RS METH 00016)

[TR_AMETH_00213] Relate diagnostic mappings to instances of Executables [It may be necessary that different instances of a particular application software (i.e., different Processes based on the very same Executable) require different diagnostic mappings. Therefore, a relation between a particular diagnostic mapping and a particular Process needs to be established. Since Processes at design do not exist, yet, the (meta) model element ProcessDesign may stand in as a proxy.

This assignment may be independent of the step of designing diagnostic mappings and may be done in a final extra step (Associate Diagnostic Mapping with Process Design).



To accommodate for this potential modeling, the reference from a diagnostic mapping to Process Design has been decorated by stereotype «atpSplitable».

This step takes the partly filled in artifact Diagnostic Mapping and the artifact Process Design as inputs and results in a completely filled in Diagnostic Mapping.] (RS METH 00207, RS METH 00201, RS METH 00016)

Figure 2.13 depicts an overview of diagnostic mapping; how the involved deliverables, activities and tasks are related to each other.

2.2.4.3 Workflow

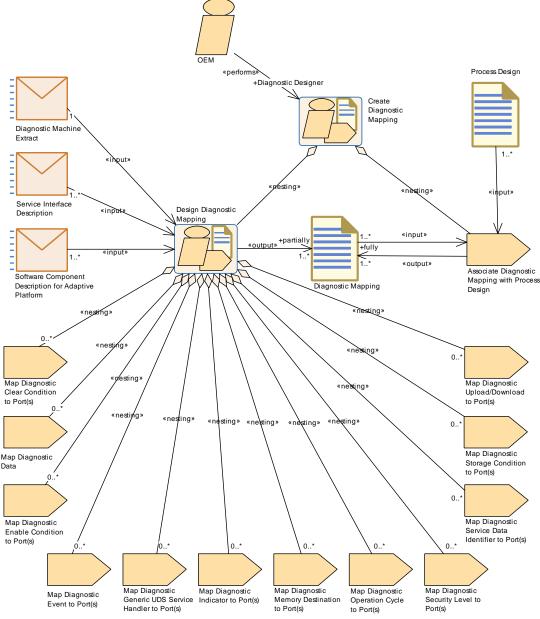


Figure 2.13: Create a Diagnostic Mapping



Activity	Create Diagnostic I	Mapping	g	
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Architecture and Design::Diagnostic Mapping			
Brief Description	Create diagnsotic ma	appings		
Description		This activity comprises all necessary tasks to create complete diagnostic mappings.		
	adaptive diagnostic the application softw service-oriented con	A diagnostic mapping is a formal model for the relation between the adaptive diagnostic management (module) and specific endpoints in the application software. This mapping enables the configuration of the service-oriented communication middleware, so that the service discovery can connect the corresponding endpoints correctly.		
Relation Type	Related Element	Mul.	Note	
Aggregates	Associate Diag- nostic Mapping with Process Design	1		
Aggregates	Design Diagnostic Mapping	1		
Performed by	OEM	1	Diagnostic Designer: The activity of designing the diagnostic mapping will probably be performed by a Diagnostic Designer of an OEM	

Table 2.10: Create Diagnostic Mapping

Activity	Design Diagnostic Mapping			
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Architecture and Design::Diagnostic Mapping			
Brief Description	Perform diagnostic r	napping	s	
Description		task wh	ssary tasks to perform the diagnostic nich associates corresponding nosticMapping(s).	
Relation Type	Related Element	Mul.	Note	
Consumes	Diagnostic Ma- chine Extract	1	All available diagnostic information at the design time	
Consumes	Service Interface Description	1*	Collection of service interfaces. Service interfaces can consist of events, methods and fields.	
Consumes	Software Component Description for Adaptive Platform	1*	Description of a software component for the Adaptive Platform with all its ports, available at design time.	
Produces	Diagnostic Map- ping	1*	partially: The diagnostic mapping for a Machine, except the linkage between the mappings and the corresponding ProcessDesigns	
Aggregates	Map Diagnostic Clear Condition to Port(s)	0*		
Aggregates	Map Diagnostic Data	0*		



Relation Type	Related Element	Mul.	Note
Aggregates	Map Diagnostic Enable Condition to Port(s)	0*	
Aggregates	Map Diagnostic Event to Port(s)	0*	
Aggregates	Map Diagnostic Generic UDS Ser- vice Handler to Port(s)	0*	
Aggregates	Map Diagnostic Indicator to Port(s)	0*	
Aggregates	Map Diagnostic Memory Desti- nation to Port (s)	0*	
Aggregates	Map Diagnostic Operation Cycle to Port(s)	0*	
Aggregates	Map Diagnostic Security Level to Port(s)	0*	
Aggregates	Map Diagnos- tic Service Data Identifier to Port(s)	0*	
Aggregates	Map Diagnostic Storage Condition to Port(s)	0*	
Aggregates	Map Diagnostic Upload/Download to Port(s)	0*	

Table 2.11: Design Diagnostic Mapping

2.3 Software Development

2.3.1 Develop Adaptive Application Software

2.3.1.1 **Purpose**

This section explains how to develop application-level software for the Adaptive Platform. First, the design of the software components is described. Based on this description, the functionality can be implemented. An overview of all relevant tasks for this use case is given in Figure 2.14. The artifact-based workflow is depicted in Figure 2.15.



2.3.1.2 Description

[TR_AMETH_00010] Application-level Software An Adaptive Application of category application-level is a collection of executables. The executables themselves can be derived from several software components. (RS_METH_00202)

[TR_AMETH_00011] Design of the software components [Based on the service interfaces, the development of adaptive application software starts with the design of the software components. The software components can have an hierarchical structure. For all software components it is defined if service interfaces are required or provided. This behavior is designed by using the corresponding ports for the software components.

(RS METH 00202)

[TR_AMETH_00012] Generation of the header files for service interface [In parallel, the header files for the service interfaces are generated. This step is independent of the design of the software component and therefore its ports. Instead, the header files are generated for all service interfaces and afterwards, the relevant ones are used for the development of the software component.

The generation includes the generation of service proxies and skeletons, which need to be implemented for a specific platform. | (RS METH 00202, RS METH 00066)

[TR_AMETH_00013] Implementation and compilation of software components | The generated header files are the basis for the implementation of the core functionality of a software component. Two typical use cases for the development exist that depend on the fact if the Build Chain Configuration is known or not known and therefore if source code or object code is delivered by the application developer.] (RS METH 00202, RS METH 00015, RS METH 00066, RS METH 00042)

[TR_AMETH_00014] Development with knowledge of the Build Chain Configuration [In this approach, the integrator hands over the Build Chain Configuration to the software developer beforehand. The software developer can build his software component against this build chain and can deliver object code back to the integrator.] (RS_METH_00202, RS_METH_00077)

[TR_AMETH_00015] Development without knowledge of the Build Chain Configuration [For this use case, the application developer is not aware of the Build Chain Configuration and needs to deliver source code to the integrator. The integrator then takes over the compilation of the the software component.] (RS_METH_-00202, RS_METH_00077)



2.3.1.3 Workflow

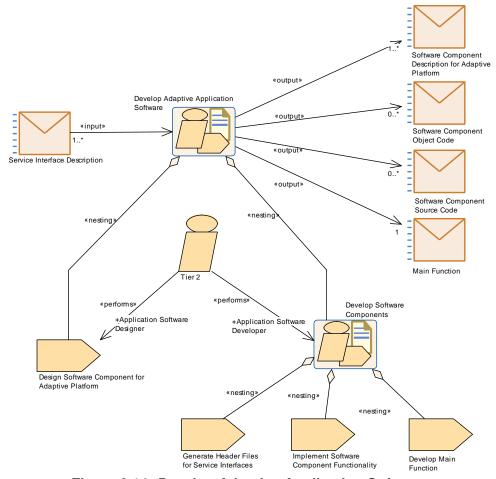


Figure 2.14: Develop Adaptive Application Software

Activity	Develop Adaptive Application Software			
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Develop Adaptive Application			
Brief Description	Design and developr	ment of	software components for Adaptive Platform	
Description	activity, Adaptive App Object Code for the main function for the is done in the proces	Develop an Adaptive Application with category application-level. In this activity, Adaptive Application Software in terms of Software Component Object Code for the Adaptive Platform is developed. In addition, the main function for the executable is developed. The integration of these is done in the proceeding step. The software component description is needed as deliverable for a later mapping of service instances to port		
Relation Type	Related Element	Mul.	Note	
Consumes	Service Interface Description	1*	Service Interfaces are the basis for the development of adaptive application software	
Produces	Main Function	1	One main function per executable is produced	



Relation Type	Related Element	Mul.	Note
Produces	Software Component Description for Adaptive Platform	1*	Output of component model for the software components
Produces	Software Component Object Code	0*	Compiled software components
Produces	Software Component Source Code	0*	Software components as source code
Aggregates	Design Software Component for Adaptive Platform	1	
Aggregates	Develop Software Components	1	

Table 2.12: Develop Adaptive Application Software

Activity	Develop Software Components			
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Develop Adaptive Application			
Brief Description	Implement the core	function	ality of an executable	
Description	In this activity, the software components for one executable are implemented and compiled. After the header files for the service interfaces are generated, the functionality can be implemented. For each executable, a main function needs to be implemented, which defines the internal communication and scheduling.			
Relation Type	Related Element	Mul.	Note	
Aggregates	Develop Main Function	1		
Aggregates	Generate Header Files for Service Interfaces	1		
Aggregates	Implement Soft- ware Component Functionality	1		
Performed by	Tier 2	1	Application Software Developer: This activity will probably be performed by an Application Software Developer of a Tier 2 company	

Table 2.13: Develop Software Components



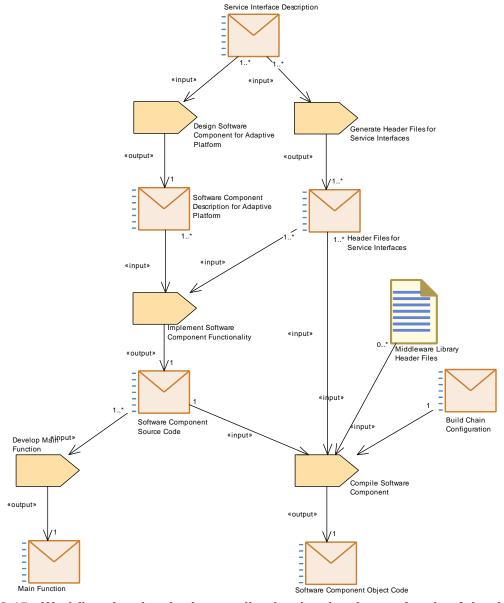


Figure 2.15: Workflow for developing application-level software for the Adaptive Platform

2.3.2 Develop Adaptive Platform-level Software

2.3.2.1 Purpose

This section explains how to develop platform-level software for the Adaptive Platform. The artifact workflow is depicted in Figure 2.16.



2.3.2.2 Description

[TR_AMETH_00035] Platform-level Software [An Adaptive Application of category platform-level is a collection of executables. The executable may consist of software components if these are based on standardized service interfaces, but may also be directly implemented without a software component model.] (RS_METH_00207, RS_-METH_00041)

[TR_AMETH_00020] Development of Platform Object Code [The platform modules, which consist of an executable, need to be developed. Similar as application-level software, they are later instantiated in terms of an Execution Manifest and then deployed on the machine. For each executable the corresponding main function needs to be developed as well. | (RS_METH_00207, RS_METH_00041)

2.3.2.3 Workflow

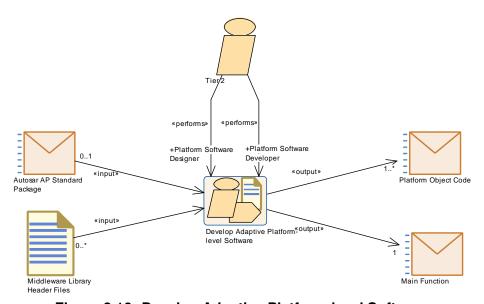


Figure 2.16: Develop Adaptive Platform-level Software

Activity	Develop Adaptive F	Develop Adaptive Platform-level Software			
Package		AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Develop Adaptive Application			
Brief Description	Develop an Adaptive	Softwa	re of category platform-level.		
Description	platform software mo together with an Exe e.g. the OS). This ac	Develop an Adaptive Software of category platform-level. These platform software modules consist of an executable and are deployed together with an Execution Manifest onto the machine (in contrast to e.g. the OS). This activity also includes the implementation of the corresponding main function.			
Relation Type	Related Element	Mul.	Note		
Consumes	Autosar AP Standard Package	01	In case standardized service interfaces are used for adaptive platform-level software		



Relation Type	Related Element	Mul.	Note
Consumes	Middleware Library Header Files	0*	Library header files needed for compiling the adaptive platform-level software
Produces	Main Function	1	Main function for platform-level executable
Produces	Platform Object Code	1*	Object code of platform module
Performed by	Tier 2	1	Platform Software Designer: The design tasks within the development of Platform-level Software will probably be performed by a Platform Software Designer of a Tier 2 company
Performed by	Tier 2	1	Platform Software Developer: The real development tasks (i.e., to write source code and the like) within the development of Platform-level Software will probably be performed by a Platform Software Developer of a Tier 2 company

Table 2.14: Develop Adaptive Platform-level Software

2.4 Integration and Deployment

2.4.1 Integrate Software

2.4.1.1 Purpose

After the implementation and compilation of the software, it needs to be integrated into one executable. Since the executable also contains platform-specific aspects, this process step also describes other activities as e.g. the development of the serialization for a specific platform and the implementation of the proxies and skeletons.

2.4.1.2 Description

[TR_AMETH_00016] Development of serialization properties [It needs to be described how the data in the service interfaces shall be serialized for the transport on the network. In particular, this is important for the communication over SOME/IP between Classic and Adaptive Platform.

For the service interfaces, the properties of the serialization will be defined. For SOME/IP, this includes the alignment, the configuration of length fields that are added in front of arrays or structures, etc. Based on this Serialization Configuration, the serialization code can be generated. The serialization is developed for a dedicated Adaptive Platform. | (RS_METH_00006, RS_METH_00077, RS_METH_00066)

[TR_AMETH_00017] Implementation of service proxies and skeletons [The service proxies and skeletons, which are contained in the Header Files for Service



Interfaces and used within the software components, need to be implemented. For this implementation, the serialization of data needs to be known. | (RS METH 00207)

[TR_AMETH_00018] Building the (Adaptive) Executable [The (Adaptive) Executable can be built based on application-level Software Component Object Code or platform-level Platform Object Code together with the respective Main Function. Additionally, the Serialization Source Code and all necessary libraries and implementations are linked to one (Adaptive) Executable.] (RS_METH_00202, RS_METH_00066, RS_METH_00042)

2.4.1.3 Workflow

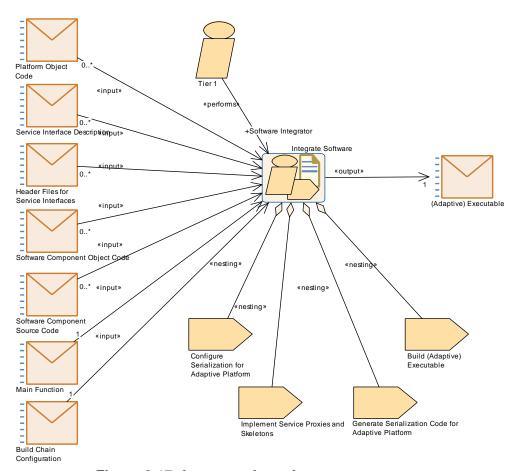


Figure 2.17: Integrate the software components



Activity	Integrate Software		
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Integration::Integrate Software		
Brief Description	Integrate software to	one ex	ecutable
Description	In this activity, the compiled software and one main function are integrated into one executable. For this step, several other artifacts may be necessary, as the serialization code, the implemented proxies and skeletons and necessary middleware libraries. Several executables can later be packaged into an Adaptive AUTOSAR		
	Application.		T
Relation Type	Related Element	Mul.	Note
Consumes	Build Chain Configuration	1	Needed for linking all artifacts
Consumes	Header Files for Service Interfaces	0*	Proxies and skeletons to be implemented
Consumes	Main Function	1	One main function per executable
Consumes	Platform Object Code	0*	Object code for platform-level executable
Consumes	Service Interface Description	0*	Needed for defining the serialization
Consumes	Software Component Object Code	0*	Object code for application-level executable
Consumes	Software Component Source Code	0*	Source code for application-level executable
Produces	(Adaptive) Executable	1	Software is integrated into one executable
Aggregates	Build (Adaptive) Executable	1	
Aggregates	Configure Serial- ization for Adaptive Platform	1	
Aggregates	Generate Serial- ization Code for Adaptive Platform	1	
Aggregates	Implement Service Proxies and Skele- tons	1	
Performed by	Tier 1	1	Software Integrator: This activity will probably be performed by a Software Integrator of a Tier 1 company

Table 2.15: Integrate Software



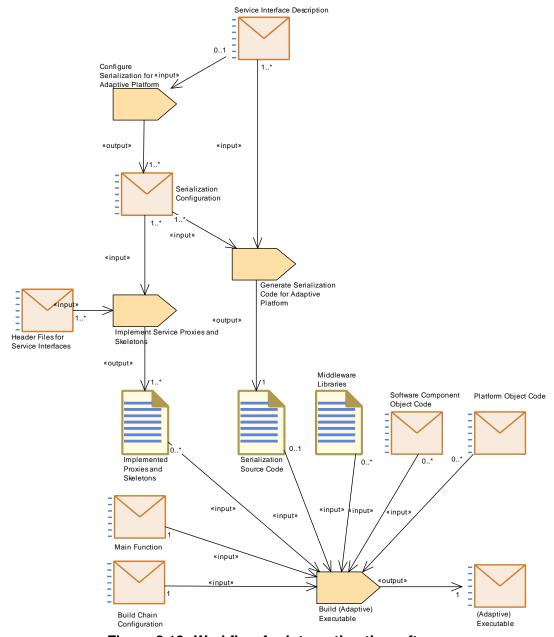


Figure 2.18: Workflow for integrating the software

2.4.2 Define and configure a Machine

As outlined in [TR_AMETH_00003], the definition and configuration is subdivided into two process steps. This section here will deal with the second one, the activities and tasks necessary for the configuration of a real adaptive ECU in order to obtain a complete Machine Manifest.



2.4.2.1 Preparatory steps

2.4.2.1.1 Purpose

This subsection describes some preparatory activities towards the real configuration step of the machine.

2.4.2.1.2 Description

[TR_AMETH_00019] Description of the Adaptive Platform [As a first preparatory step, the available hardware elements of the particular Adaptive Platform need to be specified. This can be done by means of the ECU Resources Description which enables to describe all hardware elements, like processing units, memories, sensors, actuators or pins.] (RS_METH_00207, RS_METH_00041)

ECU resources can be specified based on the ECU Resource Template [7].

[TR_AMETH_00034] Select the Operating System for Adaptive Platform [Furthermore, an operating system (OS) needs to be selected for a particular Adaptive Platform and assembled. To that, it might be necessary to port or at least to adjust the OS for the specific hardware.

The OS for the Adaptive Platform is a platform module not having an Execution Manifest. Note, that its development workflow will differ from the workflow of platform-level software. $|(RS_METH_00207, RS_METH_00041)|^{11}$

2.4.2.1.3 Workflow

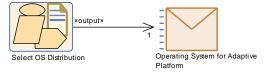


Figure 2.19: Select the OS Distribution

Activity	Select OS Distribution		
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Define and Configure Machine::Develop Platform Software		
Brief Description	Select and assemble an operating system		
Description	Select an operating system and assemble it. The workflow for the platform modules as the OS is different to the workflow of platform-level applications, which will be instantiated with an Execution Manifest.		
Relation Type	Related Element Mul. Note		

¹¹see section 2.3.2 for platform-level software development workflow details.



Relation Type	Related Element	Mul.	Note
Produces	Operating System for Adaptive Platform	1	Selected OS distribution

Table 2.16: Select OS Distribution

2.4.2.2 Configure the Machine

2.4.2.2.1 Purpose

The machine describes the computing resource on which the Adaptive AUTOSAR Software Stack is executed.

Based on the assumptions of [TR_AMETH_00003], this use case describes all definition and configuration activities for the machine, independent of the deployment information of applications or service instances. All produced content will be part of the Machine Manifest.

The overview of inputs, outputs and all tasks is given in Figure 2.20. The workflow is described in Figure 2.21.

2.4.2.2.2 Description

[TR_AMETH_00022] Definition of function group states and per-state timeouts | The configuration of a machine includes the definition of function group states and per-state timeouts.

A function group on a machine can have several states, in which functionally coherent processes will be activated or deactivated. These states need to be defined and can then be used for the start-up configuration of a process, which might depend on the function group states.

It is possible to define timeouts by means of Per State Timeouts for specific function group states. | (RS_METH_00204, RS_METH_00203)

[TR_AMETH_00217] Definition of resources [The configuration of a machine may include the definition of resources. Based on the ECU Resources Description (as an input), available hardware resources for a machine can be described .] $(RS_-METH_00204, RS_METH_00203)$

[TR_AMETH_00216] Map Processes to a particular machine The configuration of the machine includes the mapping of Processes to a particular machine via Process to Machine Mapping, assuming that one Process shall only be mapped once, to exactly one machine.

To perform this, a list of Processes supposed to run on the machine is required as input. | (RS_METH_00204, RS_METH_00203)



[TR_AMETH_00023] Configuration of the operating system [The configuration of the operating system is defined via the AdaptiveModuleInstantiation meta class. For a specific instantiation of the operating system, resource groups as well as the supported timer granularity can be defined. | (RS METH 00204, RS METH 00203)

[TR_AMETH_00214] Configuration of Platform Services [The configuration of a machine includes the machine-specific configuration of Adaptive Platform Services, like the machine-specific configuration of

- the NM module
- DoIP

](RS_METH_00204, RS_METH_00203)

[TR_AMETH_00215] Configuration of Platform Foundation Modules [Beside the configuration of the Operating System, the configuration of a machine also includes the machine-specific configuration of the Adaptive Platform Foundation Modules, like the machine-specific configuration of

• the Log & Trace module

](RS_METH_00204, RS_METH_00203)



2.4.2.2.3 Workflow

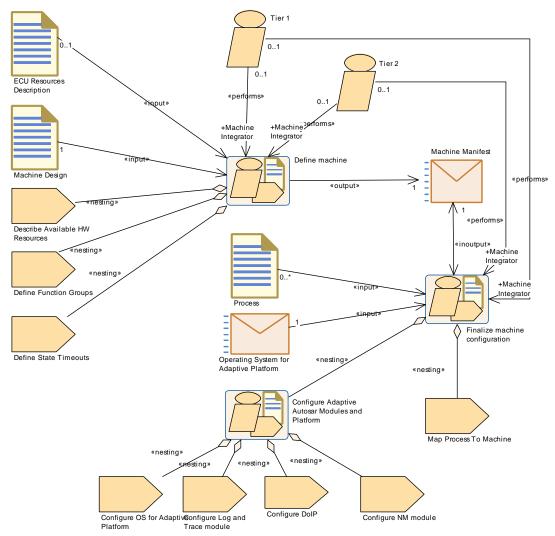


Figure 2.20: Define and Configure Machine

Activity	Define machine		
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Define and Configure Machine::Machine Configuration		
Brief Description	Create a Machine M	anifest	
Description	The activity describes tasks for the configuration of the machine, which do not depend on deployment information of applications or service instances. This includes the configuration for the communication on the network based on service discovery, the description of all function group states and the available resources. The Machine Manifest will be completed in the activity Finalize machine configuration.		
Relation Type	Related Element Mul. Note		
Consumes	ECU Resources Description	01	All resources which are available for the ECU



Relation Type	Related Element	Mul.	Note
Consumes	Machine Design	1	Configuration settings of the network connections and service discovery network exchange of a Machine
Produces	Machine Manifest	1	The machine manifest describes all the configuration settings for one Machine
Aggregates	Define Function Groups	1	
Aggregates	Define State Time- outs	1	
Aggregates	Describe Available HW Resources	1	
Performed by	Tier 1	01	Machine Integrator: This activity will probably be performed by a Machine Integrator of a Tier 1 company
Performed by	Tier 2	01	Machine Integrator: Alternatively, this activity could also be performed by a Machine Integrator of a Tier 2 company

Table 2.17: Define machine

Activity	Finalize machine c	onfigura	ation	
Package		AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Define and Configure Machine::Machine Configuration		
Brief Description	Finalize a Machine N	Manifest		
Description		nfigurati	to complete the configuration of the on of the OS and other platform modules ocesses.	
Relation Type	Related Element	Mul.	Note	
Consumes	Operating System for Adaptive Platform	1	OS to be configured	
Consumes	Process	0*	Processes dedicated to run Executables on a Machine	
Aggregates	Configure Adaptive Autosar Modules and Platform	1		
Aggregates	Map Process To Machine	1		
In/out	Machine Manifest	1	The machine manifest describes all the configuration settings for one Machine	
Performed by	Tier 1	01	Machine Integrator: This activity will probably be performed by a Machine Integrator of a Tier 1 company	
Performed by	Tier 2	01	Machine Integrator: Alternatively, this activity could also be performed by a Machine Integrator of a Tier 2 company	

Table 2.18: Finalize machine configuration



Activity	Configure Adaptive Autosar Modules and Platform		
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Define and Configure Machine::Machine Configuration		
Brief Description			
Description	Configure individual Adaptive Autosar modules, i.e., the OS as well as non-OS modules.		
Relation Type	Related Element	Mul.	Note
Aggregates	Configure DoIP	1	
Aggregates	Configure Log and Trace module	1	
Aggregates	Configure NM module	1	
Aggregates	Configure OS for Adaptive Platform	1	

Table 2.19: Configure Adaptive Autosar Modules and Platform

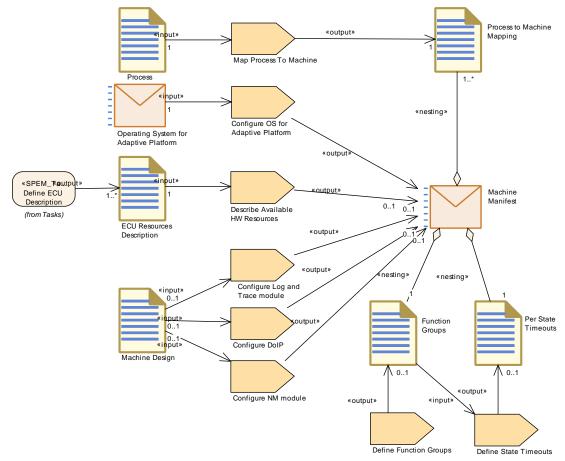


Figure 2.21: Workflow for defining and configuring an machine



2.4.3 Create Execution Manifest

2.4.3.1 **Purpose**

This use case defines all tasks, which are necessary in order to instantiate the (Adaptive) Executable. For on overview see Figure 2.22. The workflow is given in Figure 2.23.

2.4.3.2 Description

[TR_AMETH_00024] Instantiation of (Adaptive) Executable [Define the instantiation of an (Adaptive) Executable on a specific machine in terms of a process. One executable can be instantiated several times and in different ways, e.g. varying in the definition of the startup behavior. This results in several processes.] (RS_METH_-00203, RS_METH_00077)

[TR_AMETH_00025] Definition of startup behavior of a process [For each process the startup behavior can depend on function group states. Therefore, the process might have a different startup behavior in one function group state compared to a second function group state. This behavior can e.g. vary in terms of the scheduling priority or the execution dependencies to other processes. | (RS_METH_00203)

[TR_AMETH_00026] Definition of Execution Manifest [The Execution Manifest aggregates the process and its startup configuration. Therefore, one Execution Manifest is defined per process.] (RS_METH_00203)



2.4.3.3 Workflow

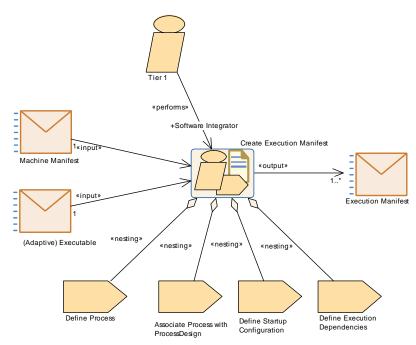


Figure 2.22: Create an Execution Manifest

Activity	Create Execution N	l anifest	
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Execution Manifest		
Brief Description	Instantiation-specific	configu	ration of executable
Description	In this activity, the processes are defined. One executable can be instantiated several times, which results in multiple processes for one executable. One Execution Manifest is defined per process and contains all its attributes including startup configuration and execution dependencies.		
Relation Type	Related Element	Mul.	Note
Consumes	(Adaptive) Executable	1	One executable can be instantiated several times
Consumes	Machine Manifest	1	Instantiation is defined on one specific machine
Produces	Execution Manifest	1*	One execution manifest per instantiated executable
Aggregates	Associate Process with Process Design	1	
Aggregates	Define Execution Dependencies	1	
Aggregates	Define Process	1	
Aggregates	Define Startup Configuration	1	
Performed by	Tier 1	1	Software Integrator: This activity will probably be performed by a Software Integrator of a Tier 1 company



Relation Type Related Element Mul. Note

Table 2.20: Create Execution Manifest

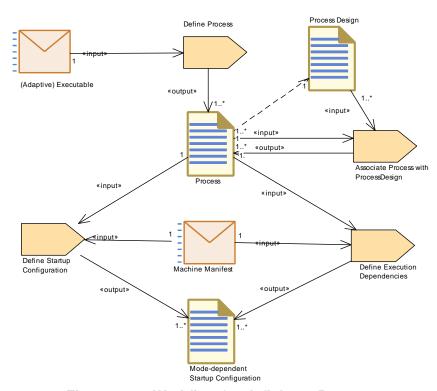


Figure 2.23: Workflow for defining a Process

2.4.4 Define and Configure Service Instances

2.4.4.1 Purpose

This use case describes the definition and configuration of service instances in the system. For an overview of all tasks see Figure 2.24. For the workflow see Figure 2.25. The outcome of this activity is the Service Instance Manifest.

2.4.4.2 Description

[TR_AMETH_00027] Configuration of Service Interface Deployment [The system responsible specifies in Service Interface Deployment Configuration how the service interfaces shall be deployed. This includes the properties describing the individual transport layer binding of the service interface.

E.g. for SOME/IP deployment, an ID for each service interface is defined. This ID needs to be unique in the system. Additionally methodID, eventID as well as event



groups are defined unambiguously in the scope of the SOME/IP service interface deployment. | (RS_METH_00206, RS_METH_00203) | 12

[TR_AMETH_00028] Configuration of Service Instances [Afterwards, the system responsible defines instances of the deployed service interfaces and decides whether the service instance is provided or consumed. In order to set up the service-oriented communication Service Instance Configuration includes properties for search or offer criteria.

E.g. for SOME/IP, an ID for each provided service instance is defined. This ID needs to be unique in the system (and should be globally unambiguous). For required service instances SOME/IP allows to specify optionally a required service instance ID (which ofcourse should be provided somewhere). \[\((RS_METH_00206, RS_METH_00203) \) \] 13

[TR_AMETH_00029] Mapping of Service Instances to Machine [The service instances will be deployed to a Machine (i.e. a Adaptive Platform instance) that will execute the service instance. This Service Instance To Machine Mapping includes technology specific properties.

E.g. for SOME/IP, the TP and IP configuration for the client and the server are described. | (RS_METH_00206, RS_METH_00203, RS_METH_00078) 14

[TR_AMETH_00033] Mapping of Service Instances to Port Prototypes [In addition, the service instances need to be mapped to their representation in the application (i.e. to instances of port prototypes) via the Service Instance To Port Prototype Mapping. This mapping is necessary in order to ensure a unique relationship between locally implemented service instances within the application and global service instances available on the network. The Service Instance To Port Prototype Mapping includes technology specific properties.

E.g. for SOME/IP the provided (and optionally also required) service instance IDs are specified. | (RS METH 00206, RS METH 00203, RS METH 00078) 15

¹²see 3.10.2.1

¹³see 3.10.2.2

¹⁴see 3.10.1.5

¹⁵see 3.10.1.4



2.4.4.3 Workflow

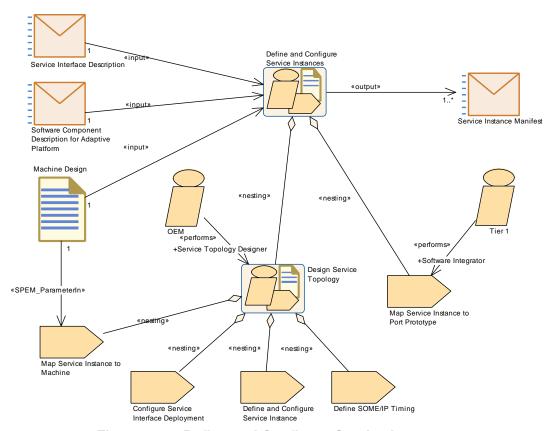


Figure 2.24: Define and Configure Service Instances

Activity	Define and Configu	ıre Serv	rice Instances
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Service Instance Definition		
Brief Description	Configuration of serv	vice inte	rface deployment and service instances
Description	This activity covers the configuration of the service interfaces for the used network layer, independent of any instantiation on the one hand as well as the definition and configuration of service instances on the other.		
Relation Type	Related Element	Mul.	Note
Consumes	Machine Design	1	Service instances will be mapped to machine
Consumes	Service Interface Description	1	Deployment of service interfaces needs to be configured
Consumes	Software Component Description for Adaptive Platform	1	Used to map the service instances to ports of a software component
Produces	Service Instance Manifest	1*	Contains all configuration settings for the service instance on a specific machine
Aggregates	Design Service Topology	1	



Relation Type	Related Element	Mul.	Note
Aggregates	Map Service Instance to Port Prototype	1	

Table 2.21: Define and Configure Service Instances

Activity	Design Service Top	ology	
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Service Instance Definition		
Brief Description	Design Service Topology		
Description	This activity subsum of a network topolog		esign tasks which are related to the design
Relation Type	Related Element	Mul.	Note
Aggregates	Configure Service Interface Deployment	1	
Aggregates	Define SOME/IP Timing	1	
Aggregates	Define and Configure Service Instance	1	
Aggregates	Map Service Instance to Machine	1	
Performed by	OEM	1	Service Topology Designer: This activity will probably be performed by a Service Topology Designer of an OEM

Table 2.22: Design Service Topology



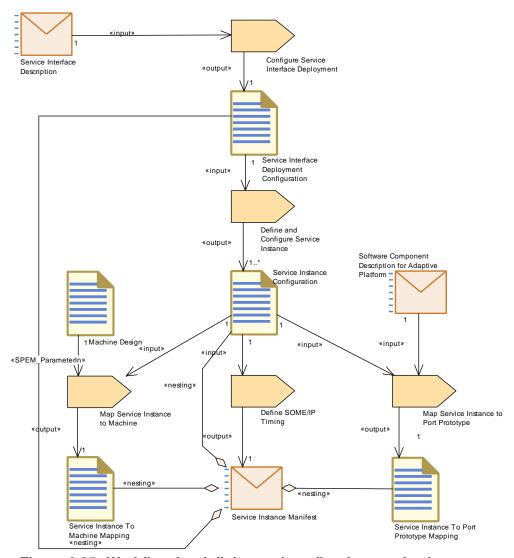


Figure 2.25: Workflow for defining and configuring service instances

2.4.5 Set up an initial Machine

Disclaimer: the content of this section is under discussion.

2.4.5.1 Purpose

This activity describes how a machine is set up so that software can be deployed onto it.



2.4.5.2 Description

[TR_AMETH_00031] Setting up an initial machine [The aim of this activity is to obtain a machine that is initially set up. 'Initially set up' means here, that the machine is able to upload and install additional software by means of Software Packages. For this purpose at least the Platform module UCM and dependent modules (like the diagnostic communication module) need to run on the initially set up machine. Thus, this activity will (at least) include the following tasks:

- 1. Install the selected Operating System on the selected target (machine).
- 2. Install all necessary Platform modules on top of the installed OS in order to be able to perform the upload and the installation of additional application software by means of Software Packages.

In order to be able to execute this activity, the following inputs are necessary:

- A selected Operating System for Adaptive Platform
- The configuration settings by means of the Machine Manifest
- Possibly, design artifacts like the Machine Design
- The Executables of the Platform and Application modules which shall be installed
- Execution Manifests and Service Instance Manifests of the Platform and Application modules which shall be installed
- Possibly, diagnostic information by means of the Diagnostic Machine Extract since the upload and installation process may use the diagnostic environment

(RS METH 00205, RS METH 00204)

Figure 2.26 shows the aforementioned; illustrating the relations of the involved entities.



2.4.5.3 Workflow

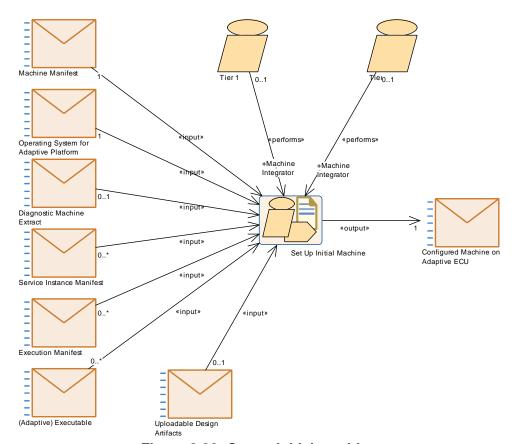


Figure 2.26: Set up initial machine

Activity	Set Up Initial Machine			
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Define and Configure Machine::Setup Machine			
Brief Description	Set up the machine based on the machine manifest			
Description	Configure and install the OS and other necessary platform modules (e.g., UCM) on the machine. The configuration settings are given by the Machine Manifest. In addition, the network connections as well as function groups are set up.			
Relation Type	Related Element	Mul.	Note	
Consumes	(Adaptive) Exe- cutable	0*	Executables of those Platform modules and Adaptive Applications that should run on a initially configured machine. Beside the OS, at least the UCM and connected Platform modules (e.g., a diagnostic communication manager) need to be installed in order to be able to upload other software.	
Consumes	Diagnostic Ma- chine Extract	01	Diagnostic extract for a Machine	
Consumes	Execution Manifest	0*	All Execution Manifests needed to run the desired adaptive application (instances or Processes) on a Machine	



Relation Type	Related Element	Mul.	Note
Consumes	Machine Manifest	1	Containing all configuration settings for the Machine
Consumes	Operating System for Adaptive Platform	1	OS to be installed on machine
Consumes	Service Instance Manifest	0*	All Service Instance Manifests needed to run the desired adaptive application (instances or Processes) on a Machine
Consumes	Uploadable Design Artifacts	01	Optional input: Additional design data which are not part of an Application or Machine Manifest
Produces	Configured Ma- chine on Adaptive ECU	1	Machine is configured and software can now be deployed
Performed by	Tier 1	01	Machine Integrator: This activity will probably be performed by a Machine Integrator of a Tier 1 company
Performed by	Tier 2	01	Machine Integrator: Alternatively, this activity could also be performed by a Machine Integrator of a Tier 2 company

Table 2.23: Set Up Initial Machine

2.4.6 Create Software PackageS

Disclaimer: the content of this section is under discussion.

2.4.6.1 **Purpose**

This use case comprises all activities and tasks to specify Software Packages.

2.4.6.2 Description

The AUTOSAR Adaptive Platform offers the ability to upload software onto machines (AUTOSAR Adaptive Platform instances) without to reflash everything.

According to the glossary [8], Software Packages are the units for deployment onto machines (AUTOSAR Adaptive Platform instances). In this respect, they are inputs for and processed by the Adaptive Platform Service UCM.

In fact, a Software Package consists of two main parts:

• a bundle of the actual software artifacts, referred to as Software Cluster here



• corresponding model data needed to control the upload and installation process of this Software Cluster executed by the UCM [9], referred to as Software Package Manifest here

Thus, from an UCM point of view, the term Software Cluster identifies a bundle of software artifacts that are uploaded together in order to be installed by the UCM. In general, a Software Cluster may contain Executables, Execution Manifests, Service Instance Manifests, Machine Manifests and other development artifacts. It should be mentioned, that a Software Cluster may be structured into sub-blocks in order to mimic the CP diagnostic workflow, where blocks are the smallest parts of update and to enable the execution of update campaigns (see details in [9]).

Otherwise, the term Software Cluster may also refer to a set of installed software entities (processes that run Executables, data or manifests) which form a logical group and which are addressable by the diagnostic management by a shared diagnostic address.

Not surprisingly, both definitions match in the sense that the bundle of software uploaded are needed to form the set of installed software entities addressed by the same diagnostic address.

A Software Cluster (in the UCM sense) is described by its model, collected in the Software Package Manifest. The root-element of this description is called Software Cluster (category ROOT_SOFTWARE_CLUSTER) [6]. From a model point of view, the sub-blocks, mentioned above, can be expressed likewise by the same meta model element SoftwareCluster, but in the role subSoftwareCluster (or category SUB_SOFTWARE_CLUSTER) [6].

The meta model supports also the expression of dependencies between <code>Soft-wareClusters</code> or <code>subSoftwareClusters</code> [6], the assignment of a diagnostic address for <code>SoftwareCluster</code> of category <code>ROOT_SOFTWARE_CLUSTER</code> and, of course, information about which artifact belongs to which <code>SoftwareCluster</code>. See [6] for a deeper insight into the respective modeling.

In general, it might be useful for integrator to store incoming artifacts as well as assembled Software Clusters into repository and manage them by some sort of data base.

Note, that the real format of the Software Package is implementation specific and not covered by any specification [9].

[TR_AMETH_00206] Create a Software Package [The following activities/tasks are needed in order to obtain a Software Package:

- Create an initial Software Package Manifest
- Collect all software artifacts that belong to a Software Cluster, structure and model them
- Model dependencies between Software Cluster of any category
- Develop installation instructions



- Create the Software Package
- Manage the data base of Software Clusters (of any category)

(RS METH 00205) 16

One input of this activity is the deliverable <code>Software Cluster Design</code> based on the meta model element <code>SoftwareClusterDesign</code> [6]. The deliverable <code>SoftwareClusterDesign</code> [6]. The deliverable <code>SoftwareClusterDesign</code> contains the requirements that have initially been formulated by an OEM. The formal structure of the <code>SoftwareClusterDesign</code> is similar to <code>SoftwareCluster[6]</code>. Thus, by means of this, the OEM is able to define the composition and structure of <code>Software Clusters</code>, dedicated diagnostic addresses as well as internal and external dependencies of <code>Software Clusters</code>.

The clear separation of the meta model elements <code>SoftwareCluster</code> and <code>SoftwareClusterDesign</code> is motivated from a methodology point of view, because different parties are involved at different design stages. To specify requirements for the structure of <code>Software Packages</code> is the genuine interest of an OEM, because he knows best about its IT- and vehicle infrastructure, whereas (most probably) a <code>Tier 1</code> company is responsible for the integration and deployment processes.

[TR_AMETH_00218] Create an initial Software Package Manifest [The main input for this step are the requirements of the OEM given by means of Software Cluster Design. Thus, this task is about to create an new Software Package Manifest and to transfer the structure and the entries of the given Software Cluster Design into the newly created Software Package Manifest. | ()

[TR_AMETH_00219] Collect all software artifacts that belong to a Software Cluster, structure and model them [On base of the Software Cluster Design o the newly created Software Package Manifest, this step includes the following sub-tasks:

- Identify necessary (software) artifacts
 - Identify necessary (software) artifacts in order to build the Software Package, also with respect to their versions
 - Check, whether there are deviations between the required and actual sets of Sub Software Clusters (by means of the aggregated artifacts and versions), if necessary solve them and re-model the Software Package Manifest accordingly
 - Check, whether there are discrepancies between the required and actual set of the (root) Software Cluster (by means of its aggregated Sub Software Clusters and versions)
- Collect belonging (software) artifacts of Sub Software Clusters

¹⁶Figure 2.27 shows the corresponding input and output deliverables.



- Collect belonging (software) artifacts of Sub Software Clusters into separate baskets ((Sub) Software Cluster Groups) in order to prepare the final step of creating the Software Package
- Execute a receiving inspection (optional)
- Store incoming artifacts into a repository

10

[TR_AMETH_00220] Model dependencies between Software Clusters of any category [Dependencies between Software Clusters of the same or different categories may already be given by the requirements of an OEM by means of a SoftwareClusterDesign. Dependencies to Software Clusters are specified by means of their identification (name) and version.

Therefore, the respective SoftwareClusterDesign is will be one input for this activity.

However, dependencies may change during the development process and the activity needs to consider it.

Thus, this task describes the handling of dependencies by at least the following subtasks:

- Check, whether the dependencies between Software Clusters of the same or different categories, given by the respective SoftwareClusterDesign are still valid
- Determine changes between the actual and required dependencies between Software Clusters of any category
- If necessary, re-model the Software Package Manifest in accordance with the outcomes of the both tasks above

10

[TR_AMETH_00221] Develop installation instructions [Installation instruction control the behavior of the UCM during the update of Software Packages. Installation instructions can either be 'add/update' meaning to install a package or 'remove' to express that a package shall be uninstalled and deleted from the machine. Installation instructions are defined per Software Cluster, independent of its category. For details, see [9].

Thus, this task may includes the sub-tasks:

- Specify installation instructions per Software Cluster (of any category)
- Develop update campaigns (optional)

The particular installation instructions are part of the Software Package Manifest.

 $\rfloor ()$



[TR_AMETH_00222] Create the Software Package [The format of the Software Package as well as the update strategy, i.e., whether you go for a complete or a delta update are implementation specific. Both issues will not be specified by AUTOSAR.

Thus, this activity handles the compilation of Software Cluster and Software Package Manifest into a Software Package.

Since AUTOSAR does not specify how the Software Package looks like, the break-down of this activity into tasks is also specific to particular OEMs and their suppliers.

10

[TR_AMETH_00223] Manage the data base of Software Clusters (of any category) [A general activity may be the management of the data base of Software Clusters with respect to all their versions, dependencies and further aspects.

It is assumed that this activity is also specific to particular OEMs/suppliers. Therefore a more fine-granular task structure will not be specified here. | ()



2.4.6.3 Workflow

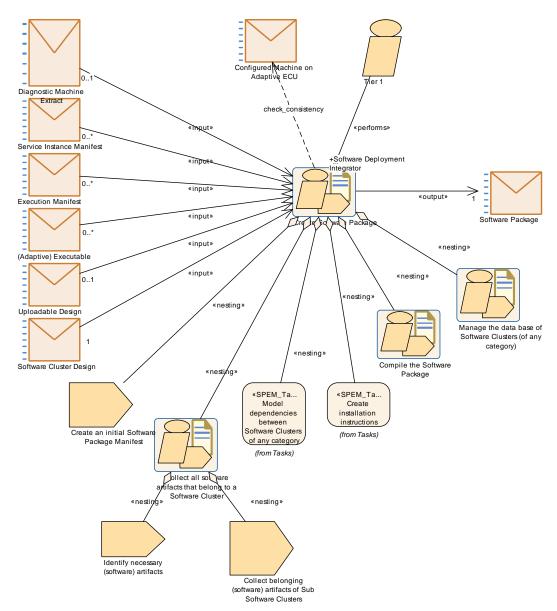


Figure 2.27: Create a Software Package

Activity	Create Software Package			
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Packaging and Provision			
Brief Description	Create a Software P	Create a Software Package		
Description	This activity describe	es the cr	reation of a Software Package.	
Relation Type	Related Element	Mul.	Note	
Consumes	(Adaptive) Executable	0*	Executables of deployed processes	
Consumes	Diagnostic Ma- chine Extract	01	Diagnostic extract for a Machine	
Consumes	Execution Manifest	0*	Several processes can be deployed	



Relation Type	Related Element	Mul.	Note
Consumes	Service Instance Manifest	0*	Several service instance manifests can be deployed
Consumes	Software Cluster Design	1	Requirements of the OEM wrt. package structure and parameters given by means of the meta model element SoftwareClusterDesign.
Consumes	Uploadable Design Artifacts	01	Optional input: Additional design data which are not part of an Application or Machine Manifest
Produces	Software Package	1	Software Package for deployment defined
Aggregates	Collect all software artifacts that belong to a Software Cluster	1	
Aggregates	Compile the Software Package	1	
Aggregates	Create an initial Software Package Manifest	1	
Aggregates	Create installation instructions	1	
Aggregates	Manage the data base of Software Clusters (of any category)	1	
Aggregates	Model dependencies between Software Clusters of any category	1	
Performed by	Tier 1	1	Software Deployment Integrator: This activity will probably be performed by a Software Deployment Integrator of a Tier 1 company

Table 2.24: Create Software Package



Activity	Collect all software	Collect all software artifacts that belong to a Software Cluster			
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Packaging and Provision				
Brief Description	Collect all software a	artifacts			
Description	On base of the Software Cluster Design o the newly created Software Package Manifest, this step includes the following tasks:				
	,		needed (software) artifacts in order to ckage, also with respect to their versions		
	Execute a rec	eiving ir	nspection (optional)		
	Store incomin	g artifac	cts into a repository		
	 Assemble belonging (software) artifacts for Sub Software Clusters into separate 'baskets' (Software Cluster Groups) in order to prepare the final step of creating the Software Package 				
	 Check, whether there are divergences within the required and actual sets of Sub Software Clusters (by means of the aggregated artifacts and versions). If necessary solve them and re-model the Software Package Manifest, accordingly 				
	 Check, whether there are discrepancies between the required and actual set of the Root Software Cluster (by means of its aggregated Sub Software Clusters and versions) 				
Relation Type	Related Element	Mul.	Note		
Aggregates	Collect belonging (software) artifacts of Sub Software Clusters	1			
Aggregates	Identify necessary (software) artifacts	1			

Table 2.25: Collect all software artifacts that belong to a Software Cluster

Activity	Compile the Softwa	Compile the Software Package			
Package		AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Packaging and Provision			
Brief Description	Compile the Softwar	e Packa	ge		
Description	whether you go for a specific. Both issues Thus, this activity co Software Package, v Package looks like.	The format of the Software Package as well as the update strategy, i.e., whether you go for a complete or a delta update are implementation specific. Both issues will not be specified by AUTOSAR. Thus, this activity copes with compilation of the belonging parts into a Software Package, without being able to specify how the Software Package looks like. Therefore, the structure of this activity by tasks is also specific to			
Relation Type	Related Element				
Consumes	(Sub) Software Cluster Group	0*	Compile all Sub Software Clusters into the Software Package		
Consumes	Software Package Manifest	1	Integrate the Software Package Manifest into the Software Package		



Relation Type	Related Element	Mul.	Note
Produces	Software Package	1	Compiled Software Package

Table 2.26: Compile the Software Package

Activity	Manage the data base of Software Clusters (of any category)			
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Packaging and Provision			
Brief Description	Manage the data ba	se of So	ftware Clusters	
Description	A general activity may be the management of the data base of Software Clusters with respect to all their versions, dependencies and further aspects. It is assumed that this activity is also specific to particular OEMs/suppliers. Therefore a more fine-granular task structure will not be specified here.			
Relation Type	Related Element	Mul.	Note	
Consumes	Software Cluster	1*	Store and manage software cluster within a repository	
Consumes	Software Package Manifest	1*	Manage meta data of corresponding Software Cluster	

Table 2.27: Manage the data base of Software Clusters (of any category)

2.4.7 Management and provision of Software Packages

Disclaimer: the content of this section is under discussion.

2.4.7.1 **Purpose**

This activity may comprise two aspects:

- The management of Software Packages ready to upload onto the machines
- The provision of Software Packages for the upload

2.4.7.2 Description

[TR_AMETH_00224] Management of Software Packages [Once Software Packages have been created, they are generally ready to be deployed to dedicated machines (Adaptive ECUs) in the field.

In order to do so, the Software Package may be stored, e.g., into a repository of packages located on a Back-end server.



The management of this repository of the Software Packages may be supported by means of data bases.

Since the management of Software Packages is an immanent task of an OEM and will differ between the companies, this activity will not be detailed further. | ()

[TR_AMETH_00225] Provision of Software Packages for machines in the field [A Back-end server may also provide some sort of (sophisticated) business logic. It may enable, e.g., a tester not only to access particular versions of particular Software Packages for upload, but also to provide change sets of different versions of Software Packages.

The handling of a concrete upload procedure is specified by diagnostic standards to some extend. However, as mentioned before, the format of the Software Package as well as the update strategy are not specified. There will be differences in handling and procedures among OEMs and therefore, this activity will not be further subdivided. ()

2.4.7.3 Workflow

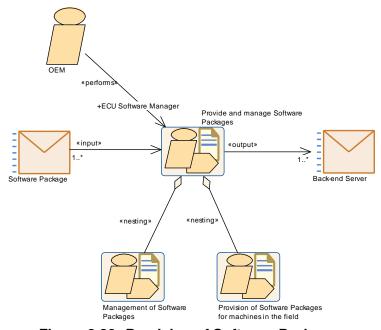


Figure 2.28: Provision of Software Packages



Activity	Provide and manage Software Packages			
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Packaging and Provision			
Brief Description	Provide and manage	Softwa	re Packages	
Description	This activity may comprise two aspects:			
	The managen the machines	nent of S	Software Packages ready to upload onto	
	The provision	of Softv	vare Packages for the upload	
Relation Type	Related Element	Mul.	Note	
Consumes	Software Package	1*	Deploy software on a Back-end server by means of Software Package	
Produces	Back-end Server	1*	Store uploadable packages (Software Packages) into a repository of a Back-end server	
Aggregates	Management of Software Pack- ages	1		
Aggregates	Provision of Soft- ware Packages for machines in the field	1		
Performed by	OEM	1	ECU Software Manager: This activity will be probably performed by an ECU Software Manager of an OEM	

Table 2.28: Provide and manage Software Packages

Activity	Management of Software Packages				
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Packaging and Provision				
Brief Description	Management of Soft	ware Pa	ckages		
Description	In order to do so, the repository of packag The management of supported by means Since the managem	Once Software Packages have been created, they are generally ready to be deployed to dedicated machines (Adaptive ECUs) in the field. In order to do so, the Software Package may be stored, e.g., into a repository of packages located on a Back-end server. The management of this repository of the Software Packages may be supported by means of data bases. Since the management of Software Packages is an immanent task of			
	an OEM and will differ between the companies, this activity will not be detailed further.				
Relation Type	Related Element	Related Element Mul. Note			
Consumes	Software Package	1*	Newly created or updated Software Packages are stored into a repository and subject of the management of all available Software Packages (including their history)		



Relation Type	Related Element	Mul.	Note
Produces	Back-end Server	1*	Software Packages are stored into a repository of Software Packages. In addition, update of a common data base of available Software Packages including their history.

Table 2.29: Management of Software Packages

Activity	Provision of Softwa	Provision of Software Packages for machines in the field			
Package		AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Packaging and Provision			
Brief Description	Provision of Softwar	e Packa	ges		
Description		Present the Software Packages in a way, that the UCM of machines are able to access the respective Software Packages.			
	business logic. It may particular versions of to provide change so to provide change so the handling of a constandards to some expectified. There will	ny enable f particulets of difference u extend. He kage as be diffe	provide some sort of (sophisticated) e, e.g., a tester not only to access llar Software Packages for upload, but also ferent versions of Software Packages. upload procedure is specified by diagnostic However, as mentioned before, the format well as the update strategy are not rences in handling and procedures among tivity will not be further subdivided.		
Relation Type	Related Element	Mul.	Note		
Consumes	Back-end Server	1	Status quo of the presentation layer of the Back-end Server		
Produces	Back-end Server	1	Organize the Back-end Server in accordance with the requirements of an OEM		

Table 2.30: Provision of Software Packages for machines in the field



3 Adaptive Methodology Library

The Adaptive Methodology Library lists all work products and tasks that are used for modeling the use cases in section 2.

3.1 Roles

3.1.1 OEM

Role	OEM			
Package	AUTOSAR Root::M2	2::Metho	dology::Methodology Library::Adaptive	
	Platform::Common Elements::Roles			
Brief Description	OEM - Original Equi	pment N	Manufacturer	
Description	OEM - Original Equi	pment N	Manufacturer	
	An OEM refers to a consumer marketpla		y that makes a final product for the	
Relation Type	Related Element	Mul.	Note	
Performs	Create Diagnostic Mapping	1	Diagnostic Designer: The activity of designing the diagnostic mapping will probably be performed by a Diagnostic Designer of an OEM	
Performs	Design Service Topology	1	Service Topology Designer: This activity will probably be performed by a Service Topology Designer of an OEM	
Performs	Design service oriented communication between Classic and Adaptive Platform	1	Service Interface Designer: This activity will probably be performed by a Service Interface Designer of an OEM	
Performs	Design signal ori- ented communica- tion between Clas- sic and Adaptive Platform	1	Service Interface Designer: This activity will probably be performed by a Service Interface Designer of an OEM	
Performs	Develop a Service Interface Description	1	Service Interface Designer: This activity will probably be performed by a Service Interface Designer	
Performs	Develop the com- munication struc- ture by means of MachineDesign	1	Machine Designer: This activity will probably be performed by a dedicated designer of an OEM.	
Performs	Provide and manage Software Packages	1	ECU Software Manager: This activity will be probably performed by an ECU Software Manager of an OEM	

Table 3.1: OEM



3.1.2 Tier 1

Role	Tier 1		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Common Elements::Roles		
Brief Description	Direct (major) suppli	ers of pa	arts to OEMs
Description	Tier 1 companies are	e direct	(major) suppliers of parts to OEMs.
Relation Type	Related Element	Mul.	Note
Performs	Create Execution Manifest	1	Software Integrator: This activity will probably be performed by a Software Integrator of a Tier 1 company
Performs	Create Software Package	1	Software Deployment Integrator: This activity will probably be performed by a Software Deployment Integrator of a Tier 1 company
Performs	Integrate Software	1	Software Integrator: This activity will probably be performed by a Software Integrator of a Tier 1 company
Performs	Map Service Instance to Port Prototype	1	Software Integrator: This activity will probably be performed by a Software Integrator of a Tier 1 company
Performs	Define machine	01	Machine Integrator: This activity will probably be performed by a Machine Integrator of a Tier 1 company
Performs	Finalize machine configuration	01	Machine Integrator: This activity will probably be performed by a Machine Integrator of a Tier 1 company
Performs	Set Up Initial Ma- chine	01	Machine Integrator: This activity will probably be performed by a Machine Integrator of a Tier 1 company

Table 3.2: Tier 1

3.1.3 Tier 2

Role	Tier 2			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Common Elements::Roles		
Brief Description	Key suppliers to tier	1 suppli	ers,	
Description		Tier 2 companies are key suppliers to tier 1 suppliers, without supplying a product directly to OEM companies.		
Relation Type	Related Element Mul. Note			
Performs	Design Software Component for Adaptive Platform	1	Application Software Designer: The design of software components will probably be performed by an Application Software Designer of a Tier 2 company	



Relation Type	Related Element	Mul.	Note
Performs	Develop Adaptive Platform-level Soft- ware	1	Platform Software Designer: The design tasks within the development of Platform-level Software will probably be performed by a Platform Software Designer of a Tier 2 company
Performs	Develop Adaptive Platform-level Soft- ware	1	Platform Software Developer: The real development tasks (i.e., to write source code and the like) within the development of Platform-level Software will probably be performed by a Platform Software Developer of a Tier 2 company
Performs	Develop Software Components	1	Application Software Developer: This activity will probably be performed by an Application Software Developer of a Tier 2 company
Performs	Define machine	01	Machine Integrator: Alternatively, this activity could also be performed by a Machine Integrator of a Tier 2 company
Performs	Finalize machine configuration	01	Machine Integrator: Alternatively, this activity could also be performed by a Machine Integrator of a Tier 2 company
Performs	Set Up Initial Ma- chine	01	Machine Integrator: Alternatively, this activity could also be performed by a Machine Integrator of a Tier 2 company

Table 3.3: Tier 2

3.2 High Level Architecture

3.2.1 Tasks

3.2.1.1 Develop Adaptive Software

Activity	Develop Adaptive Software		
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Develop Adaptive Application		
Brief Description	Develop Adaptive So	oftware	
Description			loses the development of Adaptive pplication-level as well as platform-level.
Relation Type	Related Element	Mul.	Note
Produces	Adaptive Software	1	
Aggregates	Develop Adaptive Application Software	01	
Aggregates	Develop Adaptive Platform-level Soft- ware	01	

Table 3.4: Develop Adaptive Software



3.2.1.2 Develop a Common Software Architecture

Activity	Develop a Common Software Architecture			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::General::Tasks			
Brief Description	Develop a Common	Softwar	e Architecture	
Description	A software architect analyzes vehicle functions, features and requirements necessary for a specific E/E vehicle project or project family and derives a corresponding Common Software Architecture. See [TR_AMETH_00202]			
Relation Type	Related Element Mul. Note			
Produces	Common Software Architecture	1		

Table 3.5: Develop a Common Software Architecture

3.2.1.3 Develop a Function Architecture

Activity	Develop a Function Architecture		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::General::Tasks		
Brief Description	Develop a Function	Architec	ture
Description	An E/E system architect evaluates and specifies vehicle functions, features and requirements necessary for a specific E/E vehicle project or project family. See [TR AMETH 00201]		
Relation Type	Related Element Mul. Note		
Produces	Function Architecture	1	

Table 3.6: Develop a Function Architecture

3.2.2 Work Products

3.2.2.1 Abstract System Description



Deliverable	Abstract System D	escripti	on	
Package	I	2::Metho	dology::Methodology Library::System::	
	Work products			
Brief Description	Provides an abstract	or func	tional view on the system	
Description	Description and provoto be developed. This deliverable corr category "ABSTRAC	The Abstract System Description extends the general System Description and provides an abstract or functional view on the system to be developed. This deliverable corresponds to the system description with the system category "ABSTRACT_SYSTEM_DESCRIPTION" (see		
	[TPS_SYST_01003]).		
Kind	Delivered			
Extends	System Description			
Relation Type	Related Element	Mul.	Note	
Aggregates	Overall VFB System	1		
Produced by	Develop an Ab- stract System Description	1*		
Consumed by	Develop System	0*	The abstract System Description is an optional input for the activity "Develop System". Please note, that in this step the Abstract System Description is refined to a System Description.	
Consumed by	Develop a VFB System Descrip- tion	0*	The abstract System Description is an optional input for the activity "Develop a VFB System Description". The VFB-related part of the Abstract System Description can be than refined to the concrete "Overall VFB System". Additionally, a mapping between those two views can be established.	

Table 3.7: Abstract System Description

3.2.2.2 Adaptive Software

Deliverable	Adaptive Software			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::General::Work Products			
Brief Description	Adaptive Software			
Description	Adaptive Software may be of category platform-level or application-level. An Adaptive Software may consist of one or more binaries/executables having a specific scope and purpose. Elements are \ARMethDeliverable{Software Component Description for Adaptive Platform}, \ARMethDeliverable{Software Component Source Code}, \ARMethDeliverable{Software Component Object Code}, \ARMethDeliverable{Main Function}.			
Kind				
Relation Type	Related Element Mul. Note			



Relation Type	Related Element	Mul.	Note
Produced by	Develop Adaptive Software	1	

Table 3.8: Adaptive Software

3.2.2.3 Common Software Architecture

Artifact	Common Software Architecture			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::General::Work Products			
Brief Description	Common Software Architecture			
Description	The Common Software Architecture provides a dedicated view of all software entities and their communication relation within the E/E vehicle system. "All" software entities allows any combination of Adaptive and Classic software components with the possibility of communication across Adaptive and Classic Platform. See [TR AMETH 00202]			
Kind				
Relation Type	Related Element Mul. Note			
Produced by	Develop a Com- mon Software Ar- chitecture	1		

Table 3.9: Common Software Architecture

3.2.2.4 Function Architecture

Artifact	Function Architectu	Function Architecture		
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::General::Work Products		
Brief Description	Function Architecture	е		
Description	networks representir	The Function Architecture is composed of a number of function networks representing functionalities that are needed to execute particular vehicle functions. See ITB AMETH 002011		
Kind				
Relation Type	Related Element	Related Element Mul. Note		
Produced by	Develop a Function Architecture	1		

Table 3.10: Function Architecture

3.2.2.5 System Description



Deliverable	System Description	1	
Package		2::Metho	dology::Methodology Library::System::
	Work products		
Brief Description	Partial Extract of a S	•	
Description	Generic deliverable for defining a System. It is used in different roles within the methodology.		
	In each role, this deliverable may contain variation points in its ARXML artifacts which need to be bound in later steps, e.g. when defining a subsystem from a complete system or later for the single ECUs. If such variation points are present, the System Description may optionally include PredefinedVariants in order to predefine variants for later selection and an Evaluated Variant Set.		
	Please note that this generic deliverable does not correspond to the system description with the system category "SYSTEM_DESCRIPTION" (see [TPS_SYST_01003]). The system description with the category "SYSTEM_DESCRIPTION" is represented by the deliverable "System Configuration Description".		
	category. In the Syst	em Tem	t to a description of a system with any aplate Specification "system description" is m for this kind of artifact.
Kind	Delivered		
Extended by	Abstract System Des System Constraint D		, System Configuration Description, on, System Extract
Relation Type	Related Element	Mul.	Note
Aggregates	System Description Root Element	1	
Aggregates	Communication Layers	01	
Aggregates	Mapping of Soft- ware Components to ECUs	01	
Aggregates	Mapping of Software Components to Implementations	01	
Aggregates	Rapid Prototyping Scenario	01	
Aggregates	Topology	01	
Aggregates	Alias Name Set	0*	
Aggregates	Communication Matrix	0*	
Aggregates	Data Mapping	0*	
Aggregates	Evaluated Variant Set	0*	
Aggregates	Postbuild Variant Set	0*	
Aggregates	Predefined Variant	0*	
Aggregates	System Constant Value Set	0*	



Relation Type	Related Element	Mul.	Note
Aggregates	System Signal	0*	
Aggregates	System Signal Group	0*	
Aggregates	System Timing	0*	
In/out	Select Design Time Variant	1	
Consumed by	Define System View Mapping	2	
Consumed by	Define System Safety Information	1	
Consumed by	Define a signal- based Service Interface (Signal BasedService InterfaceDeploy- ment)	1	The System Description based on the System Template on the AUTOSAR classic platform
Consumed by	Design signal ori- ented communica- tion between Clas- sic and Adaptive Platform	1	The System Description based on the System Template on the AUTOSAR classic platform is used; it contains a communication matrix description with Pdus and ISignals
Consumed by	Map ServiceInstance to Port Prototype	1	The System Description based on the System Template on the AUTOSAR classic platform
Consumed by	Map SignalBased EventDeploy- ment to ISignal Triggerings	1	The System Description based on the System Template on the AUTOSAR classic platform
Consumed by	Map SignalBased FieldDeployment to ISignalTrigger- ings	1	The System Description based on the System Template on the AUTOSAR classic platform
Consumed by	Map SignalBased MethodDeploy- ment to ISignal Triggerings	1	The System Description based on the System Template on the AUTOSAR classic platform
Consumed by	Define Alias Names	01	Needed for definition of alias names with system, system extract or ECU scope, depending of the role of the System Description.
Consumed by	Define System Variants	0*	

Table 3.11: System Description

3.3 Service Interface

This chapter contains the definition of work products and tasks used for the definition of service interfaces for the Adaptive Platform.



3.3.1 Tasks

3.3.1.1 Provide Data Types for Adaptive Platform

Task Definition	Select or define Data Types for Adaptive Platform			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Interface Definition::Tasks			
Brief Description	Define a set of AP data types for a specific project, which are not already defined by Autosar.			
Description	Select or define a set of data types, which are required for the Adaptive Platform Instance, but which are not already defined by AUTOSAR. Standardized data types can be used as input in order to copy and refine them. Already existing data types can be reused. The AP Data Types are used for specifying DataElements in service interfaces. The focus is on the definition application data types and implementation data types and the necessary data type mapping sets.			
Relation Type	Related Element	Mul.	Note	
Consumes	Autosar AP Standard Package	01	Use standardized elements (e.g. data types, compu methods) to create the corresponding elements of the specific project.	
Produces	AP Data Types	1*	Defined AP Data Types for a specific project	

Table 3.12: Select or define Data Types for Adaptive Platform

3.3.1.2 Define Service Interfaces

Task Definition	Define Service Interfaces			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Interface Definition::Tasks			
Brief Description	Define the service in generation.	Define the service interfaces that are used for the header file generation.		
Description	1	Define service interfaces by defining events, methods and fields. Additionally, a namespace for the header file generation can be defined.		
Relation Type	Related Element	Mul.	Note	
Consumes	AP Data Types	1*	Used for specifying DataElements in service interfaces	
Produces	Service Interface Description	1*	Collection of all service interfaces	

Table 3.13: Define Service Interfaces

3.3.1.3 Aggregate Service Interfaces



Task Definition	Aggregate Service	Aggregate Service Interfaces			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Interface Definition::Tasks			
Brief Description	Aggregate service in	terfaces	s to a coarse-grained service interface.		
Description	interfaces, which are a service interface n fine-grained service interfaces. Alternatively, if the solution clash due to equal n	Alternatively, if the service interface mapping would result in a name clash due to equal names of some elements of the service interfaces, then the elements can be mapped by using the service interface			
Relation Type	Related Element	Mul.	Note		
Consumes	Service Interface Description	0*	Fine-grained service interfaces		
Produces	Service Interface Description	0*	Coarse-grained service interfaces		
Produces	Service Interface Mapping	0*	Mapping between fine-grained service and coarse-grained service interfaces		

Table 3.14: Aggregate Service Interfaces

3.3.2 Work Products

3.3.2.1 AUTOSAR AP Standard Package

Deliverable	Autosar AP Standa	Autosar AP Standard Package			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Interface Definition::Work Products			
Brief Description	Package with standa Platform.	rdized <i>F</i>	AUTOSAR elements for the Adaptive		
Description	service interfaces) for	Package with standardized AUTOSAR elements (e.g. data types, service interfaces) for the Adaptive Platform. This deliverable is released by AUTOSAR and is read only within the methodology.			
Kind	AUTOSAR XML	AUTOSAR XML			
Relation Type	Related Element	Mul.	Note		
Consumed by	Develop Adaptive Platform-level Soft- ware	01	In case standardized service interfaces are used for adaptive platform-level software		
Consumed by	Develop a Service Interface Descrip- tion	01	Optional input for defining data types and service interfaces for the adaptive platform		
Consumed by	Select or define Data Types for Adaptive Platform	01	Use standardized elements (e.g. data types, compu methods) to create the corresponding elements of the specific project.		

Table 3.15: Autosar AP Standard Package



3.3.2.2 AP Data Types

Artifact	AP Data Types	AP Data Types		
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Interface Definition::Work Products		
Brief Description	Definition of data typ	es for th	ne Adaptive Platform	
Description	not already defined b	Data types, which are required for the Adaptive Platform Instance and not already defined by AUTOSAR. The AP Data Types are used for specifying DataElements in service interfaces.		
Kind	AUTOSAR XML			
Relation Type	Related Element	Mul.	Note	
Produced by	Select or define Data Types for Adaptive Platform	1*	Defined AP Data Types for a specific project	
Consumed by	Define Service Interfaces	1*	Used for specifying DataElements in service interfaces	

Table 3.16: AP Data Types

3.3.2.3 Service Interface Description

Deliverable	Service Interface Description			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Interface Definition::Work Products			
Brief Description	Collection of service	interfac	es with events, methods and fields.	
Description	Collection of service interfaces. Service interfaces can consist of events, methods and fields and are the basis for the generation of header files for a software component. In addition, the namespace used for the header file generation can be defined.			
Kind	AUTOSAR XML			
Relation Type	Related Element	Mul.	Note	
Produced by	Define Service Interfaces	1*	Collection of all service interfaces	
Produced by	Develop a Service Interface Descrip- tion	1*	All service interfaces, which are used for communication	
Produced by	Aggregate Service Interfaces	0*	Coarse-grained service interfaces	
Consumed by	Configure Service Interface Deployment	1	Deployment is configured for each service interface	
Consumed by	Define and Configure Service Instances	1	Deployment of service interfaces needs to be configured	
Consumed by	Define a signal- based Service Interface (Signal BasedService InterfaceDeploy- ment)	1*	Description of the Service Interfaces	



Relation Type	Related Element	Mul.	Note
Consumed by	Design Diagnostic Mapping	1*	Collection of service interfaces. Service interfaces can consist of events, methods and fields.
Consumed by	Design Software Component for Adaptive Platform	1*	All service interfaces that shall be implemented by the software component
Consumed by	Design service oriented communication between Classic and Adaptive Platform	1*	Description of the Service Interfaces which communicate to CP in a service-oriented manner
Consumed by	Design signal oriented communication between Classic and Adaptive Platform	1*	Description of the Service Interfaces which communicate to CP in a signal-oriented manner
Consumed by	Develop Adaptive Application Software	1*	Service Interfaces are the basis for the development of adaptive application software
Consumed by	Generate Header Files for Service Interfaces	1*	For all service interfaces header files are generated.
Consumed by	Generate Serial- ization Code for Adaptive Platform	1*	Service interfaces that are implemented by the software components are needed for generating the serialization code
Consumed by	Map Diagnostic Data	1*	Collection of service interfaces. Service interfaces can consist of events, methods and fields.
Consumed by	Map Event	1*	Description of the Service Interfaces which communicate to CP in a service-oriented manner
Consumed by	Map Field	1*	Description of the Service Interfaces which communicate to CP in a service-oriented manner
Consumed by	Map Fire and Forget	1*	Description of the Service Interface which communicates to CP in a service-oriented manner
Consumed by	Map Method	1*	Description of the Service Interfaces which communicate to CP in a service-oriented manner
Consumed by	Map ServiceInstance to Port Prototype	1*	Description of the Service Interfaces
Consumed by	Map SignalBased EventDeploy- ment to ISignal Triggerings	1*	Description of the Service Interfaces
Consumed by	Map SignalBased FieldDeployment to ISignalTrigger- ings	1*	Description of the Service Interfaces



Relation Type	Related Element	Mul.	Note
Consumed by	Map SignalBased MethodDeploy- ment to ISignal Triggerings	1*	Description of the Service Interfaces
Consumed by	Configure Serial- ization for Adaptive Platform	01	Optional if you only configure default values for the serialization
Consumed by	Aggregate Service Interfaces	0*	Fine-grained service interfaces
Consumed by	Integrate Software	0*	Needed for defining the serialization

Table 3.17: Service Interface Description

3.3.2.4 Service Interface Mapping

Deliverable	Service Interface M	Service Interface Mapping			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Interface Definition::Work Products			
Brief Description	Mapping from fine-grinterface.	Mapping from fine-grained service interfaces to coarse-grained service interface.			
Description	to the coarse-grained	The service interface mapping maps the fine-grained service interfaces to the coarse-grained service interfaces. In case of an element mapping, this work product contains the mapping of the elements of interfaces.			
Kind	AUTOSAR XML	AUTOSAR XML			
Relation Type	Related Element	Mul.	Note		
Produced by	Aggregate Service Interfaces	0*	Mapping between fine-grained service and coarse-grained service interfaces		
Produced by	Develop a Service Interface Descrip- tion	0*	Optionally, coarse-grained service interfaces are defined by a service interface mapping		

Table 3.18: Service Interface Mapping

3.4 Communication Mapping

3.4.1 Tasks

3.4.1.1 Map Method



Task Definition	Map Method	Map Method		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Communication Mapping::Tasks			
Brief Description	Map Method			
Description	method located in a	Map a ClientServerOperation located in a ClientServerInterface to a method located in a ServiceInterface. see TPS_MANI_03111 of AUTOSAR_TPS_ManifestSpecification		
Relation Type	Related Element	Mul.	Note	
Consumes	Client Server Inter- face Description	1*	The descriptions of Client Server Interfaces of CP	
Consumes	Service Interface Description	1*	Description of the Service Interfaces which communicate to CP in a service-oriented manner	
Produces	Service Inter- face Mapping for Service Oriented Communication	1*	Service Interface Mappings	

Table 3.19: Map Method

3.4.1.2 Map Event

Task Definition	Map Event			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Communication Mapping::Tasks			
Brief Description	Map Event			
Description	Map a VariableDataPrototype located in a SenderReceiverInterface to an event located in a ServiceInterface. see TPS MANI 03112 of of AUTOSAR TPS ManifestSpecification			
Relation Type	Related Element	Mul.	Note	
Consumes	Sender Receiver Interface Descrip- tion	1*	The descriptions of Sender Receiver Interfaces of CP	
Consumes	Service Interface Description	1*	Description of the Service Interfaces which communicate to CP in a service-oriented manner	
Produces	Service Inter- face Mapping for Service Oriented Communication	1*	Service Interface Mappings	

Table 3.20: Map Event

3.4.1.3 Map Field



Task Definition	Map Field		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Communication Mapping::Tasks		
Brief Description	Map Field		
Description	Map operations located in ClientServerOperations to getter and setter methods of a ServiceInterface. Map a VariableDataPrototype of a SenderReceiverInterface to the field notifier of the ServiceInterface. see TPS_MANI_03113 of AUTOSAR_TPS_ManifestSpecification		
Relation Type	Related Element Mul. Note		
Consumes	Client Server Inter- face Description	1*	The descriptions of Client Server Interfaces of CP
Consumes	Sender Receiver Interface Descrip- tion	1*	The descriptions of Sender Receiver Interfaces of CP
Consumes	Service Interface Description	1*	Description of the Service Interfaces which communicate to CP in a service-oriented manner
Produces	Service Interface Mapping for Service Oriented Communication	1*	Service Interface Mappings

Table 3.21: Map Field

3.4.1.4 Map Fire and Forget

Task Definition	Map Fire and Forge	et	
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Communication Mapping::Tasks		
Brief Description	Map Fire and Forget		
Description	Map a Fire&Forget method located in a ServiceInterface to a VariableDataPrototype in a SenderReceiverInterface or to a trigger of a TrigerInterface. see TPS MANI 03115 of AUTOSAR TPS ManifestSpecification		
Relation Type	Related Element	Mul.	Note
Consumes	Service Interface Description	1*	Description of the Service Interface which communicates to CP in a service-oriented manner
Consumes	Sender Receiver Interface Descrip- tion	0*	The descriptions of Sender Receiver Interfaces of CP
Consumes	Trigger Interface Description	0*	The descriptions of Trigger Interfaces
Produces	Service Inter- face Mapping for Service Oriented Communication	1*	Service Interface Mappings

Table 3.22: Map Fire and Forget



3.4.1.5 Map SignalBasedMethod to ISignalTriggerings

Task Definition	Map SignalBasedMethodDeployment to ISignalTriggerings		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Communication Mapping::Tasks		
Brief Description	Map SignalBasedMe	ethod to	ISignalTriggerings
Description	see TPS_MANI_03125 of of AUTOSAR_TPS_ManifestSpecification		
Relation Type	Related Element Mul. Note		
Consumes	System Description	1	The System Description based on the System Template on the AUTOSAR classic platform
Consumes	Service Interface Description	1*	Description of the Service Interfaces
Produces	Service Instance To Signal Mapping	1*	Mapping of SignalBasedMethodDeployment to ISignalTriggerings

Table 3.23: Map SignalBasedMethodDeployment to ISignalTriggerings

3.4.1.6 Map SignalBasedEvent to ISignalTriggerings

Task Definition	Map SignalBasedE	Map SignalBasedEventDeployment to ISignalTriggerings		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Communication Mapping::Tasks			
Brief Description	Map SignalBasedEv	ent to IS	SignalTriggerings	
Description	see TPS_MANI_031	see TPS_MANI_03124 of AUTOSAR_TPS_ManifestSpecification		
Relation Type	Related Element	Related Element Mul. Note		
Consumes	System Description	1	The System Description based on the System Template on the AUTOSAR classic platform	
Consumes	Service Interface Description	1*	Description of the Service Interfaces	
Produces	Service Instance To Signal Mapping	1*	Mapping of SignalBasedEventDeployment to ISignalTriggerings	

Table 3.24: Map SignalBasedEventDeployment to ISignalTriggerings

3.4.1.7 Map SignalBasedField to ISignalTriggerings

Task Definition	Map SignalBasedFieldDeployment to ISignalTriggerings		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Communication Mapping::Tasks		
Brief Description	Map SignalBasedField to ISignalTriggerings		
Description	see TPS_MANI_03126 of AUTOSAR_TPS_ManifestSpecification		
Relation Type	Related Element Mul. Note		



Relation Type	Related Element	Mul.	Note
Consumes	System Description	1	The System Description based on the System Template on the AUTOSAR classic platform
Consumes	Service Interface Description	1*	Description of the Service Interfaces
Produces	Service Instance To Signal Mapping	1*	Mapping of SignalBasedFieldDeployment to ISignalTriggerings

Table 3.25: Map SignalBasedFieldDeployment to ISignalTriggerings

3.4.1.8 Map ServiceInstance to PortPrototype

Task Definition	Map ServiceInstance to PortPrototype		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Communication Mapping::Tasks		
Brief Description	Map ServiceInstance	e to Port	Prototype
Description	see TPS_MANI_030	00 of Al	JTOSAR_TPS_ManifestSpecification
Relation Type	Related Element	Mul.	Note
Consumes	System Description	1	The System Description based on the System Template on the AUTOSAR classic platform
Consumes	Service Interface Description	1*	Description of the Service Interfaces
Produces	Service Instance To Signal Mapping	1*	Mapping of ServiceInstance to PortPrototype

Table 3.26: Map ServiceInstance to PortPrototype

3.4.2 Work Products

3.4.2.1 Client Server Interface Description

Deliverable	Client Server Interface Description			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Communication Mapping::Work Products			
Brief Description	Client Server Interfa	Client Server Interface Description		
Description	This represents the particular description of a ClientServerInterface of the Classic Platform.			
Kind	AUTOSAR XML	AUTOSAR XML		
Relation Type	Related Element	Mul.	Note	
Consumed by	Map Field	1*	The descriptions of Client Server Interfaces of CP	
Consumed by	Map Method	1*	The descriptions of Client Server Interfaces of CP	



Relation Type	Related Element	Mul.	Note
Consumed by	Design service oriented communication between Classic and Adaptive Platform	0*	The descriptions of Client Server Interfaces of CP are used to map a ClientServerOperation to a method in a ServiceInterface or to map a ClientServerOperation (representing getter or setter methods) to a field in a ServiceInterface

Table 3.27: Client Server Interface Description

3.4.2.2 Sender Receiver Interface Description

Deliverable	Sender Receiver Interface Description		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Communication Mapping::Work Products		
Brief Description	Sender Receiver Into	erface D	Pescription
Description	This represents a pa		description of a SenderReceiverInterface
Kind	AUTOSAR XML		
Relation Type	Related Element	Mul.	Note
Consumed by	Map Event	1*	The descriptions of Sender Receiver Interfaces of CP
Consumed by	Map Field	1*	The descriptions of Sender Receiver Interfaces of CP
Consumed by	Design service oriented communication between Classic and Adaptive Platform	0*	The descriptions of Sender Receiver Interfaces of CP are used to map a VariableDataPrototype to an Event in a ServiceInterface or to map a VariableDataPrototype to the notifier of a Field of a ServiceInterface or to map a Fire&Forget Method that is located in a ServiceInterface to a VariableDataPrototype in a SenderReceiverInterface
Consumed by	Map Fire and Forget	0*	The descriptions of Sender Receiver Interfaces of CP

Table 3.28: Sender Receiver Interface Description

3.4.2.3 Trigger Interface Description



Deliverable	Trigger Interface Description		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Communication Mapping::Work Products		
Brief Description	Trigger Interface Des	scription	
Description	This represents the particular description of the Trigger Interface of the Classic Platform.		
Kind	AUTOSAR XML		
Relation Type	Related Element	Mul.	Note
Consumed by	Design service oriented communication between Classic and Adaptive Platform	0*	The descriptions of Trigger Interfaces are used to map a Fire&Forget Method that is located in ServiceInterface to a Trigger in a TriggerInterface
Consumed by	Map Fire and Forget	0*	The descriptions of Trigger Interfaces

Table 3.29: Trigger Interface Description

3.4.2.4 Service Interface Mapping Set

Deliverable	Service Interface M	apping	Set
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Communication Mapping::Work Products		
Brief Description	Service Interface Mapping Set		
Description	Collection of Service Interface mappings		
Kind	AUTOSAR XML		
Relation Type	Related Element	Mul.	Note
Aggregates	Service Inter- face Mapping for Service Oriented Communication	1*	

Table 3.30: Service Interface Mapping Set

3.4.2.5 Service Interface Mapping for Service Oriented Communication

Artifact	Service Interface Mapping for Service Oriented Communication		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Communication Mapping::Work Products		
Brief Description	Mappings for service oriented communication		
Description	Mappings of elements of AP-based ServiceInterfaces to elements of corresponding elements of CP-based SenderReceiverInterfaces, ClientServerInterfaces and TriggerInterfaces.		
Kind	AUTOSAR XML		
Relation Type	Related Element Mul. Note		



Relation Type	Related Element	Mul.	Note
Produced by	Design service ori- ented communica- tion between Clas- sic and Adaptive Platform	1*	An InterfaceMapping results from the design of service-oriented communication between CP and AP
Produced by	Map Event	1*	Service Interface Mappings
Produced by	Map Field	1*	Service Interface Mappings
Produced by	Map Fire and Forget	1*	Service Interface Mappings
Produced by	Map Method	1*	Service Interface Mappings

Table 3.31: Service Interface Mapping for Service Oriented Communication

3.4.2.6 Service Instance To Signal Mapping Set

Deliverable	Service Instance To	Service Instance To Signal Mapping Set			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Communication Mapping::Work Products			
Brief Description	Service Instance To	Service Instance To Signal Mapping Set			
Description	Collection of Service	Collection of Service Instance to Signal mappings			
Kind	AUTOSAR XML	AUTOSAR XML			
Relation Type	Related Element	Related Element Mul. Note			
Aggregates	Service Instance To Signal Mapping	1*			

Table 3.32: Service Instance To Signal Mapping Set

3.4.2.7 Service Instance To Signal Mapping

Artifact	Service Instance To Signal Mapping			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Communication Mapping::Work Products			
Brief Description	Mappings for signal	oriented	communication	
Description	Mappings of Service	Instance	es to ISignalTriggerings.	
Kind	AUTOSAR XML			
Relation Type	Related Element	Mul.	Note	
Produced by	Design signal ori- ented communica- tion between Clas- sic and Adaptive Platform	1*	A signal-to-service mapping results from the design of signal-oriented communication between CP and AP	
Produced by	Map ServiceInstance to Port Prototype	1*	Mapping of ServiceInstance to PortPrototype	



Relation Type	Related Element	Mul.	Note
Produced by	Map SignalBased EventDeploy- ment to ISignal Triggerings	1*	Mapping of SignalBasedEventDeployment to ISignalTriggerings
Produced by	Map SignalBased FieldDeployment to ISignalTrigger- ings	1*	Mapping of SignalBasedFieldDeployment to ISignalTriggerings
Produced by	Map SignalBased MethodDeploy- ment to ISignal Triggerings	1*	Mapping of SignalBasedMethodDeployment to ISignalTriggerings

Table 3.33: Service Instance To Signal Mapping

3.5 Machine Design

3.5.1 Tasks

3.5.1.1 Define and configure the network connections of a Machine

Task Definition	Define and configu	Define and configure the network connections of a Machine			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Machine Design::Tasks			
Brief Description	Definition of all netw	ork end	points with corresponding IP address.		
Description		Define all network connections of a Machine and their configuration out of contracting. All network endpoints with corresponding IP address are specified.			
Relation Type	Related Element	Related Element Mul. Note			
Consumes	Topology	1	Description of (inter)connections between machines.		
Produces	Machine Design	01	Definition of all network connections of a Machine and their configuration		

Table 3.34: Define and configure the network connections of a Machine

3.5.1.2 Configure the Service Discovery Message Exchange

Task Definition	Configure the Serv	Configure the Service Discovery Message Exchange			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Machine Design::Tasks			
Brief Description	Definition of ports ar message exchange	Definition of ports and multicast IP addresses for service discovery message exchange			
Description		Define ports and multicast IP address over which the service discovery messages are exchanged.			
Relation Type	Related Element	Mul.	Note		
Consumes	Topology	1	Description of (inter)connections between machines.		



Relation Type	Related Element	Mul.	Note
Produces	Machine Design	01	Definition of ports and multicast IP address over which the service discovery messages are exchanged.

Table 3.35: Configure the Service Discovery Message Exchange

3.5.2 Work Products

3.5.2.1 Machine Design

Artifact	Machine Design			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive			
	Platform::Architecture and Design::Machine Design::Work Products			
Brief Description	Proxy for a Machine at design time			
Description	I		proxy for a Machine at the time when it	
	does not exist, yet, i.	e., at de	esign time.	
Kind	AUTOSAR XML		T	
Relation Type	Related Element	Mul.	Note	
Produced by	Develop the com- munication struc- ture by means of MachineDesign	1	Configuration settings of the network connections and service discovery network exchange of a Machine	
Produced by	Configure the Service Discov- ery Message Exchange	01	Definition of ports and multicast IP address over which the service discovery messages are exchanged.	
Produced by	Define and configure the network connections of a Machine	01	Definition of all network connections of a Machine and their configuration	
Consumed by	Define and Configure Service Instances	1	Service instances will be mapped to machine	
Consumed by	Define machine	1	Configuration settings of the network connections and service discovery network exchange of a Machine	
Consumed by	Map Service Instance to Machine	1	Description of machine that the service instances shall be mapped to	
Consumed by	Configure DoIP	01	Configuration settings of the network connections and service discovery network exchange of a Machine	
Consumed by	Configure Log and Trace module	01	Configuration settings of the network connections and service discovery network exchange of a Machine	
Consumed by	Configure NM module	01	Configuration settings of the network connections and service discovery network exchange of a Machine	

Table 3.36: Machine Design



3.6 Diagnostic Mapping

3.6.1 Tasks

3.6.1.1 Associate Diagnostic Mapping with Process Design

Task Definition	Associate Diagnos	Associate Diagnostic Mapping with Process Design			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Tasks				
Brief Description	Associate one Diagr	osticMa	pping with one ProcessDesign		
Description	It may be necessary that different instances of a particular application software require different diagnostic mappings. Therefore, a relation between a particular diagnostic mapping and a particular Process needs to be established. This assignment may be done in a final extra step, represented by this task. To accommodate for this potential modeling, the reference from a diagnostic mapping to Process Design has been decorated by stereotype "atpSplitable".				
Relation Type	Related Element	Mul.	Note		
Consumes	Diagnostic Map- ping	1*	The diagnostic mapping for a Machine, except the linkage between the mappings and the corresponding ProcessDesigns		
Consumes	Process Design	1*	All dedicated ProssesDesigns for a Machine		
Produces	Diagnostic Map- ping	1*	fully: The linkage between the diagnostic mappings and the corresponding ProcessDesigns		

Table 3.37: Associate Diagnostic Mapping with Process Design

3.6.1.2 Map Diagnostic Clear Condition to Port(s)

Task Definition	Map Diagnostic Clear Condition to Port(s)			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Tasks			
Brief Description	Mapping between a DiagnosticServiceInstance and a SwcServiceDependency			
Description	This task covers the mapping of a diagnostic clear condition (defined as part of the diagnostic protocol) to one or many service port instances of a particular application (instance) by means of SWC service dependencies. See [TPS MANI 01259] and [constr 1698].			
Relation Type	Related Element Mul. Note			
Consumes	Diagnostic Ma- chine Extract	1	All diagnostic information available at design time	



Relation Type	Related Element	Mul.	Note
Consumes	Software Component Description for Adaptive Platform	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Produces	Diagnostic Map- ping	1	One diagnostic clear condition to port mapping

Table 3.38: Map Diagnostic Clear Condition to Port(s)

3.6.1.3 Map Diagnostic Data

Task Definition	Map Diagnostic Data			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Tasks			
Brief Description	Mapping between a	diagnos	tic data element and an event or field	
Description	This task covers the mapping between a diagnostic data element (as part of the diagnostic protocol) and an event or field or even an element of an event or field of a DataPrototype aggregated by a ServiceInterface in the context of a PortPrototype. See [TPS_MANI_1037], [TPS_MANI_01060] and [constr_MANI_1496].			
Relation Type	Related Element	Mul.	Note	
Consumes	Diagnostic Ma- chine Extract	1	All available diagnostic information at the design time	
Consumes	Service Interface Description	1*	Collection of service interfaces. Service interfaces can consist of events, methods and fields.	
Consumes	Software Component Description for Adaptive Platform	1*	Description of a software component for the Adaptive Platform with all its ports, available at design time.	
Produces	Diagnostic Map- ping	1	One diagnostic data mapping	

Table 3.39: Map Diagnostic Data

3.6.1.4 Map Diagnostic Enable Condition to Ports

Task Definition	Map Diagnostic En	Map Diagnostic Enable Condition to Port(s)		
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Tasks		
Brief Description	Mapping of a diagno	Mapping of a diagnostic enable condition to one or many service ports		
Description	of the diagnostic pro application (instance	This task covers the mapping of a diagnostic enable condition (as part of the diagnostic protocol) to one or many service ports of a particular application (instance) by means of SwcServiceDependency. See [TPS_MANI_01050] and [constr_1502]		
Relation Type	Related Element	Mul.	Note	
Consumes	Diagnostic Ma- chine Extract	1	All available diagnostic information at the design time	



Relation Type	Related Element	Mul.	Note
Consumes	Software Component Description for Adaptive Platform	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Produces	Diagnostic Map- ping	1	One diagnostic EnableConditionToPorts mapping

Table 3.40: Map Diagnostic Enable Condition to Port(s)

3.6.1.5 Map Diagnostic Event to Port(s)

Task Definition	Map Diagnostic Event to Port(s)		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Tasks		
Brief Description	Mapping of a diagno	stic eve	nt to one or many service ports
Description	This task covers the mapping of a diagnostic event (as part of the diagnostic protocol) to one or many service ports of a particular application (instance) by means of SwcServiceDependency. See [TPS MANI 01048] and [constr 1500].		
Relation Type	Related Element	Mul.	Note
Consumes	Diagnostic Ma- chine Extract	1	All available diagnostic information at the design time
Consumes	Software Component Description for Adaptive Platform	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Produces	Diagnostic Map- ping	1	One diagnostic EventToPort mapping

Table 3.41: Map Diagnostic Event to Port(s)

3.6.1.6 Map Diagnostic Indicator to Port(s)

Task Definition	Map Diagnostic Indicator to Port(s)				
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Tasks			
Brief Description	1	Mapping between a DiagnosticServiceInstance and a SwcServiceDependency			
Description	of the diagnostic pro particular application dependencies.	This task covers the mapping of a diagnostic indicator (defined as part of the diagnostic protocol) to one or many service port instances of a particular application (instance) by means of SWC service			
Relation Type	Related Element	Related Element Mul. Note			
Consumes	Diagnostic Ma- chine Extract	1	All diagnostic information available at design time		



Relation Type	Related Element	Mul.	Note
Consumes	Software Component Description for Adaptive Platform	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Produces	Diagnostic Map- ping	1	

Table 3.42: Map Diagnostic Indicator to Port(s)

3.6.1.7 Map Diagnostic Generic UDS Service Handler to Port(s)

Task Definition	Map Diagnostic Generic UDS Service Handler to Port(s)		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Tasks		
Brief Description	Mapping between a DiagnosticServiceInstance and a SwcServiceDependency		
Description	This task covers the mapping of diagnostic service instances representing a diagnostic generic UDS service handler (defined as part of the diagnostic protocol) to one or many service port instances of a particular application (instance) by means of SWC service dependencies. See [TPS_MANI_01264] and [constr_1703].		
Relation Type	Related Element	Mul.	Note
Consumes	Diagnostic Ma- chine Extract	1	All diagnostic information available at design time
Consumes	Software Component Description for Adaptive Platform	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Produces	Diagnostic Map- ping	1	One diagnostic generic UDS service handler to port mapping

Table 3.43: Map Diagnostic Generic UDS Service Handler to Port(s)

3.6.1.8 Map Diagnostic Memory Destination to Port(s)



Task Definition	Map Diagnostic Memory Destination to Port(s)		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Tasks		
Brief Description	Mapping between a DiagnosticServiceInstance and a SwcServiceDependency		
Description	This task covers the mapping of a diagnostic memory destination (defined as part of the diagnostic protocol) to one or many service port instances of a particular application (instance) by means of SWC service dependencies. See [TPS_MANI_01261] and [constr_1700].		
Relation Type	Related Element	Mul.	Note
Consumes	Diagnostic Ma- chine Extract	1	All diagnostic information available at design time
Consumes	Software Component Description for Adaptive Platform	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Produces	Diagnostic Map- ping	1	One diagnostic memory destination to port mapping

Table 3.44: Map Diagnostic Memory Destination to Port(s)

3.6.1.9 Map Diagnostic Operation Cycle to Port(s)

Task Definition	Map Diagnostic Operation Cycle to Port(s)		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Tasks		
Brief Description	Mapping of a diagno	stic ope	ration cycle to one or many service ports
Description	This task covers the mapping of a diagnostic operation cycle (as part of the diagnostic protocol) to one or many service ports of a particular application (instance) by means of SwcServiceDependency. See [TPS MANI 01049] and [constr 1501].		
Relation Type	Related Element	Mul.	Note
Consumes	Diagnostic Ma- chine Extract	1	All available diagnostic information at the design time
Consumes	Software Component Description for Adaptive Platform	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Produces	Diagnostic Map- ping	1	One diagnostic OperationCycleToPorts mapping

Table 3.45: Map Diagnostic Operation Cycle to Port(s)

3.6.1.10 Map Diagnostic Security Level to Port(s)



Task Definition	Map Diagnostic Sec	Map Diagnostic Security Level to Port(s)			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Tasks				
Brief Description	•	Mapping between a DiagnosticServiceInstance and a SwcServiceDependency			
Description	part of the diagnostic of a particular applic dependencies. See [TPS_MANI_01	This task covers the mapping of a diagnostic security level (defined as part of the diagnostic protocol) to one or many service port instances of a particular application (instance) by means of SWC service dependencies. See [TPS_MANI_01262] and [constr_1701].			
Relation Type	Related Element	Mul.	Note		
Consumes	Diagnostic Ma- chine Extract	1	All diagnostic information available at design time		
Consumes	Software Component Description for Adaptive Platform	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.		
Produces	Diagnostic Map- ping	1	One diagnostic security level to port mapping		

Table 3.46: Map Diagnostic Security Level to Port(s)

3.6.1.11 Map Diagnostic Service Data Identifier to Port(s)

Task Definition	Map Diagnostic Service Data Identifier to Port(s)			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Tasks			
Brief Description	Mapping between a DiagnosticServiceInstance and a SwcServiceDependency			
Description	This task covers the mapping of a diagnostic data identifier (DID, defined as part of the diagnostic protocol) to one or many service port instances of a particular application (instance) by means of SWC service dependencies. See [TPS_MANI_01263] and [constr_1702].			
Relation Type	Related Element	Mul.	Note	
Consumes	Diagnostic Ma- chine Extract	1	All diagnostic information available at design time	
Consumes	Software Component Description for Adaptive Platform	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.	
Produces	Diagnostic Map- ping	1	One diagnostic service data identifier to port mapping	

Table 3.47: Map Diagnostic Service Data Identifier to Port(s)

3.6.1.12 Map Diagnostic Storage Condition to Port(s)



Task Definition	Map Diagnostic Storage Condition to Port(s)			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Tasks			
Brief Description	Mapping of a diagno	stic stor	age condition to one or many service ports	
Description	This task covers the mapping of a diagnostic storage condition (as part of the diagnostic protocol) to one or many service ports of a particular application (instance) by means of SwcServiceDependency. See [TPS MANI 01051] and [constr 1503]			
Relation Type	Related Element	Mul.	Note	
Consumes	Diagnostic Ma- chine Extract	1	All available diagnostic information at the design time	
Consumes	Software Component Description for Adaptive Platform	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.	
Produces	Diagnostic Map- ping	1	One diagnostic storage condition to port mapping	

Table 3.48: Map Diagnostic Storage Condition to Port(s)

3.6.1.13 Map Diagnostic Upload/Download to Port(s)

Task Definition	Map Diagnostic Up	load/Do	ownload to Port(s)		
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Tasks			
Brief Description	''	Mapping between a DiagnosticServiceInstance and a SwcServiceDependency			
Description	upload/download pu to one or many servi (instance) by means	This task covers the mapping of diagnostic service instances for upload/download purposes (defined as part of the diagnostic protocol) to one or many service port instances of a particular application (instance) by means of SWC service dependencies. See [TPS MANI 01266] and [constr 1704].			
Relation Type	Related Element	Mul.	Note		
Consumes	Diagnostic Ma- chine Extract	1	All diagnostic information available at design time		
Consumes	Software Component Description for Adaptive Platform	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.		
Produces	Diagnostic Map- ping	1	One diagnostic upload/download to port mapping		

Table 3.49: Map Diagnostic Upload/Download to Port(s)



3.6.2 Work Products

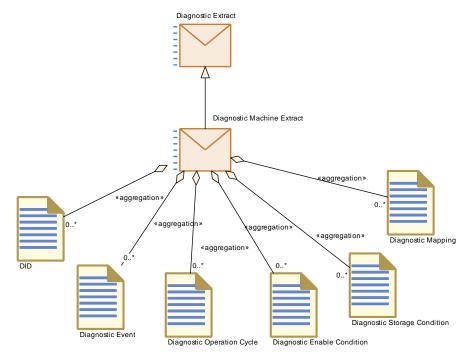


Figure 3.1: Structure of the Diagnostic Machine Extract

3.6.2.1 Diagnostic Machine Extract

Deliverable	Diagnostic Machine Extract		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Work Products		
Brief Description	Diagnostic information	on of a N	Machine
Description	This deliverable con	tains dia	gnostic information of a Machine.
Kind	AUTOSAR XML		
Extends	Diagnostic Extract		
Relation Type	Related Element	Mul.	Note
Aggregates	DID	0*	
Aggregates	Diagnostic Enable Condition	0*	
Aggregates	Diagnostic Event	0*	
Aggregates	Diagnostic Map- ping	0*	
Aggregates	Diagnostic Operation Cycle	0*	
Aggregates	Diagnostic Storage Condition	0*	
Consumed by	Design Diagnostic Mapping	1	All available diagnostic information at the design time



Relation Type	Related Element	Mul.	Note
Consumed by	Map Diagnostic Clear Condition to Port(s)	1	All diagnostic information available at design time
Consumed by	Map Diagnostic Data	1	All available diagnostic information at the design time
Consumed by	Map Diagnostic Enable Condition to Port(s)	1	All available diagnostic information at the design time
Consumed by	Map Diagnostic Event to Port(s)	1	All available diagnostic information at the design time
Consumed by	Map Diagnostic Generic UDS Ser- vice Handler to Port(s)	1	All diagnostic information available at design time
Consumed by	Map Diagnostic Indicator to Port(s)	1	All diagnostic information available at design time
Consumed by	Map Diagnostic Memory Desti- nation to Port (s)	1	All diagnostic information available at design time
Consumed by	Map Diagnostic Operation Cycle to Port(s)	1	All available diagnostic information at the design time
Consumed by	Map Diagnostic Security Level to Port(s)	1	All diagnostic information available at design time
Consumed by	Map Diagnostic Service Data Identifier to Port(s)	1	All diagnostic information available at design time
Consumed by	Map Diagnostic Storage Condition to Port(s)	1	All available diagnostic information at the design time
Consumed by	Map Diagnostic Upload/Download to Port(s)	1	All diagnostic information available at design time
Consumed by	Collect belonging (software) artifacts of Sub Software Clusters	01	Diagnostic extract for a Machine
Consumed by	Create Software Package	01	Diagnostic extract for a Machine
Consumed by	Identify necessary (software) artifacts	01	Diagnostic extract for a Machine
Consumed by	Set Up Initial Machine	01	Diagnostic extract for a Machine

Table 3.50: Diagnostic Machine Extract

3.6.2.2 DID



Artifact	DID			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Work Products			
Brief Description				
Description	This represents the definition of a diagnostic data identifier. Data Identified according to ISO 14229-1[1]. This 16 bit value uniquely defines one ore more data elements (parameters) that can are used in diagnostics to read, write or control data.			
Kind				
Relation Type	Related Element Mul. Note			
Aggregated by	Diagnostic Ma- chine Extract	0*		

Table 3.51: DID

3.6.2.3 Diagnostic Enable Condition

Artifact	Diagnostic Enable	Diagnostic Enable Condition		
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Work Products		
Brief Description				
Description	Represents the defin	Represents the definition of a diagnostic enable condition.		
Kind				
Relation Type	Related Element	Mul.	Note	
Aggregated by	Diagnostic Ma- chine Extract	0*		

Table 3.52: Diagnostic Enable Condition

3.6.2.4 Diagnostic Event

Artifact	Diagnostic Event			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Work Products			
Brief Description				
Description	Represents the definition of a diagnostic event. A diagnostic event uniquely identifies a fault path of the system. An application monitors the system and reports events to the DM.			
Kind				
Relation Type	Related Element Mul. Note			
Aggregated by	Diagnostic Ma- chine Extract	0*		

Table 3.53: Diagnostic Event



3.6.2.5 Diagnostic Mapping

Artifact	Diagnostic Mappin	g				
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Work Products				
Brief Description	Diagnostic Mappings	Diagnostic Mappings				
Description		This represents the mapping of information related to the diagnostic protocol content and the application software.				
	In detail, it contains	the resu	ilts of the following tasks:			
	DiagnosticSet	rviceDa	taMapping			
	DiagnosticSer	rviceSw	Mapping			
	DiagnosticEve	entPortN	Mapping			
	DiagnosticOp	eration(CyclePortMapping			
	DiagnosticEna	ableCor	nditionPortMapping			
	DiagnosticSto	rageCo	nditionPortMapping			
Kind	AUTOSAR XML					
Relation Type	Related Element	Mul.	Note			
Aggregated by	Diagnostic Ma- chine Extract	0*				
Produced by	Map Diagnostic Clear Condition to Port(s)	1	One diagnostic clear condition to port mapping			
Produced by	Map Diagnostic Data	1	One diagnostic data mapping			
Produced by	Map Diagnostic Enable Condition to Port(s)	1	One diagnostic EnableConditionToPorts mapping			
Produced by	Map Diagnostic Event to Port(s)	1	One diagnostic EventToPort mapping			
Produced by	Map Diagnostic Generic UDS Ser- vice Handler to Port(s)	1	One diagnostic generic UDS service handler to port mapping			
Produced by	Map Diagnostic Indicator to Port(s)	1				
Produced by	Map Diagnostic Memory Desti- nation to Port (s)	1	One diagnostic memory destination to port mapping			
Produced by	Map Diagnostic Operation Cycle to Port(s)	1	One diagnostic OperationCycleToPorts mapping			
Produced by	Map Diagnostic Security Level to Port(s)	1	One diagnostic security level to port mapping			



Relation Type	Related Element	Mul.	Note
Produced by	Map Diagnostic Service Data Identifier to Port(s)	1	One diagnostic service data identifier to port mapping
Produced by	Map Diagnostic Storage Condition to Port(s)	1	One diagnostic storage condition to port mapping
Produced by	Map Diagnostic Upload/Download to Port(s)	1	One diagnostic upload/download to port mapping
Produced by	Associate Diagnostic Mapping with Process Design	1*	fully: The linkage between the diagnostic mappings and the corresponding ProcessDesigns
Produced by	Design Diagnostic Mapping	1*	partially: The diagnostic mapping for a Machine, except the linkage between the mappings and the corresponding ProcessDesigns
Consumed by	Associate Diag- nostic Mapping with Process Design	1*	The diagnostic mapping for a Machine, except the linkage between the mappings and the corresponding ProcessDesigns

Table 3.54: Diagnostic Mapping

3.6.2.6 Diagnostic Operation Cycle

Artifact	Diagnostic Operation Cycle			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Work Products			
Brief Description				
Description	Represents a definition of an operation cycle that is base of the event qualifying and for DEM scheduling. An operation cycle is the execution of monitor within an application, from a start point to a defined end point inside the application run.			
Kind				
Relation Type	Related Element Mul. Note			
Aggregated by	Diagnostic Ma- chine Extract	0*		

Table 3.55: Diagnostic Operation Cycle

3.6.2.7 Diagnostic Storage Condition



Artifact	Diagnostic Storage Condition			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Diagnostic Mapping::Work Products			
Brief Description				
Description	Represents the defir	Represents the definition of a diagnostic storage condition.		
Kind				
Relation Type	Related Element	Mul.	Note	
Aggregated by	Diagnostic Ma- chine Extract	0*		

Table 3.56: Diagnostic Storage Condition

3.7 Adaptive Software

This chapter contains the definition of work products and tasks used for the development of Adaptive Software.

3.7.1 Tasks

3.7.1.1 Generate Header Files for Service Interfaces

Task Definition	Generate Header F	Generate Header Files for Service Interfaces			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Tasks			
Brief Description	Generate header file	s for se	rvice interfaces with proxies and skeletons		
Description	header files are gene specific software cor header file and one s contains the header	Header files are generated based on service interfaces. Therefore, the header files are generated regardless of the usage of services by a specific software component. For each service interface one proxy header file and one skeleton header file is generated. The generation contains the header files for the implementation of the software component as well as the service proxies and skeletons, which need to			
Relation Type	Related Element	Related Element Mul. Note			
Consumes	Service Interface Description	1*	For all service interfaces header files are generated.		
Produces	Header Files for Service Interfaces	1*	One proxy header file and one skeleton header file per service interface are generated.		

Table 3.57: Generate Header Files for Service Interfaces

3.7.1.2 Design Software Component for Adaptive Platform



Task Definition	Design Software Co	ompone	ent for Adaptive Platform		
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Tasks			
Brief Description	Design a software co interfaces.	Design a software component with ports that implement service interfaces.			
Description	service interface. If a an RPort is used. If i	A software component is defined with its ports. Each port implements a service interface. If a software component requires a service interface, an RPort is used. If it provides a service interface, an PPort is used. A hierarchy of software components is described by a composition.			
Relation Type	Related Element	Mul.	Note		
Performed by	Tier 2	1	Application Software Designer: The design of software components will probably be performed by an Application Software Designer of a Tier 2 company		
Consumes	Service Interface Description	1*	All service interfaces that shall be implemented by the software component		
Produces	Software Component Description for Adaptive Platform	1	Software component model with the ports that implement service interfaces		

Table 3.58: Design Software Component for Adaptive Platform

3.7.1.3 Implement Software Component Functionality

Task Definition	Implement Software Component Functionality			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Tasks			
Brief Description	Implement the core to	function	ality of the software component.	
Description	In this task, the core functionality of the software component is implemented. This can be done independently of the main function of the executable, where the scheduling local to the executable is described.			
Relation Type	Related Element	Mul.	Note	
Consumes	Header Files for Service Interfaces	1*	Proxy and skeleton header files are the basis for implementing the software component	
Consumes	Software Component Description for Adaptive Platform	1*	The software component model as input for the implementation of the software component.	
Produces	Software Component Source Code	1	The source code of the software component	

Table 3.59: Implement Software Component Functionality

3.7.1.4 Compile Software Component



Task Definition	Compile Software (Compor	nent		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Tasks				
Brief Description	Compile the software	e compo	onent in order to produce object code.		
Description	Compile the software service interfaces.	Compile the software component together with the header files for service interfaces.			
	software component used compiler and c application develope given beforehand to On the other hand, t	This task can be performed by the application developer in case software component object code shall be delivered. In this case, the used compiler and compiler settings need to be agreed on between application developer and integrator. This Build Chain Configuration is given beforehand to the application developer. On the other hand, this task can be performed by the integrator. In this case, the application developer has delivered the source code directly to the integrator.			
Relation Type	Related Element	Mul.	Note		
Consumes	Build Chain Con- figuration	1	Settings used for compiling the software component		
Consumes	Software Component Source Code	1	Source code of the software component for compilation		
Consumes	Header Files for Service Interfaces	1*	Used header files of the software component for compilation		
Consumes	Middleware Library Header Files	0*	Library header files needed for compiling the software components		
Produces	Software Component Object Code	1	Object code of the software component after compilation		

Table 3.60: Compile Software Component

3.7.1.5 Develop Main Function

Task Definition	Develop Main Fund	Develop Main Function			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Tasks			
Brief Description	Develop the main fu	nction fo	or one executable.		
Description	one main function is flow of the executable	For one executable, which can contain several software components, one main function is developed. The main function defines the control flow of the executable including the scheduling of the software components inside the executable.			
Relation Type	Related Element	Related Element Mul. Note			
Consumes	Software Component Source Code	1*	Scheduling and communication of several software components within one executable is defined		
Produces	Main Function	1	One main function per executable		

Table 3.61: Develop Main Function

3.7.1.6 Configure Serialization for Adaptive Platform



Task Definition	Configure Serialization for Adaptive Platform		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Tasks		
Brief Description	Define serialization	propertie	es for the Adaptive Platform
Description	Define the properties of the serialization, i.e. how the data in the service interfaces shall be serialized for the transport on SOME/IP. The alignment, session handling, size of length indicator and endianness needs to be defined.		
Relation Type	Related Element Mul. Note		
Consumes	Service Interface Description	01	Optional if you only configure default values for the serialization
Produces	Serialization Configuration	1*	Serialization properties for the service interfaces

Table 3.62: Configure Serialization for Adaptive Platform

3.7.1.7 Generate Serialization Code for Adaptive Platform

Task Definition	Generate Serializat	Generate Serialization Code for Adaptive Platform			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Tasks			
Brief Description	Generate serialization	n code	for service interfaces.		
Description	Generate the serialize	Generate the serialization code based on the configuration settings.			
Relation Type	Related Element	Related Element Mul. Note			
Consumes	Serialization Configuration	1*	Configuration settings are the basis for generating the serialization code.		
Consumes	Service Interface Description	1*	Service interfaces that are implemented by the software components are needed for generating the serialization code		
Produces	Serialization Source Code	1	Source code for the serialization can be generated		

Table 3.63: Generate Serialization Code for Adaptive Platform

3.7.1.8 Implement Service Proxies and Skeletons

Task Definition	Implement Service	Implement Service Proxies and Skeletons		
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Tasks		
Brief Description	Implement service p	Implement service proxies and skeletons for an Adaptive Platform		
Description	calls that are used for	Service proxies and skeletons for an Adaptive Platform, i.e. the method calls that are used for service-oriented communication, are implemented. The implementation is based on the serialization settings		
Relation Type	Related Element	Related Element Mul. Note		
Consumes	Header Files for Service Interfaces	1*	Header files contain proxies and skeletons to be implemented	



Relation Type	Related Element	Mul.	Note
Consumes	Serialization Configuration	1*	Serialization of data is needed for implementing service proxies and skeletons
Produces	Implemented Proxies and Skeletons	1*	Implementation of service proxies and skeletons given as source code

Table 3.64: Implement Service Proxies and Skeletons

3.7.1.9 Build (Adaptive) Executable

Task Definition	Build (Adaptive) Ex	Build (Adaptive) Executable			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Tasks			
Brief Description	Build executable bas	ed on o	ne or more software components.		
Description	code and necessary	The software components are linked together with the serialization code and necessary middleware libraries. Together with the main function, the executable is build.			
Relation Type	Related Element	Mul.	Note		
Consumes	Build Chain Configuration	1	Settings for the compiler and linker		
Consumes	Main Function	1	One main function per executable		
Consumes	Serialization Source Code	01	Serialization for the executable		
Consumes	Implemented Proxies and Skeletons	0*	Source code of service proxies and skeletons		
Consumes	Middleware Li- braries	0*	Libraries needed to build the executable		
Consumes	Platform Object Code	0*	Platform modules to be linked together to one executable		
Consumes	Software Component Object Code	0*	Software component to be linked together to one executable		
Produces	(Adaptive) Executable	1	One executable is built		

Table 3.65: Build (Adaptive) Executable

3.7.2 Work Products

3.7.2.1 Build Chain Configuration



Deliverable	Build Chain Configuration			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Work Products			
Brief Description	Used compiler and c	ompiler	settings for building the executable	
Description	The Build Chain Configuration contains the used compiler and compiler settings. These settings are platform implementation specific.			
Kind	Text			
Relation Type	Related Element	Mul.	Note	
Consumed by	Build (Adaptive) Executable	1	Settings for the compiler and linker	
Consumed by	Compile Software Component	1	Settings used for compiling the software component	
Consumed by	Integrate Software	1	Needed for linking all artifacts	

Table 3.66: Build Chain Configuration

3.7.2.2 Header Files for Service Interfaces

Deliverable	Header Files for Se	rvice In	terfaces	
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Work Products			
Brief Description	Header files generat	ed for se	ervice interfaces	
Description	The generated head	er files o	of service interfaces consist of	
			service discovery and method invocation cription and reception	
	 skeleton head 	ler files t	for method calls and event publishing	
	The header files are	the has	is for implementing the functionality of a	
	software component		is for implementing the functionality of a	
Kind	Source Code			
Relation Type	Related Element	Mul.	Note	
Produced by	Generate Header	1*	One proxy header file and one skeleton	
	Files for Service Interfaces		header file per service interface are generated.	
Consumed by	Compile Software	1*	Used header files of the software	
Consumed by	Component	1	component for compilation	
Consumed by	Implement Service	1*	Header files contain proxies and	
	Proxies and Skele- tons		skeletons to be implemented	
Consumed by	10110	4 *	Duayay and alcalaton bandon files and the	
Consumed by	Implement Soft- ware Component	1*	Proxy and skeleton header files are the basis for implementing the software	
	Functionality		component	
Consumed by	Integrate Software	0*	Proxies and skeletons to be implemented	

Table 3.67: Header Files for Service Interfaces

3.7.2.3 (Adaptive) Executable



Deliverable	(Adaptive) Executable			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive			
	Platform::Adaptive Application::Work Products			
Brief Description	Executable containing one or more software components			
Description	The executable can contain an arbitrary hierarchy of software components. The software components contain the functionality of the executable. Executables can be of category application-level or platform-level.			
Kind	Executable			
Relation Type	Related Element	Mul.	Note	
Produced by	Build (Adaptive) Executable	1	One executable is built	
Produced by	Integrate Software	1	Software is integrated into one executable	
Consumed by	Create Execution Manifest	1	One executable can be instantiated several times	
Consumed by	Define Process	1	Executable to be instantiated	
Consumed by	Collect belonging (software) artifacts of Sub Software Clusters	0*	Executables of deployed processes	
Consumed by	Create Software Package	0*	Executables of deployed processes	
Consumed by	Identify necessary (software) artifacts	0*	Executables of deployed processes	
Consumed by	Set Up Initial Machine	0*	Executables of those Platform modules and Adaptive Applications that should run on a initially configured machine. Beside the OS, at least the UCM and connected Platform modules (e.g., a diagnostic communication manager) need to be installed in order to be able to upload other software.	

Table 3.68: (Adaptive) Executable

3.7.2.4 Implemented Service Proxies and Skeletons

Artifact	Implemented Proxies and Skeletons		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Work Products		
Brief Description	Implemented service	proxies	s and skeletons
Description	Implemented source code for the service proxies and skeletons.		
Kind	Source Code		
Relation Type	Related Element	Mul.	Note
Produced by	Implement Service Proxies and Skele- tons	1*	Implementation of service proxies and skeletons given as source code



Relation Type	Related Element	Mul.	Note
Consumed by	Build (Adaptive)	0*	Source code of service proxies and
	Executable		skeletons

Table 3.69: Implemented Proxies and Skeletons

3.7.2.5 Main Function

Deliverable	Main Function			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Work Products		
Brief Description	Main function of an e	executat	ble	
Description	control flow of the ex	This artifact is the main function for one executable. It contains the control flow of the executable including the scheduling of the software components inside the executable.		
Kind	Source Code	Source Code		
Relation Type	Related Element	Mul.	Note	
Produced by	Develop Adaptive Application Software	1	One main function per executable is produced	
Produced by	Develop Adaptive Platform-level Soft- ware	1	Main function for platform-level executable	
Produced by	Develop Main Function	1	One main function per executable	
Consumed by	Build (Adaptive) Executable	1	One main function per executable	
Consumed by	Integrate Software	1	One main function per executable	

Table 3.70: Main Function

3.7.2.6 Serialization Configuration for Adaptive Platform

Deliverable	Serialization Configuration		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Work Products		
Brief Description	Configuration of seri	alizatior	of the data in the service interface
Description	Settings necessary for the serialization of the data in the service interfaces. For SOME/IP, this is e.g. the length of length fields that is put in front of an array.		
Kind	AUTOSAR XML		
Relation Type	Related Element	Mul.	Note
Produced by	Configure Serial- ization for Adaptive Platform	1*	Serialization properties for the service interfaces
Consumed by	Generate Serial- ization Code for Adaptive Platform	1*	Configuration settings are the basis for generating the serialization code.



Relation Type	Related Element	Mul.	Note
Consumed by	Implement Service Proxies and Skele- tons	1*	Serialization of data is needed for implementing service proxies and skeletons

Table 3.71: Serialization Configuration

3.7.2.7 Serialization Source Code

Artifact	Serialization Source Code		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Work Products		
Brief Description	Serialization of data		
Description	Source code for seri	alizing o	lata with SOME/IP.
Kind	Source Code		
Relation Type	Related Element	Mul.	Note
Produced by	Generate Serial- ization Code for Adaptive Platform	1	Source code for the serialization can be generated
Consumed by	Build (Adaptive) Executable	01	Serialization for the executable

Table 3.72: Serialization Source Code

3.7.2.8 Software Component Description for Adaptive Platform

Deliverable	Software Compone	nt Desc	cription for Adaptive Platform		
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Work Products			
Brief Description	Description of a soft	ware co	mponent for the Adaptive Platform		
Description	its ports. A RPort is interface. A PPort is	Description of a software component for the Adaptive Platform with all its ports. A RPort is used, if the software component requires a service interface. A PPort is used, if the software component provides a service interface. A software component can also be of type composition.			
Kind	AUTOSAR XML				
Relation Type	Related Element	Mul.	Note		
Produced by	Design Software Component for Adaptive Platform	1	Software component model with the ports that implement service interfaces		
Produced by	Develop Adaptive Application Software	1*	Output of component model for the software components		
Consumed by	Define and Configure Service Instances	1	Used to map the service instances to ports of a software component		
Consumed by	Map Service Instance to Port Prototype	1	In case the service instances are mapped to ports of a software component		



Relation Type	Related Element	Mul.	Note
Consumed by	Design Diagnostic Mapping	1*	Description of a software component for the Adaptive Platform with all its ports, available at design time.
Consumed by	Implement Soft- ware Component Functionality	1*	The software component model as input for the implementation of the software component.
Consumed by	Map Diagnostic Clear Condition to Port(s)	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Consumed by	Map Diagnostic Data	1*	Description of a software component for the Adaptive Platform with all its ports, available at design time.
Consumed by	Map Diagnostic Enable Condition to Port(s)	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Consumed by	Map Diagnostic Event to Port(s)	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Consumed by	Map Diagnostic Generic UDS Service Handler to Port(s)	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Consumed by	Map Diagnostic Indicator to Port(s)	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Consumed by	Map Diagnostic Memory Desti- nation to Port (s)	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Consumed by	Map Diagnostic Operation Cycle to Port(s)	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Consumed by	Map Diagnostic Security Level to Port(s)	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Consumed by	Map Diagnos- tic Service Data Identifier to Port(s)	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Consumed by	Map Diagnostic Storage Condition to Port(s)	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.
Consumed by	Map Diagnostic Upload/Download to Port(s)	1*	Description of software component for the Adaptive Platform with all their (service) ports, known at design time.

Table 3.73: Software Component Description for Adaptive Platform

3.7.2.9 Software Component Object Code



Deliverable	Software Compone	Software Component Object Code		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Work Products			
Brief Description	Object code of one s	oftware	component	
Description	components belong	Compiled software component source code. Since these software components belong to application-level executables, their implementation is restricted to use the standardized ara API.		
Kind	Object Code			
Relation Type	Related Element	Mul.	Note	
Produced by	Compile Software Component	1	Object code of the software component after compilation	
Produced by	Develop Adaptive Application Software	0*	Compiled software components	
Consumed by	Build (Adaptive) Executable	0*	Software component to be linked together to one executable	
Consumed by	Integrate Software	0*	Object code for application-level executable	

Table 3.74: Software Component Object Code

3.7.2.10 Software Component Source Code

Deliverable	Software Compone	Software Component Source Code		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Adaptive Application::Work Products			
Brief Description	Source code of the o	core fund	ctionality of a software component	
Description	software component	This deliverable contains the source code of the core functionality of a software component. The deliverable includes documentation of the software component.		
	the software compor	In case the integrator is completely responsible for the compilation of the software components and the build of the executable, the source code will be delivered directly.		
Kind	Source Code			
Relation Type	Related Element	Mul.	Note	
Produced by	Implement Soft- ware Component Functionality	1	The source code of the software component	
Produced by	Develop Adaptive Application Software	0*	Software components as source code	
Consumed by	Compile Software Component	1	Source code of the software component for compilation	
Consumed by	Develop Main Function	1*	Scheduling and communication of several software components within one executable is defined	
Consumed by	Integrate Software	0*	Source code for application-level executable	

Table 3.75: Software Component Source Code



3.8 Platform and Machine

This chapter contains the definition of work products and tasks, which are used for the definition and configuration of a machine.

3.8.1 Tasks

3.8.1.1 Define ECU Description

The reference to the performing role is given in [1].

Task Definition	Define ECU Descrip	otion		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::System:: Tasks			
Brief Description	Define a particular E	CU's re	sources.	
Description	Define a particular ECU's resources by describing Hardware Elements, pins, connections. The HW Elements are the main describing elements of an ECU, e.g processing units, memory, peripherals, sensors and actuators. HW Elements have a unique name and can be identified within the ECU description. HW Elements do not necessarily have to be described on the level of an ECU. It is possible to describe HW Elements as parts of other HW Elements. By this means, a hierarchical description of HW Elements can be created. HW Elements provide HW PinGroups and HW Pins for being interconnected among each others. HW PinGroups allow a rough description of how certain groups of HWPins are arranged. The detailed description can be done using the HW Pins.HW Connections are used to describe connection on several levels:connections between HW Elements, connections between HW			
Relation Type	Related Element	Mul.	Note	
Performed by	System Engineer	1		
Produces	ECU Resources Description	1*	Decription of the ECU	

Table 3.76: Define ECU Description

3.8.1.2 Describe Available HW Resources

Task Definition	Describe Available I	Describe Available HW Resources			
Package	I	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Machine Configuration::Tasks			
Brief Description	Description of availab	Description of available hardware resources for the machine			
Description	Optional step for dese Machine.	Optional step for describing available hardware resources for the Machine.			
Relation Type	Related Element	Mul.	Note		



Relation Type	Related Element	Mul.	Note
Consumes	ECU Resources Description	1	Definition of available HW resources for the Machine based on the description of the ECU
Produces	Machine Manifest	01	Available hardware resources of machine

Table 3.77: Describe Available HW Resources

3.8.1.3 Define Function Groups

Task Definition	Define Function Gr	oups		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Machine Configuration::Tasks			
Brief Description	Define Function grou	ups of th	e Machine	
Description	Define function group states of the Machine. Function groups with function group states individually control groups of functionally coherent Application processes.			
Relation Type	Related Element Mul. Note			
Produces	Function Groups	01	Function groups defined for the Machine	

Table 3.78: Define Function Groups

3.8.1.4 Define State Timeouts

Task Definition	Define State Timeouts		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Machine Configuration::Tasks		
Brief Description	Define timeouts for function group states		
Description	Define timeouts for function group states in terms of enter / exit timeouts.		
Relation Type	Related Element	Mul.	Note
Consumes	Function Groups	1	Function Groups of a Machine
Produces	Per State Timeouts	01	PerState Timeouts defined for a Machine

Table 3.79: Define State Timeouts

3.8.1.5 Map Process To Machine

Task Definition	Map Process To Ma	Map Process To Machine		
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Machine Configuration::Tasks		
Brief Description	Map processes to a	Map processes to a particular Machine		
Description	Map processes to a	Map processes to a particular Machine.		
Relation Type	Related Element	Related Element Mul. Note		
Consumes	Process	1	Description of a dedicated Process	
Produces	Process to Machine Mapping	1	Mapping of exactly one Process to exactly one Machine	



Relation Type	Related Element	Mul.	Note
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Table 3.80: Map Process To Machine

3.8.1.6 Configure OS for Adaptive Platform

Task Definition	Configure OS for A	Configure OS for Adaptive Platform			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Machine Configuration::Tasks			
Brief Description	Configuration of the	platform	and the platform modules		
Description		Configure the operating system, e.g. the resource groups and the timer granularity can be defined.			
Relation Type	Related Element Mul. Note				
Consumes	Operating System for Adaptive Platform	1	OS to be configured		
Produces	Machine Manifest	01	Configuration settings of OS		

Table 3.81: Configure OS for Adaptive Platform

3.8.1.7 Configure Log and Trace module

Task Definition	Configure Log and Trace module			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Machine Configuration::Tasks			
Brief Description	Configure the Log a	nd Trace	e module	
Description		Define the Machine-specific configuration settings for the Log and Trace functional cluster.		
Relation Type	Related Element	Mul.	Note	
Consumes	Machine Design	01	Configuration settings of the network connections and service discovery network exchange of a Machine	
Produces	Machine Manifest	1	Configuration of the Log and Trace module	

Table 3.82: Configure Log and Trace module

3.8.1.8 Configure DoIP

Task Definition	Configure DoIP				
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Machine Configuration::Tasks			
Brief Description	Configure DoIP	Configure DoIP			
Description	Define the Machine-	Define the Machine-specific configuration settings for DoIP.			
Relation Type	Related Element	Related Element Mul. Note			
Consumes	Machine Design	01	Configuration settings of the network connections and service discovery network exchange of a Machine		



Relation Type	Related Element	Mul.	Note
Produces	Machine Manifest	01	Configuration of DoIP

Table 3.83: Configure DoIP

3.8.1.9 Configure NM module

Task Definition	Configure NM mod	ule		
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Machine Configuration::Tasks		
Brief Description	Configure the NM m	Configure the NM module		
Description	Define the Machine-	Define the Machine-specific configuration settings for the NM module.		
Relation Type	Related Element	Mul.	Note	
Consumes	Machine Design	01	Configuration settings of the network connections and service discovery network exchange of a Machine	
Produces	Machine Manifest	01	Configuration of the NM module	

Table 3.84: Configure NM module

3.8.2 Work Products

3.8.2.1 Middleware Library Header Files

Artifact	Middleware Library Header Files				
Package	1	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Platform::Work Products			
Brief Description	Header files of midd	leware li	braries		
Description	Header files of middle development.	Header files of middleware libraries, which are needed for application development.			
Kind	Source Code				
Relation Type	Related Element	Mul.	Note		
Consumed by	Compile Software Component	0*	Library header files needed for compiling the software components		
Consumed by	Develop Adaptive Platform-level Soft- ware	0*	Library header files needed for compiling the adaptive platform-level software		

Table 3.85: Middleware Library Header Files

3.8.2.2 Middleware Libraries



Artifact	Middleware Libraries		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Platform::Work Products		
Brief Description	Middleware libraries	that are	needed in order to build the executable
Description	Object code of middleware libraries. These are linked together with other object code in order to build an Executable.		
Kind	Object Code		
Relation Type	Related Element Mul. Note		
Consumed by	Build (Adaptive) Executable	0*	Libraries needed to build the executable

Table 3.86: Middleware Libraries

3.8.2.3 ECU Resources Description

The references to other tasks and work products are given in [1].

Artifact	ECU Resources De	ECU Resources Description			
Package	AUTOSAR Root::M2 Work products	AUTOSAR Root::M2::Methodology::Methodology Library::System:: Work products			
Brief Description	Definition of the reso	Definition of the resources available on an ECU.			
Description	description of hardw peripherals, pins, ha a software compone describe an already structure. It is not in support the design or represented as a set	Definition of the resources available on an ECU. It mainly contains a description of hardware elements (like physical memory sections or peripherals, pins, hardware connections) which need to be referred by a software component or a basic software description. The focus is to describe an already engineered piece of hardware, its content and structure. It is not in the focus of the ECU Resource Description to support the design of electronics hardware itself. In the XML it is represented as a set of HwDescriptionEntity -s			
Kind	AUTOSAR XML				
Relation Type	Related Element	Mul.	Note		
Aggregated by	Complete ECU Description	1			
Produced by	Define ECU Description	1*	Decription of the ECU		
Consumed by	Describe Available HW Resources	1	Definition of available HW resources for the Machine based on the description of the ECU		
Consumed by	Define System Topology	1*			
Consumed by	Define BSW Interfaces	01			
Consumed by	Define ECU Abstraction Component	01			
Consumed by	Define machine	01	All resources which are available for the ECU		
Consumed by	Extend Topology	01			
Consumed by	Generate ECU Executable	01	may be used to set up build environment Meth.bindingTime = CompileTime		



Relation Type	Related Element	Mul.	Note
Consumed by	Implement a BSW Module	01	Meth.bindingTime = SystemDesignTime
Consumed by	Measure Compo- nent Resources	01	
Consumed by	Measure Re- sources	01	
Consumed by	Define Complex Driver Component	0*	
Consumed by	Define VFB Sensor or Actuator Component	0*	
Use meta model element	HwElement	1	

Table 3.87: ECU Resources Description

3.8.2.4 Configured Machine on Adaptive ECU

Deliverable	Configured Machin	Configured Machine on Adaptive ECU			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Machine Configuration::Work Products			
Brief Description	Configured Adaptive	Platforr	m instance		
Description	configured machine,	This work product is a configured Adaptive Platform instance, i.e. a configured machine, where software can be deployed on. The configuration settings are based on the Machine Manifest.			
Kind	Custom	Custom			
Relation Type	Related Element	Related Element Mul. Note			
Produced by	Set Up Initial Machine	1	Machine is configured and software can now be deployed		

Table 3.88: Configured Machine on Adaptive ECU

3.8.2.5 Machine Manifest

Deliverable	Machine Manifest		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Machine Configuration::Work Products		
Brief Description	Configuration of the	machine)
Description	Description of deployment content for the configuration of the machine, independent of any service instances or applications.		
Kind	AUTOSAR XML		
Relation Type	Related Element	Mul.	Note
Aggregates	Function Groups	1	Function Groups configuration of a machine
Aggregates	Per State Timeouts	1	PerState Timeouts configuration of a Machine
Aggregates	Process to Machine Mapping	1*	All ProcessToMachineMappings of a Machine



Relation Type	Related Element	Mul.	Note
Produced by	Configure Log and Trace module	1	Configuration of the Log and Trace module
Produced by	Define machine	1	The machine manifest describes all the configuration settings for one Machine
Produced by	Configure DoIP	01	Configuration of DoIP
Produced by	Configure NM module	01	Configuration of the NM module
Produced by	Configure OS for Adaptive Platform	01	Configuration settings of OS
Produced by	Describe Available HW Resources	01	Available hardware resources of machine
In/out	Finalize machine configuration	1	The machine manifest describes all the configuration settings for one Machine
Consumed by	Create Execution Manifest	1	Instantiation is defined on one specific machine
Consumed by	Define Execution Dependencies	1	Execution dependencies are defined per machine mode.
Consumed by	Define Startup Configuration	1	Startup configuration is defined per machine mode given in the Machine Manifest
Consumed by	Set Up Initial Ma- chine	1	Containing all configuration settings for the Machine

Table 3.89: Machine Manifest

3.8.2.6 Platform Object Code

Deliverable	Platform Object Co	de	
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Platform::Work Products		
Brief Description	Object code of platfo	rm-leve	l software
Description	This is the object code of platform modules. It might be based on standardized service interfaces, as e.g. for the Adaptive Diagnostic Manager, where part of the platform module has been implemented in terms of a software component. Alternatively, the implementation is not based on software components and hence pure platform object code (as e.g. Execution Management). A main function is needed in order to build the executable.		
Kind	Object Code		
Relation Type	Related Element	Mul.	Note
Produced by	Develop Adaptive Platform-level Soft- ware	1*	Object code of platform module
Consumed by	Build (Adaptive) Executable	0*	Platform modules to be linked together to one executable
Consumed by	Integrate Software	0*	Object code for platform-level executable

Table 3.90: Platform Object Code



3.8.2.7 Operating System for Adaptive Platform

Deliverable	Operating System for Adaptive Platform		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Platform::Work Products		
Brief Description	Operating System for	r the Ad	laptive Platform
Description	The operating system for the Adaptive Platform is a platform module, which does not have an Execution Manifest and therefore does not follow the workflow of platform-level applications. The OS is the basis for configuring and setting up the machine.		
Kind	Source Code		
Relation Type	Related Element	Mul.	Note
Produced by	Select OS Distribution	1	Selected OS distribution
Consumed by	Configure OS for Adaptive Platform	1	OS to be configured
Consumed by	Finalize machine configuration	1	OS to be configured
Consumed by	Set Up Initial Machine	1	OS to be installed on machine

Table 3.91: Operating System for Adaptive Platform

3.8.2.8 Process to Machine Mapping

Artifact	Process to Machine Mapping		
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Define and Configure Machine::Machine Configuration		
Brief Description			
Description	A Process to Machine Mapping links exactly one Process to exactly one machine.		
Kind			
Relation Type	Related Element Mul. Note		
Produced by	Map Process To Machine	1	Mapping of exactly one Process to exactly one Machine

Table 3.92: Process to Machine Mapping

3.8.2.9 Function Groups



Artifact	Function Groups			
Package	AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Define and Configure Machine::Machine Configuration			
Brief Description				
Description	This artifact contains	This artifact contains the configuration of function groups of a machine.		
Kind				
Relation Type	Related Element	Mul.	Note	
Produced by	Define Function Groups	01	Function groups defined for the Machine	
Consumed by	Define State Time- outs	1	Function Groups of a Machine	

Table 3.93: Function Groups

3.8.2.10 Per State Timeouts

Artifact	Per State Timeouts	Per State Timeouts			
Package		AUTOSAR Root::M2::Methodology::Methodology Use Cases::Adaptive Platform::Deployment::Define and Configure Machine::Machine Configuration			
Brief Description	Define state timeouts	3			
Description	This artifact contains states.	This artifact contains the configuration of timeouts for function group states.			
Kind					
Relation Type	Related Element	Mul.	Note		
Produced by	Define State Time- outs	01	PerState Timeouts defined for a Machine		

Table 3.94: Per State Timeouts

3.9 Execution Manifest

This chapter contains the definition of work products and tasks, which are used for creating the execution manifest.

3.9.1 Tasks

3.9.1.1 Define Process



Task Definition	Define Process		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Execution Manifest::Tasks		
Brief Description	Define a process as	an insta	Intiation of an executable
Description	Define the instantiation of executables. An executable can be instantiated several times (e.g. with different startup parameters) resulting in different processes.		
Relation Type	Related Element	Mul.	Note
Consumes	(Adaptive) Executable	1	Executable to be instantiated
Produces	Process	1*	Different instantiation of executables can result in different processes.

Table 3.95: Define Process

3.9.1.2 Define Startup Configuration

Task Definition	Define Startup Con	Define Startup Configuration			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Execution Manifest::Tasks			
Brief Description	Define the startup co	onfigurat	tion for one process		
Description	Define the startup co	onfigurat	tion for one process per machine mode.		
Relation Type	Related Element	Related Element Mul. Note			
Consumes	Machine Manifest	1	Startup configuration is defined per machine mode given in the Machine Manifest		
Consumes	Process	1	Startup configuration to be defined for process		
Produces	Mode-dependent Startup Configura- tion	1*	Startup configuration of a process for each mode		

Table 3.96: Define Startup Configuration

3.9.1.3 Define Execution Dependencies

Task Definition	Define Execution D	Define Execution Dependencies			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Execution Manifest::Tasks			
Brief Description	Define execution de	pendenc	cies to other processes		
Description	per machine mode.	Define the execution dependencies for one process to other processes per machine mode. Referencing other processes means that they shall be launched before this process is started.			
Relation Type	Related Element	Related Element Mul. Note			
Consumes	Machine Manifest	1	Execution dependencies are defined per machine mode.		
Consumes	Process	1	Execution dependencies defined for one process		



Relation Type	Related Element	Mul.	Note
Produces	Mode-dependent Startup Configura- tion	1*	Execution dependencies of a process for each mode

Table 3.97: Define Execution Dependencies

3.9.1.4 Associate Process with Process Design

Task Definition	Associate Process with ProcessDesign			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Execution Manifest::Tasks			
Brief Description				
Description	Establish a 1:1 relation between a actual process and its placeholder during the design phase ProcessDesign.			
Relation Type	Related Element	Mul.	Note	
Consumes	Process	1*	Process as input in order to link it to the respective ProcessDesign	
Consumes	Process Design	1*	ProcessDesign as placeholder during design time for the real Process	
Produces	Process	1*	A Process references a respective ProcessDesign	

Table 3.98: Associate Process with ProcessDesign

3.9.2 Work Products

3.9.2.1 Execution Manifest

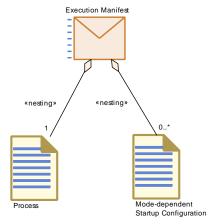


Figure 3.2: Structure of Deliverable Execution Manifest



Deliverable	Execution Manifest			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Execution Manifest::Work Products			
Brief Description	Definition of a proce	ss and a	all its properties	
Description	defined for a specific	machir	nes the process with all its properties. It is ne by referencing its modes in the startup n manifest is defined per process.	
Kind	AUTOSAR XML			
Relation Type	Related Element	Mul.	Note	
Aggregates	Process	1	The process is defined via the Execution Manifest	
Aggregates	Mode-dependent Startup Configura- tion	0*	For each process the startup configuration can be defined in the Execution Manifest	
Produced by	Create Execution Manifest	1*	One execution manifest per instantiated executable	
Consumed by	Collect belonging (software) artifacts of Sub Software Clusters	0*	Several processes can be deployed	
Consumed by	Create Software Package	0*	Several processes can be deployed	
Consumed by	Identify necessary (software) artifacts	0*	Several processes can be deployed	
Consumed by	Set Up Initial Machine	0*	All Execution Manifests needed to run the desired adaptive application (instances or Processes) on a Machine	

Table 3.99: Execution Manifest

3.9.2.2 Process

Artifact	Process		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Execution Manifest::Work Products		
Brief Description	Instantiation of an ex	ecutabl	e
Description	The process is the top-level element of the Execution Manifest and references an executable. It is the unit of deployment on the AUTOSAR adaptive platform and refers to a POSIX process.		
Kind	AUTOSAR XML		
Relation Type	Related Element	Mul.	Note
Produced by	Associate Process with Process Design	1*	A Process references a respective ProcessDesign
Produced by	Define Process	1*	Different instantiation of executables can result in different processes.
Consumed by	Define Execution Dependencies	1	Execution dependencies defined for one process



Relation Type	Related Element	Mul.	Note
Consumed by	Define Startup Configuration	1	Startup configuration to be defined for process
Consumed by	Map Process To Machine	1	Description of a dedicated Process
Consumed by	Associate Process with Process Design	1*	Process as input in order to link it to the respective ProcessDesign
Consumed by	Finalize machine configuration	0*	Processes dedicated to run Executables on a Machine

Table 3.100: Process

3.9.2.3 Process Design

Artifact	Process Design				
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Common Design Artifacts::Work Products			
Brief Description	Proxy for a Process	at desig	n time		
Description	does not exist, yet, i.	This element stands in as a proxy for a Process at the time when it does not exist, yet, i.e., at design time, although the element Process is needed during runtime in order to distinguish different instances of Executables.			
Kind	AUTOSAR XML				
Relation Type	Related Element	Mul.	Note		
Consumed by	Associate Diag- nostic Mapping with Process Design	1*	All dedicated ProssesDesigns for a Machine		
Consumed by	Associate Process with Process Design	1*	ProcessDesign as placeholder during design time for the real Process		

Table 3.101: Process Design

3.9.2.4 Mode-dependent Startup Configuration

Artifact	Mode-dependent S	Mode-dependent Startup Configuration		
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Execution Manifest::Work Products		
Brief Description	Startup configuration	of a pr	ocess	
Description	Startup configuration mode.	Startup configuration for one process and depending on the machine mode.		
Kind	AUTOSAR XML	AUTOSAR XML		
Relation Type	Related Element	Mul.	Note	
Produced by	Define Execution Dependencies	1*	Execution dependencies of a process for each mode	



Relation Type	Related Element	Mul.	Note
Produced by	Define Startup	1*	Startup configuration of a process for
	Configuration		each mode

Table 3.102: Mode-dependent Startup Configuration

3.9.2.5 Process Design

Artifact	Process Design			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Common Design Artifacts::Work Products		
Brief Description	Proxy for a Process	at desig	n time	
Description	does not exist, yet, i.	This element stands in as a proxy for a Process at the time when it does not exist, yet, i.e., at design time, although the element Process is needed during runtime in order to distinguish different instances of Executables.		
Kind	AUTOSAR XML			
Relation Type	Related Element	Mul.	Note	
Consumed by	Associate Diag- nostic Mapping with Process Design	1*	All dedicated ProssesDesigns for a Machine	
Consumed by	Associate Process with Process Design	1*	ProcessDesign as placeholder during design time for the real Process	

Table 3.103: Process Design

3.10 Service Instance

This chapter contains the definition of work products and tasks necessary for instantiating the services.

3.10.1 Tasks

3.10.1.1 Configure Service Interface Deployment



Task Definition	Configure Service Interface Deployment			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Service Instance Manifest::Tasks			
Brief Description	Configure the binding of a Service Interface to a transport layer			
Description	Define the transport layer (e.g. SOME/IP or User Defined) and configure the binding of a service interface to this transport layer. For all elements of the service interface, i.e., events, methods and fields, the deployment is configured.			
	For SOME/IP, an identifier for the service interface is defined. This ID needs to be uniquely defined system-wide and is send as service ID in SOME/IP service discovery messages. In addition, message IDs and SOME/IP event groups for a logical grouping of events are defined. The IDs for messages and event groups need to be uniquely defined in the context of the enclosing SomeipServiceInterface. The User Defined service interface deployment can e.g. be used			
	machine local IPC communication.			
	The responsibility of the configuration of service interface deployment lies with the system responsible.			
Relation Type	Related Element	Mul.	Note	
Consumes	Service Interface Description	1	Deployment is configured for each service interface	
Produces	Service Inter- face Deployment Configuration	1	Configuration of binding of a service interface to a transport layer	

Table 3.104: Configure Service Interface Deployment

3.10.1.2 Define and Configure Service Instance

Task Definition	Define and Configu	Define and Configure Service Instance			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Service Instance Manifest::Tasks			
Brief Description	Define the service in	Define the service instances and configure their search or offer criteria			
Description	several times for differinstances. There can functionality of a service instance configure search critical for provided stance the required service version needs to be a service.	Define service instances. A service interface can be instantiated several times for different purposes resulting in several service instances. There can be provided service instances (server) if the functionality of a service interface is provided, and there can be required service instances (client) in case a service is required. Configure search criteria for required service instances and offer criteria for provided service instances. For search criteria in SOME/IP, the required service instance IDs and required service interface version needs to be defined. Also, required event groups can be specified. For offer criteria in SOME/IP, the provided service instance			
Relation Type	Related Element	Related Element Mul. Note			
Consumes	Service Inter- face Deployment Configuration	1	Instances of service interfaces to be defined		



	Relation Type	Related Element	Mul.	Note
ĺ	Produces	Service Instance	1*	Service instances and their configuration
		Configuration		defined

Table 3.105: Define and Configure Service Instance

3.10.1.3 Define SOME/IP timing

Task Definition	Define SOME/IP Timing		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Service Instance Manifest::Tasks		
Brief Description	Define the timing for	SOME/	IP for the server and the client
Description	Define SOME/IP timing for the server (SomeipSdServerServiceInstanceConfig, SomeipSdServerEventTimingConfig) and the client (SomeipSdClientServiceInstanceConfig, SomeipSdClientEventGroupTimingConfig). This task is optional and only necessary if communication via SOME/IP is used.		
Relation Type	Related Element	Mul.	Note
Consumes	Service Instance Configuration	1	Timing for service instances to be defined
Produces	Service Instance Manifest	1	Timing for service instances contributes to Service Instance Manifest

Table 3.106: Define SOME/IP Timing

3.10.1.4 Map Service Instance to Port Prototype

Task Definition	Map Service Instan	Map Service Instance to Port Prototype			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Service Instance Manifest::Tasks				
Brief Description	Define mapping of s	Define mapping of service instance to a port prototype			
Description	ServiceInstanceToPo order to ensure a un instances within the	Map service instance to a software component port using the ServiceInstanceToPortPrototypeMapping. This mapping is needed in order to ensure a unique relationship between all local service instances within the application (represented by software component ports) and the service instances on the network (e.g. SOME/IP service instances).			
Relation Type	Related Element	Related Element Mul. Note			
Performed by	Tier 1	1	Software Integrator: This activity will probably be performed by a Software Integrator of a Tier 1 company		
Performed by Consumes	Tier 1 Service Instance Configuration	1	probably be performed by a Software		



Relation Type	Related Element	Mul.	Note
Produces	Service Instance To Port Prototype Mapping	1	Mapping contributes to Service Instance Manifest

Table 3.107: Map Service Instance to Port Prototype

3.10.1.5 Map Service Instance to Machine

Task Definition	Map Service Instance to Machine			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Service Instance Manifest::Tasks			
Brief Description	Define mapping of s	ervice ir	stance to machine	
Description	Map service instance to a machine via a communication connector using the ServiceInstanceToMachineMapping. This allows to configure the communication without any assumptions on the applications. For SOME/IP, IP and TP configuration for the client and the server are defined.			
Relation Type	Related Element	Mul.	Note	
Consumes	Machine Design	1	Description of machine that the service instances shall be mapped to	
Consumes	Service Instance Configuration	1	Service instances to be mapped to machine	
Produces	Service Instance To Machine Map- ping	1	Mapping contributes to Service Instance Manifest	

Table 3.108: Map Service Instance to Machine

3.10.2 Work Products

3.10.2.1 Service Interface Deployment Configuration

Artifact	Service Interface Deployment Configuration			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Service Instance Manifest::Work Products			
Brief Description	Deployment configur	ation fo	r a service interface	
Description	Description of deployment configuration with respect to a transport layer for a service interface. For SOME/IP, service interface ID, message IDs and event groups are defined.			
Kind	AUTOSAR XML			
Relation Type	Related Element	Mul.	Note	
Produced by	Configure Service Interface Deployment	1	Configuration of binding of a service interface to a transport layer	
Consumed by	Define and Configure Service Instance	1	Instances of service interfaces to be defined	

Table 3.109: Service Interface Deployment Configuration



3.10.2.2 Service Instance Configuration

Artifact	Service Instance Configuration			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Service Instance Manifest::Work Products			
Brief Description	Definition and configuration of the service instances			
Description	Required as well as provided service instances are defined and configured. For the configuration, the search criteria for required service instances and offer criteria for provided service instances are specified.			
Kind	AUTOSAR XML			
Relation Type	Related Element Mul. Note			
Produced by	Define and Configure Service Instance	1*	Service instances and their configuration defined	
Consumed by	Define SOME/IP Timing	1	Timing for service instances to be defined	
Consumed by	Map Service Instance to Machine	1	Service instances to be mapped to machine	
Consumed by	Map Service Instance to Port Prototype	1	Service instances to be mapped to port prototypes	

Table 3.110: Service Instance Configuration

3.10.2.3 Service Instance To Machine Mapping

Artifact	Service Instance To Machine Mapping			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Service Instance Manifest::Work Products		
Brief Description				
Description		Service Instances shall be mapped to a Machine (to be more precise: to a communication connector of a Machine)		
Kind				
Relation Type	Related Element	Mul.	Note	
Produced by	Map Service Instance to Machine	1	Mapping contributes to Service Instance Manifest	

Table 3.111: Service Instance To Machine Mapping

3.10.2.4 Service Instance To Port Prototype Mapping



Artifact	Service Instance To Port Prototype Mapping				
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Service Instance Manifest::Work Products			
Brief Description					
Description	context (the instance levels of the software With this mapping it	Service Instances need to be mapped to Port Prototypes in instance context (the instance context includes process, executable, all nesting levels of the software composition and the port prototype). With this mapping it is possible to define how specific Port Prototypes are represented in the middleware in terms of service configuration.			
Kind					
Relation Type	Related Element	Mul.	Note		
Produced by	Map Service Instance to Port Prototype	1	Mapping contributes to Service Instance Manifest		

Table 3.112: Service Instance To Port Prototype Mapping

3.10.2.5 Service Instance Manifest

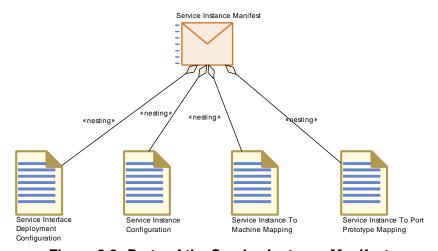


Figure 3.3: Parts of the Service Instance Manifest

Deliverable	Service Instance M	Service Instance Manifest			
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Service Instance Manifest::Work Products			
Brief Description	Definition and config	uration	of a service instance		
Description	discovery. The mapp defined. Optionally, t	Definition of a service instance with its configuration for the service discovery. The mapping of the service instances to the machine is defined. Optionally, the mapping of service instances to the software component ports is specified.			
Kind	AUTOSAR XML				
Relation Type	Related Element	Related Element Mul. Note			
Aggregates	Service Instance Configuration	1			



Relation Type	Related Element	Mul.	Note
Aggregates	Service Instance To Machine Map- ping	1	
Aggregates	Service Instance To Port Prototype Mapping	1	
Aggregates	Service Inter- face Deployment Configuration	1	
Produced by	Define SOME/IP Timing	1	Timing for service instances contributes to Service Instance Manifest
Produced by	Define and Configure Service Instances	1*	Contains all configuration settings for the service instance on a specific machine
Consumed by	Collect belonging (software) artifacts of Sub Software Clusters	0*	Several service instance manifests can be deployed
Consumed by	Create Software Package	0*	Several service instance manifests can be deployed
Consumed by	Identify necessary (software) artifacts	0*	Several service instance manifests can be deployed
Consumed by	Set Up Initial Ma- chine	0*	All Service Instance Manifests needed to run the desired adaptive application (instances or Processes) on a Machine

Table 3.113: Service Instance Manifest

3.11 Deployment

This chapter contains the definition of work products and tasks necessary for deploying Software Packages.

3.11.1 Tasks

3.11.1.1 Create an initial Software Package Manifest



Task Definition	Create an initial Software Package Manifest			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Deployment::Tasks			
Brief Description	Create an initial Soft	ware Pa	ackage Manifest	
Description	The main input for this step are the requirements of the OEM given by means of the Software Cluster Design. This task is about to create an new Software Package Manifest and to transfer the structure and the entries of the given Software Cluster Design into the newly created Software Package Manifest.			
Relation Type	Related Element	Mul.	Note	
Consumes	Software Cluster Design	1	Requirements regarding Software Clusters by the OEM	
Produces	Software Package Manifest	1	partially: Initial meta data of a respective Software Package	

Table 3.114: Create an initial Software Package Manifest

3.11.1.2 Identify necessary (software) artifacts

Task Definition	Identify necessary (software) artifacts				
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Deployment::Tasks				
Brief Description	Identify necessary a	rtifacts			
Description	, , ,	Identify necessary (software) artifacts in order to build the Software Package, also with respect to their versions.			
	Check, whether there are divergences within the required and actual sets of Sub Software Clusters (by means of the aggregated artifacts and versions), if necessary solve them and re-model the Software Package Manifest accordingly. Check, whether there are discrepancies between the required and actual set of the Root Software Cluster (by means of its aggregated Sub Software Clusters and versions)				
Relation Type	Related Element	Mul.	Note		
Consumes	Diagnostic Ma- chine Extract	01	Diagnostic extract for a Machine		
Consumes	Software Cluster Design	01	Requirements that have initially been formulated by an OEM		
	Here, not necessarily needed since the data is already available in Software Package Manifest				
Consumes	Software Package Manifest	01	Meta data which are already transferred from Software Cluster Design		
Consumes	Uploadable Design Artifacts	01	Optional input: Additional design data which are not part of an Application or Machine Manifest		
Consumes	(Adaptive) Exe- cutable	0*	Executables of deployed processes		



Relation Type	Related Element	Mul.	Note
Consumes	Execution Manifest	0*	Several processes can be deployed
Consumes	Service Instance Manifest	0*	Several service instance manifests can be deployed
Produces	Software Package Manifest	1	Updates of the meta data after checks

Table 3.115: Identify necessary (software) artifacts

3.11.1.3 Collect belonging (software) artifacts of Sub Software Clusters

Task Definition	Collect belonging (software) artifacts of Sub Software Clusters			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Deployment::Tasks			
Brief Description	Collect belonging ar	tifacts		
Description	Collect belonging (software) artifacts of Sub Software Clusters into separate baskets (Sub Software Cluster Group) in order to prepare the final step of creating the Software Package (Optional) Execute a receiving inspection of the software artifacts			
Relation Type	Related Element	Mul.	Note	
Consumes	Software Package Manifest	1	Already consolidated meta data (after checks and re-modeling)	
Consumes	Diagnostic Ma- chine Extract	01	Diagnostic extract for a Machine	
Consumes	Uploadable Design Artifacts	01	Optional input: Additional design data which are not part of an Application or Machine Manifest	
Consumes	(Adaptive) Exe- cutable	0*	Executables of deployed processes	
Consumes	Execution Manifest	0*	Several processes can be deployed	
Consumes	Service Instance Manifest	0*	Several service instance manifests can be deployed	
Produces	(Sub) Software Cluster Group	0*	Collection of corresponding artifacts (per Sub Software Cluster)	

Table 3.116: Collect belonging (software) artifacts of Sub Software Clusters

3.11.1.4 Model dependencies between Software Clusters



Task Definition	Model dependencie	es betw	een Software Clusters of any category	
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Deployment::Tasks			
Brief Description	Model dependencies	3		
Description	Thus, this activity describes the handling of dependencies by at least the following tasks:			
	 Check, whether the dependencies between Software Clusters of the same or different categories, given by the respective SoftwareClusterDesign are still valid 			
	 Determine changes between the actual and required dependencies between Software Clusters of any category 			
	If necessary, re-model the Software Package Manifest in accordance with the outcomes of the both tasks above			
Relation Type	Related Element	Mul.	Note	
Consumes	Software Package Manifest	1	Dependencies of the Software Package Manifest were transferred from the Software Cluster Design	
Consumes	(Sub) Software Cluster Group	0*	Optional source in order to check dependencies between Software Clusters (of any category)	
Produces	Software Package Manifest	1	Re-modeled (consolidated) dependencies between Software Clusters of any category	

Table 3.117: Model dependencies between Software Clusters of any category

3.11.1.5 Create installation instructions

Task Definition	Create installation instructions			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Deployment::Tasks			
Brief Description	Create installation in	structio	าร	
Description	update of Software F 'add/update' meanin package shall be uninstructions are defir category. Thus, this activity ma	Package g to inst nstalled ned per s ay includ ation ins	structions per Software Cluster (of any	
Relation Type	Related Element Mul. Note			
Consumes	Software Package Manifest	1	Software Package Manifest without or incomplete installation instructions	



Relation Type	Related Element	Mul.	Note
Produces	Software Package	1	Software Package Manifest, enhanced
	Manifest		by installation instruction

Table 3.118: Create installation instructions

3.11.2 Work Products

3.11.2.1 Software Cluster Design

Deliverable	Software Cluster Design			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Deployment::Work Products			
Brief Description	Software Cluster De	sign		
Description	The deliverable Software Cluster Design contains the requirements that have initially been formulated by an OEM. The formal structure of the corresponding meta model element SoftwareClusterDesign is similar to its counterpart SoftwareCluster. Thus, by means of this, the OEM is able to define the composition and structure of Software Clusters, dedicated diagnostic addresses as well as internal and external dependencies of Software Cluster.			
Kind	AUTOSAR XML			
Relation Type	Related Element	Mul.	Note	
Consumed by	Create Software Package	1	Requirements of the OEM wrt. package structure and parameters given by means of the meta model element SoftwareClusterDesign.	
Consumed by	Create an initial Software Package Manifest	1	Requirements regarding Software Clusters by the OEM	
Consumed by	Identify necessary (software) artifacts	01	Requirements that have initially been formulated by an OEM	
			Here, not necessarily needed since the data is already available in Software Package Manifest	
Use meta model element	SoftwareCluster Design	1		

Table 3.119: Software Cluster Design



3.11.2.2 Software Package

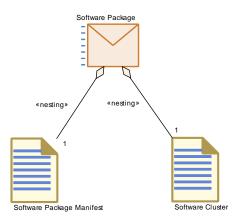


Figure 3.4: Parts of a Software Package

Deliverable	Software Package			
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Deployment::Work Products			
Brief Description	Container to deploy software artifacts to a machine			
Description	According to the AUTOSAR glossary, Software Packages are the units for deployment onto machines (AUTOSAR Adaptive Platform instances). In this respect, they are inputs for and processed by the Adaptive Platform Service UCM} (Update and Configuration Management). In fact, a Software Package consists of two main parts: • a bundle of the actual software artifacts, referred to as Software			
	Cluster			
	 corresponding model data needed to control the upload and installation process of this Software Cluster executed by the UCM 			
Kind	Custom			
Relation Type	Related Element	Mul.	Note	
Aggregates	Software Cluster	1		
Aggregates	Software Package Manifest	1		
Produced by	Compile the Soft- ware Package	1	Compiled Software Package	
Produced by	Create Software Package	1	Software Package for deployment defined	
Consumed by	Management of Software Pack- ages	1*	Newly created or updated Software Packages are stored into a repository and subject of the management of all available Software Packages (including their history)	
Consumed by	Provide and manage Software Packages	1*	Deploy software on a Back-end server by means of Software Package	



Table 3.120: Software Package

3.11.2.3 Software Cluster

Artifact	Software Cluster	Software Cluster		
Package		AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Deployment::Work Products		
Brief Description	Software Cluster			
Description	bundle of software a installed by the UCM Executable(s), Executable Machine Manifest(s) mentioned, that a So in order to mimic the	Thus, from an UCM point of view, the term Software Cluster identifies a bundle of software artifacts that are uploaded together in order to be installed by the UCM. In general, a Software Cluster may contain Executable(s), Execution Manifest(s), Service Instance Manifest(s), Machine Manifest(s) and other development artifacts. It should be mentioned, that a Software Cluster may be structured into sub-blocks in order to mimic the CP diagnostic workflow, where blocks are the smallest parts of update and to enable the execution of update campaigns. Otherwise, the term Software Cluster may also refer to a set of installed software entities (processes that run executables, data or manifests) which form a logical group and which are addressable by the diagnostic management by a shared diagnostic address.		
	installed software en manifests) which for the diagnostic mana			
	Not surprisingly, both definitions match in the sense that the bundle of software uploaded are needed to form the set of installed software entities addressed by the same diagnostic address.			
Kind	Custom	Custom		
Relation Type	Related Element	Mul.	Note	
Consumed by	Manage the data base of Software Clusters (of any category)	1*	Store and manage software cluster within a repository	

Table 3.121: Software Cluster

3.11.2.4 Software Package Manifest

Artifact	Software Package Manifest		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Deployment::Work Products		
Brief Description	Software Package Manifest		
Description	Model, based on meta model element SoftwareCluster, needed to control the upload and installation process of a Software Cluster executed by the UCM.		
Kind	AUTOSAR XML		
Relation Type	Related Element Mul. Note		



Relation Type	Related Element	Mul.	Note
Produced by	Create an initial Software Package Manifest	1	partially: Initial meta data of a respective Software Package
Produced by	Create installation instructions	1	Software Package Manifest, enhanced by installation instruction
Produced by	Identify necessary (software) artifacts	1	Updates of the meta data after checks
Produced by	Model dependencies between Software Clusters of any category	1	Re-modeled (consolidated) dependencies between Software Clusters of any category
Consumed by	Collect belonging (software) artifacts of Sub Software Clusters	1	Already consolidated meta data (after checks and re-modeling)
Consumed by	Compile the Soft- ware Package	1	Integrate the Software Package Manifest into the Software Package
Consumed by	Create installation instructions	1	Software Package Manifest without or incomplete installation instructions
Consumed by	Model dependencies between Software Clusters of any category	1	Dependencies of the Software Package Manifest were transferred from the Software Cluster Design
Consumed by	Manage the data base of Software Clusters (of any category)	1*	Manage meta data of corresponding Software Cluster
Consumed by	Identify necessary (software) artifacts	01	Meta data which are already transferred from Software Cluster Design
Use meta model element	SoftwareCluster	1	

Table 3.122: Software Package Manifest

3.11.2.5 (Sub) Software Cluster Group

Deliverable	(Sub) Software Cluster Group		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Deployment::Work Products		
Brief Description	(Sub) Software Cluster Group		
Description	Basket to collect the (software) artifacts of a Sub Software Cluster		
Kind	Custom		
Relation Type	Related Element	Mul.	Note
Produced by	Collect belonging (software) artifacts of Sub Software Clusters	0*	Collection of corresponding artifacts (per Sub Software Cluster)
Consumed by	Compile the Soft- ware Package	0*	Compile all Sub Software Clusters into the Software Package



Relation Type	Related Element	Mul.	Note
Consumed by	Model dependencies between Software Clusters of any category	0*	Optional source in order to check dependencies between Software Clusters (of any category)

Table 3.123: (Sub) Software Cluster Group

3.11.2.6 Uploadable Design Artifacts

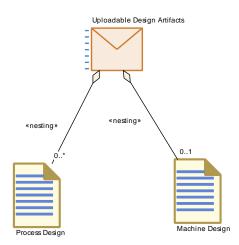


Figure 3.5: Design artifacts needed to be uploaded to the Machine

Deliverable	Uploadable Design	Artifac	ts
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Architecture and Design::Common Design Artifacts::Work Products		
Brief Description	Design artifacts need	ded nee	ded to be uploaded to the Machine
Description	Covers design artifacts, i.e., 'Machine Design' and 'Process Design', that are needed to be uploaded to the Machine in addition to the Manifests.		
Kind	AUTOSAR XML		
Relation Type	Related Element	Mul.	Note
Aggregates	Machine Design	01	
Aggregates	Process Design	0*	
Consumed by	Collect belonging (software) artifacts of Sub Software Clusters	01	Optional input: Additional design data which are not part of an Application or Machine Manifest
Consumed by	Create Software Package	01	Optional input: Additional design data which are not part of an Application or Machine Manifest
Consumed by	Identify necessary (software) artifacts	01	Optional input: Additional design data which are not part of an Application or Machine Manifest
Consumed by	Set Up Initial Machine	01	Optional input: Additional design data which are not part of an Application or Machine Manifest



Table 3.124: Uploadable Design Artifacts

3.11.2.7 Back-end server

Deliverable	Back-end Server		
Package	AUTOSAR Root::M2::Methodology::Methodology Library::Adaptive Platform::Deployment::Work Products		
Brief Description	Repository of upload	lable pa	ckages on a Back-end server
Description	Repository of uploadable packages (Software Packages) including corresponding data bases and server programs in order to provide dedicated versions, change sets and the like to the Machines (Adaptive ECUs) in the field.		
Kind	Custom		
Relation Type	Related Element	Mul.	Note
Produced by	Provision of Soft- ware Packages for machines in the field	1	Organize the Back-end Server in accordance with the requirements of an OEM
Produced by	Management of Software Pack- ages	1*	Software Packages are stored into a repository of Software Packages. In addition, update of a common data base of available Software Packages including their history.
Produced by	Provide and manage Software Packages	1*	Store uploadable packages (Software Packages) into a repository of a Back-end server
Consumed by	Provision of Soft- ware Packages for machines in the field	1	Status quo of the presentation layer of the Back-end Server

Table 3.125: Back-end Server



A Change History

A.1 Change History for AP 19-11

A.1.1 Added Constraints in 19-11

none

A.1.2 Changed Constraints in 19-11

none

A.1.3 Deleted Constraints in 19-11

none

A.1.4 Added Traceables in 19-11

none

A.1.5 Changed Traceables in 19-11

Number	Heading
[TR_AMETH_00001]	Disentangle service interface handling
[TR_AMETH_00002] [TR_AMETH_00003] [TR_AMETH_00004] [TR_AMETH_00006]	editorial changes, fix tech-term references
[TR_AMETH_00008]	Disentangle service interface handling
[TR_AMETH_00018] [TR_AMETH_00021]	editorial changes, fix tech-term references
[TR_AMETH_00022]	remove machine state (which was replaced by function group states)
[TR_AMETH_00024]	editorial changes, fix tech-term references
[TR_AMETH_00025]	remove machine state (which was replaced by function group states)





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Number	Heading
[TR_AMETH_00034] [TR_AMETH_00201] [TR_AMETH_00202] [TR_AMETH_00204]	editorial changes, fix tech-term references
[TR_AMETH_00205]	editorial changes, replace outdated term 'executable group' by 'adaptive executable'.
[TR_AMETH_00207] [TR_AMETH_00208] [TR_AMETH_00209]	editorial changes, fix tech-term references
[TR_AMETH_00212]	editorial changes, consider all currently defined diagnostic mappings
[TR_AMETH_00216] [TR_AMETH_00213] [TR_AMETH_00219] [TR_AMETH_00220] [TR_AMETH_00221] [TR_AMETH_00222] [TR_AMETH_00223]	editorial changes, fix tech-term references

Table A.1: Changed Traceables in 19-11

A.1.6 Deleted Traceables in 19-11

none

A.2 Change History for AP 19-03

A.2.1 Added Constraints in 19-03

none

A.2.2 Changed Constraints in 19-03

none

A.2.3 Deleted Constraints in 19-03

none

A.2.4 Added Traceables in 19-03

none



A.2.5 Changed Traceables in 19-03

none

A.2.6 Deleted Traceables in 19-03

none

A.3 Change History for AP 18-10

A.3.1 Added Constraints in 18-10

none

A.3.2 Changed Constraints in 18-10

none

A.3.3 Deleted Constraints in 18-10

none

A.3.4 Added Traceables in 18-10

none

A.3.5 Changed Traceables in 18-10

Number	Heading
[TR_AMETH_00004]	Creation of the Execution Manifest
[TR_AMETH_00020]	Development of Platform Object Code
[TR_AMETH_00026]	Definition of Execution Manifest
[TR_AMETH_00031]	Setting up an initial machine





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Number	Heading	
[TR_AMETH_00034]	Select the Operating System for Adaptive Platform	

Table A.2: Changed Traceables in 18-10

A.3.6 Deleted Traceables in 18-10

Number	Heading	
[TR_AMETH_00211]	Pool Executables together to form ExecutableGroups	

Table A.3: Deleted Traceables in 18-10

A.4 Change History for AP 18-03

A.4.1 Added Specification Items in AP 18-03

Number	Heading	
[TR_AMETH_00211]	Pool Executables together to form ExecutableGroups	
[TR_AMETH_00212]	Design a diagnostic mapping	
[TR_AMETH_00213]	Relate diagnostic mappings to instances of Executables	
[TR_AMETH_00214]	Configuration of Platform Services	
[TR_AMETH_00215]	Configuration of Platform Foundation Modules	
[TR_AMETH_00216]	Map Processes to a particular machine	
[TR_AMETH_00217]	Definition of resources	
[TR_AMETH_00218]	Create an initial Software Package Manifest	
[TR_AMETH_00219]	Collect all software artifacts that belong to a Software Cluster, structure	
	and model them	
[TR_AMETH_00220]	Model dependencies between Software Clusters of any category	
[TR_AMETH_00221]	Develop installation instructions	
[TR_AMETH_00222]	Create the Software Package	
[TR_AMETH_00223]	Manage the data base of Software Clusters (of any category)	
[TR_AMETH_00224]	Management of Software Packages	
[TR_AMETH_00225]	Provision of Software Packages for machines in the field	
[TR_AMETH_00226]	Documentation of work products	

Table A.4: Added specification items in AP 18-03

A.4.2 Changed Specification Items in AP 18-03

Number	Heading	
[TR_AMETH_00205]	Integrate Software	
[TR_AMETH_00206]	Create a Software Package	
[TR_AMETH_00021]	Configuration of network communication for machine	
[TR_AMETH_00208]	Map a single ServiceInterface to PortInterface elements	
[TR_AMETH_00031]	Setting up an initial machine	
[TR_AMETH_00022]	Definition of machine states, function group states and per-state timeouts	

Table A.5: Changed specification items in AP 18-03



A.4.3 Deleted Specification Items in AP 18-03

Number	Heading
TR_AMETH_00032	Deploying the Software Package

Table A.6: Deleted specification items in AP 18-03

A.5 Change History for AP 17-10

A.5.1 Added Specification Items in AP 17-10

Number	Heading
[TR_AMETH_00200]	Domains of development utilized for the methodology of the AUTOSAR Adap-
	tive Platform
[TR_AMETH_00201]	Develop a Function Architecture
[TR_AMETH_00202]	Develop a Common Software Architecture
[TR_AMETH_00203]	Provide views of subsystems
[TR_AMETH_00204]	Develop the System
[TR_AMETH_00205]	Integrate Software to form AdaptiveAutosarApplications
[TR_AMETH_00206]	Create SoftwareCluster
[TR_AMETH_00207]	Design communication between Classic Platform ECUs and Adaptive Platform
	machines
[TR_AMETH_00208]	Map a single ServiceInterface to PortInterface elements
[TR_AMETH_00209]	Define a signal-based ServiceInterface
[TR_AMETH_00210]	Map signals to services

Table A.7: Added specification items in AP 17-10

A.5.2 Changed Specification Items in AP 17-10

Number	Heading	
[TR_AMETH_00100]	Scope of the Methodology for the Adaptive Platform	
[TR_AMETH_00101]	Definition of tasks, work products and use cases	
[TR_AMETH_00102]	Types of work products	
[TR_AMETH_00001]	Description of the services in a system	
[TR_AMETH_00002]	Development of the software	
[TR_AMETH_00006]	Deployment of the application software	
[TR_AMETH_00032]	Deploying the Software Package	
[TR_AMETH_00033]	Mapping of Service Instances to Port Prototypes	

Table A.8: Changed specification items in AP 17-10

A.5.3 Deleted Specification Items in AP 17-10

Number	Heading	
[TR_AMETH_00030]	Machine-driven and model-driven approach	

Table A.9: Deleted specification items in AP 17-10



A.6 Change History for AP 17-03

A.6.1 Added Specification Items in AP 17-03

Number	Heading	
[TR_AMETH_00100]	Scope of the Methodology for the Adaptive Platform	
[TR_AMETH_00101]	Definition of tasks, work products and use cases	
[TR_AMETH_00102]	Types of work products	
[TR_AMETH_00001]	Description of the services in a system	
[TR_AMETH_00002]	Development of the software	
[TR_AMETH_00003]	Configuration of the machine	
[TR_AMETH_00004]	Creation of the [Application Manifest]	
[TR_AMETH_00005]	Configuration of the service instances	
[TR_AMETH_00006]	Deployment of the application software	
[TR_AMETH_00007]	Definition of data types for the Adaptive Platform	
[TR_AMETH_00008]	Definition of service interfaces for the Adaptive Platform	
[TR_AMETH_00009]	Aggregating service interfaces for reducing the bus load	
[TR_AMETH_00010]	Application-level Software	
[TR_AMETH_00011]	Design of the software components	
[TR_AMETH_00012]	Generation of the header files for service interface	
[TR_AMETH_00013]	Implementation and compilation of software components	
[TR_AMETH_00014]	Development with knowledge of the Build Chain Configuration	
[TR_AMETH_00015]	Development without knowledge of the Build Chain Configuration	
[TR_AMETH_00016]	Development of serialization properties	
[TR_AMETH_00017]	Implementation of service proxies and skeletons	
[TR_AMETH_00018]	Building the (Adaptive) Executable	
[TR_AMETH_00019]	Description of the Adaptive Platform	
[TR_AMETH_00020]	Development of Platform Software	
[TR_AMETH_00021]	Configuration of network communication for machine	
[TR_AMETH_00022]	Definition of machine states and resources	
[TR_AMETH_00023]	Configuration of the operating system	
[TR_AMETH_00024]	Instantiation of (Adaptive) Executable	
[TR_AMETH_00025]	Defintion of startup behavior of a process	
[TR_AMETH_00026]	Defintion of [Application Manifest]	
[TR_AMETH_00027]	Configuration of Service Interface Deployment	
[TR_AMETH_00028]	Configuration of Service Instances	
[TR_AMETH_00029]	Deployment of Service Instances	
[TR_AMETH_00030]	Machine-driven and model-driven approach	
[TR_AMETH_00031]	Setting up the machine	
[TR_AMETH_00032]	Deploying the Software Package	
[TR_AMETH_00033]	Mapping of Service Instances to Application Endpoints	
[TR_AMETH_00034]	Selecting the Operating System for Adaptive Platform	
[TR_AMETH_00035]	Platform-level Software	

Table A.10: Added specification items in AP 17-03

A.6.2 Changed Specification Items in AP 17-03

N/A



A.6.3 Deleted Specification Items in AP 17-03

N/A



B Used classes in Manifest files

B.1 Used classes in Machine Manifest

Used Class	Base
CryptoKeySlot	other
CryptoModuleInstantiation	other
DoIpInstantiation	other
DoIpNetworkConfiguration	other
DoIpRequestConfiguration	other
EnterExitTimeout	other
EthernetCluster	PackageableElement
EthernetCommunicationConnector	other
EthernetNetworkConfiguration	other
EthernetPhysicalChannel	other
GenericModuleInstantiation	other
LogAndTraceInstantiation	other
Machine	PackageableElement
MachineDesign	PackageableElement
ModeDeclaration	other
ModeDeclarationGroup	PackageableElement
ModeDeclarationGroupPrototype	other
NetworkEndpoint	other
NmConfig	PackageableElement
NmInstantiation	other
OsModuleInstantiation	other
Processor	other
ProcessorCore	other
PureLocalTimeBase	other
ResourceGroup	other
SomeipServiceDiscovery	other
SynchronizedMasterTimeBase	other
SynchronizedSlaveTimeBase	other
TimeSyncModuleInstantiation	other
UdpNmCluster	other
UdpNmNode	other

Table B.1: Used classes in MachineManifest

B.2 Used classes in Execution Manifest

Used Class	Base
AliveSupervision	other
CheckpointTransition	other
DeadlineSupervision	other
ExecutionDependency	other
GlobalSupervision	other
HealthChannelExternalStatus	other
HealthChannelSupervision	other
HttpAcceptEncoding	other
LocalSupervision	other



LogicalSupervision	other
ModeDeclaration	other
ModeDeclarationGroup	PackageableElement
ModeDeclarationGroupPrototype	other
PersistencyFile	PackageableElement
PersistencyFileArray	PackageableElement
PersistencyKeyValueDatabase	PackageableElement
PersistencyKeyValuePair	other
PersistencyPortPrototypeToFileArrayMapping	PackageableElement
PersistencyPortPrototypeToKeyValueDatabaseMapping	PackageableElement
PhmActionList	other
PhmContributionToMachineMapping	PackageableElement
PhmLogicalExpression	other
PhmRule	other
PlatformHealthManagementContribution	PackageableElement
PlatformPhmActionItem	other
Process	PackageableElement
ProcessPhmActionItem	other
ProcessToMachineMapping	other
ProcessToMachineMappingSet	PackageableElement
RestHttpPortPrototypeMapping	PackageableElement
ServiceInstanceToPortPrototypeMapping	PackageableElement
StartupConfig	other
StartupConfigSet	PackageableElement
StartupOption	other
StateDependentStartupConfig	other
SupervisionCheckpoint	other
WatchdogPhmActionItem	other

Table B.2: Used classes in ExecutionManifest

B.3 Used classes in Service Instance Manifest

Used Class	Base
CryptoServiceCertificate	PackageableElement
CryptoServiceKey	PackageableElement
CryptoServicePrimitive	PackageableElement
DdsEventDeployment	other
DdsEventQosProps	other
DdsMethodQosProps	other
DdsProvidedServiceInstance	PackageableElement
DdsRequiredServiceInstance	PackageableElement
DdsServiceInstanceToMachineMapping	PackageableElement
DdsServiceInterfaceDeployment	PackageableElement
E2EProfileConfiguration	other
E2EProfileConfigurationSet	PackageableElement
End2EndEventProtectionProps	other
InitialSdDelayConfig	other
ProvidedSomeipServiceInstance	PackageableElement
ProvidedUserDefinedServiceInstance	PackageableElement
RequestResponseDelay	other
RequiredSomeipServiceInstance	PackageableElement



RequiredUserDefinedServiceInstance	PackageableElement
SecOcJobRequirement	other
SecOcSecureComProps	other
SecureComPropsSet	PackageableElement
ServiceInterfaceElementSecureComConfig	other
SomeipCollectionProps	other
SomeipEventDeployment	other
SomeipEventGroup	other
SomeipEventProps	other
SomeipFieldDeployment	other
SomeipMethodDeployment	other
SomeipMethodProps	other
SomeipProvidedEventGroup	other
SomeipRequiredEventGroup	other
SomeipSdClientEventGroupTimingConfig	PackageableElement
SomeipSdClientServiceInstanceConfig	PackageableElement
SomeipSdServerEventGroupTimingConfig	PackageableElement
SomeipSdServerServiceInstanceConfig	PackageableElement
SomeipServiceInstanceToMachineMapping	PackageableElement
SomeipServiceInterfaceDeployment	PackageableElement
SomeipServiceVersion	other
TagWithOptionalValue	other
TlsCryptoCipherSuite	other
TlsSecureComProps	other
UserDefinedEventDeployment	other
UserDefinedFieldDeployment	other
UserDefinedMethodDeployment	other
UserDefinedServiceInstanceToMachineMapping	PackageableElement
UserDefinedServiceInterfaceDeployment	PackageableElement

Table B.3: Used classes in ServiceInstanceManifest

B.4 Used classes in Software Distribution

Used Class	Base
DiagnosticSoftwareClusterProps	PackageableElement
SoftwareActivationDependencyCompareCondition	other
SoftwareActivationDependencyFormula	other
SoftwareActivationDependencyLogicalOperatorEnum	other
SoftwareActivationDependencyOperatorEnum	other
SoftwareCluster	PackageableElement
SoftwareClusterDesign	PackageableElement
SoftwareClusterDesignDependency	other
SoftwareClusterDiagnosticAddressSemanticsEnum	other
SoftwareClusterDoipDiagnosticAddress	other
SoftwarePackage	PackageableElement
SoftwarePackageActionTypeEnum	other
SoftwarePackageActivationActionEnum	other
SoftwarePackageStep	other
UcmDescription	other
UcmStep	other
VehicleDriverNotification	other



VehicleDriverNotificationEnum	other
VehiclePackage	PackageableElement
VehicleRolloutStep	other

Table B.4: Used classes in SoftwareDistribution